

CPE403 – Advanced Embedded Systems

Design Assignment 5

DO NOT REMOVE THIS PAGE DURING SUBMISSION:

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Github Repository link (root): https://github.com/PeppersJ/v4e0nk_i3

Youtube Playlist link (root): <https://drive.google.com/drive/u/2/folders/1fJ029-AAWjTnN-OrRqNLd0iLwKGm6A08>

Follow the submission guideline to be awarded points for this Assignment.

Submit the following for all Assignments:

1. In the document, for each task submit the modified or included code (from the base code) with highlights and justifications of the modifications. Also include the comments. If no base code is provided, submit the base code for the first task only.
2. Create a private Github repository with a random name (no CPE/403, Lastname, Firstname). Place all labs under the root folder TIVAC, sub-folder named Assignment1, with one document and one video link file for each lab, place modified c files named as asng_taskxx.c.
3. If multiple c files or other libraries are used, create a folder asng1_t01 and place these files inside the folder.
4. The folder should have a) Word document (see template), b) source code file(s) with startup_ccs.c and other include files, c) text file with youtube video links (see template).
5. Submit the doc file in canvas before the due date. The root folder of the github assignment directory should have the documentation and the text file with youtube video links.
6. Organize your youtube videos as playlist under the name "cpe403". The playlist should have the video sequence arranged as submission or due dates.
7. Only submit pdf documents. Do not forget to upload this document in the github repository and in the canvas submission portal.

1. Code for Tasks. for each task submit the modified or included code (from the base code) with highlights and justifications of the modifications. Also include the comments. If no base code is provided, submit the base code for the first task only. Use separate page for each task.

Collector and Sensor: smsgs.h

```
/*! Length of the button press portion of the sensor data message */
#define SMSGS_BUTTON_PRESS_LEN 2
/*! Button Press Request message length (over-the-air length) */
#define SMSGS_BUTTON_PRESS_REQUEST_MSG_LEN 1
/*! Button Press Request message length (over-the-air length) */
#define SMSGS_BUTTON_PRESS_RESPONSE_MSG_LEN 2

/*!
Message IDs for Sensor data messages. When sent over-the-air in a message,
this field is one byte.
*/
typedef enum
{
...
    /* Button Press request msg */
    Smsgs_cmdIds_ButtonPressReq = 18,
    /* Button Press response msg */
    Smsgs_cmdIds_ButtonPressRsp = 19
} Smsgs_cmdIds_t;
/*!

Frame Control field states what data fields are included in reported
sensor data, each value is a bit mask value so that they can be combined
(OR'd together) in a control field.
When sent over-the-air in a message this field is 2 bytes.
*/
typedef enum
{
...
    /*! Button Press */
    Smsgs_dataFields_buttonPress = 0x0800,
} Smsgs_dataFields_t;

/*!
Button Press Sensor Field
*/
typedef struct _Smsgs_buttonpressfield_t {
...
    /*! Button Press count out of button press sensor */
    uint16_t count;
} Smsgs_buttonPressField_t;

/*!
Sensor Data message: sent from the sensor to the collector
```

```

*/
typedef struct _Smsgs_sensormsg_t
{
...
    /*!
     * Button Press field - valid only if Smsgs_dataFields_buttonPress
     * is set in frameControl.
     */
    Smsgs_buttonPressField_t buttonPress;
} Smsgs_sensorMsg_t;

```

Collector: collector.h

```

/* Default configuration frame control */
#define CONFIG_FRAME_CONTROL (Smsgs_dataFields_tempSensor | \
                             Smsgs_dataFields_lightSensor | \
                             Smsgs_dataFields_humiditySensor | \
                             Smsgs_dataFields_msgStats | \
                             Smsgs_dataFields_configSettings | \
                             Smsgs_dataFields_buttonPress)

/*!
 * @brief Build and send the button press message to a device.
 *
 * @param pDstAddr - destination address of the device to send the message
 *
 * @return Collector_status_success, Collector_status_invalid_state
 *         or Collector_status_deviceNotFound
 */
extern Collector_status_t Collector_sendButtonPressRequest(ApiMac_sAddr_t *pDstAddr);

