MLP for XDot21

November 24, 2024

```
[5]: # first neural network with keras tutorial
      import tensorflow as tf
      from tensorflow import keras
      from numpy import loadtxt
      from keras.models import Sequential
      from keras.layers import Dense
      #from keras.wrappers.scikit_learn import KerasRegressor
      from scikeras.wrappers import KerasClassifier, KerasRegressor
      from sklearn.model_selection import cross_val_score
      from sklearn.model_selection import KFold
      from sklearn.datasets import make_regression
      from sklearn.preprocessing import MinMaxScaler
      from sklearn.metrics import mean_absolute_error
      from numpy import asarray
      from numpy import unique
      from numpy import argmax
      import matplotlib.pyplot as plt
      import pandas as pd
      from sklearn.model_selection import train_test_split
      import numpy as np
      from tensorflow.keras.utils import plot model
      from sklearn.preprocessing import StandardScaler
 [7]: # load the dataset
      dataset = loadtxt('Data/Dataset_xdot21.csv', delimiter=',')
 [9]: # #ESSAI 3 ----OK
      X = dataset[:,0:6]
      y = dataset[:,6]
      scalarX, scalarY = MinMaxScaler(feature_range=(0,1)),__
       →MinMaxScaler(feature_range=(0,0.75))
      scalarX.fit(X)
      scalarY.fit(y.reshape(133,1))
      X = scalarX.transform(X)
      y=np.array(y).reshape(133,1)
      y = scalarY.transform(y)
[11]: print(y)
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[13]: # define the keras model
model = Sequential()
model.add(Dense(20, input_dim=6, kernel_initializer='normal',
activation='relu')) #kernel_initializer='normal'
model.add(Dense(1, kernel_initializer='normal', activation='linear')) #linear
print(model.summary())
```

H:\Anaconda\Lib\site-packages\keras\src\layers\core\dense.py:87: UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model

```
Model: "sequential"
      Layer (type)
                                         Output Shape
                                                                        Param #
      dense (Dense)
                                         (None, 20)
                                                                            140
      dense_1 (Dense)
                                         (None, 1)
                                                                             21
      Total params: 161 (644.00 B)
      Trainable params: 161 (644.00 B)
      Non-trainable params: 0 (0.00 B)
     None
[15]: model.compile(optimizer='adam', loss='mean_absolute_error')
[17]: # fit the keras model on the dataset
      history = model.fit(X, y, epochs=100, batch_size=8, verbose=2,__
       ⇔validation_split=0.25)
     Epoch 1/100
     13/13 - 1s - 41ms/step - loss: 0.0978 - val_loss: 0.7501
     Epoch 2/100
     13/13 - Os - 3ms/step - loss: 0.0953 - val_loss: 0.7495
     Epoch 3/100
     13/13 - Os - 3ms/step - loss: 0.0951 - val_loss: 0.7501
     Epoch 4/100
     13/13 - Os - 3ms/step - loss: 0.0949 - val_loss: 0.7496
     Epoch 5/100
     13/13 - Os - 3ms/step - loss: 0.0949 - val_loss: 0.7496
     Epoch 6/100
     13/13 - Os - 3ms/step - loss: 0.0949 - val_loss: 0.7493
     Epoch 7/100
     13/13 - Os - 3ms/step - loss: 0.0949 - val_loss: 0.7492
     Epoch 8/100
     13/13 - Os - 3ms/step - loss: 0.0948 - val_loss: 0.7489
     Epoch 9/100
     13/13 - Os - 3ms/step - loss: 0.0947 - val_loss: 0.7469
     Epoch 10/100
```

super().__init__(activity_regularizer=activity_regularizer, **kwargs)

