

Hand-in Exercise 2 solution

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Abstract

In this document, the solutions for the two problems are given for the Hand-in Exercise 2 in the course Numerical recipes for astrophysics.

1 Question1 Dark Matter Halo

The shared modules for the this question are given by:

```
1 import numpy as np
2 import matplotlib.pyplot as plt
3 from mpl_toolkits.mplot3d import Axes3D
```

question1.py

1.1 a

We wrote a random number generator that returns random floating numbers between the lower limit and the upper limit(here[0,1]). We combined 64.bit XOR-shift and MLCG. The higher 32 bits of the output of 64.bit XOR shift is used as the input for MLCG. And we generated 1000 and 1000000 random numbers to test its quality. The code specific to this question is given by:

```
1 #(a)
2 def RNG(seed, low, up, n):
3     #Seed is the seed. Low is the lower limit and up is the upper limit.
4     #n is the number of random numbers we need to generate
5     ran=np.zeros(n)
6     init=np.uint64(seed)
7     a1=np.uint64(21)
8     a2=np.uint64(35)
9     a3=np.uint64(4)
10    #MLCG
11    m=2**64
12    a=2685821657736338717
13    for i in range(n):
14        #64 bit xor shift
15        x=init
16        x=x^(x>>a1)
17        x=x^(x<<a2)
18        x=x^(x>>a3)
19        #x as input for a multip linear congruential generator
20        Id=np.uint64(int(x)*a%m)
21        #use the high 32bits
22        ran[i]=low+(up-low)*(Id>>np.uint(32))/(2**32)
23        #update the state of next number
24        init=Id
25    return ran
26
27 print('run (a)')
28 seed=31
29 print('The seed is:',seed)
30 a1=RNG(seed,0,1,1000)
31
32 plt.scatter(a1[:-1],a1[1:])
33 plt.xlabel('xi')
34 plt.ylabel('xi+1')
35 plt.title('1000 random numbers')
36 plt.savefig('./plots/Q1ascatter.png',dpi=150)
37 plt.close()
```

```

38 a2=RNG(seed,0,1,1000000)
39 yerr=np.sqrt(1e6*0.05)
40
41 entries, edges, _ =plt.hist(a2,bins=20,range=(0,1),histtype='step',label='sample')
42 #plot poisson uncertainties(the same for all bins)
43 bin_centers=0.5*(edges[:-1]+edges[1:])
44 yexp=np.ones_like(bin_centers)*1e6*0.05
45 plt.errorbar(bin_centers,yexp,yerr=np.sqrt(1e6*0.05),fmt='r.',capsize=3,label='Poisson')
46 #only show [45000,55000] to see the number more clearly
47 plt.ylim(45000,55000)
48 plt.xlabel('bin')
49 plt.ylabel('number')
50 plt.title('1000000 random numbers histogram')
51 plt.legend()
52 plt.savefig('./plots/Q1ahistogram.png',dpi=150)
53 plt.close()
54 #calculate the Pearson correlation coefficient for 100000 numbers
55 #r(xi,xi+1)
56 ri_i1=(np.mean(a2[:99999]*a2[1:100000])-np.mean(a2[:99999])*np.mean(a2[1:100000]))/(np.std(a2[:99999])*np.std(a2[1:100000]))
57 #r(xi,xi+2)
58 ri_i2=(np.mean(a2[:99998]*a2[2:100000])-np.mean(a2[:99998])*np.mean(a2[2:100000]))/(np.std(a2[:99998])*np.std(a2[2:100000]))
59
60 print('The Pearson correlation coefficient r(xi,xi+1) is: ',ri_i1)
61 print('The Pearson correlation coefficient r(xi,xi+2) is: ',ri_i2)
62 #write out result
63 file1=open('Q1a.txt','w')
64 file1.write('\nThe seed is: ')
65 file1.write(str(seed))
66 file1.write('\nThe Pearson correlation coefficient r(xi,xi+1) is:{:.6f}'.format(ri_i1))
67 file1.write('\nThe Pearson correlation coefficient r(xi,xi+2) is:{:.6f}'.format(ri_i2))
68 file1.close()

```

question1.py

The seed of this entire program is 31. Firstly, we generated 1000 randoms numbers between 0 and 1 and plot them in a scatter plot, see Figure 1.

Then we generate 1e6 random numbers between 0 and 1. And bin them in 20 bins 0.05 wide. For each bin, the theoretical value is 50000, so the poisson uncertainty is $\sqrt{50000}$. The result is shown in Figure 2.

In addition, we calculate the Pearson correlation coefficient $r_{x_i x_{i+1}}$ and $r_{x_i x_{i+2}}$ for 1e5 numbers. The result is given by:

```

1 The seed is: 31
2 The Pearson correlation coefficient r(xi,xi+1) is:0.003535
3 The Pearson correlation coefficient r(xi,xi+2) is:0.001840
4

```

Q1a.txt

The absolute values are much smaller than 1, which means that these random numbers have little correlations with each other. Our random number generator has a good quality and can be used for following steps.

1.2 b

We used the transformation method to generate radial distribution of particles. At first, we integrate Hernquist profile from 0 to r and that is $\frac{M*r^2}{(r+a)^2}$. Then we need to normalize it by dividing $M_{dm}(r=\infty)$ and get the $CDF = \frac{r^2}{(r+a)^2}$. The CDF is also the enclosed mass fraction. Then we invert the CDF so that we can sample points: $y = \frac{a*\sqrt{x}}{1-\sqrt{x}}$. x is random numbers between 0 and 1. We use our RNG(random number generators) to generate 1e6 points in $[0,1]$ and use the invert CDF to transfer them to random numbers following the Hernquist distribution.

The code specific to this question is give by:

```

1 #(b)
2 print('run (b)')
3 def Hernquist(r):
4     Mdm=1e12
5     #unit of a:kpc
6     a=80
7     return Mdm*a/(2*np.pi*r*np.power(r+a,3))
8
9

