
Monte Carlo Tree Search for the Pokemon Trading Card Game

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Abstract

The Pokemon Trading Card Game is a popular turn-based card game usually played by two players. Its partially observable, stochastic, multi-agent nature combined with its complex rules, large state space, and demand for long-term planning make it an interesting target for modern artificial intelligence research efforts. An agent based on a Monte Carlo Tree Search (MCTS) algorithm with added knowledge via a heuristic function was developed and tested in games of PCG against human players and other agents. Although the MCTS agent performed well against random agents, its performance against human players was worse than expected. Possible explanations for this performance gap are explored and suggestions for future research and technical enhancements are proposed.

1. Introduction

The Pokemon Trading Card game has several characteristics that make it an interesting problem in artificially intelligent agent design. The general format and objective of the game, as well as its formal environment characterization and other important characteristics are summarized below.

1.1. Background: The Pokemon Trading Card Game

You have cards and play them and stuff

1.2. Summary: Game Environment

It's partially observable and all that other junk It's got a large branching factor It requires long-term planning in an uncertain game tree

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2. Methodology

In an effort to develop an agent which could play the Pokemon Card Game competently against human players, the developers implemented a custom state representation and game logic from scratch, then created an agent based on a Monte Carlo Tree Search (MCTS) and a well-tuned heuristic function.

2.1. Game Logic and State Representation

We had some state and some game logic functions that looked like this.

2.2. The Agent Program

The Monte Carlo Tree Search algorithm was chosen as the basis of the Pokemon Card Game agent because the algorithm has seen wide success in a variety of related games such as Poker, Settlers of Catan, and the "Magic: The Gathering" card game. Furthermore, agents based on planning or rule-based approaches wouldn't be robust enough to create new strategies for brand new decks. The minimax algorithm also proves to be an undesirable candidate due to the partially observable and stochastic nature of the game environment as well as the large branching factor and need for long-term planning. The MCTS algorithm, on the other hand, has been applied to similar games and can be easily adapted to partially observable and stochastic environments. It also can exhibit long-term planning and works well in environments with a large branching factor, such as Go.

2.2.1. MONTE CARLO TREE SEARCH IMPLEMENTATION DETAILS

A full description of the MCTS algorithm and its properties is left to previous research while a summary of the implementation used in the PCG agent is provided.

The MCTS algorithm works by building a search tree node-by-node and estimating the effectiveness of each node by

simulating many games which visit that node and keeping track of the expectation of reward.

The MCTS agent developed for the PCG agent maintains a persistent game tree structure which is saved between turns. At the beginning of a turn, the current state is located in the current game tree and set as the new root node. In this way, results of simulations in previous turns can still provide information about the usefulness of nodes still under consideration. Next, the MCTS algorithm, consisting of Selection, Expansion, Simulation, and Back-propagation stages (described below) are repeated in a loop for up to five seconds. Each iteration may add up to one new node to the search tree and simulates one play-out to the end of the game. Usually, the PCG agent was able to complete 15,000 such iterations per turn on a consumer-grade laptop computer. Finally, the child of the root node with the highest computed value is chosen as the next action.

Each iteration of the MCTS algorithm consists of four stages as noted previously: Selection, Expansion, Simulation, and Back-propagation. The implementation of each stage is described below.

Selection: Starting from the root node, "optimal children are selected recursively until a node which is a leaf node or a node which still has un-expanded children is encountered. When selecting children, one must be careful to balance the exploitation of nodes which are known to be favorable to the current player and nodes which have not been explored as much. To accomplish this goal, the Upper Confidence Bounds formula was used. Namely, at each step the child node which maximizes the following equation was chosen:

$$v_i + C \times \sqrt{\frac{\ln N}{n_i}}$$

2.2.2. HEURISTIC FUNCTION

Describe the heuristic function here

3. Results

Some stuff about how we tested

3.1. Test Results

Results vs random AI, observations vs humans

3.2. Explanations and Future Work

4. Conclusion