

Seminar 9

1) $g: \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}, g(x, y) = ax_1y_1 + bx_1y_2 + bx_2y_1 + cx_2y_2$

a) $g \in L^S(\mathbb{R}^2, \mathbb{R}^2, \mathbb{R})$

b) g produs scalar $\Leftrightarrow \begin{cases} a > 0 \\ ac - b^2 > 0 \end{cases} \Leftrightarrow (\mathbb{R}^2, g) \text{ s. v.e.r.}$

$g(x, y) = \sum_{i,j=1}^2 g_{ij} x_i y_j$

$G = \begin{pmatrix} a & b \\ b & c \end{pmatrix}$ \Rightarrow g formă biliniară
 $G = G^T$

$\Rightarrow g \in L^S(\mathbb{R}^2, \mathbb{R}^2, \mathbb{R})$

$Q: \mathbb{R}^2 \rightarrow \mathbb{R}: Q(x) = ax_1^2 + 2bx_1x_2 + cx_2^2$

Q poz. def. $\Leftrightarrow \Delta_1 = a > 0$
 $\Delta_2 = \det G = ac - b^2 > 0$ (Metoda Jacobi)

$\Rightarrow \text{sgn} = (2, 0)$

2) $g: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$ formă biliniară

$G = \begin{pmatrix} 3 & 2 & 0 \\ 2 & 2 & 2 \\ 0 & 2 & 1 \end{pmatrix}$ matricea asociată în rap. cu \mathcal{B}_0 .

Este (\mathbb{R}^3, g) sp. v.e.r.?

$$G = G^T \Rightarrow g \in L^s(\mathbb{R}^3, \mathbb{R}^3, \mathbb{R})$$

$Q: \mathbb{R}^3 \rightarrow \mathbb{R}$ forma pătratică asociată

$$Q(x) = 3x_1^2 + 4x_1x_2 + 2x_2^2 + 4x_2x_3 + x_3^2$$

Q este poz. def.?

Metoda Jacobi

$$\Delta_1 = 3$$

$$\Delta_2 = 2$$

$$\Delta_3 = 6 - 12 - 4 = -10$$

$$\Rightarrow \text{sgn} = (2, 1)$$

$$\exists \mathcal{R}^1 \text{ a.i. } Q(x) = \frac{1}{3}x_1^2 + \frac{3}{2}x_2^2 - \frac{1}{5}x_3^2$$

$\Rightarrow Q$ nu e poz. def.

$\Rightarrow g$ nu e produs scalar.

$\Rightarrow (\mathbb{R}^3, g)$ nu e s.v.e.r.

Metoda Gauss.

$$Q(x) = \frac{1}{3} (9x_1^2 + 12x_1x_2) + 2x_2^2 + 4x_2x_3 + x_3^2 =$$

$$= \frac{1}{3} (3x_1 + 2x_2)^2 - \frac{4}{3}x_2^2 + 2x_2^2 + 4x_2x_3 + x_3^2 =$$

$$= \frac{1}{3} (3x_1 + 2x_2)^2 + \frac{2}{3}x_2^2 + 4x_2x_3 + x_3^2 =$$

$$= \frac{1}{3} (3x_1 + 2x_2)^2 + \frac{2}{3} (x_2^2 + 6x_2x_3) + x_3^2 =$$

$$= \frac{1}{3} (3x_1 + 2x_2)^2 + \frac{2}{3} \cdot (x_2 + 3x_3)^2 - 5x_3^2$$

$$3) (\mathbb{R}^3, g_0), g_0: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$g_0(x, y) = x_1 y_1 + x_2 y_2 + x_3 y_3$$

$$U = \{x \in \mathbb{R}^3 / x_1 + x_2 - x_3 = 0\} = \{x \in \mathbb{R}^3 / g_0(x, y) = 0\} \text{ unde } y = (1, 1, -1)$$

$$a) U^\perp$$

$$b) \mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2 \text{ reper orthonormal in } \mathbb{R}^3$$