```

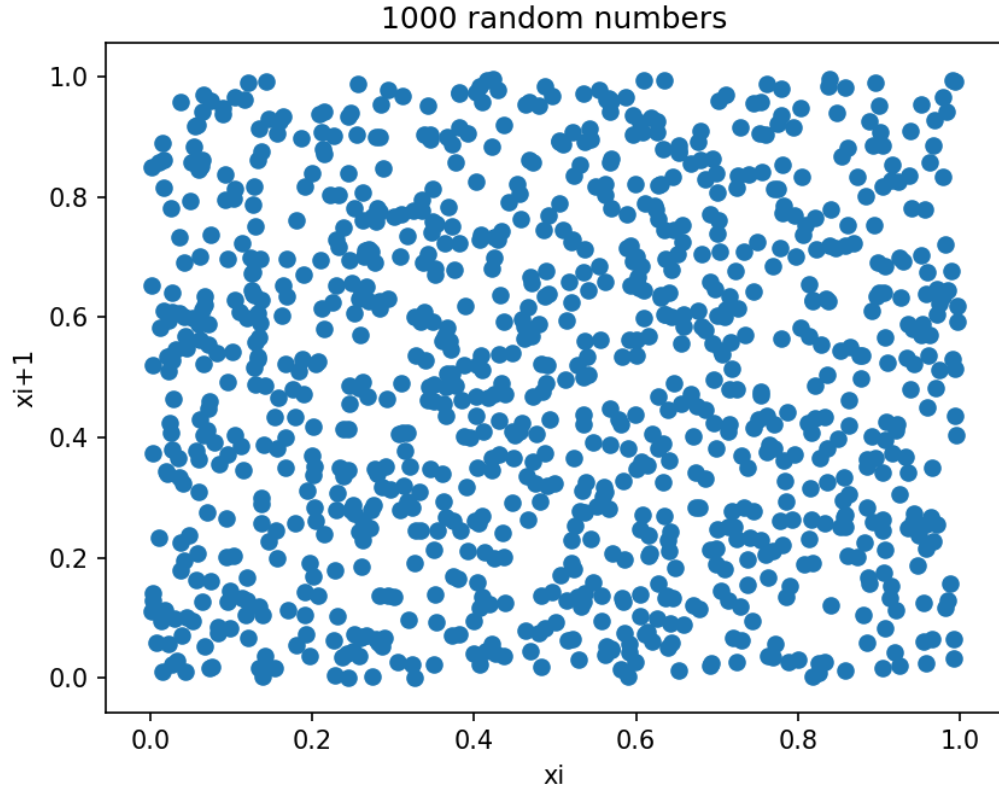


Figure 1: Sequential random numbers against each other(x_{i+1} vs x_i). We can see that these points scattered irregularly, which shows our random numbers have little influence on each other.

```

10 def cdf_Hernq(r):
11     a=80
12     #the cumulative distribution function of the Hernquist function(normalized to 1)
13     return np.power(r/(a+r),2)
14
15 #the inverse of CDF
16 def invercdf(x):
17     a=80
18     return a*np.sqrt(x)/(1-np.sqrt(x))
19 #sampling, a2 is the result of 1a(1e6 uniformed numbers in [0,1])
20 inver=invercdf(a2)
21 inver_sum,inver_bin=np.histogram(inver,bins=10000,range=(0,10000))
22 inver_frac=np.zeros_like(inver_sum)
23 #the enclosed fraction of particles
24 for i in range(inver_frac.size):
25     inver_frac[i]=np.sum(inver_sum[:i+1])
26 inver_frac=inver_frac/np.sum(inver_sum)
27 plt.plot(inver_bin[1:],inver_frac,label='sampled particles fraction')
28
29 #the expected amount of enclosed fraction of mass
30 radius=np.linspace(0,10000,1000)
31 expected_frac=cdf_Hernq(radius)
32 plt.plot(radius,expected_frac,label='expect mass fraction')
33 plt.legend()
34 plt.xlabel('r[kpc]')
35 plt.ylabel('fraction')
36 plt.savefig('./plots/Q1bfraction.png',dpi=150)
37 plt.close()

```

question1.py

We compare the enclosed fraction of particles at a certain radius with the expected amount of enclosed fraction of mass in Figure 3.

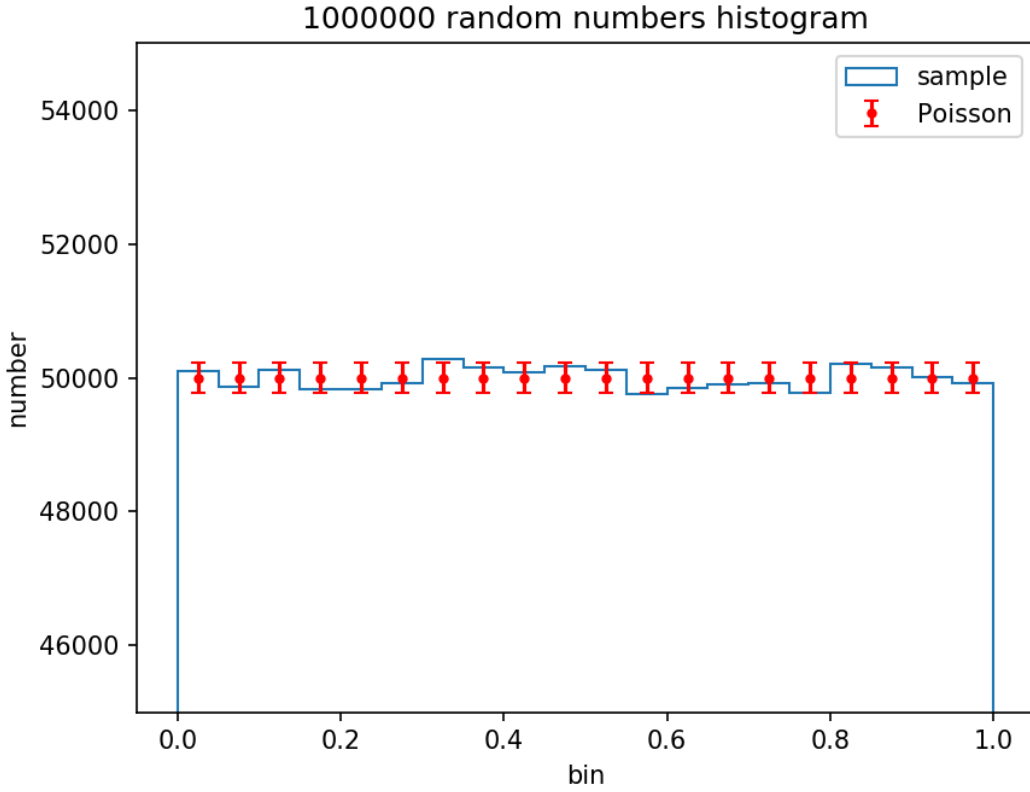


Figure 2: Histogram of 10^6 random numbers. The blue line shows the histogram of the 10^6 numbers and the red error bar shows the poisson uncertainty. We can see that the value of each bin agrees with the mean value within the poisson uncertainty.

1.3 c

We generated a 3D distribution of 10^3 particles in a Hernquist profile. We used 1000 random numbers for r , another 1000 random numbers for θ and another random numbers for ϕ . Because we need θ and ϕ distribute uniformly on a sphere, we should use the inverse transform method to calculate $p(\theta)$ and $p(\phi)$. The probability of having a point in an element area dA should be constant over the sphere. So $\theta = \arccos(1-2*x_1)$ and $\phi = 2*\pi*x_2$, where x_1 and x_2 are uniformed random numbers in $[0,1]$. The code specific to this question is give by:

```

1 #(c)
2 print('run (c)')
3 #phi using 1000 random numbers in a2
4 phi=2*np.pi*np.copy(a2[10000:11000])
5 #theta using another 1000 random numbers in a2
6 theta=np.arccos(1-2*np.copy(a2[20000:21000]))
7 x=np.copy(inver[:1000])*np.sin(theta)*np.cos(phi)/(4*np.pi*np.sqrt(inver[:1000]))
8 y=np.copy(inver[:1000])*np.sin(theta)*np.sin(phi)/(4*np.pi*np.sqrt(inver[:1000]))
9 z=np.copy(inver[:1000])*np.cos(theta)/(4*np.pi*np.sqrt(inver[:1000]))
10 #3d scatter plot
11 fig=plt.figure()
12 ax=fig.add_subplot(111,projection='3d')
13 ax.scatter(x,y,z)
14 ax.set_xlabel('x[kpc]')
15 ax.set_ylabel('y[kpc]')
16 ax.set_zlabel('z[kpc]')
17 ax.set_title('3D scatter plot of 1000 particles')
18 plt.savefig('./plots/Q1c3d.png',dpi=150)
19 plt.close()
20 #make a plot of theta and phi
21 fig2=plt.figure()
22 ax2=fig2.add_subplot(111,projection='3d')
23 ax2.scatter(np.sin(theta)*np.cos(phi),np.sin(theta)*np.sin(phi),np.cos(theta))
24 ax2.set_xlabel('x[kpc]')
25 ax2.set_ylabel('y[kpc]')
26 ax2.set_zlabel('z[kpc]')

