

PDA

PDA

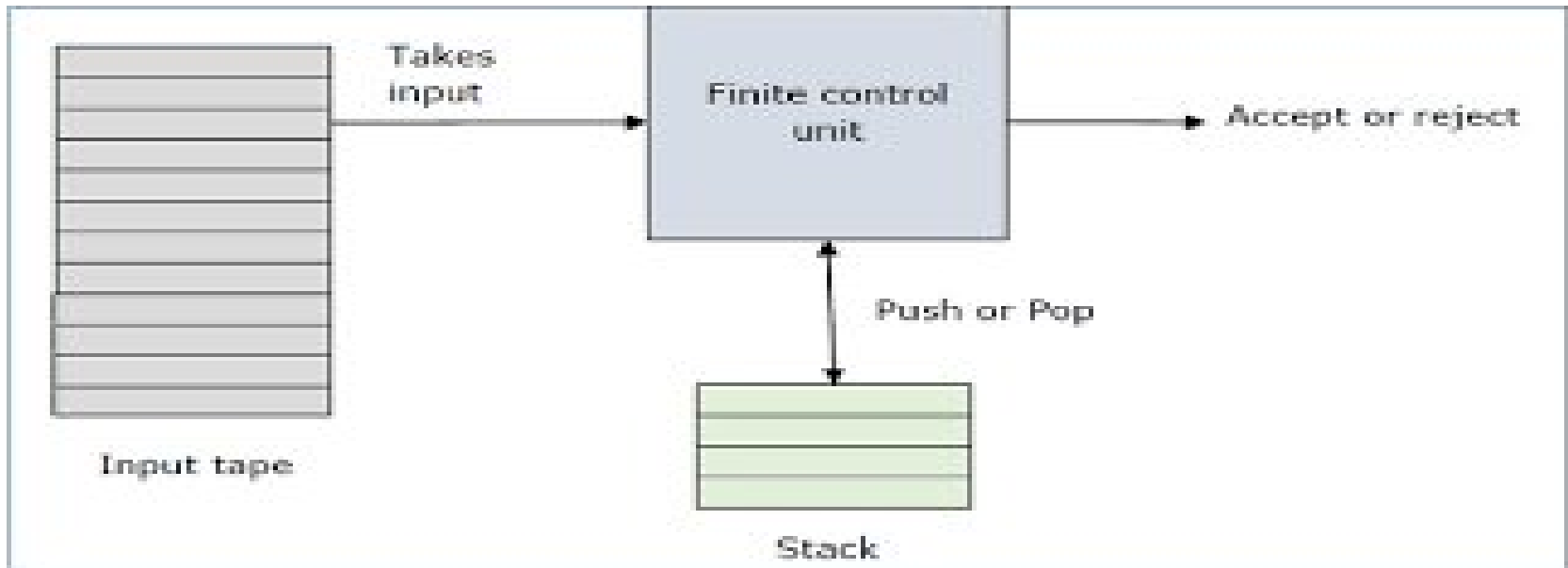
- Pushdown Automata
- PDA is the Class of Automata associated with CFL
- Finite Automata **cannot recognize all context free languages** as FA has strictly finite memory whereas the recognition of a CFL may require storing an unbounded amount of information.

PDA

- Eg-
- $L=\{a^n b^n \mid n \geq 0\}$
- When scanning the string, we must check that all a's precede the first b, we also need to count the number of a's
- Since n is unbounded, this counting cannot be done with a finite memory.
- We want a machine that can count without limit

PDA

- A pushdown automaton is –
"Finite state machine" + "a stack"



- A pushdown automaton has three components –
 - 1) an input tape,
 - 2) a control unit, and
 - 3) a stack with infinite size.
- The stack head scans the top symbol of the stack.

