LINKÖPING UNIVERSITY

Department of Computer and Information Science Division of Statistics and Machine Learning Mattias Villani 2016-09-23 Advanced Machine Learning Master and PhD course

Gaussian Processes - Computer Lab

Deadline: See LISAMTeacher: Mattias VillaniGrades: Pass/FailSubmission: Via LISAM

You should use R to solve the lab since the computer exam will be in R.

Output: an individual report and a group report to be presented on the seminar.

Attach your code in LISAM as separate files.

1. **Implementing Gaussian process regression from scratch**. This first exercise will have you writing your own code for the Gaussian process regression model:

$$y = f(x) + \varepsilon \quad \varepsilon \sim N(0, \sigma_n^2)$$

 $f \sim GP \left[0, k(x, x')\right].$

When it comes to the posterior distribution for f, I **strongly** suggest that you implement Algorithm 2.1 on page 19 of Rasmussen and Willams (RW) book. That algorithm uses the Cholesky decomposition (chol() in R) to attain numerical stability. Here is what you need to do:

- (a) Write your own code for simulating from the posterior distribution of f(x) using the squared exponential kernel. The function (name it posteriorGP) should return vectors with the posterior mean and variance of f, both evaluated at a set of x-values (x^*) . You can assume that the prior mean of f is zero for all x. The function should have the following inputs:
 - i. x (vector of training inputs)
 - ii. y (vector of training targets/outputs)
 - iii. xStar (vector of inputs where the posterior distribution is evaluated, i.e. x^* . As in my slides).
 - iv. hyperParam (vector with two elements σ_f and ℓ)
 - v. sigmaNoise (σ_n) .

[Hint: I would write a separate function for the Kernel (see my GaussianProcess.R function on the course web page) which is then called from the posteriorGP function.]

(b) Now let the prior hyperparameters be $\sigma_f = 1, \ell = 0.3$. Update this prior with a single observation: (x, y) = (0.4, 0.719). Assume that the noise standard deviation is known to be $\sigma_n = 0.1$. Plot the posterior mean of f over the interval $x \in [-1, 1]$. Plot also 95% probability (pointwise) bands for f.

\boldsymbol{x}	-1.0	-0.6	-0.2	0.4	0.8
y	0.768	-0.044	-0.940	0.719	-0.664

Table 1: Simple data set for GP regression.

- (c) Update your posterior from 1b) with another observation: (x, y) = (-0.6, -0.044). Plot the posterior mean of f over the interval $x \in [-1, 1]$. Plot also 95% probability bands for f. [Hint: updating the posterior after one observation with a new observation gives the same result as updating the prior directly with the two observations. Bayes is beautiful!]
- (d) Compute the posterior distribution of f using all 5 data points in Table 1 below (note that the two previous observations are included in the table). Plot the posterior mean of f over the interval $x \in [-1, 1]$. Plot also 95% probability intervals for f.
- (e) Repeat 1d), this time with the hyperparameters $\sigma_f = 1, \ell = 1$. Compare the results.
- 2. Gaussian process regression on real data using the kernlab package. This exercise lets you explore the kernlab package on a data set of daily mean temperature in Stockholm (Tullinge) during the period January 1, 2010 December 31, 2015. I have removed the leap year day February 29, 2012 to make your life simpler. You can read the dataset with the command:

read.csv('https://github.com/STIMALiU/AdvMLCourse/raw/master/GaussianProcess/Code/TempTullinge.csv', header=TRUE,
sep=';')

Create the variable time which records the day number since the start of the dataset (i.e. time= $1, 2, ..., 365 \cdot 6 = 2190$). Also, create the variable day that records the day number since the start of each year (i.e. day= 1, 2, ..., 365, 1, 2, ..., 365). Estimating a GP on 2190 observations can take some time on slower computers, so let's thin out the data by only using every fifth observation. This means that your time variable is now time= 1, 6, 11, ..., 2186 and day= 1, 6, 11, ..., 361, 1, 6, ..., 361.