instead.

```
13/13 - Os - 3ms/step - loss: 0.0947 - val_loss: 0.7467
Epoch 11/100
13/13 - Os - 3ms/step - loss: 0.0945 - val_loss: 0.7477
Epoch 12/100
13/13 - 0s - 3ms/step - loss: 0.0945 - val loss: 0.7465
Epoch 13/100
13/13 - Os - 3ms/step - loss: 0.0945 - val_loss: 0.7453
Epoch 14/100
13/13 - Os - 3ms/step - loss: 0.0944 - val_loss: 0.7462
Epoch 15/100
13/13 - Os - 3ms/step - loss: 0.0947 - val_loss: 0.7463
Epoch 16/100
13/13 - Os - 3ms/step - loss: 0.0948 - val_loss: 0.7439
Epoch 17/100
13/13 - Os - 3ms/step - loss: 0.0947 - val_loss: 0.7420
Epoch 18/100
13/13 - Os - 3ms/step - loss: 0.0942 - val_loss: 0.7410
Epoch 19/100
13/13 - Os - 3ms/step - loss: 0.0942 - val_loss: 0.7402
Epoch 20/100
13/13 - Os - 3ms/step - loss: 0.0941 - val_loss: 0.7403
Epoch 21/100
13/13 - Os - 3ms/step - loss: 0.0939 - val_loss: 0.7394
Epoch 22/100
13/13 - Os - 3ms/step - loss: 0.0937 - val_loss: 0.7380
Epoch 23/100
13/13 - 0s - 3ms/step - loss: 0.0935 - val_loss: 0.7328
Epoch 24/100
13/13 - Os - 3ms/step - loss: 0.0934 - val_loss: 0.7342
Epoch 25/100
13/13 - Os - 3ms/step - loss: 0.0932 - val_loss: 0.7299
Epoch 26/100
13/13 - Os - 3ms/step - loss: 0.0931 - val_loss: 0.7321
Epoch 27/100
13/13 - 0s - 3ms/step - loss: 0.0926 - val loss: 0.7283
Epoch 28/100
13/13 - Os - 3ms/step - loss: 0.0924 - val_loss: 0.7248
Epoch 29/100
13/13 - Os - 3ms/step - loss: 0.0924 - val_loss: 0.7163
Epoch 30/100
13/13 - Os - 3ms/step - loss: 0.0916 - val_loss: 0.7244
Epoch 31/100
13/13 - Os - 3ms/step - loss: 0.0918 - val_loss: 0.7176
Epoch 32/100
13/13 - Os - 3ms/step - loss: 0.0914 - val_loss: 0.7107
Epoch 33/100
13/13 - Os - 3ms/step - loss: 0.0914 - val_loss: 0.7172
Epoch 34/100
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13/13 - Os - 3ms/step - loss: 0.0905 - val_loss: 0.7048
Epoch 35/100
13/13 - Os - 3ms/step - loss: 0.0903 - val_loss: 0.7021
Epoch 36/100
13/13 - 0s - 3ms/step - loss: 0.0894 - val loss: 0.6997
Epoch 37/100
13/13 - Os - 3ms/step - loss: 0.0890 - val_loss: 0.6915
Epoch 38/100
13/13 - Os - 3ms/step - loss: 0.0884 - val_loss: 0.6881
Epoch 39/100
13/13 - Os - 3ms/step - loss: 0.0877 - val_loss: 0.6805
Epoch 40/100
13/13 - Os - 3ms/step - loss: 0.0870 - val_loss: 0.6799
Epoch 41/100
13/13 - Os - 3ms/step - loss: 0.0861 - val_loss: 0.6683
Epoch 42/100
13/13 - Os - 3ms/step - loss: 0.0859 - val_loss: 0.6601
Epoch 43/100
13/13 - Os - 3ms/step - loss: 0.0852 - val_loss: 0.6502
Epoch 44/100
13/13 - Os - 3ms/step - loss: 0.0841 - val_loss: 0.6478
Epoch 45/100
13/13 - Os - 3ms/step - loss: 0.0834 - val_loss: 0.6484
Epoch 46/100
13/13 - Os - 3ms/step - loss: 0.0829 - val_loss: 0.6340
Epoch 47/100
13/13 - 0s - 3ms/step - loss: 0.0815 - val_loss: 0.6313
Epoch 48/100
13/13 - Os - 3ms/step - loss: 0.0817 - val_loss: 0.6266
Epoch 49/100
13/13 - Os - 3ms/step - loss: 0.0806 - val_loss: 0.6197
Epoch 50/100
13/13 - Os - 3ms/step - loss: 0.0792 - val_loss: 0.5962
Epoch 51/100
13/13 - 0s - 3ms/step - loss: 0.0784 - val loss: 0.6094
Epoch 52/100
13/13 - Os - 3ms/step - loss: 0.0775 - val_loss: 0.5947
Epoch 53/100
13/13 - Os - 3ms/step - loss: 0.0760 - val_loss: 0.5865
Epoch 54/100
13/13 - Os - 3ms/step - loss: 0.0753 - val_loss: 0.5810
Epoch 55/100
13/13 - Os - 3ms/step - loss: 0.0746 - val_loss: 0.5677
Epoch 56/100
13/13 - Os - 3ms/step - loss: 0.0743 - val_loss: 0.5686
Epoch 57/100
13/13 - Os - 3ms/step - loss: 0.0730 - val_loss: 0.5545
Epoch 58/100
```

