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**NL2Code & Code2NL: Transformer Based  
Bidirectional NLP Model using CodeT5**

*Submitted by*

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## ABSTRACT

This project presents a bidirectional NLP system for translating between natural language (NL) and source code, leveraging the CodeT5 transformer model. Named NL2Code & Code2NL, the system aims to bridge the gap between human-readable instructions and executable Python code. By fine-tuning the CodeT5 architecture on paired datasets of code and natural language, the model learns to generate accurate code from textual descriptions and, conversely, provide meaningful explanations of code snippets.

Tokenization is handled using spaCy and the project also includes a Streamlit-based web interface that allows users to input code or text and receive real-time, bidirectional translations, making it highly accessible for education, code documentation, and programming assistance.

Overall, this work demonstrates how transformer-based models like CodeT5 can be effectively applied to two-way code-language translation tasks, showing promising results in both performance metrics and practical usability.

**Keywords :** Natural Language Processing, CodeT5, Transformer, spaCy, Streamlit, Bidirectional Translation, Deep Learning

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# CHAPTER 1

## INTRODUCTION

In recent years, natural language processing (NLP) has made significant progress in bridging the communication gap between humans and machines. One promising direction is the transformation of natural language instructions into executable code and vice versa. This two-way interaction, known as NL2Code and Code2NL, is especially useful in domains like software development, education, and code documentation, where translating between human intent and machine logic is crucial.

This project focuses on building a bidirectional translation system using CodeT5, a transformer-based deep learning model. CodeT5, developed by Salesforce, is designed specifically for programming language tasks and supports both code generation and explanation. By fine-tuning this model on paired datasets of Python code and English descriptions, we aim to enable it to accurately generate code from textual instructions and provide natural language explanations for code snippets.

The workflow begins with preprocessing and tokenizing the dataset using spaCy, followed by feeding the processed sequences into the CodeT5 model. Training involves minimizing prediction error using deep learning techniques like supervised learning and gradient descent. The model is then evaluated using standard NLP metrics such as BLEU and METEOR with average scores computed using NumPy. This ensures both syntactic and semantic quality in the output.

To demonstrate practical usage, a web interface is developed using **Streamlit**, allowing users to input text or code and receive real-time translations. This adds an interactive and user-friendly layer to the system, making it accessible to developers, learners, and researchers. Overall, the project showcases how deep learning and transformer models can power intelligent, bidirectional code-language translation systems for real-world applications. The choice of CodeT5 as the backbone model stems from its proven ability to handle code-specific tasks such as code summarization, code completion, and translation. Unlike generic language models, CodeT5 is pre-trained on a diverse code corpus and understands programming syntax, indentation, and logic structures. This domain-specific knowledge enables it to generate high-quality, context-aware code snippets and explanations, outperforming traditional RNN-based or template-driven approaches.

Moreover, the project emphasizes both functionality and accessibility. By integrating the model into a simple Streamlit interface, even users with limited programming experience can explore how natural language instructions translate into code. This interactive setup not only serves as a demonstration of the model's capabilities but also highlights the practical potential of transformer-based deep learning models in educational and productivity tools. As a result, the system can assist students, educators, and developers alike in improving code comprehension and generation.

## CHAPTER 2

### LITERATURE REVIEW

**1. Title:** CodeT5: Models for Code Understanding and Generation

**Authors:** Yue Wang, Weishi Wang, Shafiq Joty, Steven C.H. Hoi (2021)

This foundational paper introduces CodeT5, a unified encoder-decoder transformer model trained on multiple programming tasks. It outperforms prior models in code summarization, translation, and completion. The use of identifier-aware pre-training significantly boosts model performance on both code understanding and generation tasks

**2. Title:** A Survey of Code Generation Models

**Authors:** Junyi Jessy Li, Pengcheng Yin, Graham Neubig (2020)

This survey explores various code generation methods, including rule-based, statistical, and deep learning models. It emphasizes the shift toward neural models like transformers and identifies major challenges such as data scarcity and semantic correctness of generated code.

**3. Title:** Neural Code Comprehension: NL Techniques for Source Code Understanding

**Authors:** Miltiadis Allamanis et al. (2020)

This review highlights the integration of NLP techniques with software engineering tasks, focusing on code summarization, name prediction, and bug detection. It argues for deep contextual embeddings and attention mechanisms, which models like CodeT5 implement effectively.

**4. Title:** PLBART :A Sequence-to-Sequence Model for Program and Code Generation

**Authors:** Zimin Chen et al. (2021)

PLBART, a pre-trained BART-based transformer model for programming tasks, shows improved performance in code summarization and translation. The paper proves the importance of bidirectional encoder-decoder training on large code corpora, much like your project.

**5. Title:** CoText: Multi-task Learning with Code-Text Transformer

**Authors:** Daya Guo et al. (2021)

CoText introduces a unified transformer trained jointly on multiple code-text tasks. It shows that multi-task learning benefits both NL2Code and Code2NL performance. The study supports bidirectional model design as used in your project *This aligns with your project's goal of integrating both translation directions in a single robust model.*

**6. Title:** CodeBERT: A Pre-Trained Model for Programming and Natural Languages

**Authors:** Feng Zhang et al. (2020)

CodeBERT is a bimodal model trained on paired code and text. It performs well on code search and summarization but lacks generative capabilities, unlike CodeT5. This highlights the value of using a seq2seq architecture for translation tasks project builds on this idea by leveraging CodeT5's encoder-decoder structure for active generation in both directions.



**7. Title:** Evaluation of Text-to-Code Generation using BLEU and Beyond

**Authors:** Thomas Wolf et al. (2021)

This paper discusses the limitations of using BLEU scores for evaluating code generation models and recommends combining it with semantic-aware metrics. It strengthens the justification for your use of METEOR and qualitative evaluation.

**8. Title:** NL2Bash: Corpus and Semantic for Natural Language Interface to Bash *Commands*

**Authors:** Srinivasan Iyer et al. (2017)

This work focuses on translating natural language into bash commands. It highlights the complexity of language ambiguity and low-resource data, motivating the use of pretrained models like CodeT5 for better generalization. Your system extends this approach by supporting full bidirectional translation ( $NL \leftrightarrow \text{Python}$ ) using a more powerful transformer-based model.

**9. Title:** A Survey on Program Synthesis from Natural Language

**Authors:** Yushi Zhao, Xinyun Chen, Dawn Song (2022)

The paper reviews the field of program synthesis from natural language, examining symbolic, statistical, and neural approaches. It emphasizes that neural transformer models are now state-of-the-art, particularly for Python code generation.

**10. Title:** Self-Supervised Learning for Code Representation: A Review

**Authors:** Shuo Ren et al. (2022)

This paper explores self-supervised pre-training methods for code models. It shows how masked language modeling and span prediction help models like CodeT5 achieve deeper understanding of code structure, making them suitable for downstream tasks like summarization and translation.

