Necessities:

* Glue (preference is superglue)
* Screw driver
* Scissors
* 3D Printer
* PLA
* Shock cord
* Fishing line

instructions:

1. Thread the shock cord and the fishing line through each of the fingers.
2. Connect the fingers to the hand.
3. Connect the hand with the wrist piece with the use of glue.
4. Install the servos in the wrist piece.
5. Thread the fishing line through 1 of the holes of the servo and knot it off. (The thread of the thumb goes to the lower servo, the other fingers go to the upper servo.)
6. Connect the electronics as indicated on the schematic and upload the code to the Arduino.
7. Close the wrist cover with superglue.
8. Add the arm joint.
9. Attach the arm joint to the limb by tightening the strap.
10. Connect the electrodes of the sensor to the muscle of your choice.