- (a) Familiarize yourself with the following functions in kernlab, in particular the gausspr and kernelMatrix function. Do ?gausspr and read the input arguments and the output. Also, go through my KernLabDemo.R carefully; you will need to understand it. Now, define your own square exponential kernel function (with parameters ℓ (ell) and σ_f (sigmaf)), evaluate it in the point x = 1, x' = 2, and use the kernelMatrix function to compute the covariance matrix $K(\mathbf{x}, \mathbf{x}_{\star})$ for the input vectors $\mathbf{x} = (1, 3, 4)^T$ and $\mathbf{x}_{\star} = (2, 3, 4)^T$.
- (b) Consider first the model:

$$temp = f(time) + \varepsilon \quad \varepsilon \sim N(0, \sigma_n^2)$$

 $f \sim GP \left[0, k(time, time') \right]$

Let σ_n^2 be the residual variance from a simple quadratic regression fit (using the lm() function in R). Estimate the above Gaussian process regression model using the squared exponential function from 2a) with $\sigma_f = 20$ and $\ell = 0.2$. Use the predict function to compute the posterior mean at every data point in the training datasets. Make a scatterplot of the data and superimpose the posterior mean of f as a curve (use type="1" in the plot function). Play around with different values on σ_f and ℓ (no need to write this in the report though).

- (c) Kernlab can compute the posterior variance of f, but I suspect a bug in the code (I get weird results). Do you own computations for the posterior covariance matrix of f (hint: Algorithm 2.1 in RW), and use information in that matrix to plot 95% (pointwise) posterior probability bands for f. Use $\sigma_f = 20$ and $\ell = 0.2$. Superimpose those bands on the figure with the posterior mean in 2b).
- (d) Consider now the model

$$temp = f(day) + \varepsilon \quad \varepsilon \sim N(0, \sigma_n^2)$$

 $f \sim GP \left[0, k(day, day') \right]$

Estimate the model using the squared exponential function from 2a) with $\sigma_f = 20$ and $\ell = 6 \cdot 0.2 = 1.2$. (I multiplied ℓ by 6 compared to when you used time as input variable since kernlab automatically standardizes the data which makes the distance between points larger for day compared to time). Superimpose the posterior mean from this model on the fit (posterior mean) from the model with time using $\sigma_f = 20, \ell = 0.2$. Note that this plot should also have the time variable on the horizontal axis. Compare the results from using time to the ones with day. What are the pros and cons of each model?

(e) Now implement a generalization of the periodic kernel given in my slides from Lecture 2 of the GP topic (Slide 6)

$$k(x, x') = \sigma_f^2 \exp\left(-\frac{2\sin^2\left(\pi |x - x'|^2 / d\right)}{\ell_1^2}\right) \times \exp\left(-\frac{1}{2} \frac{|x - x'|^2}{\ell_2^2}\right).$$

Note that we have two different length scales here, and ℓ_2 controls the correlation between the same day in different years (ℓ_2). So this kernel has four hyperparameters σ_f , ℓ_1 , ℓ_2 and the period d. Estimate the GP model using the time variable with this kernel with hyperparameters $\sigma_f = 20$, $\ell_1 = 1$, $\ell_2 = 10$ and d = 365/sd(time). The reason for the rather strange period here is that kernlab standardized inputs to have standard deviation of 1. Compare the fit to the previous two models (with $\sigma_f = 20$, $\ell = 0.2$). Discuss the results

3. Gaussian process classification using the kernlab package. Download the banknote fraud data:

data <- read.csv('https://github.com/STIMALiU/AdvMLCourse/raw/master/GaussianProcess/Code/banknoteFraud.csv',
header=FALSE, sep=',')
names(data) <- c("varWave", "skewWave", "kurtWave", "entropyWave", "fraud")</pre>

data[,5] <- as.factor(data[,5])</pre>

You can read about this dataset here. Choose 1000 observations as training data using the following command (i.e. use the vector SelectTraining to subset the training observations) set.seed(111); SelectTraining <- sample(1:dim(data)[1], size = 1000, replace = FALSE)

- (a) Use kernlab to fit a Gaussian process classification model for fraud on the training data, using kernlab. Use kernlab's the default kernel and hyperparameters. Start with using only the first two covariates varWave and skewWave in the model. Plot contours of the prediction probabilities over a suitable grid of values for varWave and skewWave. Overlay the training data for fraud = 1 (as blue points) and fraud = 0 (as red points). You can take a lot of code for this from my KernLabDemo.R. Compute the confusion matrix for the classifier and its accuracy.
- (b) Using the estimated model from 3a), make predictions for the testset. Compute the accuracy.

(c) Train a model using all four covariates. Make predictions on the test and compare the accuracy to the model with only two covariates.

Good luck!

- Mattias