

DC-Micromotors

Precious Metal Commutation

2 mNm

For combination with

Gearheads:
15A, 16/7, 16A

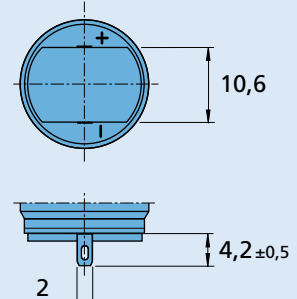
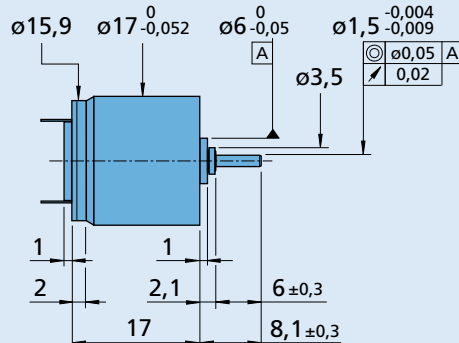
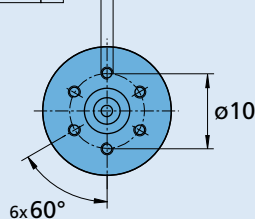
Encoders:
IE2-1024, IE2-16

Series 1717 ... SR

	1717 T	003 SR	006 SR	012 SR	018 SR	024 SR	
1 Nominal voltage	U_N	3	6	12	18	24	V
2 Terminal resistance	R	1,07	4,3	17,1	50,1	68,8	Ω
3 Output power	$P_{2 \max.}$	1,97	1,96	1,97	1,5	1,96	W
4 Efficiency, max.	$\eta_{\max.}$	69	69	70	68	70	%
5 No-load speed	n_0	14 000	14 000	14 000	12 300	14 000	rpm
6 No-load current (with shaft \varnothing 1,5 mm)	I_0	0,091	0,046	0,023	0,013	0,011	A
7 Stall torque	M_H	5,37	5,34	5,38	4,66	5,36	mNm
8 Friction torque	M_R	0,18	0,18	0,18	0,18	0,17	mNm
9 Speed constant	k_n	4 820	2 410	1 210	709	602	rpm/V
10 Back-EMF constant	k_E	0,207	0,414	0,829	1,41	1,66	mV/rpm
11 Torque constant	k_M	1,98	3,96	7,92	13,5	15,9	mNm/A
12 Current constant	k_I	0,505	0,253	0,126	0,074	0,063	A/mNm
13 Slope of n-M curve	$\Delta n / \Delta M$	2 610	2 620	2 600	2 640	2 610	rpm/mNm
14 Rotor inductance	L	17	65	260	760	1 040	μH
15 Mechanical time constant	τ_m	16	16	16	16	16	ms
16 Rotor inertia	J	0,59	0,58	0,59	0,58	0,59	gcm ²
17 Angular acceleration	$\alpha_{\max.}$	92	92	92	80	92	$\cdot 10^3 \text{ rad/s}^2$
18 Thermal resistance	$R_{th 1} / R_{th 2}$	4,5 / 27					K/W
19 Thermal time constant	τ_{w1} / τ_{w2}	2 / 210					s
20 Operating temperature range:							
– motor		-30 ... +85 (optional version	-55 ... +125)				°C
– rotor, max. permissible		+125					°C
21 Shaft bearings		sintered bearings	ball bearings	ball bearings, preloaded			
22 Shaft load max.:		(standard)	(optional version)	(optional version)			
– with shaft diameter		1,5	1,5	1,5			mm
– radial at 3 000 rpm (3 mm from bearing)		1,2	5	5			N
– axial at 3 000 rpm		0,2	0,5	0,5			N
– axial at standstill		20	10	10			N
23 Shaft play							
– radial	\leq	0,03	0,015	0,015			mm
– axial	\leq	0,2	0,2	0			mm
24 Housing material		steel, black coated					
25 Weight		18					g
26 Direction of rotation		clockwise, viewed from the front face					
Recommended values - mathematically independent of each other							
27 Speed up to	$n_{e \max.}$	10 000	10 000	10 000	10 000	10 000	rpm
28 Torque up to	$M_{e \max.}$	2	2	2	2	2	mNm

Orientation with respect to motor terminals not defined

6x $\varnothing 0,3$ A M1,6 1,6 deep



1717 T ... SR