Deterministic PDA: Formal Definition

- A list of seven elements is called a 7-tuple,
- A PDA can be defined as a 7-tuple

PDA: Formal Definition

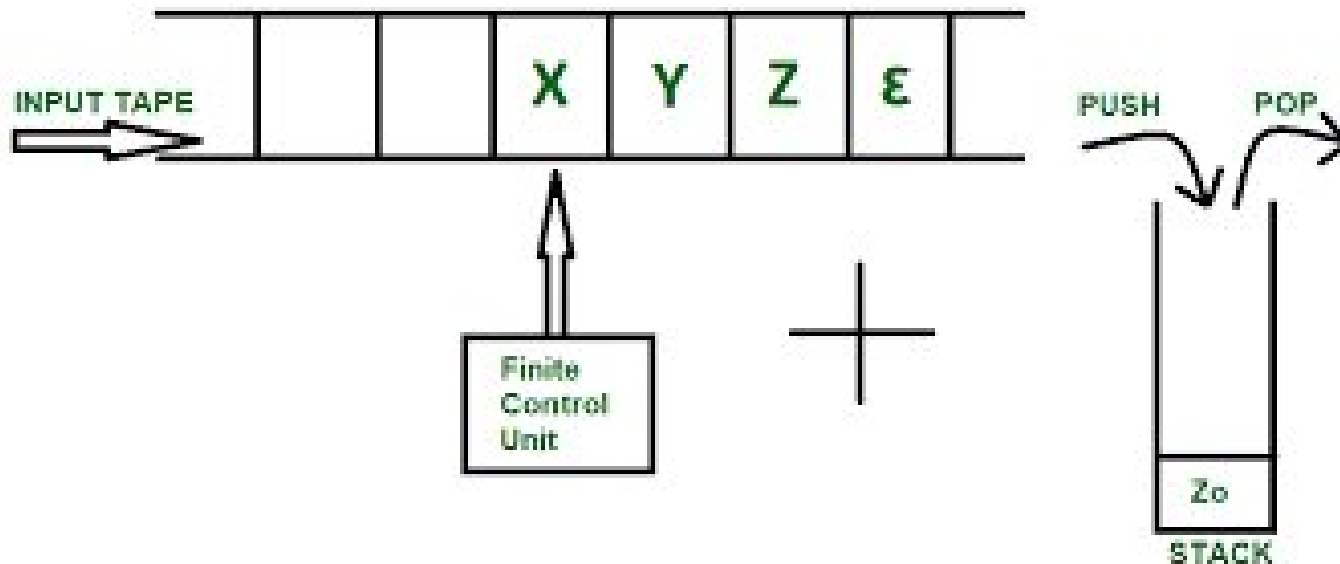
PDA is denoted by 7 Tuple: $M=(Q, \Sigma, \Gamma, \delta, q_0, z, F)$ where

- Q : Finite set of Internal states of the Control Unit
- Σ : Finite input alphabet
- Γ : Finite Set of Stack Symbols/ Pushdown symbols
- $\delta: Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$: Transition function(TF)
or
- $\delta: Q \times \Sigma_{\epsilon} \times \Gamma_{\epsilon} \rightarrow Q \times \Gamma_{\epsilon}^*$
- q_0 : Start state of Control Unit, $q_0 \in Q$
- z : Stack start Symbol, $z \in \Gamma$, Initially present in the stack
- F : Set of Final States/ Accept State, $F \subseteq Q$

δ Function

δ Function:-

- $\delta: Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$: Transition function(TF)
or
- $\delta: Q \times \Sigma_{\epsilon} \times \Gamma_{\epsilon} \rightarrow Q \times \Gamma_{\epsilon}^*$