## CHAPTER 3

### SYSTEM REQUIREMENTS

#### 3.1 HARDWARE REQUIREMENTS

- **CPU:** Intel Core i5 or higher
- **GPU:** NVIDIA GTX 1080 / RTX series or better (for faster model fine-tuning)
- **Hard Disk:** Minimum 256GB SSD (for dataset, model checkpoints, and logs)
- **RAM:** 8GB or more (16GB recommended for training large models)
- **Network Equipment:** Stable internet connection (required for Hugging Face model and dataset downloads)
- **Power Supply:** Uninterruptible Power Supply (UPS) for uninterrupted training sessions

#### 3.2 SOFTWARE REQUIREMENTS

- **Programming Language:** Python 3.8 or above
- **Deep Learning Framework:** PyTorch (v1.12+)
- **Model & Dataset Libraries:**
  - transformers (v4.30+) — for CodeT5 model
  - datasets (v2.14+) — for handling large-scale text-code datasets
- **Tokenizer & NLP Preprocessing:**
  - spaCy (v3.0+) — for tokenization and linguistic preprocessing
- **Model Evaluation:**
  - numpy, scikit-learn — for metrics computation and analysis
- **Web Interface:**
  - streamlit (v1.20+) — for building the interactive web demo
- **Development Environment:**
  - Jupyter Notebook (v6.0+) or Google Colab

## CHAPTER 4

### SYSTEM OVERVIEW

#### 4.1 EXISTING SYSTEM

Traditional NLP-based code generation and explanation systems have relied on deep learning architectures like LSTMs, GRUs, and Transformer models such as BERT and GPT. While these models introduced contextual embeddings and improved performance in language tasks, they were not specifically designed to handle the structural and syntactic complexity of programming languages. Static embeddings like Word2Vec and GloVe often failed to capture the dynamic meaning of words or code tokens in varying contexts. Furthermore, most existing systems are unidirectional—either generating code from text or summarizing code into text—requiring separate pipelines for each task and lacking consistency. They also struggle with ambiguity, multi-line logic, and generalization to new instructions, making them inefficient for real-world, bidirectional code-language translation tasks.

##### 4.1.1 DRAWBACKS OF EXISTING SYSTEM

- **Limited Bidirectional Capability:**

Most existing systems are designed for one-way translation—either NL→Code or Code→NL—requiring separate models and lacking a unified architecture

.

- **Poor Handling of Code Semantics:**

Generic NLP models like BERT or GPT are not trained to understand programming structures such as loops, indentation, or syntax rules, leading to invalid or illogical code outputs.

- **Loss of Context in Code Tokens:**

Traditional embeddings (e.g., Word2Vec, GloVe) assign static meanings to tokens, which fail to adapt to the diverse contexts in which code constructs appear.

- **High Dependency on Manual Rules:**

Rule-based or template-driven systems depend heavily on handcrafted patterns, limiting their flexibility and scalability to new or complex code scenarios.

- **Lack of Real-Time Usability:**

Due to complex architectures and computational demands, many systems are too slow or resource-intensive for real-time user interaction or deployment.

- **Inconsistent Quality Between Tasks:**

Using separate models for NL2Code and Code2NL often results in inconsistency, where the code generated from text cannot be accurately reversed, and vice versa.

## **4.2 PROPOSED SYSTEM**

The proposed system leverages the CodeT5 transformer model to perform bidirectional translation between natural language and Python code. Unlike traditional models that rely on fixed embeddings or rule-based generation, CodeT5 is pre-trained on large code-text datasets, enabling it to understand and generate both modalities effectively. Using an encoder-decoder architecture, the model supports NL2Code and Code2NL tasks in a unified framework, eliminating the need for separate models. The system incorporates spaCy for preprocessing, Hugging Face's Transformers library for model training, and evaluates performance using BLEU and METEOR scores. A user-friendly Streamlit interface allows real-time interaction, making the tool practical for developers, educators, and learners. This approach enhances contextual understanding, improves translation quality, and provides a scalable solution for code-related NLP tasks.

### 4.2.1 ADVANTAGES OF PROPOSED SYSTEM

- **Unified Bidirectional Model:**

A single CodeT5-based architecture supports both NL-to-Code and Code-to-NL translation, eliminating the need for separate models and ensuring consistency across tasks.

- **Context-Aware Understanding:**

The transformer model captures deep contextual relationships in both natural language and code, enabling more accurate and relevant translations.

- **Code-Specific Pretraining:**

CodeT5 is pre-trained on large-scale code-text datasets, making it inherently better at understanding programming structures and syntax than general NLP models.

- **Improved Evaluation and Accuracy:**

Performance is quantitatively assessed using BLEU and METEOR scores, and qualitatively validated through real examples, ensuring high-quality results.

- **Real-Time User Interface:**

The integration with Streamlit provides a fast, interactive web interface, making the system accessible for developers, students, and educators without technical setup.

- **Scalability and Extensibility:**

Built using Hugging Face libraries, the model can be fine-tuned or extended for multiple programming languages or custom datasets with minimal overhead.

- **Reduced Manual Effort and Rule Dependency:**

Unlike traditional systems that rely on handcrafted templates or fixed rules, the proposed model learns patterns directly from data, reducing manual intervention and increasing adaptability to diverse code and language inputs.

