

# SRS\_CIS-520-001 2020A Final Version A

Claudia Zhu

TOTAL POINTS

**73 / 75**

QUESTION 1

Problem 1 18 pts

1.1 a 2 / 2

- ✓ - 0 pts Correct
- 2 pts Incorrect

1.2 b 2 / 2

- ✓ - 0 pts Correct
- 2 pts Incorrect

1.3 c 2 / 2

- ✓ - 0 pts Correct

1.4 d 2 / 2

- ✓ - 0 pts Correct
- 2 pts Incorrect

1.5 e 2 / 2

- ✓ - 0 pts Correct
- 2 pts Incorrect

1.6 f 2 / 2

- ✓ - 0 pts Correct
- 2 pts Incorrect

1.7 g 2 / 2

- ✓ - 0 pts Correct
- 2 pts Incorrect

1.8 h 2 / 2

- ✓ - 0 pts Correct
- 2 pts Incorrect

1.9 i 2 / 2

- ✓ - 0 pts Correct

- 2 pts Incorrect

QUESTION 2

Problem 2 27 pts

2.1 a 3 / 3

- ✓ - 0 pts Correct
- 3 pts Incorrect

2.2 b 3 / 3

- ✓ - 0 pts Correct

2.3 c 3 / 3

- ✓ - 0 pts Correct
- 3 pts Incorrect

2.4 d 3 / 3

- ✓ - 0 pts Correct
- 3 pts Incorrect

2.5 e 3 / 3

- ✓ - 0 pts Correct
- 3 pts Incorrect

2.6 f 3 / 3

- ✓ - 0 pts Correct
- 3 pts Incorrect

2.7 g 3 / 3

- ✓ - 0 pts Correct
- 3 pts Incorrect

2.8 h 3 / 3

- ✓ - 0 pts Correct
- 3 pts Incorrect

2.9 i 3 / 3

- ✓ - 0 pts Correct
- 3 pts Incorrect

QUESTION 3

3 Problem 3 8 / 10

- 0 pts Correct
- 1 pts Everything correct, missing explicit derivation
- ✓ - 2 pts Correct logic, correct derivation, correct  $h^*$ , incorrect diagram
- 4 pts Correct logic, partially correct derivation, correct  $h^*$ , correct diagram
- 5 pts Correct logic, partially correct derivation, correct  $h^*$ , missing/incorrect diagram
- 5 pts Correct logic, partially correct derivation, missing/incorrect  $h^*$ , correct diagram
- 7 pts Correct logic, everything else either missing/incorrect
- 7 pts Incorrect logic and derivation, everything else correct
- 10 pts Incorrect

QUESTION 4

Problem 4 10 pts

4.1 a 2 / 2

- ✓ - 0 pts Correct
- 2 pts Click here to replace this description.

4.2 b 4 / 4

- ✓ - 0 pts Correct
- 1 pts incorrect result for  $\pi$
- 1 pts incorrect result for  $\lambda_a$
- 1 pts incorrect results for  $\lambda_b$
- 1 pts no derivation
- 4 pts Click here to replace this description.

4.3 c 4 / 4

- ✓ - 0 pts Correct
- 4 pts Click here to replace this description.
- 1 pts incorrect result for  $\pi$

QUESTION 5

Problem 5 10 pts

5.1 a 2 / 2

- ✓ - 0 pts Correct
- 1 pts Incorrect derivation

5.2 b 3 / 3

- ✓ - 0 pts Correct
- 2 pts Incorrect derivation
- 1 pts Incorrect final answer
- 1 pts no derivation

5.3 c 5 / 5

- ✓ - 0 pts Correct
- 1 pts No derivation
- 1 pts final answer is incorrect
- 4 pts Only some derivations are correct. Logic is mostly incorrect.
- 5 pts Incorrect.

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Version A

464505 85

1a) 60

1d)  $h_1, h_2, h_3, h_4$

1g)  $x_3$

1b) 165

1e)  $O(kd)$

1h)  $\pi^*(1) = c, \pi^*(2) = b, \pi^*(3) = c$

1c) 1

1f) 120000

1j)  $(-1, 2)^T$

---

2a) 0.2

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1.1a 2 / 2

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2.7 g 3 / 3

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2.8 h 3 / 3

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2.9 i 3 / 3

✓ - 0 pts Correct

- 3 pts Incorrect



$$\begin{aligned}
 3) \text{er}_0[h^*] &= \inf_{h: X \rightarrow \{1,2,3\}} \text{er}_0[h] \\
 &= E_{(x,y) \sim D} [\ell(y, h(x))]
 \end{aligned}$$