$$\mathcal{R}_1 = \text{reper orthonormal in } U$$

$$\mathcal{R}_2 = \text{reper orthonormal in } U^\perp$$

$$a) U^\perp = \{y \in \mathbb{R}^3 / g(x, y) = 0, \forall x \in U\}$$

$$U^\perp = \langle \{1, 1, -1\} \rangle$$

$$b) U = \langle \{(1, 0, 1), (0, 1, 1)\} \rangle$$

$$U = \{(x_1, x_2, x_1 + x_2) / x_1, x_2 \in \mathbb{R}\}$$

$$x_1(1, 0, 1) + x_2(0, 1, 1)$$

$$\dim U = 2.$$

$$\{f_1, f_2\} \text{ reper in } U.$$

Obs pentru a)

$$g_0(y, f_1) = 0, g_0(y, f_2) = 0.$$

$$\begin{cases} y_1 + y_3 = 0 \\ y_2 + y_3 = 0 \end{cases} \Rightarrow \begin{cases} y_1 = -y_3 \\ y_2 = -y_3 \end{cases}$$

Aplicăm Gram-Schmidt.

$$e_1 = f_1 = (1, 0, 1)$$

$$e_2 = f_2 - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} \cdot e_1 = (0, 1, 1) - \frac{1}{2} (1, 0, 1) = \left(-\frac{1}{2}, 1, \frac{1}{2}\right) = \frac{1}{2}(-1, 2, 1)$$

$$\langle f_2, e_1 \rangle = \langle f_2, f_1 \rangle = 1$$

$$\langle e_1, e_1 \rangle = \langle f_1, f_1 \rangle = 2.$$

$$\{f_1, f_2\} \longrightarrow \{e_1, e_2\} \longrightarrow \{e'_1, e'_2\}.$$

$$e'_1 = \frac{e_1}{\|e_1\|} = \frac{1}{\sqrt{2}} \cdot (1, 0, 1)$$

$$e'_2 = \frac{e_2}{\|e_2\|} = \frac{1}{\sqrt{6}} (-1, 2, 1)$$

$$\text{Obs: } v = \alpha \cdot u, \alpha \geq 0.$$

$$\frac{v}{\|v\|} = \frac{u}{\|u\|}$$

$$\mathcal{B}_2 = \left\{ \frac{1}{\sqrt{3}} (1, 1, -1) \right\} \text{ reper în } V^\perp$$

4) $(\mathbb{C}, +, \cdot)_{\mathbb{R}}$, $g: \mathbb{C} \times \mathbb{C} \rightarrow \mathbb{R}$ formă biliniară

$$G = \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix} \text{ mat. asociată lui } g \text{ în rap. cu } \mathcal{B}_0 = \{e, i\}$$

a) (\mathbb{C}, g) s.v.e.r.

$$G = G^T \Rightarrow g \in L^s(\mathbb{C}, \mathbb{C}; \mathbb{R})$$

$$z = x_1 + i x_2$$

$$Q: \mathbb{C} \rightarrow \mathbb{R}, Q(z) = g(z, z) = x_1^2 + 4x_1x_2 + 5x_2^2$$

Metoda Jacobi

$$\Delta_1 = 1 > 0$$

$$\Delta_2 = 1 > 0.$$

$$\Rightarrow \exists Q' \text{ cu } Q(x) = x_1^2 + x_2^2$$

$$\Rightarrow \text{Sgn} = (2, 0)$$

$\Rightarrow Q$ poz. def. $\Rightarrow g$ prod. scalar.

Met. Gauss

$$Q(x) = x_1^2 + 4x_1x_2 + 5x_2^2 = (x_1 + 2x_2)^2 + x_2^2$$

$$\begin{cases} x_1' = x_1 + 2x_2 \\ x_2' = x_2 \end{cases} \Rightarrow Q(x) = x_1'^2 + x_2'^2$$

$$z = x_1 + x_2$$

$$z' = y_1 + y_2$$

b) ~~#~~

$u = 2 - i$ versor in rap. cu g . ?