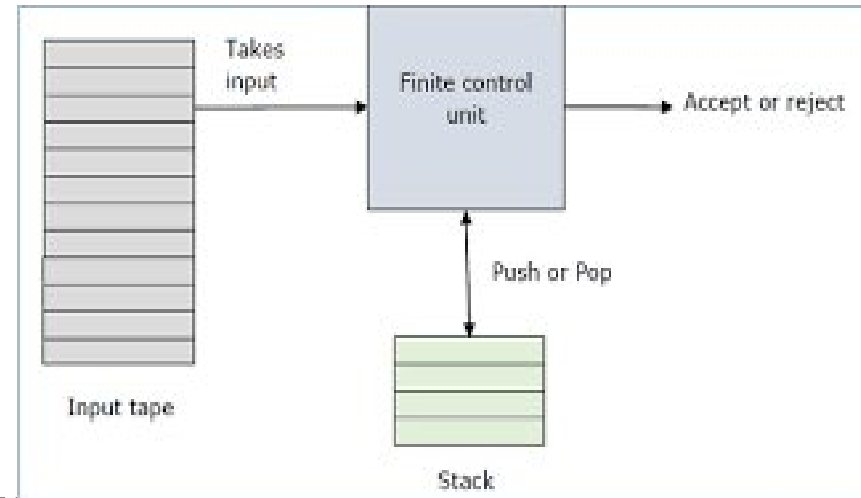
δ Function

δ Function:-

- $\delta: Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma^* \rightarrow Q \times \Gamma^*$: Transition function(TF)
or
- $\delta: Q \times \Sigma \times \Gamma \rightarrow Q \times \Gamma$

Domain-

- The Arguments are :-
 - 1) Current State of the control Unit
 - 2) Current Input Symbol
 - 3) Current Symbol on the Top of the stack



Range-

- The Set of pair (q,x) where :-
 - 1) q is Next state of the control Unit
 - 2) x is a string which is put on the top of the stack , in place of the single symbol there before

δ Function

δ Function:-

- $\delta: Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma^* \rightarrow Q \times \Gamma^*$: Transition function(TF)
or
- $\delta: Q \times \Sigma_\epsilon \times \Gamma_\epsilon \rightarrow Q \times \Gamma_\epsilon^*$

Domain-

- The Arguments are :-
 - 1) Current State of the control Unit
 - 2) Current Input Symbol- Can be ϵ , indicating a move that does not consume an input symbol, Also called ϵ or Null Transition
 - 3) Current Symbol on the Top of the stack- δ is defined so that it needs a stack symbol, no move is possible if the stack is empty

Instantaneous Description

Let $M=(Q, \Sigma, \Gamma, \delta, q_0, z, F)$ be a pda

An Instantaneous Description(ID) is (q,x,α)

where $q \in Q, x \in \Sigma^*, \alpha \in \Gamma^*$

- 1) q is the Current State of the control Unit
 - 2) x is the Unread part of the input string/The part of the input to be processed
 - Say a_1, a_2, \dots, a_n
 - The PDA will process in a_1, a_2, \dots, a_n order only
 - 3) α are the stack contents with the left most symbol indicating the top of the stack
- This triplet is called ID

Instantaneous Description

- A move from one ID to another will be denoted by Turnstile notation
- \vdash sign is called a “turnstile notation” and represents one move.

Move Relation-

Let M be a PDA

A move relation between IDs are defined as:-

$(q, a_1 a_2 \dots a_n, z_1 z_2 \dots z_n) \vdash (q', a_2 \dots a_n, \beta z_2 \dots z_n)$
if $\delta(q, a_1, z_1) = (q', \beta)$

PDA Example 1

Design a PDA for accepting the language $L = \{a^n b^n \mid n \geq 1\}$

Logic-

PDA Example 1

Design a PDA for accepting the language $L = \{a^n b^n \mid n \geq 1\}$

Rules-

PDA Example 1

Design a PDA for accepting the language $L = \{a^n b^n \mid n \geq 1\}$

Simulation-

PDA Example 2

Design a PDA for accepting the language $L = \{a^n b^{2n} \mid n \geq 1\}$

Logic-

PDA Example 2

Design a PDA for accepting the language $L = \{a^n b^{2n} \mid n \geq 1\}$

Rules-

PDA Example 2

Design a PDA for accepting the language $L = \{a^n b^{2n} \mid n \geq 1\}$

Simulation-

PDA Example 3

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) = n_b(w)\}$

Logic-

PDA Example 3

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) = n_b(w)\}$

Transition Rules-

- String “aababb”