```

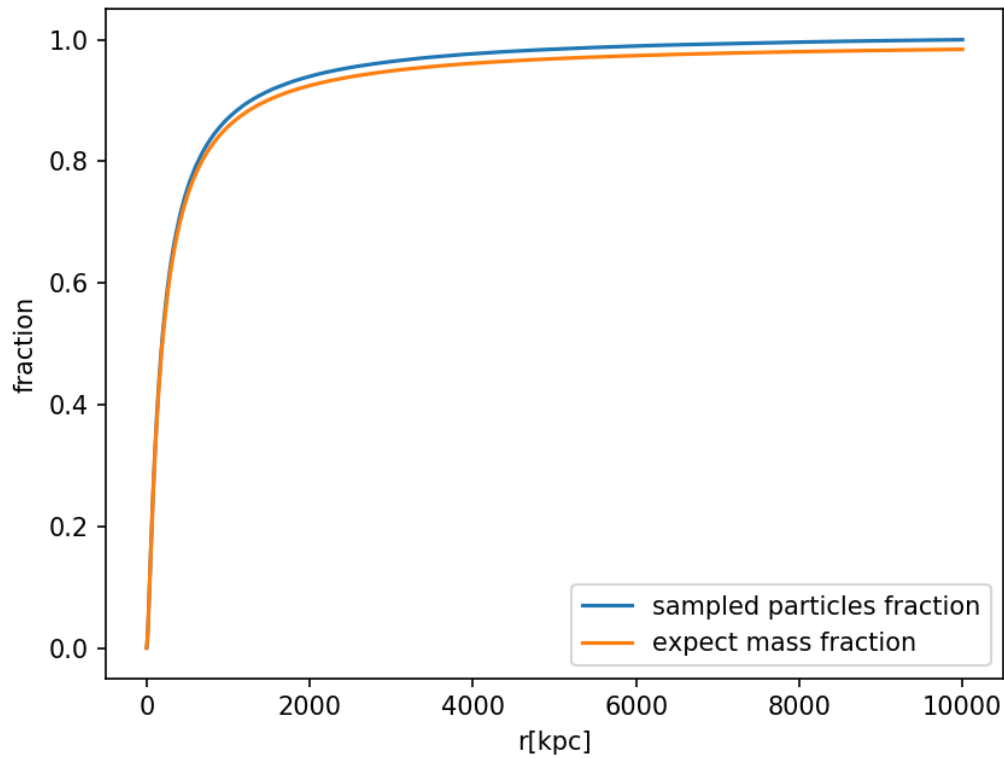


Figure 3: Enclosed fraction of particles and expected enclosed mass fraction. The blue is our sampled results and the orange line is the expected value. The sampled results are slightly higher than the expected value at large radius. The reason is that the sampled value reaches 1 at the largest radius we generated but the expected value goes to 1 only when radius reaches infinity. The radius we generate always has a certain value not infinity. When the number of points increases, the error will become smaller and the sampled line will become very close to the expected one.

```

27 ax2.set_title('random numbers on a sphere')
28 plt.savefig('./plots/Q1csphere.png',dpi=150)
29 plt.close()

```

question1.py

The 3D scatter plot is given by Figure 4. And the distribution of θ and ϕ on a sphere is given by Figure 5.

1.4 d

We wrote a differentiation routine using ridder's method and calculated $\frac{d\rho(x)}{dr}$ at $r=1.2a$ numerically and analytically. The code specific to this question is give by:

```

1 #(d)
2 print('run (d)')
3 #ridder's method for differentiation
4 def ridder_der(f,x,h0=0.1,m=10,d=2):
5     #m:order; h0:initial interval(need to be adjusted for different functions)
6     #two arrays to store previous and current results
7     rdr=np.zeros(m)
8     rdr2=np.zeros(m)
9     hh=h0
10    for i in range(m):
11        #central difference
12        rdr[i]=0.5*(f(x+hh)-f(x-hh))/hh
13        hh=hh/d
14
15    result=np.copy(rdr[0])
16    den=1
17    mul=d**2

```

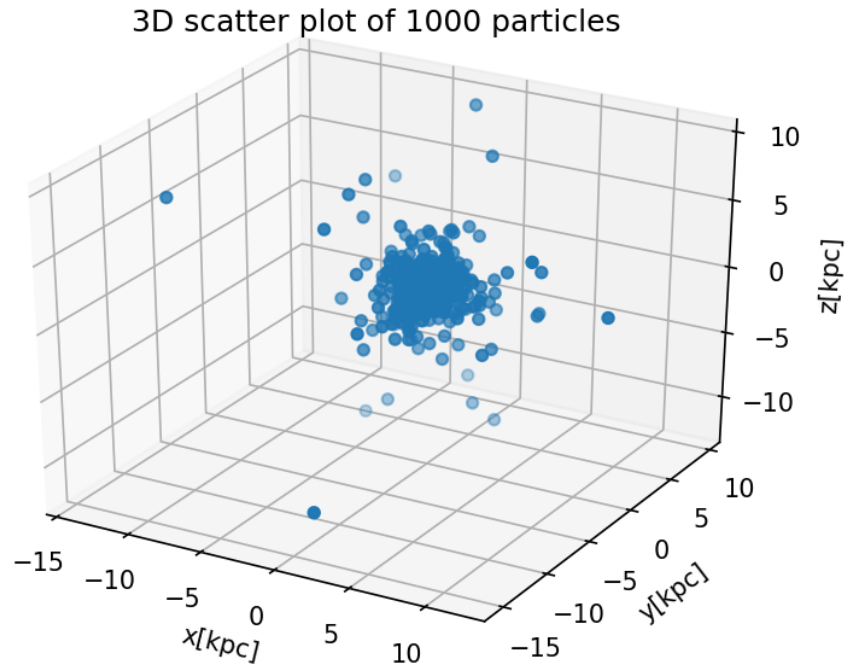


Figure 4: The 3D scatter plot of 1000 random points in a Hernquist profile.

```

18 #initial error(larger number)
19 err=10
20 for i in range(1,m):
21     den*=mul
22     for j in range(m-i):
23         #calculate new values
24         rdr2[j]=(den*rdr[j+1]-rdr[j])/(den-1)
25         errn=max(abs(rdr2[j]-rdr[j]),abs(rdr2[j]-rdr[j+1]))
26         if errn<err:
27             #compare recent results: if error goes down, go to higher order
28             err=errn
29             result=rdr2[j]
30         #terminate early if the error grows
31         elif errn>3*err:
32             return result
33     #put new values to the old array
34     rdr=np.copy(rdr2)
35 return result
36
37 numer_result=riddler_der(Hernquist,x=1.2*80,h0=1,m=10,d=2)
38 print('The numerical result is:{:.10f}'.format(numer_result))
39
40 #analytical result of Hernquist
41 def Hernquist_rd(r):
42     Mdm=1e12
43     #unit of a:kpc
44     a=80
45     return (Mdm*a*0.5/np.pi)*(-(1/(np.power(r,2)*np.power(r+a,3)))-3/(r*np.power(r+a,4)))
46 analy_result=Hernquist_rd(1.2*80)
47 print('The analytical result is:{:.10f}'.format(analy_result))
48
49 #write out result
50 file2=open('Qld.txt','w')
51 file2.write('The numerical result is:{:.10f}'.format(numer_result))
52 file2.write('\nThe analytical result is:{:.10f}'.format(analy_result))
53 file2.close()