$$\begin{aligned}
 &= E_x E_{y|x} \left[ \mathbb{1}(h(x)=2) \eta_1 + 2 \cdot \mathbb{1}(h(x)=3) \eta_1 \right. \\
 &\quad \left. + \mathbb{1}(h(x)=1) \eta_2 + \mathbb{1}(h(x)=3) \eta_2 \right. \\
 &\quad \left. + 2 \cdot \mathbb{1}(h(x)=1) \eta_3 + \mathbb{1}(h(x)=2) \eta_3 \right]
 \end{aligned}$$

$$\begin{aligned}
 &= E_x E_{y|x} \left[ \mathbb{1}(h(x)=1) (2\eta_3 + \eta_2) \right. \\
 &\quad \left. + \mathbb{1}(h(x)=2) (\eta_1 + \eta_3) \right. \\
 &\quad \left. + \mathbb{1}(h(x)=3) (2\eta_3 + \eta_2) \right]
 \end{aligned}$$

$$= E \left[ \min(2\eta_3 + \eta_2, \eta_1 + \eta_3, 2\eta_1 + \eta_2) \right] \leftarrow \text{minimize this}$$

Choose  $h(x)=1$  when  $2\eta_3 + \eta_2 < \eta_1 + \eta_3$ ,  $2\eta_3 + \eta_2 < 2\eta_1 + \eta_2$

Choose  $h(x)=2$  when  $\eta_1 + \eta_3 < 2\eta_3 + \eta_2$ ,  $\eta_1 + \eta_3 < 2\eta_1 + \eta_2$

Choose  $h(x)=3$  when  $2\eta_1 + \eta_2 < 2\eta_3 + \eta_2$ ,  $2\eta_1 + \eta_2 < \eta_1 + \eta_3$



### 3 Problem 3 8 / 10

- 0 pts Correct
- 1 pts Everything correct, missing explicit derivation
- ✓ - 2 pts **Correct logic, correct derivation, correct  $h^*$ , incorrect diagram**
- 4 pts Correct logic, partially correct derivation, correct  $h^*$ , correct diagram
- 5 pts Correct logic, partially correct derivation, correct  $h^*$ , missing/incorrect diagram
- 5 pts Correct logic, partially correct derivation, missing/incorrect  $h^*$ , correct diagram
- 7 pts Correct logic, everything else either missing/incorrect
- 7 pts Incorrect logic and derivation, everything else correct
- 10 pts Incorrect

$$\begin{aligned}
 4a) \ln \mathcal{L}_c(\theta) &= \sum_{i=1}^m \ln(p(x_i, z_i, \theta)) \\
 &= \sum_{i=1}^m \ln\left(\left(\pi \frac{\lambda_A^{x_i} e^{-\lambda_A}}{x_i!}\right)^{z_i} \left((1-\pi) \frac{\lambda_B^{x_i} e^{-\lambda_B}}{x_i!}\right)^{1-z_i}\right) \\
 &= \sum_{i=1}^m \left( \ln\left(\left(\pi \frac{\lambda_A^{x_i} e^{-\lambda_A}}{x_i!}\right)^{z_i}\right) + \ln\left(\left((1-\pi) \frac{\lambda_B^{x_i} e^{-\lambda_B}}{x_i!}\right)^{1-z_i}\right) \right) \\
 &= \sum_{i=1}^m \left( z_i \ln(\pi) + x_i z_i \ln(\lambda_A) + (-z_i) \lambda_A \cancel{\ln(e)} - z_i \ln(x_i!) \right. \\
 &\quad \left. + (1-z_i) \ln(1-\pi) + (1-z_i) x_i \ln(\lambda_B) - (1-z_i) \lambda_B \cancel{\ln(e)} \right. \\
 &\quad \left. - (1-z_i) \ln(x_i!) \right)
 \end{aligned}$$


---

4.1 a 2 / 2

✓ - 0 pts Correct

- 2 pts [Click here to replace this description.](#)



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4b)  $\hat{\theta} \leftarrow$  to find, we will take partials wrt  $\pi$ ,  $\lambda_A$ ,  $\lambda_B$

Soln for  $\hat{\pi}$ : 
$$\frac{\partial \ln \mathcal{L}_c}{\partial \pi} = \frac{\partial}{\partial \pi} \left( \sum_{i=1}^m z_i \ln(\pi) + (1-z_i) \ln(1-\pi) \right)$$

$\Rightarrow \left[ \sum_{i=1}^m \left( \frac{z_i}{\pi} - \frac{1-z_i}{1-\pi} \right) = 0 \right]$  Soln for this.