$$\|u\|_g = \sqrt{g(u, u)} = \sqrt{Q(u)} = \sqrt{4 - 8 + 5} = 1 \Rightarrow u \text{ versor.}$$

$$c) \langle \{u\} \rangle^\perp = \{z \in \mathbb{C} / g(z, u) = 0\} = \mathbb{R}$$

$$g(z, z') = x_1 y_1 + 2x_1 y_2 + 2x_2 y_1 + 5x_2 y_2$$

$$\Rightarrow y_1 = 2 \\ y_2 = -1$$

$$g(z, u) = 2x_1 - 2x_1 + 4x_2 - 5x_2 = -x_2 = 0$$

d) Să se ortonormeze \mathcal{B}_0 în rap. cu g . Să se aplice Gram-Schmidt)

$$\mathcal{B}_0 = \{1, i\} = \{f_1, f_2\} \xrightarrow{\mathcal{R}^*} \{e_1, e_2\} \xrightarrow{\mathcal{R}^2} \{e_1', e_2'\}$$

$$e_1 = f_1 = 1$$

$$e_2 = f_2 - \frac{g(f_2, e_1)}{g(e_1, e_1)} \cdot e_1 = i - \frac{2}{1} \cdot 1 = -2 + i$$

$$\underbrace{g(f_2, e_1)}_{\substack{\text{cu } i \\ \text{cu } 1-i}} = 2 \cdot 1 = 2$$

$$\underbrace{g_0(z, z')}_{\substack{\text{cu } x_1 \\ \text{cu } x_2}} = x_1 y_1 + x_2 y_2$$

$$g(e_1, e_1) = 1$$

$$e_1' = \frac{e_1}{\|e_1\|_g} = e_1$$

$$e_2' = \frac{e_2}{\|e_2\|_g} = e_2$$

$$\|e_2\|_g = \sqrt{g(e_2, e_2)} = \sqrt{g(-2+i, -2+i)} =$$

$$= \sqrt{g(-2+i, -2+i)} = \sqrt{g(-u, -u)} = \sqrt{(-1)^2 \cdot g(u, u)} = 1.$$

e) Să se afle intersecția dintre cercul unitate în (\mathbb{C}, g_0) și (\mathbb{C}, g)

$$S'_{g_0} = \{z \in \mathbb{C} / \|z\|_{g_0} = 1\} = \{z = x_1 + ix_2 / x_1^2 + x_2^2 = 1\}$$

$$S'_g = \{z \in \mathbb{C} / \|z\|_g = 1\} = \{z = x_1 + ix_2 / x_1^2 + 4x_1x_2 + 5x_2^2 = 1\}$$

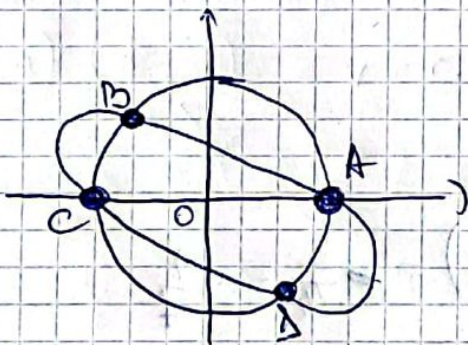
$$\begin{cases} x_1^2 + x_2^2 = 1 \\ x_1^2 + 4x_1x_2 + 5x_2^2 = 1 \end{cases} \Rightarrow z = \cos t + i \sin t$$

$$4x_2^2 + 4x_1x_2 = 0$$

$$\Rightarrow 4x_2(x_1 + x_2) = 0 \Rightarrow \sin t = 0 \Rightarrow x_2 = 0$$

$$\Rightarrow t = k\pi$$

$$x_1 + x_2 = 0 \Rightarrow \sin t + \cos t = 0 \Rightarrow \tan t = -1 \Rightarrow t = -\frac{\pi}{4} + k\pi, k \in \mathbb{Z}$$



$$z_A = 1$$

$$z_B = -\frac{\sqrt{2}}{2} + i\frac{\sqrt{2}}{2}$$

$$z_C = -1$$

$$z_D = \frac{\sqrt{2}}{2} - \frac{\sqrt{2}}{2}i$$

$$5) (\mathbb{R}^3, g_0), \mathcal{Q} = \{f_1 = (1, 2, 3), f_2 = (0, 1, 1), f_3 = (1, 2, 5)\}$$

a) \mathcal{Q} reper. Să se orthonormeze

b) $f_1 \times f_2$

c) $f_1 \wedge f_2 \wedge f_3$

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$$g_0: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$g_0(x, y) = x_1 y_1 + x_2 y_2 + x_3 y_3$$