```

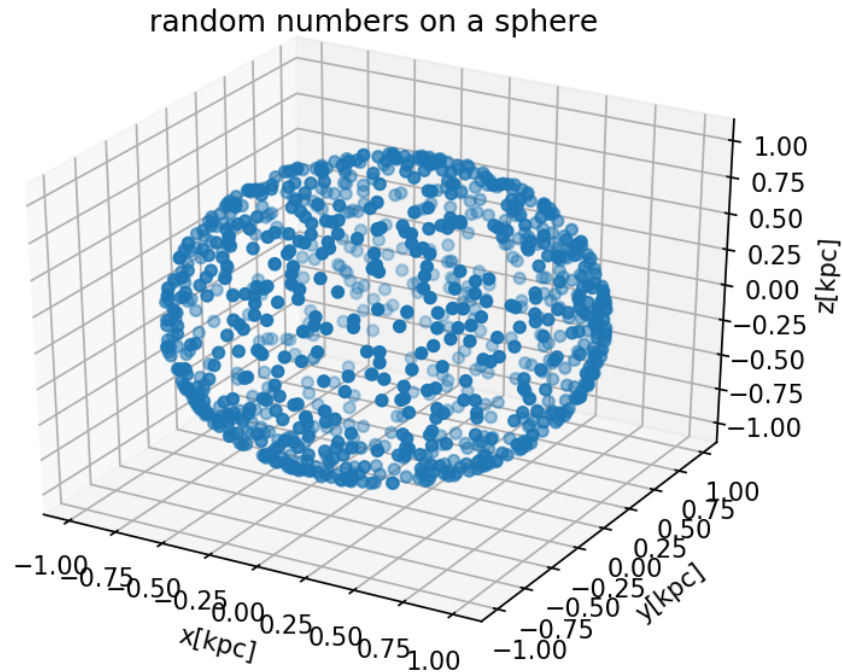


Figure 5: The distribution of θ and ϕ on a sphere. We can see that they are uniform distributed on a sphere.

question1.py

We chose the maximum order=10 and initial interval $h=0.1$ for ridder's method. The result is given by:

```
1 The numerical result is:-668.0899855228
2 The analytical result is:-668.0899855230
```

Q1d.txt

We can see that the numerical value agrees with the analytical value with a relative error close to 10^{-12} , which is very close to the limit of ridder's method(10^{-14}).

1.5 e

We used Newton-Raphson method to find the root when $\Delta=200$ and 500 . The code specific to this question is give by:

```
1 #(e)
2 print('run (e)')
3 def NR(f,a,h=0.001):
4     #Newton-Raphson method
5     #use ridder's differentiation to calculate the derivative, h is the initial h0 for
6     #ridder_der
7     #accuracy
8     acc=1e-6
9     #the maximum number of bisection iteration
10    term=int(1e3)
11    x0=a
12    for i in range(term):
13        #notice: need to adjust h for different function
14        x0_der=ridder_der(f,x0,h0=h)
15        if x0_der==0:
16            #if the derivative ==0, return this point, though it's not a good result
17            return x0
18    x1=x0-f(x0)/x0_der
```

```

18         if abs(f(x1))<acc:
19             #find the root successfully
20             return x1
21         x0=x1
22         #don't find a root with an accuracy smaller than acc under the maximum number of
23         iterations
24         #return the most recent one
25         return x0
26
27 def f1(x):
28     pc=150
29     return Hernquist(x)-200*pc
30
31 def f2(x):
32     pc=150
33     return Hernquist(x)-500*pc
34
35 def mass(x):
36     Mdm=1e12
37     a=80
38     return Mdm*np.power(x,2)/np.power(a+x,2)
39
40 #using Newton-Raphson method to find the root
41 R200=NR(f1,1,h=0.0001)
42 R500=NR(f2,1,h=0.0001)
43 M200=mass(R200)
44 M500=mass(R500)
45 #check
46 print('check function(R200) value:',f1(R200))
47
48 print('R200[kpc] is:',R200)
49 print('M200[Molar] is:',M200)
50
51 #check
52 print('check function(R500) value:',f2(R500))
53 print('R500[kpc] is:',R500)
54 print('M500[Molar] is:',M500)
55 #write out results
56 file3=open('Q1e.txt','w')
57 file3.write('check function(R200) value:{:}'.format(f1(R200)))
58 file3.write('\nR200[kpc] is:{:.6f}'.format(R200))
59 file3.write('\nM200[solar] is:{:.6e}'.format(M200))
60 file3.write('\ncheck function(R500) value:{:}'.format(f2(R500)))
61 file3.write('\nR500[kpc] is:{:.6f}'.format(R500))
62 file3.write('\nM500[solar] is:{:.6e}'.format(M500))
63 file3.close()

```

question1.py

The results are given by:

```

1 check function(R200) value:5.275069270282984e-10
2 R200[kpc] is:88.582774
3 M200[solar] is:2.761037e+11
4 check function(R500) value:6.83940015733242e-10
5 R500[kpc] is:60.808375
6 M500[solar] is:1.864961e+11

```

Q1e.txt

We also show the function value at the root we found, and they are very close to 0. Our root algorithm finds good results. One thing needs to notice is that because we used ridder's method to calculate the differentiation, the initial interval needs to be adjusted for different functions so that it can give us the best results.

1.6 f

We used the downhill simplex method to find the minimum of this potential. Because downhill simplex method requires sort algorithm, we also wrote the mergesort to sort the array and returns its index after sorting. The code specific to this question is give by:

```

1 #(f)
2 print('run (f)')
3 def mergesort(arr, left, right, index):
4     #mergesort arr from arr[left] to arr[right]

```



```

5  #caution: arr will be changed to the sorted array!
6  #Copy it before using this function if you want to keep the initial arr.
7  #also return the index after sorting
8  #recursion
9  if left < right:
10     mid = int(0.5 * (left + right))
11     #sort the left part
12     mergesort(arr, left, mid, index)
13     #sort the right part
14     mergesort(arr, mid + 1, right, index)
15
16     #merge and sort arr from arr[left] to arr[right]. mid is the last index of the left
part
17     #Both of arr[left:mid+1] and arr[mid+1:right] are already sorted
18     i = left
19     j = mid + 1
20     arr_new = np.zeros_like(arr[left:right + 1])
21     index_new = np.zeros_like(index[left:right + 1])
22     d = 0
23     while i <= mid and j <= right:
24         #put the smaller one to arr_new[d]
25         if arr[i] <= arr[j]:
26             arr_new[d] = arr[i]
27             index_new[d] = index[i]
28             i += 1
29         else:
30             arr_new[d] = arr[j]
31             index_new[d] = index[j]
32             j += 1
33         d += 1
34     #One part is ended and all of the rest of another part are smaller or larger than
previous elements.
35     if i <= mid:
36         #put the rest of the left part to arr_new(because are they sorted, we put them
directly to arr_new)
37         arr_new[d:] = np.copy(arr[i:mid + 1])
38         index_new[d:] = np.copy(index[i:mid + 1])
39     else:
40         #put the rest of the right part to arr_new
41         arr_new[d:] = np.copy(arr[j:right + 1])
42         index_new[d:] = np.copy(index[j:right + 1])
43     #put arr_new back to arr
44     arr[left:right + 1] = arr_new
45     index[left:right + 1] = index_new
46
47 #minization
48 def downhill_simplex(f, init_x):
49     #downhill method to find the minimum of f
50     #N dimension requires N+1 points
51     #dimention
52     N = init_x.size
53     #generate N+1 points
54     step1 = -100
55     step2 = 10
56     point = np.zeros((N + 1, N))
57     point[0] = np.copy(init_x)
58     fun = np.zeros(N + 1)
59     fun[0] = f(point[0])
60     for i in range(N):
61         point[i + 1, 0] = point[i, 0] + step1
62         point[i + 1, 1] = point[i, 0] + step2
63         fun[i + 1] = f(point[i + 1])
64     #maximum number of iteration
65     term = 10000
66     #target accuracy
67     acc = 1e-10
68     #record the best point of each iterations
69     trace = np.copy(point[0])
70
71     #start iteration
72     for i in range(term):
73         #sort
74         fun_ind = np.argsort(N + 1)
75         mergesort(fun, 0, N, fun_ind)
76         point = point[fun_ind]
77         #check if find the minimum