$\Rightarrow \sum_{i=1}^m \frac{z_i}{\pi} = \sum_{i=1}^m \frac{1-z_i}{1-\pi}$

$\Rightarrow \frac{1}{\pi} \sum_{i=1}^m z_i = \frac{1}{1-\pi} \sum_{i=1}^m 1-z_i$

$\Rightarrow (1-\pi) \sum_{i=1}^m z_i = \pi \sum_{i=1}^m 1-z_i$

$\Rightarrow \sum_{i=1}^m z_i - \cancel{\pi \sum_{i=1}^m z_i} = m\pi - \cancel{\pi \sum_{i=1}^m z_i}$

$\Rightarrow \sum_{i=1}^m z_i = m\pi \quad \therefore \boxed{\hat{\pi} = \frac{1}{m} \sum_{i=1}^m z_i}$

2nd Der test:

$$\frac{\partial^2 \ln \mathcal{L}_c}{\partial \pi^2} = - \sum_{i=1}^m \frac{z_i}{\pi^2} + \frac{1-z_i}{(1-\pi)^2}$$

$z_i$  always non-negative, so  $\frac{\partial^2 \ln \mathcal{L}_c}{\partial \pi^2}$  always negative

$\Rightarrow \hat{\pi}$  is maximum



4b)

Solve for  $\hat{\lambda}_A$ :

$$\frac{\partial^2 \ln \Sigma_c}{\partial \lambda_A^2} = - \sum_{i=1}^m \frac{x_i z_i}{\lambda_A^2} \quad \lambda_A, x_i, z_i \geq 0$$

$\Rightarrow$  2nd deriv always neg.  
 $\Rightarrow \hat{\lambda}_A$  is max.

$$\frac{\partial \ln \Sigma_c}{\partial \lambda_A} = \frac{\partial}{\partial \lambda_A} \left[ \sum_{i=1}^m x_i z_i \ln(\lambda_A) - z_i \lambda_A \right]$$

$$\Rightarrow \left[ \sum_{i=1}^m \left( \frac{x_i z_i}{\lambda_A} - z_i \right) = 0 \right] \quad \text{solve this}$$

$$\Rightarrow \sum_{i=1}^m \frac{x_i z_i}{\lambda_A} = \sum_{i=1}^m z_i \Rightarrow \frac{1}{\lambda_A} \sum_{i=1}^m x_i z_i = \sum_{i=1}^m z_i$$

$$\Rightarrow \lambda_A = \frac{\sum_{i=1}^m x_i z_i}{\sum_{i=1}^m z_i}$$

$$\hat{\lambda}_A = \frac{\sum_{i=1}^m x_i z_i}{\sum_{i=1}^m z_i}$$

Solve for  $\hat{\lambda}_B$ :

$$\frac{\partial \ln \Sigma_c}{\partial \lambda_B} = \frac{\partial}{\partial \lambda_B} \left[ \sum_{i=1}^m x_i (1-z_i) \lambda_B - (1-z_i) \lambda_B \right]$$

$$\Rightarrow \left[ \sum_{i=1}^m \left( \frac{x_i (1-z_i)}{\lambda_B} - (1-z_i) \right) = 0 \right] \quad \text{solve.}$$

$$\Rightarrow \hat{\lambda}_B = \frac{\sum_{i=1}^m x_i (1-z_i)}{\sum_{i=1}^m (1-z_i)}$$

$$\frac{\partial^2 \ln \Sigma_c}{\partial \lambda_B^2} = - \sum_{i=1}^m \frac{x_i (1-z_i)}{\lambda_B^2}$$

$$x_i, (1-z_i), \lambda_B^2 \geq 0$$

$$\therefore \frac{\partial^2 \ln \Sigma_c}{\partial \lambda_B^2} \leq 0$$

$$\Rightarrow \hat{\lambda}_B \text{ is local max.}$$

4.2 b 4 / 4

✓ - 0 pts Correct

- 1 pts incorrect result for  $\pi$
- 1 pts incorrect result for  $\lambda_a$
- 1 pts incorrect results for  $\lambda_b$
- 1 pts no derivation
- 4 pts [Click here to replace this description.](#)



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4c) Sorry, I ran out of time, but we go through the steps in part L using  $\gamma_i^t$  instead of  $z_i$ .