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13/13 - Os - 3ms/step - loss: 0.0719 - val_loss: 0.5451
Epoch 59/100
13/13 - Os - 3ms/step - loss: 0.0714 - val_loss: 0.5372
Epoch 60/100
13/13 - 0s - 3ms/step - loss: 0.0702 - val loss: 0.5320
Epoch 61/100
13/13 - Os - 3ms/step - loss: 0.0699 - val_loss: 0.5103
Epoch 62/100
13/13 - Os - 3ms/step - loss: 0.0681 - val_loss: 0.5164
Epoch 63/100
13/13 - Os - 3ms/step - loss: 0.0674 - val_loss: 0.4971
Epoch 64/100
13/13 - Os - 3ms/step - loss: 0.0671 - val_loss: 0.5109
Epoch 65/100
13/13 - Os - 3ms/step - loss: 0.0670 - val_loss: 0.4662
Epoch 66/100
13/13 - Os - 3ms/step - loss: 0.0651 - val_loss: 0.4892
Epoch 67/100
13/13 - Os - 3ms/step - loss: 0.0619 - val_loss: 0.4523
Epoch 68/100
13/13 - Os - 3ms/step - loss: 0.0657 - val_loss: 0.4408
Epoch 69/100
13/13 - Os - 3ms/step - loss: 0.0612 - val_loss: 0.4812
Epoch 70/100
13/13 - Os - 3ms/step - loss: 0.0608 - val_loss: 0.4492
Epoch 71/100
13/13 - 0s - 3ms/step - loss: 0.0590 - val_loss: 0.4235
Epoch 72/100
13/13 - Os - 3ms/step - loss: 0.0573 - val_loss: 0.4387
Epoch 73/100
13/13 - Os - 3ms/step - loss: 0.0565 - val_loss: 0.4187
Epoch 74/100
13/13 - Os - 3ms/step - loss: 0.0561 - val_loss: 0.4117
Epoch 75/100
13/13 - 0s - 3ms/step - loss: 0.0549 - val loss: 0.4174
Epoch 76/100
13/13 - Os - 3ms/step - loss: 0.0542 - val_loss: 0.3982
Epoch 77/100
13/13 - Os - 3ms/step - loss: 0.0532 - val_loss: 0.3945
Epoch 78/100
13/13 - Os - 3ms/step - loss: 0.0527 - val_loss: 0.3723
Epoch 79/100
13/13 - Os - 3ms/step - loss: 0.0515 - val_loss: 0.3942
Epoch 80/100
13/13 - Os - 3ms/step - loss: 0.0518 - val_loss: 0.3813
Epoch 81/100
13/13 - Os - 3ms/step - loss: 0.0503 - val_loss: 0.3585
Epoch 82/100
```

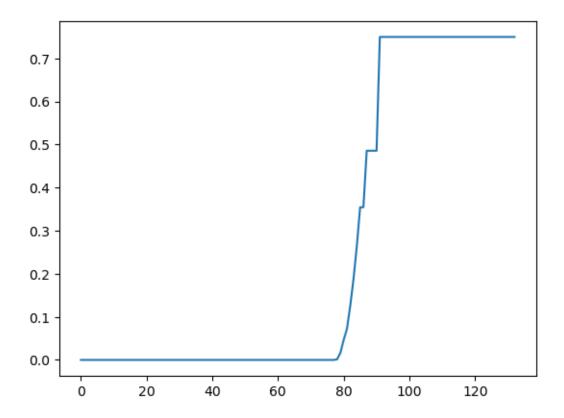
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13/13 - Os - 3ms/step - loss: 0.0510 - val_loss: 0.3426
     Epoch 83/100
     13/13 - Os - 3ms/step - loss: 0.0510 - val_loss: 0.3936
     Epoch 84/100
     13/13 - 0s - 3ms/step - loss: 0.0493 - val loss: 0.3625
     Epoch 85/100
     13/13 - Os - 3ms/step - loss: 0.0470 - val_loss: 0.3095
     Epoch 86/100
     13/13 - Os - 3ms/step - loss: 0.0481 - val_loss: 0.3306