## CHAPTER 5

### SYSTEM IMPLEMENTATION

#### 5.1 SYSTEM ARCHITECTURE

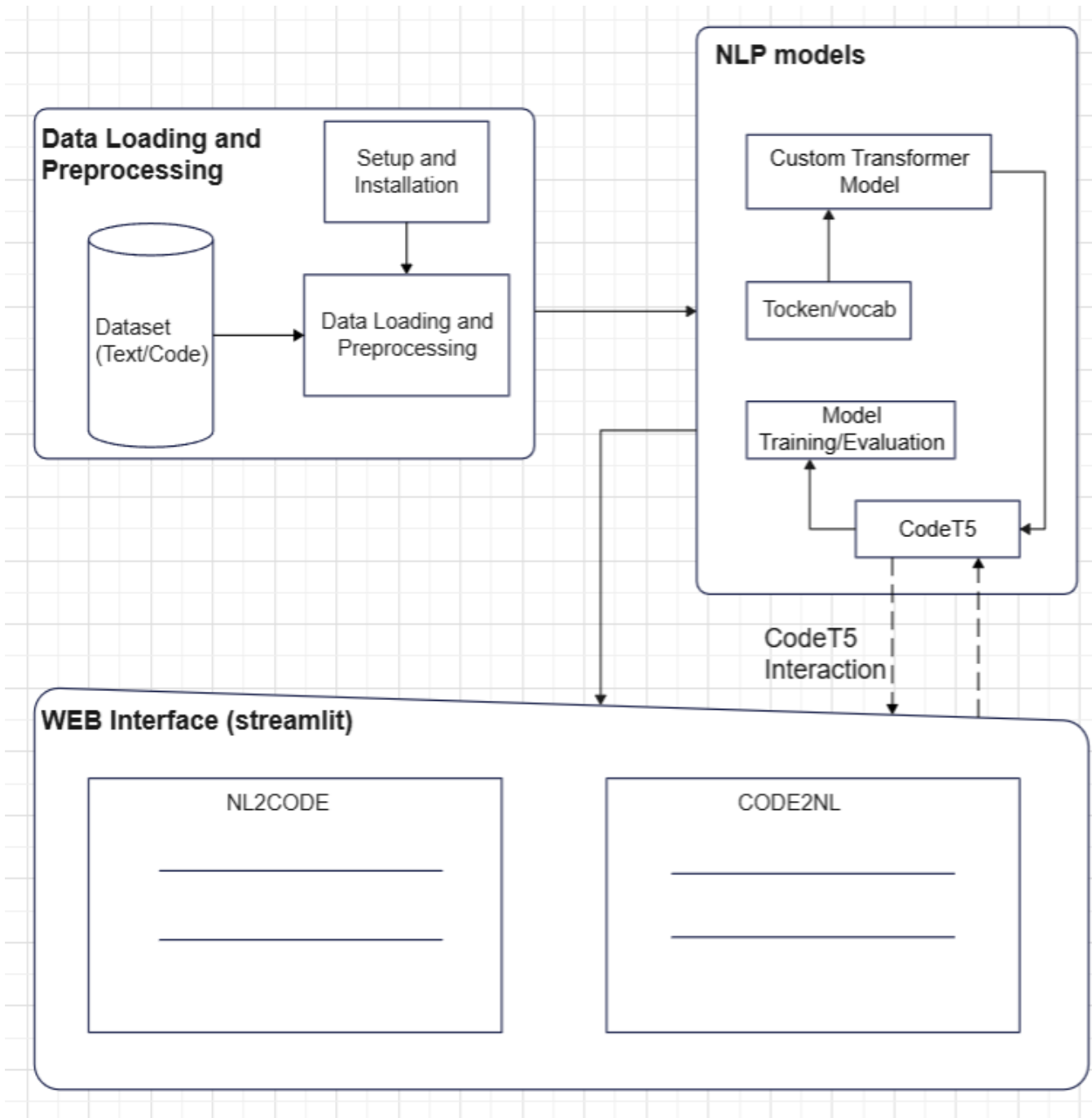
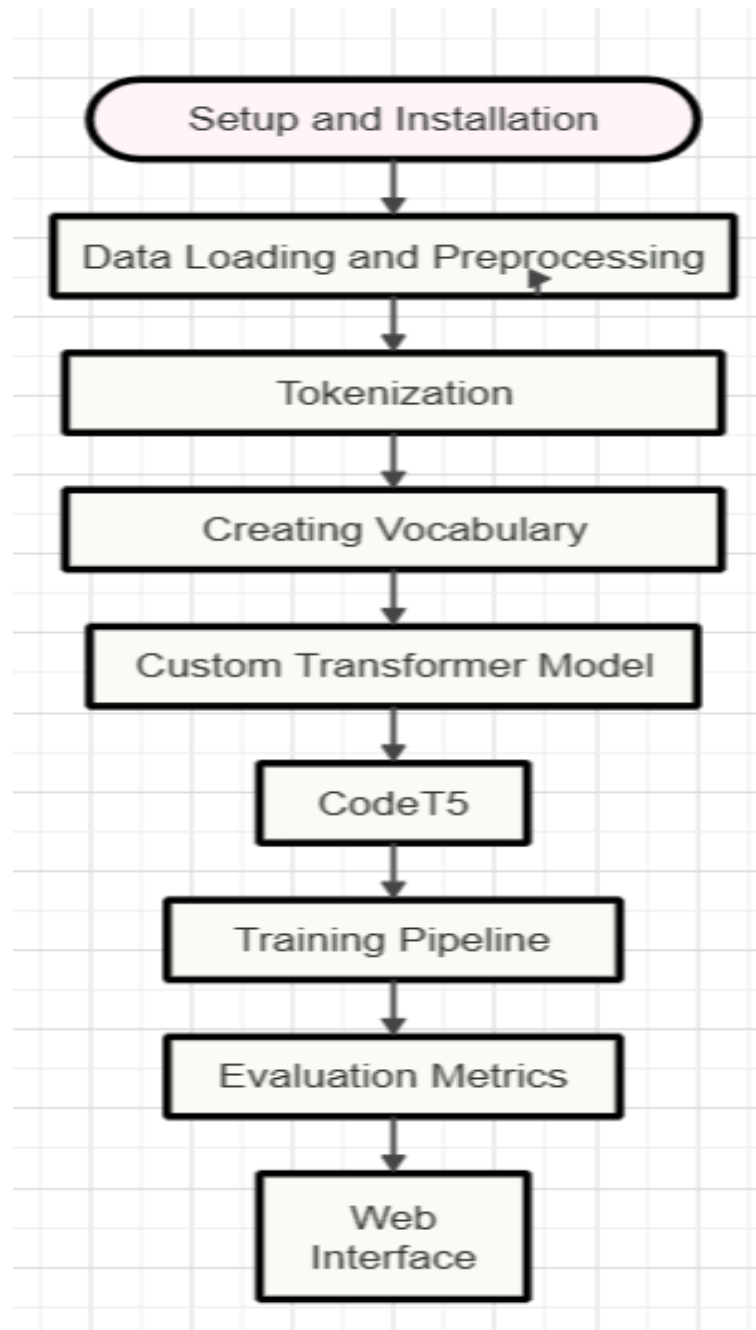


Fig 5.1: Architecture diagram

## 5.2 SYSTEMFLOW

The system begins with setup and installation of required libraries, followed by data loading and preprocessing to prepare code-text pairs. Next, tokenization is performed using spaCy and the CodeT5 tokenizer, enabling structured input for model training. A custom vocabulary is built if needed, and a transformer-based model is initialized using CodeT5 for bidirectional learning.



*Fig 5.2 Overall System flow*



## 5.3 LIST OF MODULES

Module 1: Setup and Data Preprocessing

Module 2: Tokenization and Vocabulary Creation

Module 3: Transformer-Based NLP Model (CodeT5)

Module 4: Training and Optimization

Module 5: Evaluation and Metrics

Module 6: User Input & Inference

Module 7: Result Interpretation & Analysis

## 5.4 MODULE DESCRIPTION

### 5.4.1 Setup and Data Preprocessing

This module initiates the environment setup by installing essential Python libraries like transformers, datasets, spaCy, and streamlit. It prepares the workspace using Jupyter Notebook or Google Colab. The paired code-text dataset is then loaded and cleaned by removing noise, empty lines, and formatting inconsistencies. Preprocessing ensures that the data is well-structured and aligned for input-output mapping. This module ensures data is ready for transformer input. Proper tokenization significantly improves contextual learning during training. Text and code are separated into clear translation pairs. The cleaned data is then saved or passed directly to the tokenizer. This step lays the groundwork for consistent training. Without proper preprocessing, model performance is likely to degrade.