So we obtain that

↑  
As per EM Algorithm.

$$\bar{\eta}^{t+1} = \frac{1}{m} \sum_{i=1}^m \gamma_i^t$$

$$\lambda_A^{t+1} = \frac{\sum_{i=1}^m \gamma_i^t x_i}{\sum_{i=1}^m \gamma_i^t}$$

$$\lambda_B^{t+1} = \frac{\sum_{i=1}^m (1 - \gamma_i^t) x_i}{\sum_{i=1}^m (1 - \gamma_i^t + 1)}$$

4.3 C 4 / 4

✓ - 0 pts Correct

- 4 pts [Click here to replace this description.](#)

- 1 pts incorrect result for pi



5a) Let  $S$  be sequence  $(s_1, s_2, s_3)$  we want to find

$$\begin{aligned} P(S) &= P(s_1 = \text{calm}, s_2 = \text{excited}, s_3 = \text{calm}) \\ &= P(s_1 = \text{calm}) P(s_2 = \text{excited} | s_1 = \text{calm}) P(s_3 = \text{calm} | s_2 = \text{excited}) \\ &= \pi_c \times A_{ce} \times A_{ec} = 0.7 \times 0.4 \times 0.2 \\ &= \boxed{0.056} \end{aligned}$$

5b) Let  $S$  be initial state,  $o$  be initial observation

$$\begin{aligned} P(S = \text{calm} | O = \text{swim}) &= \frac{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm})}{P(O = \text{swim})} \quad \text{Bayes} \\ &= \frac{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm})}{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm}) + P(O = \text{swim} | S = \text{excited}) P(S = \text{excited})} \\ &= \frac{\phi_{cs} \pi_c}{\phi_{cs} \pi_c + \phi_{es} \pi_e} = \frac{0.1 \times 0.7}{0.7 \times 0.1 + 0.5 \times 0.3} = \frac{0.07}{0.22} = \frac{7}{22} = \boxed{0.318} \end{aligned}$$

5c) Let  $S$  be sequence (rest, swim). We want to find

$$P(O) = P(O, Q_1) + P(O, Q_2) + P(O, Q_3) + P(O, Q_4)$$

$$Q_1 = (\text{calm}, \text{calm}) \quad Q_2 = (\text{calm}, \text{excited}) \quad Q_3 = (\text{excited}, \text{calm}) \quad Q_4 = (\text{excited}, \text{excited})$$

$$P(O, Q_i) = p(q_1) p(q_2 | q_1) p(o_1 | q_1) p(o_2 | q_2) \quad |(o_1, o_2) = O \quad (q_1, q_2) = Q_i$$

$$P(O, Q_1) = \pi_c + \phi_{cr} + A_{cc} + \phi_{cs} = 0.7 \times 0.3 \times 0.6 \times 0.1$$

$$P(O, Q_2) = \pi_c + \phi_{cr} + A_{ce} + \phi_{es} = 0.7 \times 0.3 \times 0.4 + 0.5$$

$$P(O, Q_3) = \pi_e + \phi_{er} + A_{ec} + \phi_{cs} = 0.3 \times 0.1 \times 0.2 \times 0.1$$

$$P(O, Q_4) = \pi_e + \phi_{er} + A_{ee} + \phi_{es} = 0.3 \times 0.1 \times 0.8 \times 0.5$$

$$\boxed{P(O) = 0.0672}$$



5.1 a 2 / 2

✓ - 0 pts Correct

- 1 pts Incorrect derivation

5a) Let  $S$  be sequence  $(s_1, s_2, s_3)$  we want to find

$$\begin{aligned} P(S) &= P(s_1 = \text{calm}, s_2 = \text{excited}, s_3 = \text{calm}) \\ &= P(s_1 = \text{calm}) P(s_2 = \text{excited} | s_1 = \text{calm}) P(s_3 = \text{calm} | s_2 = \text{excited}) \\ &= \pi_c \times A_{ce} \times A_{ec} = 0.7 \times 0.4 \times 0.2 \\ &= \boxed{0.056} \end{aligned}$$

5b) Let  $S$  be initial state,  $o$  be initial observation

$$\begin{aligned} P(S = \text{calm} | O = \text{swim}) &= \frac{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm})}{P(O = \text{swim})} \quad \text{Bayes} \\ &= \frac{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm})}{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm}) + P(O = \text{swim} | S = \text{excited}) P(S = \text{excited})} \\ &= \frac{\phi_{cs} \pi_c}{\phi_{cs} \pi_c + \phi_{es} \pi_e} = \frac{0.1 \times 0.7}{0.7 \times 0.1 + 0.5 \times 0.3} = \frac{0.07}{0.22} = \frac{7}{22} = \boxed{0.318} \end{aligned}$$