```

```

78     ran=abs((fun[0]-fun[-1])/(0.5*(fun[0]+fun[-1])))
79     if ran<acc:
80         #find the best guess x0
81         trace=np.vstack((trace,point[0]))
82         return point[0],trace
83     #centroid of the first N points
84     xcen=np.mean(point[: -1],axis=0)
85     #propose a new point by reflecting
86     xtry=2*xcen-point[-1]
87     if f(xtry)>=fun[0] and f(xtry)<fun[-1]:
88         #new points is better but not the best,accept it
89         point[-1]=np.copy(xtry)
90         fun[-1]=f(xtry)
91         trace=np.vstack((trace,point[0]))
92     elif f(xtry)<fun[0]:
93         #new point is the very best
94         #propose a new point by expanding further
95         xexp=2*xtry-xcen
96         if f(xexp)<f(xtry):
97             #xexp is better, accept it
98             point[-1]=np.copy(xexp)
99             fun[-1]=f(xexp)
100            trace=np.vstack((trace,xexp))
101        else:
102            #accept the reflected one
103            point[-1]=np.copy(xtry)
104            fun[-1]=f(xtry)
105            trace=np.vstack((trace,xtry))
106    else:
107        #xtry is the baddest
108        trace=np.vstack((trace,point[0]))
109        #propose a new point by contracting
110        xtry=0.5*(xcen+point[-1])
111        if f(xtry)<fun[-1]:
112            #accept
113            point[-1]=np.copy(xtry)
114            fun[-1]=f(xtry)
115        else:
116            #zoom on the best point by contracting all others to it
117            point[1:]=0.5*(xcen+point[1:])
118            for i in range(N):
119                fun[i+1]=f(point[i+1])
120    #the target accuracy is not reached after the maximum of iterations
121    #return the current best one and trace
122    return point[0],trace
123
124 def Hernquist2d(var):
125     x,y=var
126     a=80
127     Mdm=1e12
128     G=4.3*1e-6 #unit:kpc km^2 s^-2 Msol^-1
129     return -G*Mdm/(a+np.sqrt(np.power(x-1.3,2)+2*np.power(y-4.2,2)))
130
131 def distance(point,end):
132     return np.sqrt(np.sum(np.power(point-end,2)))
133
134 final_point,trace= downhill_simplex(Hernquist2d,np.array([-1000,-200]))
135
136 #calculate the distance from the final point
137 dis=np.zeros(trace.shape[0])
138 for i in range(trace.shape[0]):
139     dis[i]=distance(trace[i],trace[-1])
140
141 print('The minimum of this potential is {}'.format(Hernquist2d(final_point)))
142 print('The final point is ',final_point)
143
144 file4=open('Q1f.txt','w')
145 file4.write('The minimum of this potential is {:.6f}'.format(Hernquist2d(final_point)))
146 file4.write('\nThe final point(x,y) is:{}'.format(final_point))
147 file4.close()
148
149 plt.plot(dis)
150 plt.xlabel('the number of iterations')
151 plt.ylabel('distance')
152 plt.savefig('./plots/Q1f.png',dpi=150)
153 plt.close()

```

The final point and its potential is given by:

```
1 The minimum of this potential is -53749.999979
2 The final point(x,y) is:[1.30000001 4.20000002]
```

Q1f.txt

It matched with the analytical result (1.3,4.2) with an error about $1e-8$. The distance from the final point at each iteration is given by Figure 6.

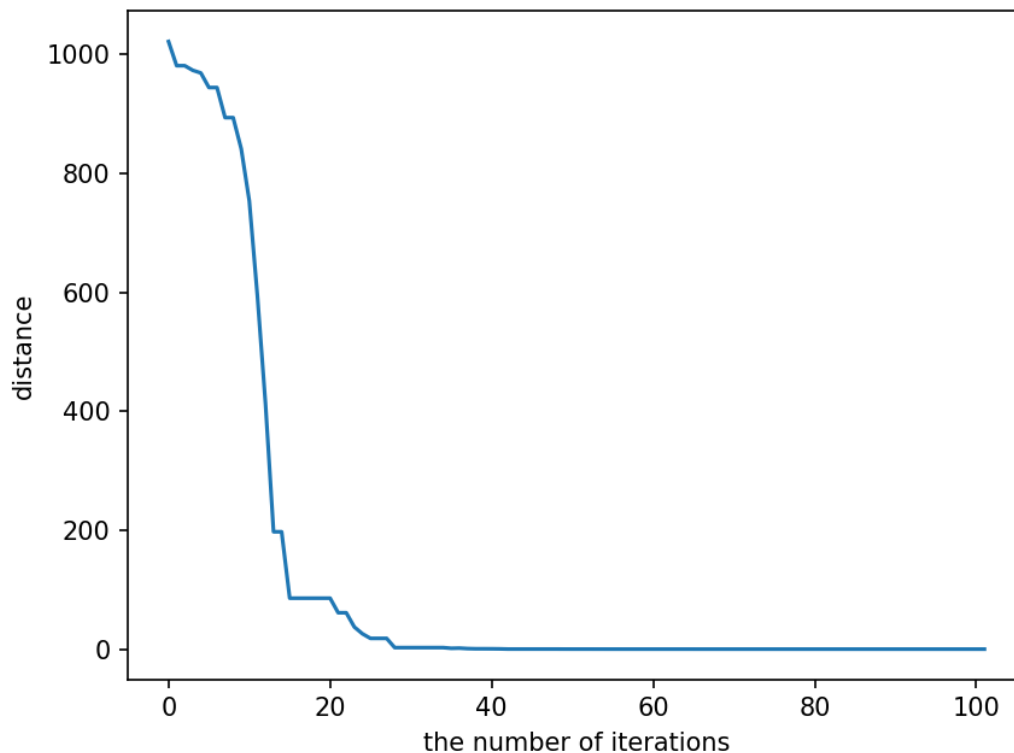


Figure 6: The number of iterations versus the distance from the final point. We can see that it almost successfully reached the final location after 30 iterations. But one thing needs to notice that we need to choose the initial points in a good way. We are already given one point and need to choose another 2 points. If we add the same value to each points in all dimensions, it might not go to the minimum. Instead, these points go close to each other and end at some wrong location. This phenomenon needs to be explored further.

2 question2 Satellite galaxies around a massive central Part2

The shared modules are given by:

```
1 #question2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 seed=31
6 def RNG(seed, low, up, n):
7     #Seed is the seed. Low is the lower limit and up is the upper limit.
8     #n is the number of random numbers we need to generate
9     ran=np.zeros(n)
10    init=np.uint64(seed)
11    a1=np.uint64(21)
12    a2=np.uint64(35)
13    a3=np.uint64(4)
```

```

14  #MLOG
15  m=2**64
16  a=2685821657736338717
17  for i in range(n):
18      #64 bit xor shift
19      x=init
20      x=x^(x>>a1)
21      x=x^(x<<a2)
22      x=x^(x>>a3)
23      #x as input for a multip linear congruential generator
24      Id=np.uint64(int(x)*a%m)
25      #use the high 32bits
26      ran[i]=low+(up-low)*(Id>>np.uint(32))/(2**32)
27      #update the state of next number
28      init=Id
29  return ran

```

question2.py

2.1 a

We wrote a 1D minimization algorithm using the bracket to find the bracket and using the golden search to tighten the bracket until we reached our target accuracy. Finding the maximum of $N(x)$ equals to finding the minimum of $-N(x)$.