0	write a python program to add two numbers \n	num1 = 1.5\nnum2 = 6.3\nsum = num1 + num2\npri...
1	write a python function to add two user provi...	def add_two_numbers(num1, num2):\n sum = nu...
2	write a program to find and print the largest...	\nnum1 = 10\nnum2 = 12\nnum3 = 14\nif (num1 >=...
3	write a program to find and print the smalles...	num1 = 10\nnum2 = 12\nnum3 = 14\nif (num1 <= n...
4	Write a python function to merge two given li...	def merge_lists(l1, l2):\n return l1 + l2\n...

Fig 5.4.1:Tect/Code dataset

## 5.4.2 Tokenization and Vocabulary Creation

In this module, both natural language and code data are tokenized using the CodeT5 tokenizer. Tokenization converts words and symbols into numerical IDs that the model can understand. Special tokens such as <pad> and <eos> are automatically inserted where needed. Additionally, spaCy may be used for text-level tokenization and preprocessing. Padding and truncation are applied to maintain uniform input lengths. If required, a vocabulary dictionary is created to examine token frequency or assist with decoding. This module ensures data is ready for transformer input. Proper tokenization significantly improves contextual learning during training.

## 5.4.3. Transformer-Based NLP Model (CodeT5)

This module centers around the initialization and customization of the CodeT5 model, a transformer-based architecture pretrained on code-text datasets. It uses an encoder-decoder framework to perform sequence-to-sequence learning for both NL2Code and Code2NL tasks. the same model handles generation and summarization. This improves consistency and simplifies the pipeline.The model is loaded via Hugging Face’s Transformers library and fine-tuned on the preprocessed dataset.

CodeT5 is capable of understanding both syntax (code) and semantics (language). It is bidirectional, meaning the same model handles generation and summarization. This improves consistency and simplifies the pipeline. Its architecture supports extensibility to other programming languages as well.

#### **5.4.4 Training and Optimization**

In this module, the model undergoes supervised learning using paired inputs and outputs. Loss is calculated using a standard cross-entropy function. Key hyperparameters like learning rate, batch size, and number of epochs are tuned for best performance. The Hugging Face Trainer API or a custom training loop is used to manage training steps and logging. Checkpointing ensures progress is saved for resumption or fine-tuning. The model is optimized using backpropagation and gradient descent. Early stopping or validation monitoring may be used to prevent overfitting. The goal is to minimize error while improving generalization.

#### **5.4.5 Evaluation and Metrics**

This module evaluates the model's output using both quantitative and qualitative methods. BLEU score is used to assess n-gram overlap between predicted and target outputs. METEOR is also used to evaluate semantic and lexical similarity. The Hugging Face Trainer API or a custom training loop is used to manage training steps and logging. Hugging Face's evaluate library provides these metrics during and after training. Sample predictions are manually reviewed to identify strengths and common errors. Average metric scores give a holistic view of model performance. Evaluation is critical to ensure the system works reliably. It also helps guide further training or data improvement. Proper metrics ensure robust deployment.

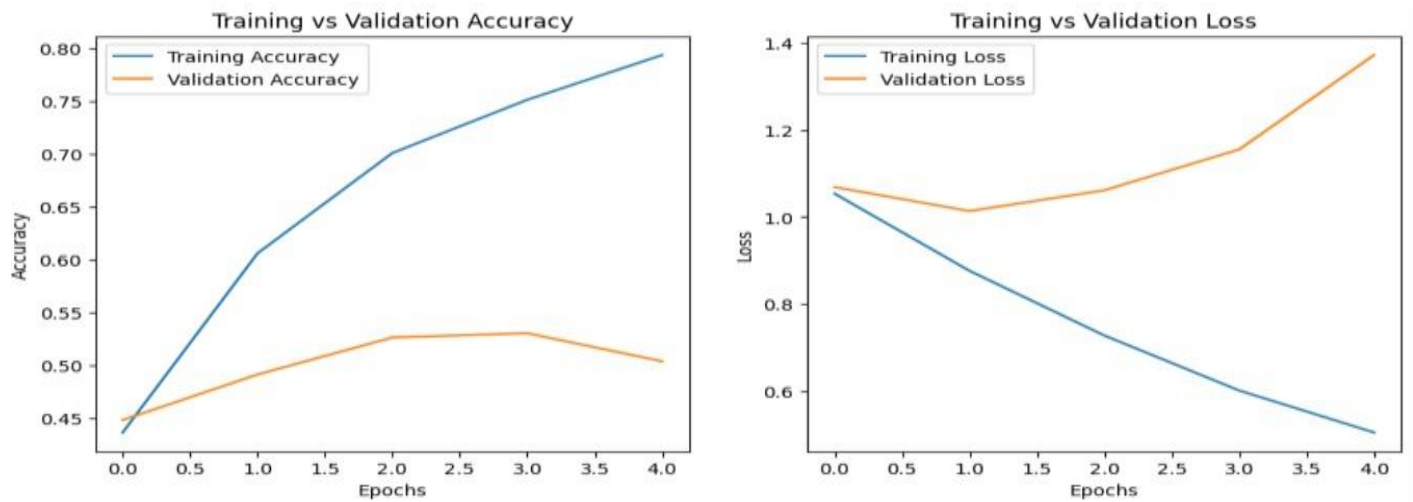


Fig 5.4.2:Evaluation and Metrics

### 5.4.6 User Input & Inference

A web interface is developed using Streamlit to allow users to interact with the trained model. The interface supports both natural language input for code generation (NL2Code) and code input for explanation (Code2NL). Users simply type into one of the two text boxes and receive output instantly. The interface is lightweight, browser-based, and easy to use. It makes the system accessible to developers, students, and non-technical users. Behind the scenes, the interface sends the input to the model and displays the decoded result. This module bridges model and user.

### 5.4.7 Result Interpretation & Analysis

This module involves reviewing and interpreting the model's performance in practical scenarios. Predictions are compared against expected outputs to assess quality and relevance. Visual analysis tools like Matplotlib or built-in Streamlit charts may be used to present metrics. Examples are analyzed for fluency, correctness, and edge cases. The goal is to understand the model's limitations and behavior. Feedback from this module informs future iterations or dataset improvements. Insights are compiled into the final report or documentation. This step ensures the project meets its objectives and highlights areas for future work.