5c) Let  $S$  be sequence (rest, swim). We want to find

$$\begin{aligned} P(O) &= P(O, Q_1) + P(O, Q_2) + P(O, Q_3) + P(O, Q_4) \\ Q_1 &= (\text{calm}, \text{calm}) \quad Q_2 = (\text{calm}, \text{excited}) \quad Q_3 = (\text{excited}, \text{calm}) \quad Q_4 = (\text{excited}, \text{excited}) \\ P(O, Q_i) &= p(q_1) p(q_2 | q_1) p(o_1 | q_1) p(o_2 | q_2) \quad |(o_1, o_2) = O \quad (q_1, q_2) = Q_i \\ P(O, Q_1) &= \pi_c + \phi_{cr} + A_{cc} + \phi_{cs} = 0.7 \times 0.3 \times 0.6 \times 0.1 \\ P(O, Q_2) &= \pi_c + \phi_{cr} + A_{ce} + \phi_{es} = 0.7 \times 0.3 \times 0.4 + 0.5 \\ P(O, Q_3) &= \pi_e + \phi_{er} + A_{ec} + \phi_{cs} = 0.3 \times 0.1 \times 0.2 \times 0.1 \\ P(O, Q_4) &= \pi_e + \phi_{er} + A_{ee} + \phi_{es} = 0.3 \times 0.1 \times 0.8 \times 0.5 \end{aligned}$$

$$\boxed{P(O) = 0.0672}$$

5.2 b 3 / 3

✓ - **0 pts** Correct

- **2 pts** Incorrect derivation

- **1 pts** Incorrect final answer

- **1 pts** no derivation



5a) Let  $S$  be sequence  $(s_1, s_2, s_3)$  we want to find

$$\begin{aligned} P(S) &= P(s_1 = \text{calm}, s_2 = \text{excited}, s_3 = \text{calm}) \\ &= P(s_1 = \text{calm}) P(s_2 = \text{excited} | s_1 = \text{calm}) P(s_3 = \text{calm} | s_2 = \text{excited}) \\ &= \pi_c \times A_{ce} \times A_{ec} = 0.7 \times 0.4 \times 0.2 \\ &= \boxed{0.056} \end{aligned}$$

5b) Let  $S$  be initial state,  $o$  be initial observation

$$\begin{aligned} P(S = \text{calm} | O = \text{swim}) &= \frac{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm})}{P(O = \text{swim})} \quad \text{Bayes} \\ &= \frac{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm})}{P(O = \text{swim} | S = \text{calm}) P(S = \text{calm}) + P(O = \text{swim} | S = \text{excited}) P(S = \text{excited})} \\ &= \frac{\phi_{cs} \pi_c}{\phi_{cs} \pi_c + \phi_{es} \pi_e} = \frac{0.1 \times 0.7}{0.7 \times 0.1 + 0.5 \times 0.3} = \frac{0.07}{0.22} = \frac{7}{22} = \boxed{0.318} \end{aligned}$$

5c) Let  $S$  be sequence (rest, swim). We want to find

$$P(O) = P(O, Q_1) + P(O, Q_2) + P(O, Q_3) + P(O, Q_4)$$

$$Q_1 = (\text{calm}, \text{calm}) \quad Q_2 = (\text{calm}, \text{excited}) \quad Q_3 = (\text{excited}, \text{calm}) \quad Q_4 = (\text{excited}, \text{excited})$$

$$P(O, Q_i) = p(q_1) p(q_2 | q_1) p(o_1 | q_1) p(o_2 | q_2) \quad |(o_1, o_2) = O \quad (q_1, q_2) = Q_i$$

$$P(O, Q_1) = \pi_c + \phi_{cr} + A_{cc} + \phi_{cs} = 0.7 \times 0.3 \times 0.6 \times 0.1$$

$$P(O, Q_2) = \pi_c + \phi_{cr} + A_{ce} + \phi_{es} = 0.7 \times 0.3 \times 0.4 + 0.5$$

$$P(O, Q_3) = \pi_e + \phi_{er} + A_{ec} + \phi_{cs} = 0.3 \times 0.1 \times 0.2 \times 0.1$$

$$P(O, Q_4) = \pi_e + \phi_{er} + A_{ee} + \phi_{es} = 0.3 \times 0.1 \times 0.8 \times 0.5$$

$$\boxed{P(O) = 0.0672}$$

5.3 C 5 / 5

✓ - **0 pts** Correct

- **1 pts** No derivation

- **1 pts** final answer is incorrect

- **4 pts** Only some derivations are correct. Logic is mostly incorrect.

- **5 pts** Incorrect.