The code of this subquestion is given by:

```

1  #(a)
2  print('run (a)')
3  def bracketmin(f, x1, x2):
4      a=x1
5      b=x2
6      if f(a)<f(b):
7          #switch a and b to ensure that f(b)<f(a)
8          a, b=b, a
9      #propose a new point
10     #golden ratio
11     w=1.618
12     c=b+(b-a)*w
13     while f(c)<f(b):
14         #use a, b, c to find a new point by fitting a parabola
15         d=b-0.5*(np.power(b-a, 2)*(f(b)-f(c))-np.power(b-c, 2)*(f(b)-f(a)))/((b-a)*(f(b)-f(c))-(
16         b-c)*(f(b)-f(a)))
17         if ((d-c)*(d-b))<0:
18             #d is between b and c
19             if f(d)<f(c):
20                 #find the bracket
21                 return b, d, c
22             elif f(d)>f(b):
23                 #find the bracket
24                 return a, b, d
25             #the parabola is a bad fit
26             d=c+(c-b)*w
27         else:
28             #d is beyond c
29             if abs(b-d)>20*abs(c-b):
30                 #d is too far away. take another step
31                 d=c+(c-b)*w
32             #move all points over
33             a, b, c=b, c, d
34             if f(a)<f(b):
35                 #always ensure f(b)<f(a)
36                 a, b=b, a
37     return a, b, c
38
39  def golden_search_min(f, bracket):
40     #bracket is a tuple(a<c)
41     a, b, c=bracket
42     acc=1e-6
43     w=0.38197
44     #maximum of iteration
45     term=int(1e6)
46     for i in range(term):

```

```

47 #identify the larger interval
48 #choose d inside the interval in a self-similar way
49 if abs(a-b)>abs(b-c):
50     d=b+(a-b)*w
51 else:
52     d=b+(c-b)*w
53 if abs(c-a)>acc:
54     if f(d)<f(b):
55         #tighten towards d
56         if ((d-a)*(d-b))<0:
57             #d is in between a and b
58             c,b=b,d
59         else:
60             #d is in between b and c
61             a,b=b,d
62     else:
63         if ((d-a)*(d-b))<0:
64             #d is in between a and b
65             a=d
66         else:
67             #d is in between b and c
68             c=d
69     else:
70         #reached the accuracy
71         if f(d)<f(b):
72             return d
73         else:
74             return b
75
76 def Nsate(x):
77     a=2.4
78     b=0.25
79     c=1.7
80     Nsat=100
81     A=256/(5*np.power(np.pi,1.5))
82     return -4*np.pi*A*Nsat*np.power(x,a-1)*np.power(1/b,a-3)*np.exp(-np.power(x/b,c))
83
84
85 bracket=bracketmin(Nsate,0,5)
86 x_max=golden_search_min(Nsate,bracket)
87 N_max=-Nsate(x_max)
88 print('The braket is: ',bracket)
89 print('x at the maximum is:',x_max)
90 print('N(x) at the maximum is:', N_max)
91 #write out result
92 file1=open('Q2a.txt','w')
93 file1.write('The braket after bracketmin is:{:}' .format(bracket))
94 file1.write('\nx at the maximum is:{:10f}' .format(x_max))
95 file1.write('\nN(x) at the maximum is:{:10f}' .format(N_max))
96 file1.close()

```

question2.py

The results are given by:

```

1 The braket after bracketmin is:(0, 5, 13.09)
2 x at the maximum is:0.2230177593
3 N(x) at the maximum is:270.1096030529

```

Q2a.txt

Given (0,5), the bracket algorithm returns (0,5,13.09). Though it exceeds $x_{\max}=5$, we set $N(x)=0$ where $x \geq 5$, because $N(x) \geq 0$ changes smoothly to 0. It does not influence the maximization process.

2.2 b

Because this question only concerns the radial dimension, we can transfer it to 1d sampling, ignoring θ and ϕ . We used the rejection sample to generate the 1000 points.

The code of this subquestion is given by:

```

1 #(b)
2 print('run (b)')
3 def N_norm(x):
4     a=2.4
5     b=0.25

```

```

6     c=1.7
7     A=256/(5*np.power(np.pi,1.5))
8     return 4*np.pi*A*np.power(x,a-1)*np.power(1/b,a-3)*np.exp(-np.power(x/b,c))
9
10    def gx(x):
11        #normalize N to 1
12        N_max=2.7010960100989907
13        return N_norm(x)/N_max
14    #rejection sample
15    def reject_sample(f,x_ran,num):
16        #num is the number of points we want to generate
17        point=np.zeros(num)
18        #seed is the seed of we set for the entire program(global variable)
19        ths=np.copy(seed)
20        a,b=x_ran
21        count=0
22        #the number of random numbers we generate every time
23        smal=10000
24        while count<num:
25            y1=RNG(seed=ths,low=0,up=1,n=smal)
26            ths+=11
27            x1=RNG(seed=ths,low=a,up=b,n=smal)
28            ths+=3
29            i=0
30            while i in range(smal) and count<num:
31                if y1[i]<=f(x1[i]):
32                    #accept it
33                    point[count]=x1[i]
34                    count+=1
35                    i+=1
36            return point
37    #generate 10000 points
38    po_num=10000
39    point_sam=reject_sample(gx,x_ran=(0,5),num=po_num)
40    N_sam=np.zeros(po_num)
41    for i in range(po_num):
42        N_sam[i]=-Nsate(point_sam[0])
43
44    #make a plot
45    arra=np.arange(0.0001,5,0.001)
46    #normalize N(x)
47    plt.plot(np.log10(arra),np.log10(-Nsate(arra)/100),label='N(x)')
48    #log bin
49    bins=np.logspace(np.log10(0.0001),np.log10(5),21)
50    hist,bin_edges=np.histogram(point_sam,bins=bins)
51    hist2=np.copy(hist!=0)
52    bins_cen=0.5*(bins[:-1]+bins[1:])
53    width=bin_edges[1:]-bin_edges[:-1]
54    plt.plot(np.log10(bins_cen[hist2]),np.log10(hist[hist2]/width[hist2])-4,'-o',label='sampled')
55    plt.legend()
56    plt.xlabel('log10(x)')
57    plt.ylabel('log10(N(x))')
58    plt.savefig('./plots/Q2b.png',dpi=150)
59    plt.close()

```

question2.py

Figure 7 shows the histogram of our 10000 sampled points and the normalized $N(x)$.