a)

$$\begin{vmatrix} 1 & 0 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 5 \end{vmatrix} = 2 \neq 0 \Rightarrow \mathcal{Q} \text{ sli'}$$

$$\dim \mathcal{Q} = \dim \mathbb{R}^3 \text{ f } \mathcal{Q} \text{ reper}$$

$$e_1 = f_1 = (1, 2, 3)$$

$$e_2 = f_2 - \frac{\langle f_2, e_1 \rangle}{\langle e_1, e_1 \rangle} \cdot e_1$$

$$e_3 = f_3 - \frac{\langle f_3, e_1 \rangle}{\langle e_1, e_1 \rangle} \cdot e_1 - \frac{\langle f_3, e_2 \rangle}{\langle e_2, e_2 \rangle} \cdot e_2$$

$$\langle f_2, e_1 \rangle = \langle f_2, f_1 \rangle = 0 + 2 + 3 = 5$$

$$\langle e_1, e_1 \rangle = \langle f_1, f_1 \rangle = 1 + 4 + 9 = 14$$

$$e_2 = (0, 1, 1) - \frac{5}{14} \cdot (1, 2, 3) = \left(-\frac{5}{14}, \frac{4}{14}, -\frac{1}{14}\right) =$$

$$= \frac{1}{14} (-5, 4, -1)$$

$$\langle f_3, e_1 \rangle = \langle f_3, f_1 \rangle = 20$$

$$\langle f_3, e_2 \rangle = \frac{1}{14} (-5 + 8 - 5) = -\frac{2}{14} = -\frac{1}{7}$$

$$\langle e_2, e_2 \rangle = \frac{1}{14^2} (25 + 16 + 1) = \frac{42}{14^2} = \frac{3}{14}$$

$$e_3 = (1, 2, 5) - \frac{20}{14} \cdot (1, 2, 3) - \frac{\frac{1}{7}}{\frac{3}{14}} \cdot \frac{1}{14} (-5, 4, -1)$$

$$\begin{aligned} \text{cre}_3 &= \left(1 - \frac{10}{7} - \frac{5}{21}, 2 - \frac{20}{7} + \frac{4}{21}, 5 - \frac{30}{7} - \frac{1}{21}\right) = \\ &= \frac{1}{21} (21 - 30 - 5, 42 - 60 + 4, 105 - 90 - 1) = \\ &= \frac{1}{21} (-14, -14, 14) = \frac{14}{21} (-1, -1, 1) = \boxed{\frac{2}{3}(-1, -1, 1)} \end{aligned}$$

$$e_1' = \frac{e_1}{\|e_1\|} = \frac{(1, 2, 3)}{\sqrt{14}}$$

$$e_2' = \frac{e_2}{\|e_2\|} = \frac{1}{\sqrt{42}} \cdot e_2 = \frac{1}{\sqrt{42}} \cdot (-5, 4, -1)$$

$$e_3' = \frac{e_3}{\|e_3\|} = \frac{1}{\sqrt{3}} (-1, -1, 1)$$

$$\begin{aligned} \text{b) } f_1 \wedge f_2 &= \begin{vmatrix} e_1^0 & e_2^0 & e_3^0 \\ 1 & 2 & 3 \\ 0 & 1 & 1 \end{vmatrix} = e_1^0 \cdot \begin{vmatrix} 2 & 3 \\ 1 & 1 \end{vmatrix} - e_2^0 \cdot \begin{vmatrix} 1 & 3 \\ 0 & 1 \end{vmatrix} + \\ &+ e_3^0 \cdot \begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix} = (-1, -1, 1) \end{aligned}$$

$$\begin{aligned} \text{c) } f_1 \wedge f_2 \wedge f_3 &= f_3 \wedge f_1 \wedge f_2 = \langle f_3, f_1 \wedge f_2 \rangle = \\ &= \langle (-1, -1, 1), (-1, -1, 1) \rangle = -1 - 1 + 1 = -1 \end{aligned}$$

$$\text{say } f_1 \wedge f_2 \wedge f_3 = \begin{vmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 0 & 1 & 1 \end{vmatrix} = 2$$