## CC2511 Week 11

#### Calendar

Week	Lecture	Lab
11 (you are here)	Assembly part 2	Assembly part 2
12	Revision & Exam prep	None (open session for assignment work)
13	None (work on your assignment)	Demonstrate your assignment

- You're nearly at the end of the subject.
- This is the last week with new content.

#### Today: More on assembly language

- Calling conventions
- Defining functions in assembly language
- Array indexing
- Mixing C and assembly code

#### Revision: what do these instructions do?

# start: mov r0, #0 ldr r1, =0x40048080 ldr r2, [r1,#4] ldr r3, [r1,r0] b start

#### A historical note

- The GNU assembler defaults to an older syntax in which ARM and Thumb modes were written differently.
- Some Thumb2 instructions cannot be expressed in the older syntax.
- To use the new syntax, place the following directive at the top of the assembly file:
  - .syntax unified
- Without this command, some instructions become unavailable, e.g. many that manipulate the higher registers.

#### How to implement functions in assembly?

- Call a function by using one of the **branch** instructions.
- Questions:
  - How to pass arguments?
  - How to communicate the return value?
  - Is a function permitted to modify the registers?
  - How does the function know where to return to (branch to) when it's done?

- Clearly, the caller and the function must agree on these points.
- The answers to these questions define a "calling convention".

#### ARM calling convention: Passing arguments

- The first four function arguments are placed in r0, r1, r2, and r3. Subsequent arguments (if any) are placed on the stack.
- The return value is placed in r0 when the function ends.

```
int f(int a, int b) {
    // a is in r0
    // b is in r1
    ...
    // the return value is in r0
}
```

#### ARM calling convention: The link register

- The return address is stored in the link register (lr).
- To call a function, use bl ("branch and link")

```
/* move arguments into r0, r1, ... */

bl func
```

- The bl instruction:
  - 1. Places the address of the next instruction (after the bl) into the link register (lr).
  - 2. Jumps to the specified label (i.e. loads its address into pc)

#### Returning from a function

• To return from a function, branch to the address stored in the link register:

```
bx lr /* branch to the address in lr */

/* This is equivalent to: */

mov pc, lr

/* but generally prefer the bx syntax */
```

#### ARM calling convention: Preserving registers

- Functions can freely modify r0-r3.
- Functions must preserve r4-r11
- r12 can be freely modified on Kinetis.
  - (R12 is also called "IP" and has a special meaning on certain systems, where it is used for dynamic linking. Small microcontrollers do not have dynamic linking, so here r12 is a general purpose register.)

- In other words, the caller can assume its data in r4-r11 is retained.
- Any time a subfunction is called, r0-r3 and r12 may be overwritten.

#### Preserving registers

- If a function uses any of r4 r11, it must restore the original values before returning.
- Can do this by pushing the old values to the stack.
- The ARM push instruction can move multiple registers at once.
  - The op-code uses a bitfield to specify which registers are to be pushed.

```
Myfunc:

push {r4-r11}

pop {r4-r11}

bx lr
```

#### The link register and nested function calls

- The link register tells a function where to return to.
- If a function calls another, then the link register will be overwritten!
- Need to save the link register before bl ("branch and link") changes it.
- The standard approach is to push it to the stack at the start of the function.

```
push {lr}
...
pop {pc} /* replace pc with the previous lr */
```

#### Complying with the calling convention

```
func:
    /* Save r4-r11 and the link register: */
    push {r4-r11, lr}
    /* Function code here */
    /* Restore r4-r11, and set pc to the old lr */
    pop {r4-r11, pc} // replaces "bx lr"
```

#### Complying with the calling convention

```
Simple_func:
/* This fn returns 0 */
/* Not saving registers
because they aren't
modified. */
    mov r0, #0
    bx lr
```

- Technically, only need to save r4r11 and Ir if they are modified.
- Very simple functions might not need to use these registers.

 Be careful: If you later change the function and forget to save the registers, you introduce a hard-to-find bug.

#### Exercise: write in assembly

```
int add(int a, int b)
    return a + b;
int main()
    add(1, 2);
```

#### Solution

```
int add(int a, int b)
                             add:
                                  add r0, r1
    return a + b;
                                  bx lr
                             main:
int main()
                                  mov r0, #1
                                  mov r1, #2
    add(1, 2);
                                  bl add
```

#### The ARM stack

- ARM CPUs use a "full, descending" stack.
- "Full" means the stack pointer points to the last item pushed.
- "Descending" means that addresses decrement when items are pushed.
- The stack pointer is called "sp".