2.3 c

At first, we selected 100 unique random galaxies from the 10000 galaxies in (b) with equal probability and not rejecting any drawn. We assume that the 10000 galaxies are unique even for those whose radii are the same, because the θ and ϕ can be different. Then we can transfer this question to generate 100 unique uniformed integers from 0 and 9999. We draw 100 galaxies out using these 100 indexes. I referred to the Fisher Yates shuffle mentioned in T5.3. The algorithm is:

- 1.generate a random integer(d1) from 0 and the number of undrawn indexes
- 2.count from the low end and pick the d1th number out from undrawn indexes
- 3.put it into the drawn list and inactive it in the original indexes list
- 4.go back to 1 until we draw 100 indexes

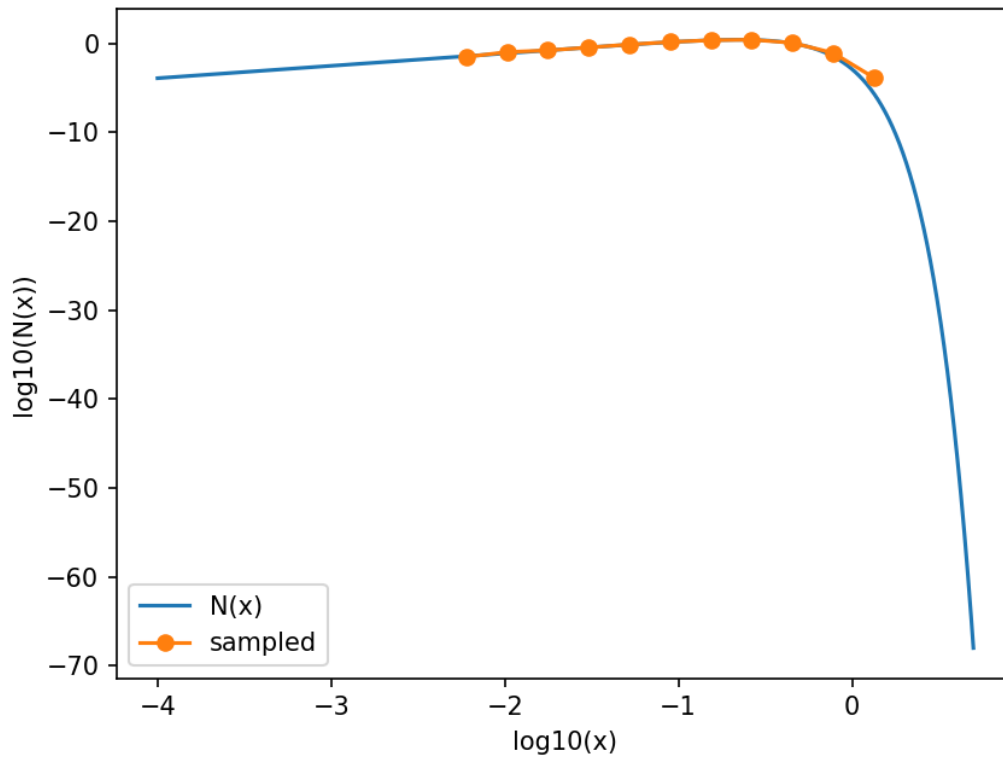


Figure 7: The histogram of our 1000 sampled point and $N(x)$. Both of them are normalized so that the integral equals 1. The blue line is the probability distribution of $N(x)$; the orange line shows the histogram divided by the bin width and the total number 10000. We can see that they agree with each other. Because the probability is very small when $x \leq 1e-3$ and $x \geq 1$, the rejection sample hardly generate points in these ranges when the number of points is small. That's why we only see points showed by the orange range.

Then we used mergesort to sort the 100 drawn galaxies from smallest to largest and plot the number of galaxies within r .

The code of this subquestion is given by:

```

1 #(c)
2 print('run (c)')
3 def mergesort(arr, left, right, index):
4     #mergesort arr from arr[left] to arr[right]
5     #caution: arr will be changed to the sorted array!
6     #Copy it before using this function if you want to keep the initial arr.
7     #also return the index after sorting
8     #recursion
9     if left < right:
10         mid = int(0.5 * (left + right))
11         #sort the left part
12         mergesort(arr, left, mid, index)
13         #sort the right part
14         mergesort(arr, mid + 1, right, index)
15
16     #merge and sort arr from arr[left] to arr[right]. mid is the last index of the left
    part
17     #Both of arr[left:mid+1] and arr[mid+1:right] are already sorted
18     i = left
19     j = mid + 1
20     arr_new = np.zeros_like(arr[left:right + 1])
21     index_new = np.zeros_like(index[left:right + 1])
22     d = 0
23     while i <= mid and j <= right:
24         #put the smaller one to arr_new[d]
25         if arr[i] <= arr[j]:
26             arr_new[d] = arr[i]
27             index_new[d] = index[i]

```

```

28         i+=1
29     else:
30         arr_new[d]=arr[j]
31         index_new[d]=index[j]
32         j+=1
33     d+=1
34     #One part is ended and all of the rest of another part are smaller or larger than
previous elements.
35     if i<=mid:
36         #put the rest of the left part to arr_new(because are they sorted, we put them
directly to arr_new)
37         arr_new[d:]=np.copy(arr[i:mid+1])
38         index_new[d:]=np.copy(index[i:mid+1])
39     else:
40         #put the rest of the right part to arr_new
41         arr_new[d:]=np.copy(arr[j:right+1])
42         index_new[d:]=np.copy(index[j:right+1])
43     #put arr_new back to arr
44     arr[left:right+1]=arr_new
45     index[left:right+1]=index_new
46
47 #select 100 random satellite galaxies
48 sele_num=100
49 drawn=np.zeros(sele_num)
50 record=np.ones(10000, dtype='bool')
51 ths=seed
52 #refer to Fisher Yates shuffle
53 for i in range(100):
54     #generate a random index from 0 and the number of remaining index list
55     dl=np.round(RNG(seed=ths, low=0, up=10000-1-i, n=1))
56     ths+=1
57     temp=0
58     #count the dlth number from the remaining index list
59     for j in range(10000):
60         if temp==dl:
61             break
62         else:
63             if record[j]==True:
64                 temp+=1
65             else:
66                 continue
67     #drawn this dlth number out and inactive this index
68     drawn[i]=np.copy(point_sam[temp])
69     record[temp]=False
70
71 #sort the 100 drawn galaxies from smallest to largest radius
72 drawn_ind=np.arange(0, sele_num)
73 mergesort(drawn, 0, sele_num-1, drawn_ind)
74
75 r=np.linspace(drawn[0], drawn[-1], 100)
76 num_r=np.zeros_like(r)
77 for i in range(r.size):
78     num_r[i]=np.sum(drawn<=r[i])
79 #plot the number of galaxies within r
80 plt.plot(r, num_r)
81 plt.xscale("log")
82 plt.xlim(1e-4, 5)
83 plt.xlabel('r')
84 plt.ylabel('number of galaxies within r')
85 plt.savefig('./plots/Q2c.png', dpi=150)
86 plt.close()

```

question2.py

The plot is given by Figure 8.

2.4 d

We used the mergesort to calculate the median, 16th and 84th percentile for this radial bin(containing the largest number of galaxies). And we divided the 10000 points into 100 haloes and made a histogram of the number of galaxies in this radial bin in each halo, where the width of each bin is 1. Then we plot poisson distribution using the poisson function we wrote in Handin1 with the mean value equals to the mean number of galaxies in this radial bin.

The code of this subquestion is given by:

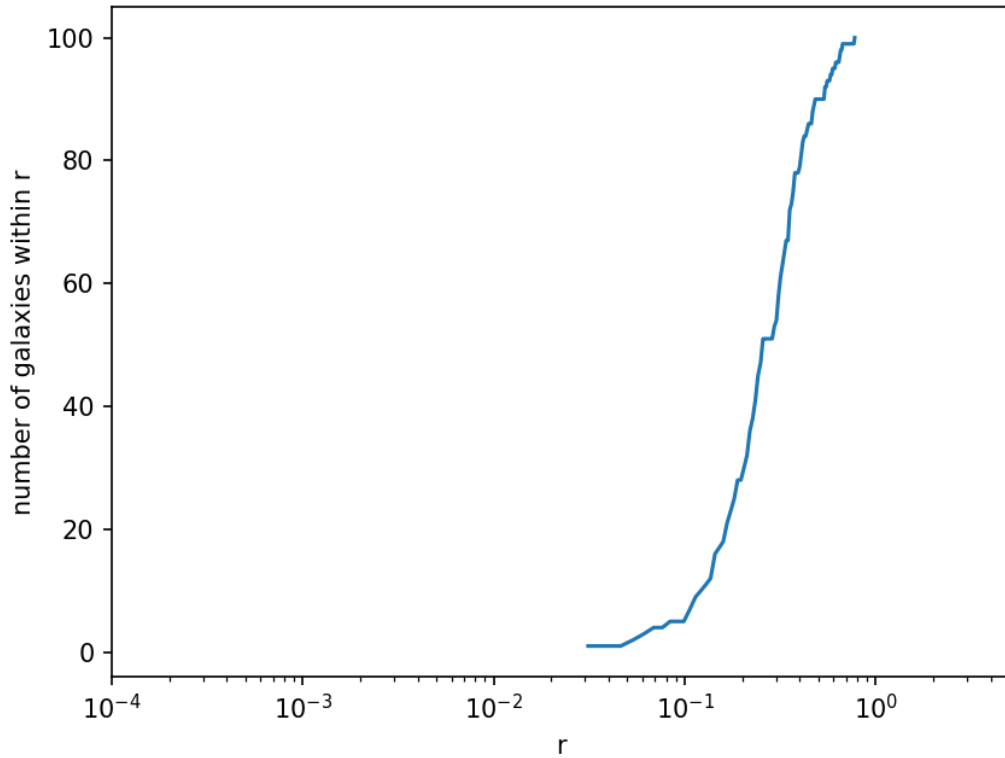


Figure 8: The number of galaxies within r for our 100 selected random samples. The number increases quickly from 0.1 to 1, because this range contains the largest number of galaxies in the original 10000 galaxies. This curve (is CDF in some way) shows that the distribution of the 100 galaxies is similar to the distribution of the original 10000 galaxies. Because we select them randomly following the 3 conditions, it agrees with our expectation.

```

1 #(d)
2 print('run (d)')
3 #find the bin from b containing the largest number of galaxies
4 histnew=np.copy(hist)
5 hist_ind=np.arange(histnew.size)
6 mergesort(histnew,0,histnew.size-1,hist_ind)
7 in1=hist_ind[-1]
8 #sorting
9 mask=(point_sam>=bin.edges[in1])*(point_sam<bin.edges[in1+1])
10 radial_bin=point_sam[mask]
11 radial_bin2=np.copy(radial_bin)
12 radial_size=radial_bin2.size
13 radial_ind=np.arange(0,radial_size)
14 mergesort(radial_bin2,0,radial_size-1,radial_ind)
15 #median of this bin
16 if radial_size%2==0:
17     #radial_size is even
18     radial_median=0.5*(radial_bin2[int(radial_size/2)]+radial_bin2[int(radial_size/2)-1])
19 else:
20     #odd
21     radial_median=radial_bin2[int(radial_size/2)]
22 #16th percentile
23 radial_16=radial_bin2[round(0.16*radial_size)]
24 #84th percentile
25 radial_84=radial_bin2[round(0.84*radial_size)]
26
27 print('median is:',radial_median)
28 print('16% is:',radial_16)
29 print('84% is:',radial_84)
30
31 filed=open('Q2d.txt','w')
32 filed.write('The median of this radial bin is:{:.10f}'.format(radial_median))

```

```

33 filed.write('\n\nThe 16th percentile of this radial bin is:{:.10f}'.format(radial_16))
34 filed.write('\n\nThe 84th percentile of this radial bin is:{:.10f}'.format(radial_84))
35 filed.close()
36 halo=np.zeros(100)
37 for i in range(100):
38     halo[i]=np.sum(mask[100*i:100*(i+1)])
39
40 halo_mean=np.mean(halo)
41 _,_,_=plt.hist(halo,bins=100,label='data')
42
43 def poisson(lm,k):
44     #lm:lambda(mean), k
45     if k==0:
46         #because of factorial, we need to calculate differently when k=0
47         return np.exp(-lm)
48     else:
49         #to prevent overflow, calculate at log space
50         arr=np.arange(1,k+1)
51         p=k*np.log(lm)-lm-np.sum(np.log(arr))
52         #return p to linear
53         return np.exp(p)
54
55 poi_k=np.arange(0,100)
56 poi_dis=np.zeros_like(poi_k,dtype='float64')
57 for i in range(poi_k.size):
58     poi_dis[i]=poisson(halo_mean,poi_k[i])
59
60 plt.plot(poi_k,100*poi_dis,label='poisson')
61 plt.xlabel('The number of galaxies')
62 plt.ylabel('frequency')
63 plt.legend()
64 plt.savefig('./plots/Q2d.png',dpi=150)
65 plt.close()

```

question2.py

The median, 16th and 84th percentile for this bin are given by:

```

1 The median of this radial bin is:0.2607563889
2 The 16th percentile of this radial bin is:0.2158485143
3 The 84th percentile of this radial bin is:0.3099758003

```

Q2d.txt

The histogram and poisson distribution are given by Figure 9.

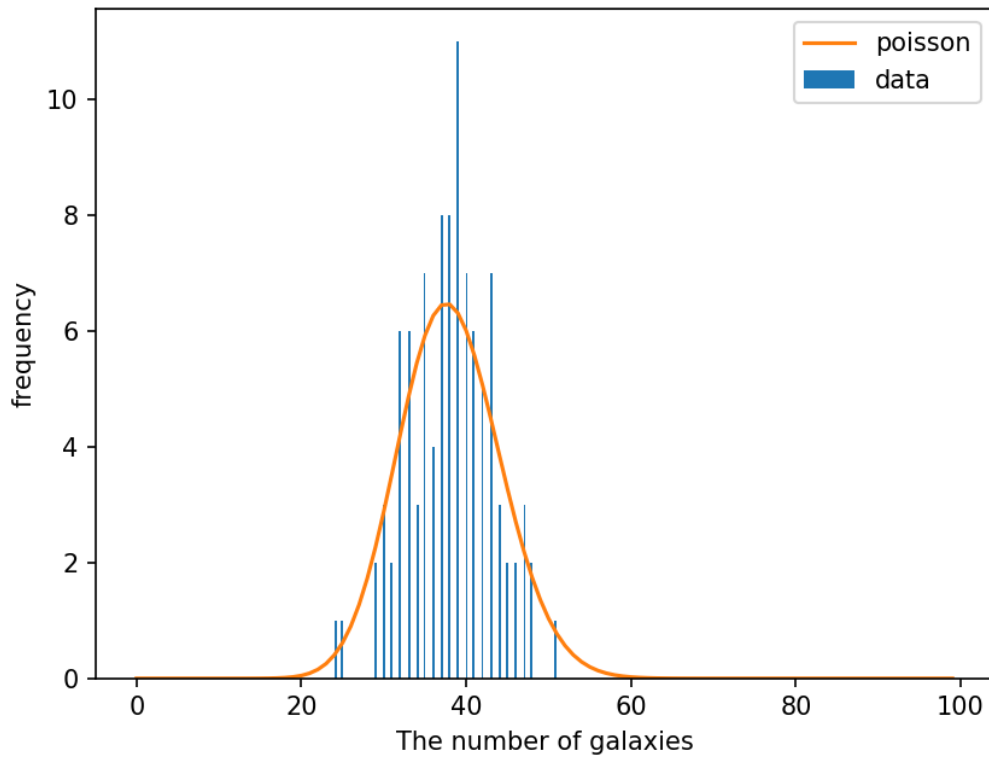


Figure 9: The histogram of the 100 values. The mean number of galaxies in this radial bin is 38.08 in our sample, which is taken as the λ for the Poisson function. The orange line Poisson distribution is multiplied by 100 so that we can compare it with the histogram. Our data agree with the Poisson distribution within some uncertainty.