

Data Structures and Algorithms

Conf. dr. ing. Guillaume Ducoffe

`guillaume.ducoffe@fmi.unibuc.ro`

Vectors

- **Static** Data Structures: The array
- From array to vector: `push_back()` and `push_front()`
- Binary Search
- Range Searching
 - Mo's algorithm

The array

- Allocate enough consecutive space for the data.

→ We only need to store the address of the first element.

```
string trivialities[2] = { "this", "class"};  
// *trivialities == trivialities[0]
```

Support double indexing.

```
int class = 5;
```

```
int exam = 3;
```

```
int grades[class][exam];
```

Red	Red	Red	Yellow	Yellow	Yellow	Green	Green
Green	Cyan	Cyan	Cyan	Purple	Purple	Purple	White
White	White	White	White	White	White	White	White
White	White	White	White	White	White	White	White
White	White	White	White	White	White	White	White
White	White	White	White	White	White	White	White
White	White	White	White	White	White	White	White
White	White	White	White	White	White	White	White

Simple routines

- Swap between two elements. Complexity: $\mathcal{O}(1)$

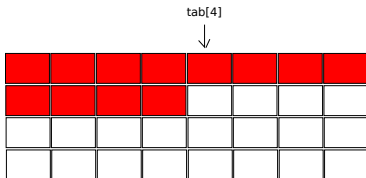
```
void swap(vector<int>& a, int i, int j) {  
    int tmp = a[i]; //copy of value a[i]  
    a[i] = a[j]; //overriding of a[i]  
    a[j] = tmp;  
}
```

- Inversion of a sub-vector of length ℓ . Complexity: $\mathcal{O}(\ell)$

```
void invert(vector<int>& a, int first, int last) {  
    for(int i = first, j = last; i < j; i++, j--){  
        swap(a,i,j)  
    }  
}
```

The array cont'd

- Pro's
 - Easy Access/Modification of a data
 - “Fast” range searching techniques, even for unsorted data



- Con's
 - **Static** allocation: the (maximal) number of elements must be fixed in advance

Need to resize. . .

From arrays to **vectors**

For us (and most programming languages...) a vector augments the array data structure with some new operations, in particular:

- **void** `push_back(int)`. Increases the size by one unit and inserts an element at the end of the array.
- **void** `push_front(int)`. Increases the size by one unit and inserts an element at the beginning of the array.

Our main algorithmic issue: despite students' dreams, these new operations are not in $\mathcal{O}(1)$. This is because (if there is not enough space available) we need to reallocate all former n elements.

Can we do better?

Doubling arrays

Implementation of `push_back`

- Our n -size array is embedded in some n' -array, for $n' \geq n$.

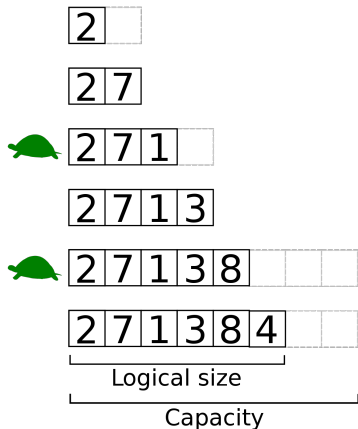
→ we may store the logical size n in some additional variable.

- `push_back` in $\mathcal{O}(1)$ as long as $n' > n$.
- If $n' = n$, then we create a bigger $2n$ -array and we reallocate.

Amortized complexity: $\mathcal{O}(1)$

Proof: at least $n/2$ elements were inserted since the last time we made a resize.

Potential function: $4 \times \#$ number of insertions - \sum length of all vectors created



Implementation of `push_back` and `push_front`

- Same idea as before, but our n -size array may not start at 0.
 - Need for another intermediate variable storing the position i_0 of the first element.
 - We need to resize if:
 - Either $n' = n$ and a `push_back` occurs;
 - Or $i_0 = 0$ and a `push_front` occurs.
 - Whenever we resize, we triple the size of the vector ($n' \mapsto 3n'$).
 - + we embed our n -size vector between pos. n' and $2n'$
- ⇒ At least $n'/3$ insertions since the last time we made a resize.

Advanced operations on vectors

Range Searching

Global Input: an n -size vector $a[]$

Definition

A range query $rq(i, j)$ asks for some information about the elements between positions i and j .

Examples:

- their sum;
- the max./min. element
- **searching a value**: given some value e , does there exist an integer $i \leq k \leq j$ s.t. $a[k] = e$?
- etc.

Searching a value in a **sorted** vector

Binary Search

Ex: Searching $e = 11$ in $[0, 1, 3, 6, 11, 18, 45]$

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Step 3: $[11, 18, 45]$, $e < 18 \longrightarrow$ Go left

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Search e in $[11, 18, 45]$

Step 3: $[11, 18, 45]$, $e < 18 \rightarrow$ Go left

Step 4: $[11]$, $e = 11 \rightarrow$ STOP.