```

Collector: collector.c

```

/*!
 * @brief Process the Sensor Data message.
 *
 * @param pDataInd - pointer to the data indication information
 */
static void processSensorData(ApiMac_mcpsDataInd_t *pDataInd)
{
...
    if(sensorData.frameControl & Smsgs_dataFields_buttonPress)
    {
        sensorData.buttonPress.count = Util_buildUint16(pBuf[0], pBuf[1]);
        pBuf += 2;
    }
...
}

```



```

pMsg->bleSensor.data[0]);
    }
    else
    {
        CUI_statusLinePrintf(csfcuiHndl, deviceStatusLine, "Sensor - Addr=0x%04x,
Temp=%d, Humidity=%d, Light=%d, Button 1 Press Count=%d, RSSI=%d",
        pSrcAddr->addr.shortAddr,
        pMsg->humiditySensor.temp,
        pMsg->humiditySensor.humidity,
        pMsg->lightSensor.rawData,
        pMsg->buttonPress.count,
        rssi);
#ifdef LPSTK
        CUI_statusLinePrintf(csfcuiHndl, lpstkDataStatusLine, "Humid=%d, Light=%d,
Accl=(%d, %d, %d, %d, %d)",
        pMsg->humiditySensor.humidity, pMsg->
>lightSensor.rawData,
        pMsg->accelerometerSensor.xAxis, pMsg->
>accelerometerSensor.yAxis,
        pMsg->accelerometerSensor.zAxis, pMsg->
>accelerometerSensor.xTiltDet,
        pMsg->accelerometerSensor.yTiltDet);
#endif
    }
    CUI_statusLinePrintf(csfcuiHndl, numJoinDevStatusLine, "%x",
getNumActiveDevices());

#ifdef MT_CSF
    MTCsf_sensorUpdateIndCB(pSrcAddr, rssi, pMsg);
#endif /* endif for MT_CSF */
}

```

Sensor: sensor.c

```

/* Keep track of number of times button has been pressed */
extern uint16_t button_press_val;
static Smsgs_buttonPressField_t buttonPress =
{
    0
};

```

```

/*!
Initialize this application.

Public function defined in sensor.h
*/
#ifdef OSAL_PORT2TIRTOS
void Sensor_init(uint8_t macTaskId)
#else
void Sensor_init(void)
#endif

```

```

{
...
#endif /* LPSTK */
    configSettings.frameControl |= Smsgs_dataFields_msgStats;
    configSettings.frameControl |= Smsgs_dataFields_configSettings;
#ifndef DMM_CENTRAL
    configSettings.frameControl |= Smsgs_dataFields_bleSensor;
#endif
    configSettings.frameControl |= Smsgs_dataFields_buttonPress;
...
}

/*!
 * @brief      MAC Data Indication callback.
 *
 * @param      pDataInd - pointer to the data indication information
 */

static void dataIndCB(ApiMac_mcpsDataInd_t *pDataInd)
{
...
    case Smsgs_cmdIds_ButtonPressReq:
        if(pDataInd->msdu.len == SMSGS_BUTTON_PRESS_REQUEST_MSG_LEN)
        {
            /* send the response message directly */
            cmdBytes[0] = (uint8_t) Smsgs_cmdIds_ButtonPressRsp;
            cmdBytes[1] = *((uint8_t*)button_press_val);
            Sensor_sendMsg(Smsgs_cmdIds_ButtonPressRsp,
                          &pDataInd->srcAddr, true,
                          SMSGS_BUTTON_PRESS_RESPONSE_MSG_LEN,
                          cmdBytes);
        }
...
}

#if !defined(OAD_IMG_A)
/*!
 * @brief      Build and send sensor data message
 */
static void processSensorMsgEvt(void)
{
...
    if(sensor.frameControl & Smsgs_dataFields_buttonPress)
    {
        memcpy(&sensor.buttonPress, &buttonPress,
              sizeof(Smsgs_buttonPressField_t));
    }
}

/*!
 * @brief      Manually read the sensors
 */
static void readSensors(void)