PDA Example 3

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) = n_b(w)\}$

Simulation-

PDA Example 4

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) > n_b(w)\}$

Logic-

- **String “aababab”**

PDA Example 4

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) > n_b(w)\}$

Transition Rules-

PDA Example 4

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) > n_b(w)\}$

Simulation-

PDA Example 5

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) < n_b(w)\}$

Logic-

- **String “abbab”**

PDA Example 5

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) < n_b(w)\}$

Transition Rules-

PDA Example 5

Design a PDA for accepting the language $L = \{w \mid w \in (a + b)^* \text{ and } n_a(w) < n_b(w)\}$

Simulation-

PDA Example 6

Design a PDA that accepts a string of well formed paranthesis.

Consider the paranthesis as (,),{,},[,]

PDA Example 7

Design a PDA for language $L = \{wcw^R \mid w \text{ is in } (0|1)^* \text{ and } w^R \text{ is reverse of } w\}$

Logic-

String 101c101

PDA Example 7

Design a PDA for language $L=\{wcw^R \mid w \text{ is in } (0|1)^* \text{ and } w^R \text{ is reverse of } w\}$

Logic-

- The PDA will go on pushing the symbols onto the stack till it encounters c in the input
- It reads c but will not push it onto the stack
- For every symbol read after c , it checks whether it matches with the topmost symbol of the stack
- If input read is 0 , $top=0$, pop
- If input read is 1 , $top=1$, pop
- If input ends, we reach z_0 , replace z_0 by null
- Stack empty
- String accepted

PDA Example 7

Design a PDA for language $L = \{wcw^R \mid w \text{ is in } (0|1)^* \text{ and } w^R \text{ is reverse of } w\}$

Transition Rules

Deterministic PDA

Non-Deterministic PDA

NPDA: Formal Definition

NPDA is denoted by 7 Tuple: $M=(Q, \Sigma, \Gamma, \delta, q_0, z, F)$ where

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- Γ : Finite Set of Stack Symbols/ Pushdown symbols
- $\delta: Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow 2^{Q \times \Gamma^*}$: Transition function(TF)
or
- $\delta: Q \times \Sigma_{\epsilon} \times \Gamma_{\epsilon} \rightarrow 2^{Q \times \Gamma^*}$
- q_0 : Start state of Control Unit, $q_0 \in Q$
- z : Stack start Symbol, $z \in \Gamma$, Initially present in the stack
- F : Set of Final States/ Accept State, $F \subseteq Q$

Non Determinism-Example 1

Design a PDA for language $L = \{ww^R \mid w \text{ is non-empty even palindromes over } \{a,b\}, w^R \text{ is reverse of } w\}$

Initial a and b read, when top=z0, it will push

Further, If we read a, top=a, Two Moves possible

- 1) Pop and advance input tape head one position**
- 2) Push the element read and advance input tape head one position**

Further, If we read b, top=b, Two Moves possible

- 1) Pop and advance input tape head one position**
- 2) Push the element read and advance input tape head one position**

Non Determinism-Example 1

Even length palindromes

String “baab”

String “baaaab”

Non Determinism-Example 1

Design a PDA for language $L = \{ww^R \mid w \text{ is non-empty even palindromes over } \{a,b\}, w^R \text{ is reverse of } w\}$

$$\delta(q_0, a, z_0) = (q_0, az_0)$$

$$\delta(q_0, b, z_0) = (q_0, bz_0)$$

$$\delta(q_0, a, a) = \{(q_0, aa), (q_1, \epsilon)\}$$

$$\delta(q_0, b, b) = \{(q_0, bb), (q_1, \epsilon)\}$$

$$\delta(q_1, a, a) = (q_1, \epsilon)$$

$$\delta(q_1, b, b) = (q_1, \epsilon)$$

$$\delta(q_1, \epsilon, z_0) = (q_1, \epsilon)$$

Practice