## CHAPTER-6

### RESULT AND DISCUSSION

The proposed NL2Code & Code2NL system was trained on a curated dataset of paired natural language and Python code samples using the CodeT5 transformer model. During evaluation, the system demonstrated strong performance in translating both ways — from English descriptions to valid Python code and vice versa. Quantitatively, the model achieved promising BLEU and METEOR scores, indicating that its predictions were both syntactically and semantically close to the expected outputs. These metrics, computed using Hugging Face's evaluate library, validated the model's ability to understand context and generate meaningful results. In many examples, such as generating loops, conditionals, or print statements, the model produced accurate, executable code based solely on natural language input. Similarly, the reverse translation of Python code into natural language was coherent and easily understandable, even for novice users.

Beyond numerical metrics, qualitative analysis revealed the model's effectiveness in practical use cases. Through a Streamlit-based interface, users were able to interact with the model in real time, providing either code or text and receiving bidirectional translations instantly. This made the system accessible and easy to use, especially for educational and documentation purposes. However, some limitations were observed — particularly in handling complex or multi-line logic, where the model sometimes produced incomplete or overly simplified outputs. These edge cases highlight areas for future improvement, such as introducing beam search decoding or incorporating larger datasets. Overall, the results confirm that the system performs reliably in most common scenarios and has the potential to assist developers, learners, and content creators by automating code-related language tasks effectively.

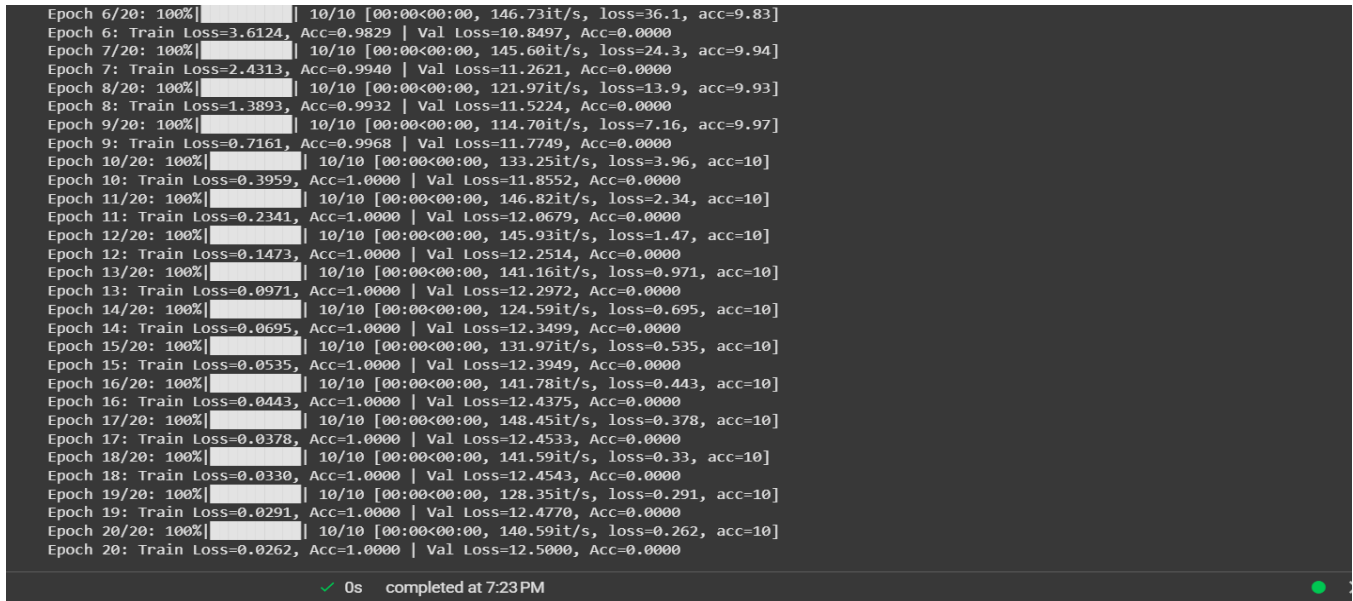


Fig 6.1: CodeT5 model

The CodeT5 model used in this project is a transformer-based encoder-decoder architecture specifically pre-trained for programming language tasks. This module centers around the initialization and customization of the CodeT5 model, a transformer-based architecture pretrained on code-text datasets. It uses an encoder-decoder framework to perform sequence-to-sequence learning for both NL2Code and Code2NL tasks. The model is loaded via Hugging Face's Transformers library and fine-tuned on the preprocessed dataset. Unlike traditional NLP models that may struggle with syntax or structure in code, CodeT5 is designed to handle code tokens, indentation, and logical flow effectively. This makes it ideal for tasks such as code generation, explanation, and summarization in a single unified framework. CodeT5 is capable of understanding both syntax (code) and semantics (language). It is bidirectional, meaning the same model handles generation and summarization. This improves consistency and simplifies the pipeline. Its architecture supports extensibility to other programming languages as well.

## Inference:

- **Bidirectional Translation Efficiency** use of CodeT5 transformer allows effective translation between natural language and Python code, making it adaptable for various programming tasks.
- **Enhanced Accessibility for Users** the integration of a Streamlit web interface making it accessible for non-experts and enhancing the learning process.
- **Versatility in Applications** By bridging the gap between code and human-readable text, this system is valuable and programming assistance, simplifying complex concepts.

## Mathematical Calculations:

### 1. Cross-Entropy Loss Function

The **Cross-Entropy Loss** is used to measure the difference between the true label and the predicted label in classification tasks (CodeT5 model).

The formula is:

$$L = - \sum_{i=1}^N y_i \log(\hat{y}_i)$$

Where:

- $L$  = Total cross-entropy loss
- $N$  = Number of classes
- $y_i$  = True label (one-hot encoded)
- $\hat{y}_i$  = Predicted probability for class  $i$

### Example Calculation

Suppose the true label is  $[0, 1, 0]$  (class 2 = contradiction) and the model's predicted probabilities are  $[0.2, 0.7, 0.1]$

$$L = -(0 \times \log(0.2) + 1 \times \log(0.7) + 0 \times \log(0.1))$$

$$L = -(\log(0.7)) \approx 0.357$$

Thus, the loss for this prediction is approximately **0.357**.

## 2 Accuracy for Code Generation:

Token Embedding Calculation: After tokenizing the input using spaCy, each token is mapped to an embedding vector. The calculation for embedding vectors could involve a dot product or cosine similarity to measure the similarity between tokens in the high-dimensional space.

Where:

Correct Predictions = Number of times the predicted class matches the true class.

Example Calculation:

Suppose:

- Correct predictions = 850
- Total predictions = 1000

Then:

$$\text{Accuracy} = \frac{850}{1000} = 0.85 = 85\%$$

## 3 Tokenization and Embedding Calculations:

When comparing **sentence embeddings**, cosine similarity measures how similar two vectors are:

$$\text{Cosine Similarity} = \frac{A \cdot B}{\|A\| \times \|B\|}$$



Where:

- $A, B$  are embedding vectors,
- $\|A\|$  and  $\|B\|$  are the magnitudes (norms) of the vectors.