     Epoch 87/100
     13/13 - Os - 3ms/step - loss: 0.0460 - val_loss: 0.3412
     Epoch 88/100
     13/13 - Os - 3ms/step - loss: 0.0454 - val_loss: 0.3315
     Epoch 89/100
     13/13 - Os - 3ms/step - loss: 0.0445 - val_loss: 0.3332
     Epoch 90/100
     13/13 - Os - 5ms/step - loss: 0.0440 - val_loss: 0.3183
     Epoch 91/100
     13/13 - Os - 4ms/step - loss: 0.0438 - val_loss: 0.3062
     Epoch 92/100
     13/13 - Os - 3ms/step - loss: 0.0435 - val_loss: 0.3020
     Epoch 93/100
     13/13 - Os - 3ms/step - loss: 0.0441 - val_loss: 0.3070
     Epoch 94/100
     13/13 - Os - 3ms/step - loss: 0.0423 - val_loss: 0.2956
     Epoch 95/100
     13/13 - 0s - 3ms/step - loss: 0.0425 - val_loss: 0.2973
     Epoch 96/100
     13/13 - Os - 3ms/step - loss: 0.0415 - val_loss: 0.2798
     Epoch 97/100
     13/13 - Os - 3ms/step - loss: 0.0408 - val_loss: 0.2772
     Epoch 98/100
     13/13 - 0s - 3ms/step - loss: 0.0402 - val_loss: 0.3009
     Epoch 99/100
     13/13 - 0s - 3ms/step - loss: 0.0411 - val loss: 0.3176
     Epoch 100/100
     13/13 - Os - 3ms/step - loss: 0.0416 - val_loss: 0.2685
[18]: # evaluate on test set
      yhat = model.predict(X)
      error = mean_absolute_error(y, yhat)
      print('MAE: %.5f' % error)
     5/5
                     Os 5ms/step
     MAE: 0.09767
[21]: print(yhat)
     [[-2.78289081e-04]
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- [-4.05335799e-04]
- [-2.96597602e-04]
- [-3.62993916e-04]
- [-2.86926515e-04]
- [-6.06518355e-04]
- [-6.06104732e-04]
- [-4.59668227e-04]
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- [-4.57932008e-04]
- [-7.48066348e-04]
- [-6.63720304e-04]
- [-4.67212521e-04]
- L-4.07212521e-04
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- [-4.46535298e-04]
- [-1.19354809e-04]
- [-1.15707400e-04]
- [-1.61209493e-04]
- [-8.43416550e-04]
- [-5.25716692e-04]
- [-2.89229676e-04]
- [-8.44891183e-05]
- [-5.32681588e-04]
- [-5.52001500e-04]
- [1.69139355e-04]
- [1.31362118e-04]
- [4.68385406e-06]
- [1.27462903e-04]
- [2.32188031e-05]
- [-3.58478690e-04]
- [-1.88919366e-04]
- [-2.31887214e-04]
- [1.61579112e-04]
- [-1.09067187e-05]
- [-1.72194792e-04]
- [-1.70679297e-04]
