Mathematics for Robotics Assignment 4

Fuzzy Logic

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 $\mathcal{D} = \{(2,1), (3,0.5), (4,0.3), (5,0.2)\}$ $\beta = \{2, 0.5\}, (3, 0.7), (4, 0.2), (5, 0.4)\}$

 $A^{c} = \overline{A} = A \left\{ X, 1 - \mu_{A}(x) \right\} =$ (2,0),(3,0.5),(4,0.7),(5,0.8)}

6) AUB = max(A(x,y),B(x,y)) = $\{(2, 1), (3,0.7), (4,0.3), (5,0.4)\} = \{(2,0), (3,0.3), (4,0.7), (5,06)\}$

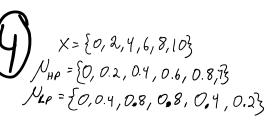
AnB=min (A(x,y)B(x,y)= {(2,0.5),(3,0.5),(4,0.2),(5,0.2){ DA-B=ANBC= (4,0,0), (5,0,0), (4,0,0), (5,0,0) {(2,05), (3,0,3), (4,0,3), (5,0)}

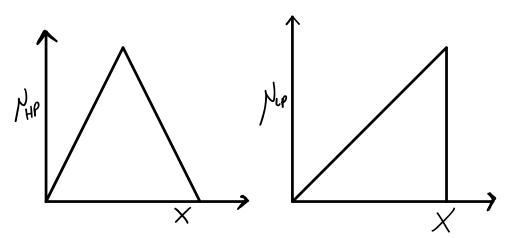
e)B-A=BnA={(2,0),(3,00),(4,0.2),(5,04)}

9) AnB = {(2,0.5), (3,0.5), (4,08), (5,0.8)}

DOJCARTEIAN PRODUCT AXB NAXB(D,S) = min { NA (O), NB(S) } $A = \{(0_1, 0.9), (02, 0.5), (03, 0.9), (04, 0.2)\}$ $B = \{((51, 0.1), ((52, 0.3), ((53, 0.8))\}$ D4 0 0 0.4

A · B = max{min { \max{0}, y_6(5)}}

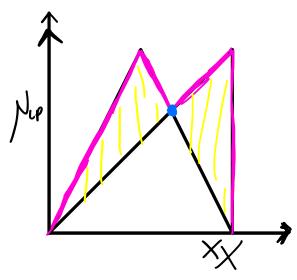




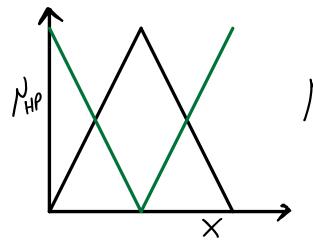
UNION:

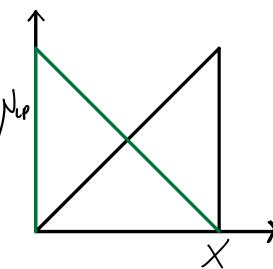
INTERSECTION:

DIFFERENCE:



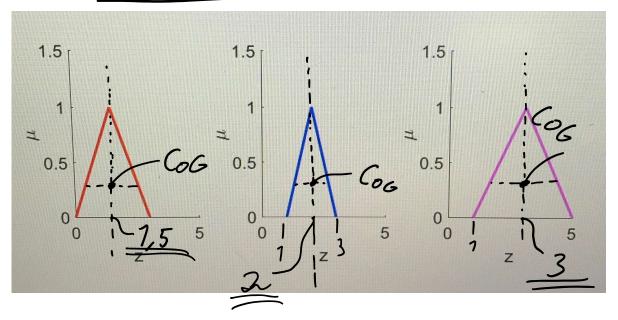
COMPLEMENT

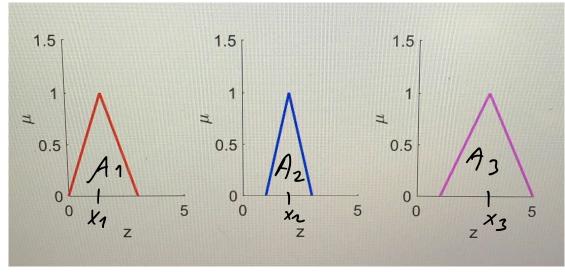




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CENTRE OF GRAVITY:





X3 = CENTRE OF URGESX AREA

CONTRE OF SUM $Cos = \frac{A_1 \times_1 + A_2 \times_2 + A_3 \times_3}{A_1 + A_2 + A_3}$

1 Task 3

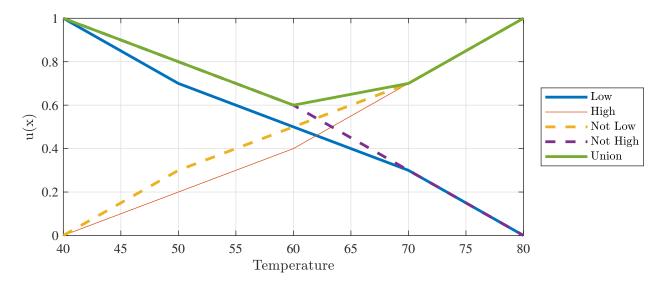


Figure 1: Task 3

```
1 clear; clc; close all;
2 %Task 1 see PDF
3 %Task 2 see PDF
4
5 %Task 3
6
7 x = [40 50 60 70 80];
8 \text{ yLow} = [1, 0.7, 0.5, 0.3, 0];
9 \text{ yHigh} = [0 \ 0.2 \ 0.4 \ 0.7 \ 1];
10
11 %a)
12 yNotLow = 1-yLow; % 0 0.3000 0.5000 0.7000 1.0000
13 %b)
14 yNotHigh = 1-yHigh; %1.0000 0.8000 0.6000 0.3000 0
16 notLow_notHigh = max(yNotLow,yNotHigh)%Union = 1.0000 0.8000
      0.6000 0.7000 1.0000
17
18 plot(x,yLow)
19 hold on
20 \text{ plot}(x,yHigh)
21 plot(x,yNotLow,'--')
22 plot(x,yNotHigh,'--')
23 plot(x,notLow_notHigh)
24 \ \mathrm{grid} \ \mathrm{on}
25 xlabel("Temperature")
26 \text{ ylabel("u(x)")}
27 legend("Low", "High", "Not Low", "Not High", "Not Low U Not High")
28 %a)
```