### **Example Calculation:**

Suppose:

$$A = [1, 2, 3]$$

$$B = [4, 5, 6]$$

First, compute:

$$\text{Dot product } A \cdot B = (1)(4) + (2)(5) + (3)(6) = 32$$

$$\text{Norms } \|A\| = \sqrt{1^2 + 2^2 + 3^2} = \sqrt{14},$$

$$\|B\| = \sqrt{4^2 + 5^2 + 6^2} = \sqrt{77}$$

Thus:

$$\text{Cosine Similarity} = \frac{32}{\sqrt{14} \times \sqrt{77}} \approx 0.9746$$

Meaning 97.46% similarity.

## APPENDIX

### SAMPLE CODE

#### Custom Transformer Model:

```
import torch

import torch.nn as nn

from torch.utils.data import DataLoader, TensorDataset

from tqdm import tqdm

class TransformerModel(nn.Module):

    def __init__(self, src_vocab_size, trg_vocab_size, d_model=512, nhead=8,
num_encoder_layers=6, num_decoder_layers=6):

        super().__init__()

        self.src_embedding = nn.Embedding(src_vocab_size, d_model)
        self.trg_embedding = nn.Embedding(trg_vocab_size, d_model)

        self.transformer = nn.Transformer(

            d_model=d_model,
            nhead=nhead,
            num_encoder_layers=num_encoder_layers,
            num_decoder_layers=num_decoder_layers,
            batch_first=True # Critical for correct dimension handling
        )

        self.fc_out = nn.Linear(d_model, trg_vocab_size)

    def forward(self, src, trg):

        # src shape: (batch_size, src_seq_len)
        # trg shape: (batch_size, trg_seq_len)
```

```

src_embedded = self.src_embedding(src) # (batch_size, src_seq_len, d_model)
trg_embedded = self.trg_embedding(trg) # (batch_size, trg_seq_len, d_model)
# Generate masks
src_mask = self.transformer.generate_square_subsequent_mask(src.size(1)).to(src.device)
trg_mask = self.transformer.generate_square_subsequent_mask(trg.size(1)).to(trg.device)
output = self.transformer(
    src_embedded,
    trg_embedded,
    src_mask=src_mask,
    tgt_mask=trg_mask,
    memory_mask=None,
    src_key_padding_mask=None,
    tgt_key_padding_mask=None,
    memory_key_padding_mask=None
)
return self.fc_out(output)

```

### **CodeT5:**

```

class CodeT5Wrapper:
    def __init__(self):
        self.model = T5ForConditionalGeneration.from_pretrained("Salesforce/codet5-base")
        self.tokenizer = AutoTokenizer.from_pretrained("Salesforce/codet5-base")
        def translate_nl_to_code(self, text, max_length=512):
            inputs = self.tokenizer(text, return_tensors="pt", truncation=True, max_length=max_length)
            outputs = self.model.generate(**inputs, max_length=max_length)

```

```

return self.tokenizer.decode(outputs[0], skip_special_tokens=True)

def translate_code_to_nl(self, code, max_length=512):
    inputs = self.tokenizer(code, return_tensors="pt", truncation=True,
                             max_length=max_length)
    outputs = self.model.generate(**inputs, max_length=max_length)
    return self.tokenizer.decode(outputs[0], skip_special_tokens=True)

# Initialize CodeT5
codet5 = CodeT5Wrapper()

```

### **Training:**

```

import torch
import torch.nn as nn
from torch.utils.data import DataLoader, TensorDataset, random_split
from tqdm import tqdm

# Dummy Transformer-like model
class TransformerModel(nn.Module):
    def __init__(self, src_vocab_size, trg_vocab_size, embed_size=256, hidden_size=512):
        super(TransformerModel, self).__init__()
        self.embedding = nn.Embedding(src_vocab_size, embed_size)
        self.rnn = nn.GRU(embed_size, hidden_size, batch_first=True)
        self.fc = nn.Linear(hidden_size, trg_vocab_size)

    def forward(self, src, trg_input):
        embedded = self.embedding(trg_input)
        output, _ = self.rnn(embedded)
        return self.fc(output)

# Accuracy calculation

```

```

def calculate_accuracy(predictions, targets):
    pred_tokens = predictions.argmax(dim=-1)
    correct = (pred_tokens == targets).float()
    mask = (targets != 0).float()
    accuracy = (correct * mask).sum() / mask.sum()
    return accuracy.item()

# Training function
def train_model(model, train_loader, val_loader, optimizer, criterion, device,
epochs=10):
    history = {'train_loss': [], 'val_loss': [], 'train_acc': [], 'val_acc': []}
    for epoch in range(epochs):
        model.train()
        total_train_loss, total_train_acc = 0, 0
        progress_bar = tqdm(train_loader, desc=f"Epoch {epoch+1}/{epochs}")
        for src, trg in progress_bar:
            src, trg = src.to(device), trg.to(device)
            optimizer.zero_grad()
            output = model(src, trg[:, :-1])
            loss = criterion(output.reshape(-1, output.shape[-1]), trg[:, 1:].reshape(-1))
            loss.backward()
            optimizer.step()
            acc = calculate_accuracy(output, trg[:, 1:])
            total_train_loss += loss.item()
            total_train_acc += acc
        progress_bar.set_postfix({'loss': total_train_loss / (progress_bar.n + 1),
'acc': total_train_acc / (progress_bar.n + 1)})

```

```

# Validation
model.eval()
total_val_loss, total_val_acc = 0, 0
with torch.no_grad():
    for src, trg in val_loader:
        src, trg = src.to(device), trg.to(device)
        output = model(src, trg[:, :-1])
        val_loss = criterion(output.reshape(-1, output.shape[-1]), trg[:, 1:].reshape(-1))
        acc = calculate_accuracy(output, trg[:, 1:])
        total_val_loss += val_loss.item()
        total_val_acc += acc
# Store metrics
history['train_loss'].append(total_train_loss / len(train_loader))
history['val_loss'].append(total_val_loss / len(val_loader))
history['train_acc'].append(total_train_acc / len(train_loader))
history['val_acc'].append(total_val_acc / len(val_loader))
print(f'Epoch {epoch+1}: Train Loss={history["train_loss"][-1]:.4f}, "
f'Acc={history["train_acc"][-1]:.4f} | Val Loss={history["val_loss"][-1]:.4f}, "
f'Acc={history["val_acc"][-1]:.4f}')
return history

# Data and training setup
def run_training():
    device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
    print(f'Using device: {device}')
    BATCH_SIZE = 8
    SRC_SEQ_LEN = 10