# Allocating memory on the stack: directly manipulate the stack pointer

```
func:
 push {r4-r11, lr} /* start of function */
 sub sp, #8 /* reserve space for two ints */
 str r0, [sp] /* example of writing to 1st variable */
 str r0, [sp,#4] /* example of writing to 2nd variable */
 add sp, #8 /* restore the stack pointer */
 pop {r4-r11, pc} /* end of function */
```

#### Sections

The current "section" is indicated by an assembly directive such as
 .text

- The "text" section:
  - Is read-only during execution (i.e. flash memory)
  - Contains executable code and constants
- The "data" section:
  - Is read-and-write during execution (i.e. RAM)
  - Contains variables

#### Statically allocating variables

```
/* At the top of the file, above the code */
    .data
    .align 2
variable_name:
    .skip 4*10 /* leave 40 bytes, i.e. 10 ints */
```

#### Labels evaluate as addresses

```
.data
     .align 2
variable_name:
     .skip 4*10 /* leave 40 bytes, i.e. 10 ints */
/* **/
     .text
     .align 2
main:
    ldr r0, =variable name
```

#### Allocation of constants

- Constants can be placed in the text section:
  - .text
  - .align 2

#### str1:

.ascii "Hello from ASM\0"

.align 2

#### const1:

.word 0x11112222

#### Loading constants

```
.text
                                  .text
     .align 2
                                  .align 2
const1:
                            main:
     .word 0x11112222
                            // Load address of const1
                                 ldr r0, =const1
                            // Load value of const1
                                 ldr r0, [r0]
```

#### Calling assembly functions from C

1. Define a function prototype telling the C compiler the data types to pass to the function:

```
// In a header file:
int add(int a, int b);
```

2. Write the function in assembly:

```
.global add
add:
  add r0, r1 /* place the return value in r0 */
  bx lr
```

## Calling C functions from assembly: complete example

```
.syntax unified
/* Constants */
    .text
msg:
    .ascii "Hello from ASM\r\n\0" /* notice the explicit trailing NULL */
/* Function */
                                                  COM5 - KiTTY
    .text
    .align 2
                                                  Hello from ASM
    .global hello
hello: /* the function name */
    push {r4-r11, lr}
    ldr r0, =msg /* first and only argument: pointer to the string */
    bl Term1_SendStr
    pop {r4-r11, pc}
```

#### Functions with more than 4 arguments

```
int asm_func(int a, int b, int c, int d, int e, int f, int g);
asm func:
/* a-d are in r0-r3 */
/* e is at [sp] but we need to use the stack to save registers: */
      push {r4-r7, lr} /* 5*4=20 bytes */
/* As a result of this push, arg4 is now at [sp+20]
      ldr r4, [sp,#20] /* argument e */
      ldr r5, [sp,#24] /* argument f */
      ldr r6, [sp,#28] /* argument g */
/* Notice that we don't remove the arguments from the stack! */
      pop {r4-r7,pc} /* return */
```

#### Common design patterns: array indexing

```
void zeroArray(int *a)
{
    int i;
    for (i=0;i<10;i++) {
        a[i] = 0;
    }
}</pre>
```

```
zeroArray:
     mov r1, #0 // value to store
      mov r2, #0 // array index (i)
loop1:
      str r1, [r0,r2]
      add r2, #4
     cmp r2, #40
     blt loop1
     bx pc
```

#### The adds and subs instructions

• Consider:

```
sub r1, #4
cmp r1, #0
bne my_loop /* branch if r1 is nonzero */
```

 The case of comparing with zero is so common that it was added to the subtract instruction:

```
subs r1, #4 /* notice s on subs */
bne my_loop /* branch if r1 is nonzero */
```

• This suffix also exists on other instructions (such as add).

### Assembly language reference page 3

## Where does assembly code provide benefits over C?

- Explicit choice of instruction to use, e.g. the size of the multiply instruction.
- Detection of integer overflows.
- Multiply and accumulate, which performs x = x + a\*b in one step.
- Parallel operations, performing the same instruction on multiple data values.

#### Multiply into a 64 bit result

- A 32-bit x 32-bit multiplication in general produces a 64-bit result.
- Expressing this in C is awkward because the cast must be done before the multiply:

long long int result = (long long int)a \* (long long int)b;

 ARM assembly has UMULL and SMULL instructions for unsigned and signed integers, respectively:

smull RdLo, RdHi, Rn, Rm

RdLo contains the least significant 32 bits of the result, RdHi contains the most significant 32 bits of the result, and Rn and Rm are the operands.

#### Detecting overflows

- The C standard says that overflows result in "undefined behaviour".
- Most implementations wrap around, i.e. INT\_MAX+1 = INT\_MIN but this is not guaranteed!
- Assembly code allows overflows to be detected using the v condition flag.

```
ldr r0, =0x7FFFFFFF /* max two's complement integer */
adds r0, #1 /* will set flag v on overflow */
bvs overflow /* branch if v is set */
```

There is also bvc (branch if v is cleared) for detecting no overflow.

#### Multiply and accumulate

- Multiply and accumulate is a common operating in digital signal processing (DSP) applications.
- The operation is x = x + a\*b.

```
umlal RdLo, RdHi, Rn, Rm
```

- 1. Multiplies Rn and Rm to produce a 64-bit result.
- 2. Adds that result with the 64-bit number already in RdLo, RdHi.
- 3. Stores the new result back into RdLo, RdHi.

#### Summary

- Function arguments are in r0-r3.
- Must preserve r4-r11 and Ir by pushing these to the stack and popping them at the end of the function (pop the old Ir into pc).
- The return value is placed in r0.

 The task in this week's lab is to implement a high-performance assembly code function (and try to be faster than a C implementation).