```

```

{
#if defined(TEMP_SENSOR)
    /* Read the temp sensor values */
    tempSensor.ambienceTemp = Ssf_readTempSensor();
    tempSensor.objectTemp = tempSensor.ambienceTemp;
#endif
#ifndef LPSTK
    Lpstk_Accelerometer accel;
    humiditySensor.temp = (uint16_t)Lpstk_getTemperature();
    humiditySensor.humidity = (uint16_t)Lpstk_getHumidity();
    hallEffectSensor.flux = Lpstk_getMagFlux();
    lightSensor.rawData = (uint16_t)Lpstk_getLux();
    Lpstk_getAccelerometer(&accel);
    accelerometerSensor.xAxis = accel.x;
    accelerometerSensor.yAxis = accel.y;
    accelerometerSensor.zAxis = accel.z;
    accelerometerSensor.xTiltDet = accel.xTiltDet;
    accelerometerSensor.yTiltDet = accel.yTiltDet;
#endif /* LPSTK */
    buttonPress.count = button_press_val;
}

/*!
 * @brief Build and send sensor data message
 *
 * @param pDstAddr - Where to send the message
 * @param pMsg - pointer to the sensor data
 *
 * @return true if message was sent, false if not
 */
static bool sendSensorMessage(ApiMac_sAddr_t *pDstAddr, Smsgs_sensorMsg_t *pMsg)
{
...
    if(pMsg->frameControl & Smsgs_dataFields_buttonPress)
    {
        len += SMSGS_BUTTON_PRESS_LEN;
    }
...
    if(pMsg->frameControl & Smsgs_dataFields_buttonPress)
    {
        pBuf = Util_bufferUint16(pBuf, pMsg->buttonPress.count);
    }
...
}

/*!
 * @brief Filter the frameControl with readings supported by this device.
 *
 * @param frameControl - suggested frameControl
 *
 * @return new frame control settings supported
 */
static uint16_t validateFrameControl(uint16_t frameControl)
{
...

```

```

    if(frameControl & Smsgs_dataFields_buttonPress)
    {
        newFrameControl |= Smsgs_dataFields_buttonPress;
    }

```

```

...
}

```

Sensor: ssf.c

```

/*****
Public variables
*****/
/! Number of times button 1 has been pressed */
uint16_t button_press_val = 0;

/!
The application must call this function periodically to
process any events that this module needs to process.

Public function defined in ssf.h
*/
void Ssf_processEvents(void)
{
    ...

    /* Left key press is for starting the sensor network */
    else if(keys == gLeftButtonHandle)
    {

        if(started == false)
        {
            CUI_statusLinePrintf(ssfCuiHndl, sensorStatusLine, "Starting");

            /* Tell the sensor to start */
            Util_setEvent(&Sensor_events, SENSOR_START_EVT);
            /* Wake up the application thread when it waits for clock event */
            Semaphore_post(sensorSem);
        }
        else
        {
            /* Send LED toggle request to identify collector */
            Sensor_sendIdentifyLedRequest();
            button_press_val ++;
        }
    }

    /* Clear the key press indication */
    keys = NULL;

    /* Clear the event */
    Util_clearEvent(&events, KEY_EVENT);
}

```

Sensor: Sensor.opts

```

-DLPSTK
-DTEMP_SENSOR
...

```


TI LaunchPad™ kit with CC1352R MCU

Microcontroller development kit for rapid prototyping
featuring the CC1352R microcontroller

PART NO: LAUNCHXL-CC1352R1

○ Pin aligns with LaunchPad pinout standard.

Key

- Input
- Output

LAUNCH YOUR DESIGN @ dev.ti.com/launchxl-CC1352R1

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swru525e

TI LaunchPad™ SensorTag kit with SimpleLink™ Wireless MCU

Low-power wireless sensor kit featuring the
multi-band CC1352R MCU

PART NO: LPSTK-CC1352R

○ Pin aligns with LaunchPad pinout standard.

Sensor Symbols' Legend

- Hall Effect: DRV5032
- Temp & Humidity: HDC2080
- Ambient Light: OPT3001
- Accelerometer

Key

- Input
- Output

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3. Screenshots of the IDE, physical setup, debugging process - Provide screenshot of successful compilation, screenshots of registers, variables, graphs, etc.