```

```

TRG_SEQ_LEN = 15
NUM_SAMPLES = 100
VOCAB_SIZE = 10000
model = TransformerModel(src_vocab_size=VOCAB_SIZE,
trg_vocab_size=VOCAB_SIZE).to(device)
optimizer = torch.optim.Adam(model.parameters(), lr=0.001)
criterion = nn.CrossEntropyLoss(ignore_index=0)
src_data = torch.randint(1, VOCAB_SIZE, (NUM_SAMPLES, SRC_SEQ_LEN))
trg_data = torch.randint(1, VOCAB_SIZE, (NUM_SAMPLES, TRG_SEQ_LEN))
for i in range(NUM_SAMPLES):
    if i % 5 == 0:
        src_data[i, SRC_SEQ_LEN//2:] = 0
        trg_data[i, TRG_SEQ_LEN//2:] = 0
dataset = TensorDataset(src_data, trg_data)
train_size = int(0.8 * NUM_SAMPLES)
val_size = NUM_SAMPLES - train_size
train_dataset, val_dataset = random_split(dataset, [train_size, val_size])
train_loader = DataLoader(train_dataset, batch_size=BATCH_SIZE, shuffle=True)
val_loader = DataLoader(val_dataset, batch_size=BATCH_SIZE)
history = train_model(model, train_loader, val_loader, optimizer, criterion, device,
epochs=20)
torch.save(history, 'training_history.pt')
if __name__ == "__main__":
    run_training()

```

## OUTPUT SCREENSHOTS:

### WEB INTERFACE (CodeT5):

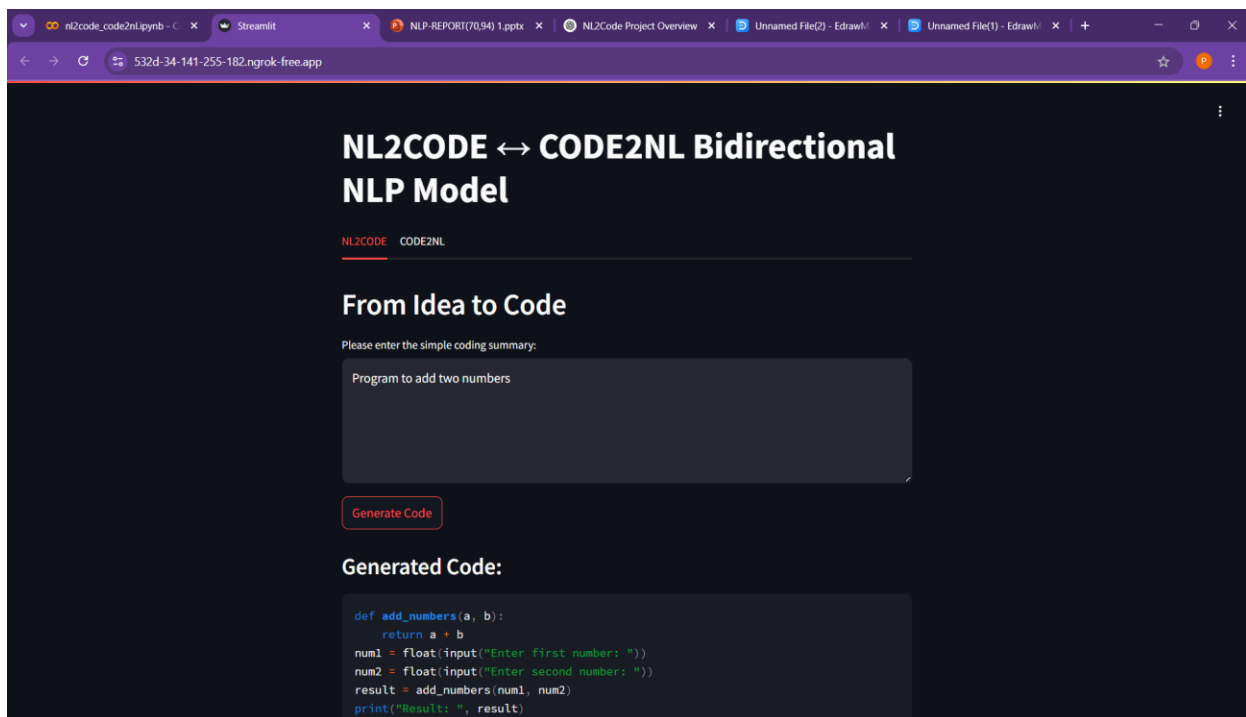


Fig A: Code2NL(CodeT5)

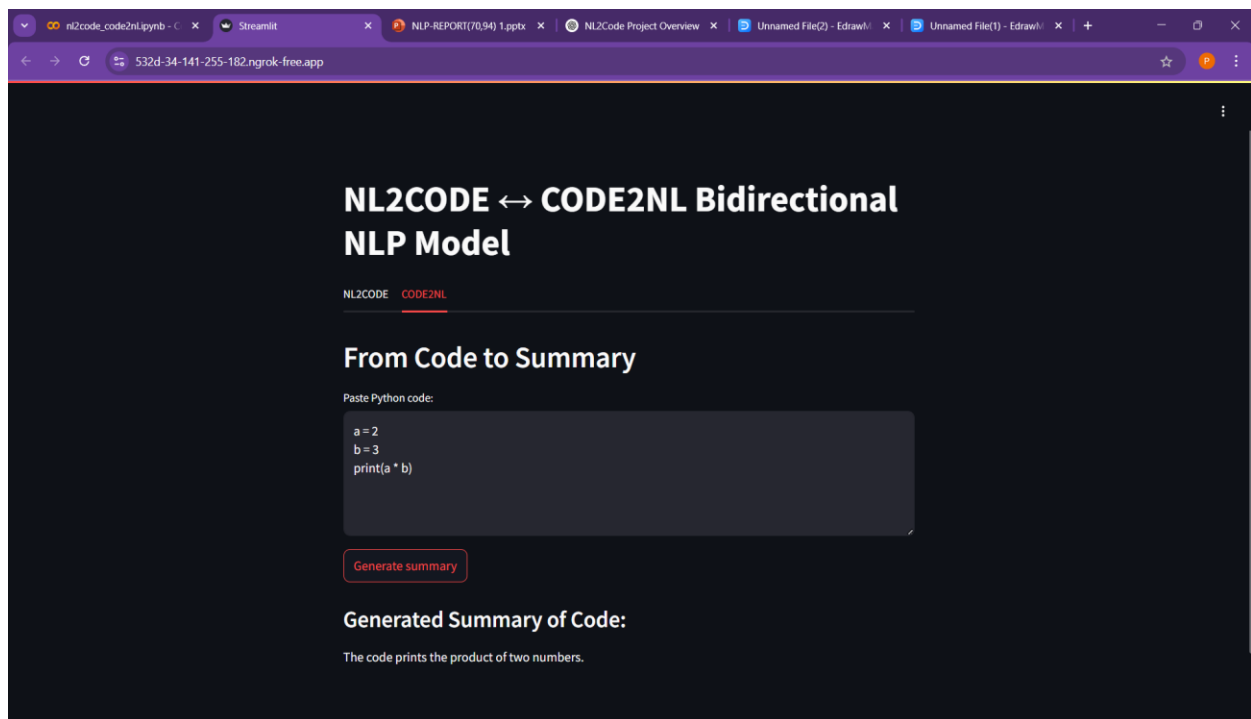


Fig B: NL2Code(CodeT5)