- [-6.65832194e-05]
- [-2.68367119e-04]
- [-2.54441053e-04]
- [5.56441955e-05]
- [1.32537098e-04]
- [1.14697730e-04]
- [-1.55188609e-04]
- [-1.28399581e-04]
- [-1.07251690e-04]
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- [-3.09258234e-04]
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- [-1.73029257e-05]
- [1.03782713e-01]
- [2.88738403e-04]
- [-2.63463589e-04]
- [3.99169289e-02]
- [-6.56398479e-05]
- [-4.76766145e-05]
- [4.96660359e-05]
- [2.02226415e-01]
- [3.20652639e-03]
- [-2.96172220e-06]
- [1.11814530e-03]
- [2.07318425e-01]
- [4.84937988e-02]
- [1.06840558e-01]
- [1.99537550e-04]
- [5.24555966e-02]
- [3.91239300e-05]
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- [1.37573807e-05]
- [-2.61047448e-04]
- [8.57539475e-02]
- [1.60566401e-02]
- [-9.20100138e-06]
- [1.13928996e-01]
- [-1.66893413e-04]
- [1.03208993e-04]
- [-1.39015226e-03]
- [8.76784697e-03]
- [1.46812931e-01]
- [1.99252635e-01]
- [2.13367984e-01]
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- [3.91103774e-01]
- [3.45948875e-01]
- [3.62819254e-01]
- [4.94096100e-01]
- [4.84270751e-01]
- [5.90294719e-01]
- [4.30817842e-01]
- [2.45215371e-01]
- [1.46851867e-01]
- [2.07783908e-01]
- [6.63169622e-01]
- [6.48764491e-01]
- [7.09936857e-01]

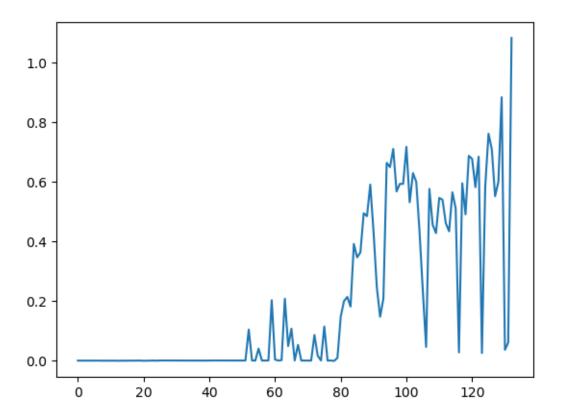
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      [ 5.92538655e-01]
      [ 7.16810048e-01]
      [ 5.30878603e-01]
      [ 6.28787220e-01]
      [ 5.99280357e-01]
      [ 4.32558060e-01]
      [ 2.33480290e-01]
      [ 4.55289930e-02]
      [ 5.75717032e-01]
      [ 4.55345005e-01]
      [ 4.27424103e-01]
      [ 5.45565307e-01]
      [ 5.39102912e-01]
      [ 4.60255057e-01]
      [ 4.33492303e-01]
      [ 5.64291000e-01]
      [ 5.10596752e-01]
      [ 2.72761416e-02]
      [ 5.94664991e-01]
      [ 4.90116417e-01]
      [ 6.86705112e-01]
      [ 6.76551163e-01]
      [ 5.81535459e-01]
      [ 6.83884084e-01]
      [ 2.50886213e-02]
      [ 5.84972560e-01]
      [ 7.60855913e-01]
      [ 7.08570957e-01]
      [ 5.51136196e-01]
      [ 5.99369526e-01]
      [ 8.83534372e-01]
      [ 3.58196795e-02]
      [ 6.06380031e-02]
      [ 1.08212614e+00]]
[23]: plt.plot(y)
```