Binary search

Implementation

//Searching e between a[l] and a[u]

```
int dichoSearh(const vector<int>& a, int e, int l, int u) {  
    //Case of an empty range  
    if(l > u)  
        return -1;  
    //Computation of the median  
    int m = (u+l)/2;  
    if(a[m] == e)  
        return m;  
    else if(a[m] < e)  
        return dichoSearh(a,e,m+1,u);  
    else  
        return dichoSearh(a,e,l,m-1);  
}
```

Binary search

Complements

- A powerful method which also applies to “almost sorted” arrays
(more on that during the labs/seminars)
- The index returned by `dichoSearch` may not be the first occurrence of the searched element `e` (and not the last one either).

Ex: `[0,1,2,3,3,3,4,5,13]`, `e = 3` \longrightarrow `m = 4` and `a[m] == e`

Binary search

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- A powerful method which also applies to “almost sorted” arrays
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Ex: $[0, 1, 2, 3, \mathbf{3}, 3, 4, 5, 13]$, $e = 3 \rightarrow m = 4$ and $a[m] == e$

Solution: Continue the search (left) **but include the median in the range**

$[0, 1, 2, 3, \mathbf{3}, 3, 4, 5, 13] \rightarrow [0, 1, 2, 3, \mathbf{3}] \rightarrow [0, 1, \mathbf{2}, 3, 3]$

$\rightarrow [\mathbf{3}, 3] \rightarrow [\mathbf{3}] \rightarrow \text{STOP}$

Variation of Binary Search

Function `first()`

//Searching the first occurrence of e between a[l] and a[u]

```
int first(const vector<int>& a, int e, int l, int u) {
```

//Case of an empty range

```
if(l > u)
```

```
    return -1;
```

//Case of a single element

```
if(l==u)
```

```
    return (a[l] == e) ? 1 : -1;
```

//Computation of the median

```
int m = (u+l)/2;
```

```
if(a[m] < e)
```

```
    return first(a,e,m+1,u);
```

```
else
```

```
    return first(a,e,l,m);
```

```
}
```

Analysis of Binary search

Question: How many elements in the range considered?

- Step 1: n elements
- Step 2:
- Step 3:
- Step $i+1$:

Analysis of Binary search

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- Step 1: n elements
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- Step 3:
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Complexity in $\mathcal{O}(\log n)$ (for an array)

Searching a value in an **unsorted** vector

Mo's algorithm

- 1) Partition the n -vector $a[]$ in \sqrt{n} blocks of equal size $n/\sqrt{n} = \sqrt{n}$.
- 2) Let $b[]$ be a copy of $a[]$. Sort each of the \sqrt{n} blocks separately in the copy. **Pre-processing time:** $\mathcal{O}(n) + \sqrt{n} \times \mathcal{O}(\sqrt{n}^2) = \mathcal{O}(n\sqrt{n})$.
- 3) Searching value e between pos. i and j .
 - Let B_1, B_2, \dots, B_r be the blocks fully between i and j . Binary search in their sorted copies.
 - The block containing $a[i]$ (resp., $a[j]$) may start before i (resp., end after j). Linear search of value e amongst the $\leq \sqrt{n}$ elements in this block that are between pos. i and j .

Query time: $\mathcal{O}(\sqrt{n}) + \mathcal{O}(r \cdot \log n) = \mathcal{O}(\sqrt{n} \log n)$.

Example

Input: $a[] = \{3, 44, 1, 7, 23, 19, 0, 101, 89\}$

Sorted copy: $b[] = \{1, 3, 44, 7, 19, 23, 0, 89, 101\}$

- Search for some value e between $i = 1$ and $j = 6$.
 - Binary search in the block $7, 19, 23$ (fully between i and j)
 - Exhaustive search in the partial block $44, 1$
 - Exhaustive search in the partial block 0 .

Remark: Exhaustive Search in $a[]$. Binary search in $b[]$.

Another example: Sum of elements

Mo's algorithm + dynamic programming:

1) In an auxiliary \sqrt{n} -size vector $c[]$, store the sum of all elements within the same block.

Ex.: if $a[] = \{3, 44, 1, 7, 23, 19, 0, 101, 89\}$ then $c[] = \{48, 49, 190\}$.

3) Sum of all elements between pos. i and j .

- Let B_1, B_2, \dots, B_r be the blocks fully between i and j . Sum the pre-computed values for these blocks (in $c[]$).
- The block containing $a[i]$ (resp., $a[j]$) may start before i (resp., end after j). Sum of the $\leq \sqrt{n}$ elements in this block that are between pos. i and j .

Ex. $i = 1, j = 6$. The sum equals $44 + 1 + c[1] + 0$.

Sum of elements: Comparison between two methods

- Using Mo's algorithm + dynamic programming.
 - Pre-processing in $\mathcal{O}(n)$ time and space;
 - Query time in $\mathcal{O}(\sqrt{n})$;
 - If an element of the vector $a[]$ is modified, then we can update the vector $c[]$ in $\mathcal{O}(1)$ (at most one block is impacted)
- **Alternative method:** Store in an auxiliary vector the values $b[i] = \sum_{k=0}^i a[k]$. Pre-processing: $\mathcal{O}(n)$
 - Query time in $\mathcal{O}(1)$! – Return $b[j] - b[i] + a[i]$
 - But if an element of the vector $a[]$ is modified, then updating the vector $b[]$ may require $\mathcal{O}(n)$ time

Questions