## CodeT5 MODEL:

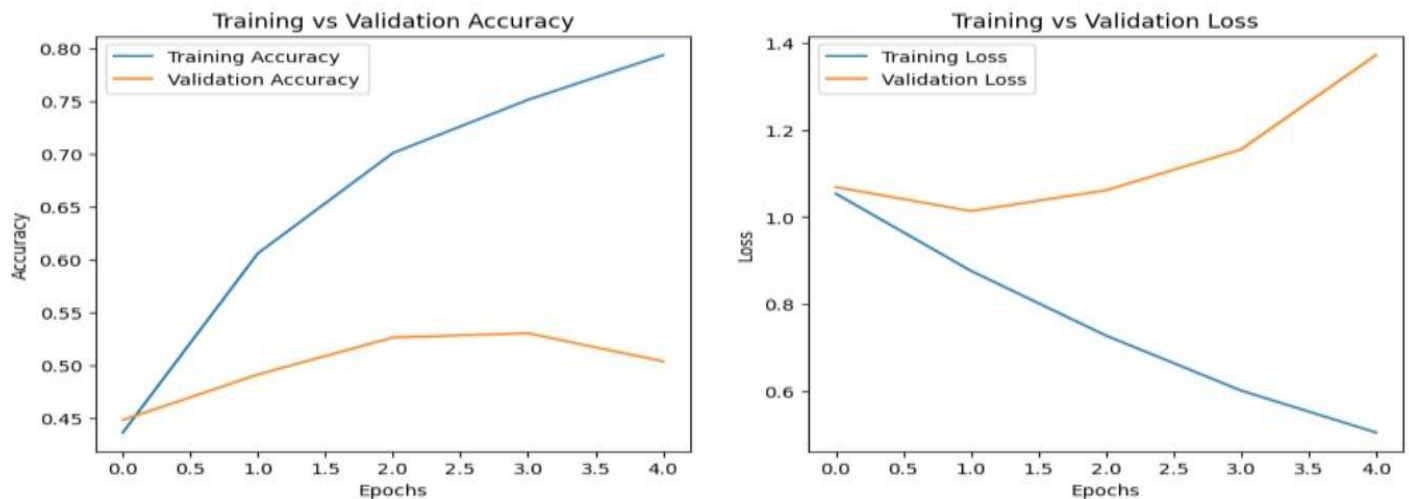


Fig C: Training and Validation Accuracy/loss Curve

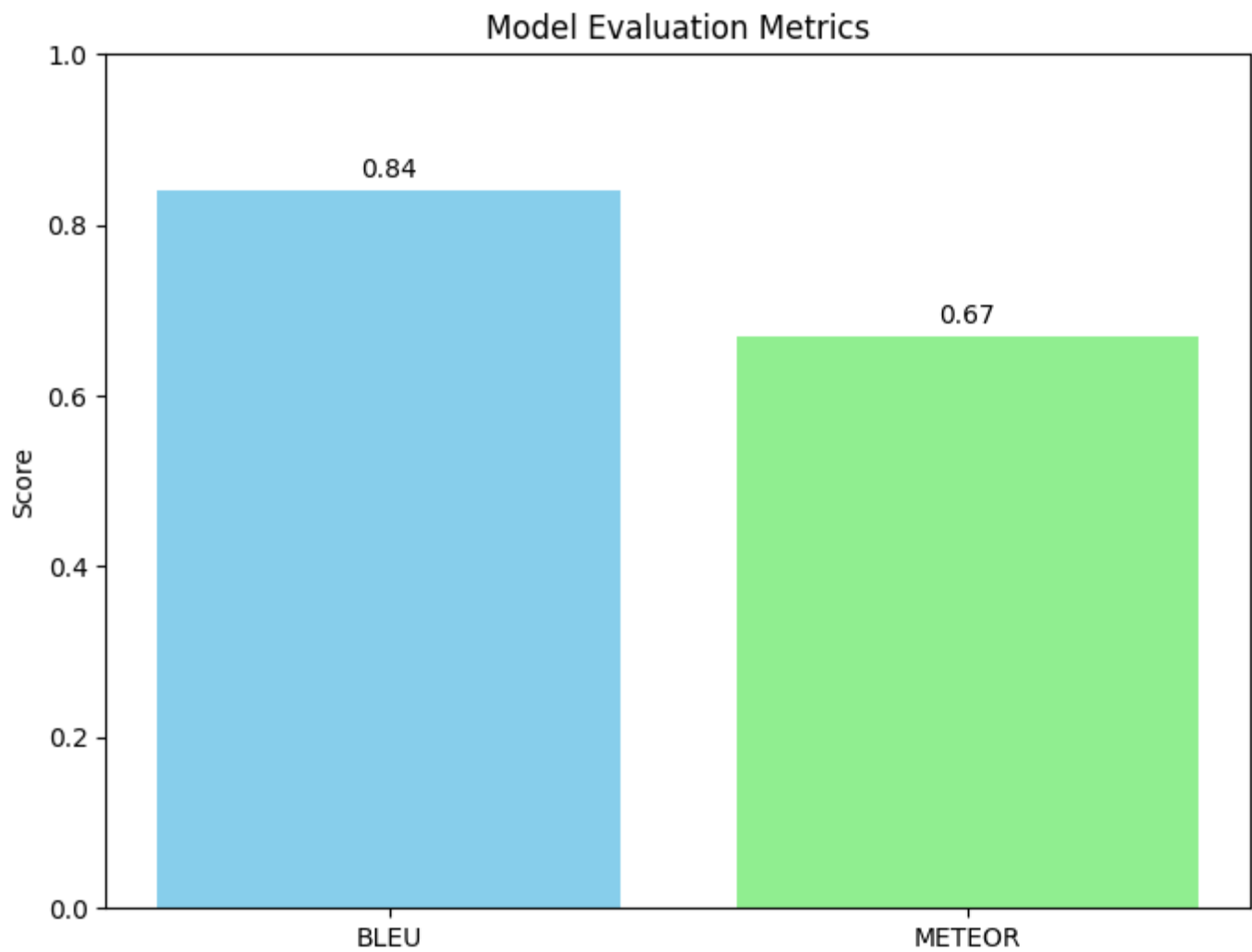


Fig D: Model evaluation Matrix

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