Collector

```
CDT Build Console [Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs]
Finished building: "../software_stack/ti15_4stack/services/nvcomp.c"

making ../src/sysbios/rom_sysbios.aem4f ...
gmake[2]: Nothing to be done for 'all'.
Building target: "Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out"
Invoking: ARM Linker
"W:/Programs/ti/ccs1011/ccs/tools/compiler/ti-cgt-arm_20.2.3.LTS/bin/armcl" --cmd_file="W:/CCS_Projects/Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs/application/defines/collector.opts" -mv:
<linking>
Finished building target: "Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out"

W:/Programs/ti/ccs1011/ccs/tools/compiler/ti-cgt-arm_20.2.3.LTS/bin/armhex -order HS --memwidth=8 --romwidth=8 --intel -o Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.hex Assignment_5_colle
Translating to Intel format...
"Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out" .resetVecs ==> .resetVecs
"Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out" .const ==> .const
"Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out" config_const ==> config_const
"Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out" .text.1 ==> .text.1
"Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out" .cinit ==> .cinit
"Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out" .text.2 ==> .text.2
"Assignment_5_collector_CC1352R1_LAUNCHXL_tirtos_ccs.out" .ccfg ==> .ccfg

**** Build Finished ****
```

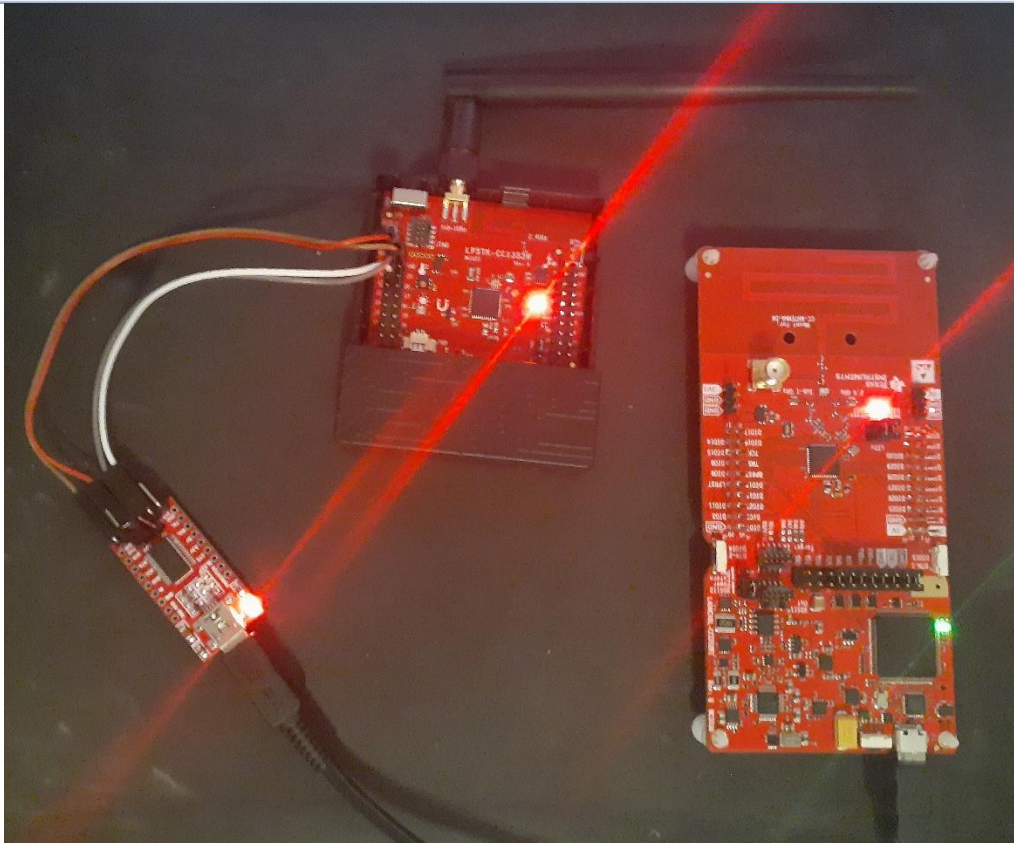
Sensor

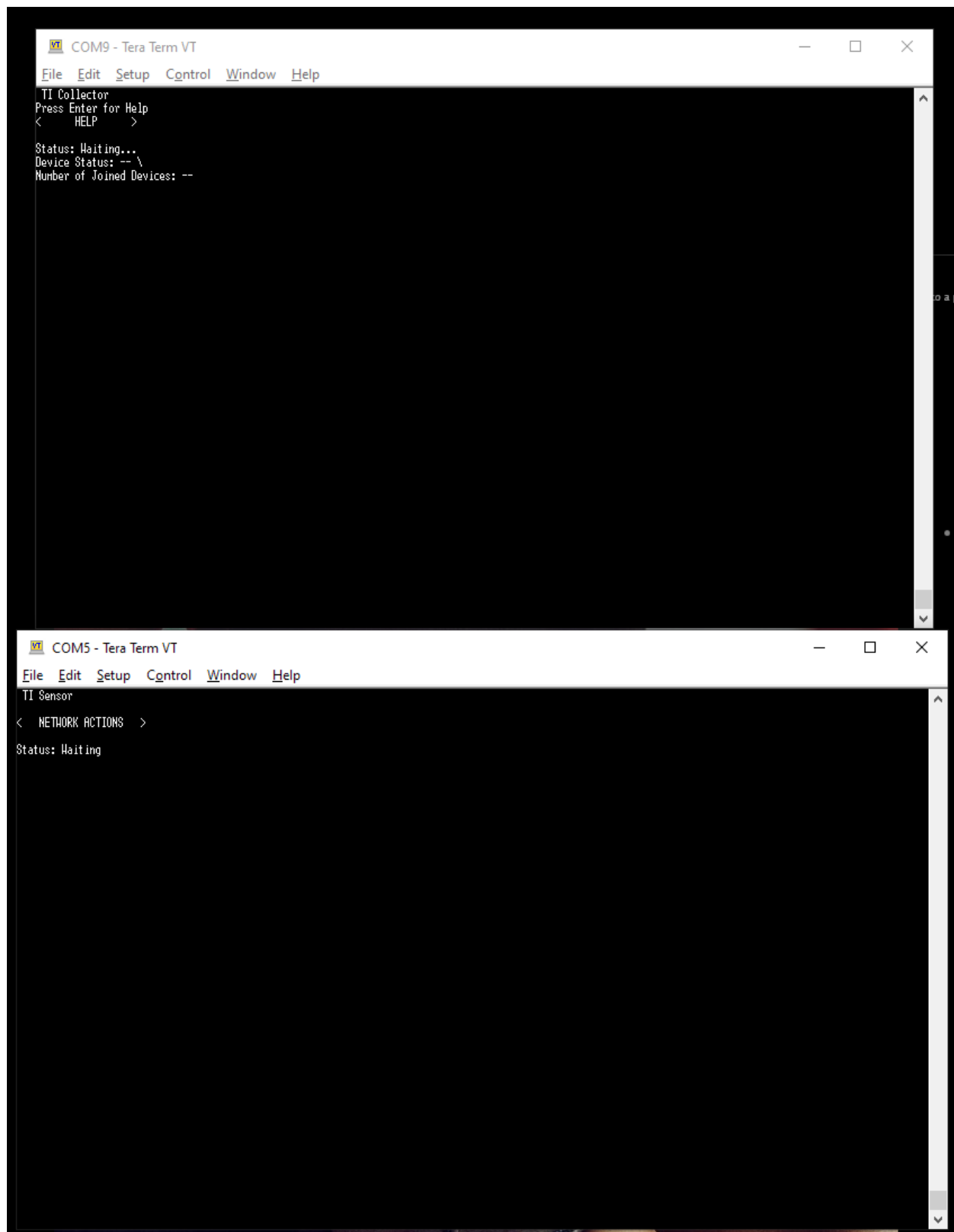
```
CDT Build Console [Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs]
Finished building: "../software_stack/ti15_4stack/services/nvcomp.c"

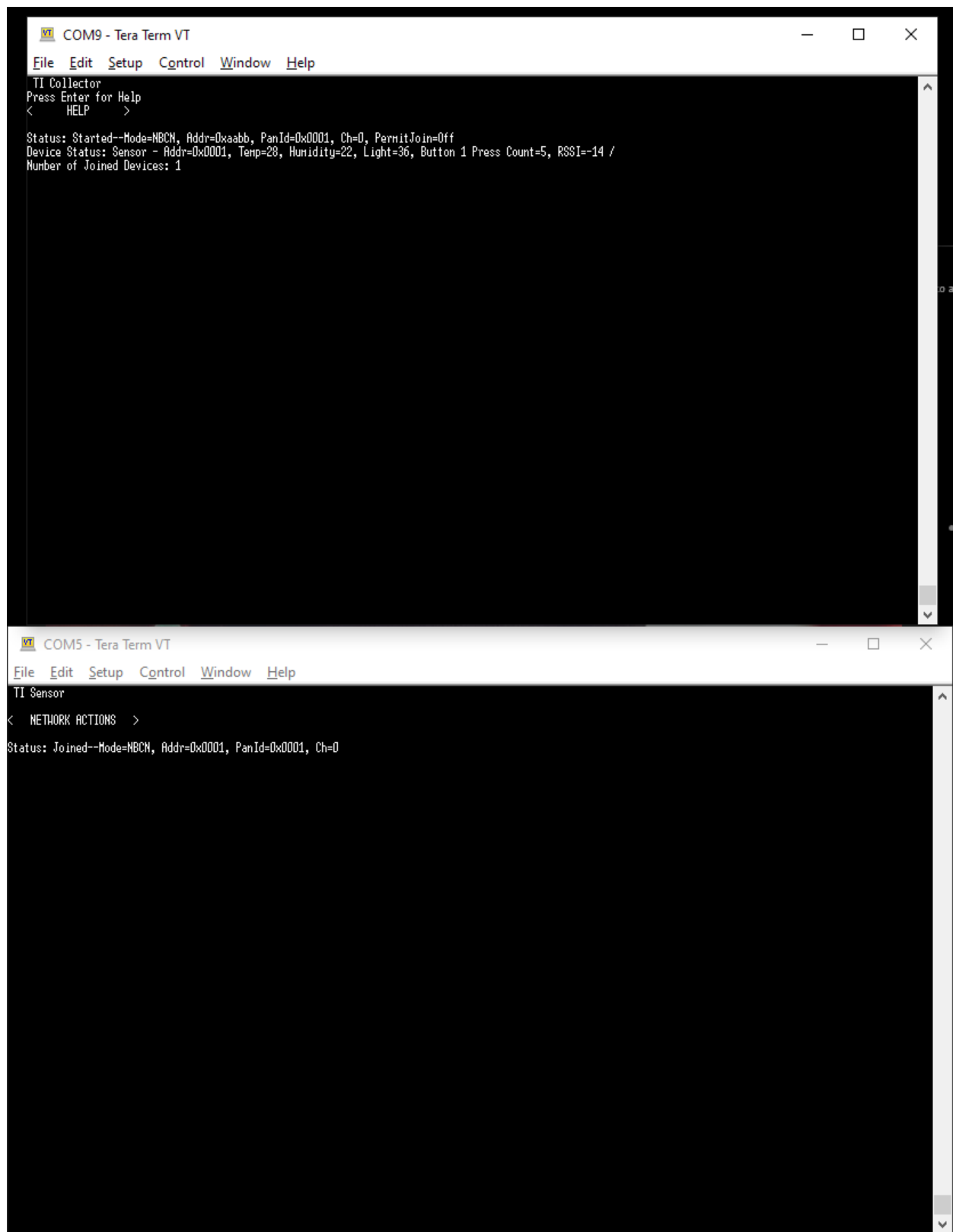
making ../src/sysbios/rom_sysbios.aem4f ...
gmake[2]: Nothing to be done for 'all'.
Building target: "Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out"
Invoking: ARM Linker
"W:/Programs/ti/ccs1011/ccs/tools/compiler/ti-cgt-arm_20.2.3.LTS/bin/armcl" --cmd_file="W:/CCS_Projects/Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs/application/defines/sensor.opts" -mv7M4 --:
<linking>
Finished building target: "Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out"

W:/Programs/ti/ccs1011/ccs/tools/compiler/ti-cgt-arm_20.2.3.LTS/bin/armhex -order HS --memwidth=8 --romwidth=8 --intel -o Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.hex Assignment_5_sensor_C
Translating to Intel format...
"Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out" .resetVecs ==> .resetVecs
"Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out" .const ==> .const
"Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out" config_const ==> config_const
"Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out" .text.1 ==> .text.1
"Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out" .cinit ==> .cinit
"Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out" .text.2 ==> .text.2
"Assignment_5_sensor_CC1352R1_LAUNCHXL_tirtos_ccs.out" .ccfg ==> .ccfg

**** Build Finished ****
```







4. Declaration

I understand the Student Academic Misconduct Policy -
<http://studentconduct.unlv.edu/misconduct/policy.html>

"This assignment submission is my own, original work".
Rishawn Peppers Johnson