[23]: [<matplotlib.lines.Line2D at 0x283e8bacec0>]



[25]: plt.plot(yhat)

[25]: [<matplotlib.lines.Line2D at 0x283eae32270>]



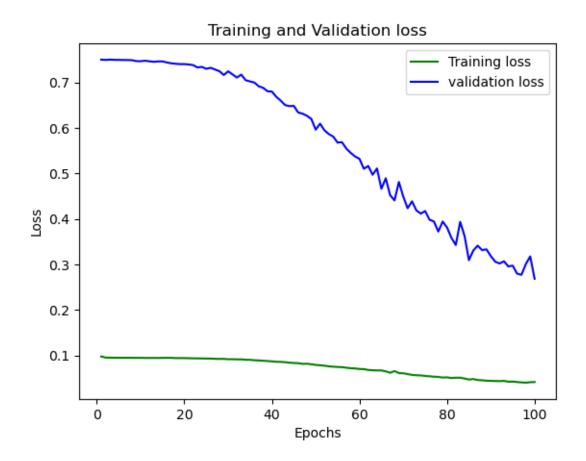
[27]: print(yhat-y)

- [[-2.78289081e-04]
- [-3.98990000e-04]
- [-3.37593956e-04]
- [-4.05335799e-04]
- [-2.96597602e-04]
- [-3.62993916e-04]
- [-2.86926515e-04]
- [-6.06518355e-04]
- [-6.06104732e-04]
- [-4.59668227e-04]
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- [-4.57932008e-04]
- [-7.48066348e-04]
- [-6.63720304e-04]
- [-4.67212521e-04]
- [-5.07488498e-04]
- [-4.46535298e-04]
- [-1.19354809e-04]
- [-1.15707400e-04]
- [-1.61209493e-04]

- [-8.43416550e-04]
- [-5.25716692e-04]
- [-2.89229676e-04]
- [-8.44891183e-05]
- [-5.32681588e-04]
- [1.69139355e-04]
- [1.31362118e-04]
- [4.68385406e-06]
- [1.27462903e-04]
- [2.32188031e-05]
- [-3.58478690e-04]
- [-1.88919366e-04]
- [-2.31887214e-04]
- [1.61579112e-04]
- [-1.09067187e-05]
- [-1.72194792e-04]
- [-1.70679297e-04]
- [-6.65832194e-05]
- [-2.68367119e-04]
- [-2.54441053e-04]
- [5.56441955e-05]
- [1.32537098e-04]
- [1.14697730e-04]
- [-1.55188609e-04]
- [-1.28399581e-04]
- [-1.07251690e-04]
- [-3.14894482e-04]
- [-1.19261793e-04]
- [-1.05537474e-04]
- [-3.09258234e-04]
- [-2.41101487e-04]
- [-1.73029257e-05]
- [1.03782713e-01]
- [2.88738403e-04]
- [-2.63463589e-04]
- [3.99169289e-02]
- [-6.56398479e-05]
- [-4.76766145e-05]
- [4.96660359e-05]
- [2.02226415e-01]
- [3.20652639e-03]
- [-2.96172220e-06]
- [1.11814530e-03]
- [2.07318425e-01]
- [4.84937988e-02]
- [1.06840558e-01]
- [1.99537550e-04]
- [5.24555966e-02]

- [3.91239300e-05]
- [-1.17820688e-04]
- [1.37573807e-05]
- [-2.61047448e-04]
- [8.57539475e-02]
- [1.60566401e-02]
- [-9.20100138e-06]
- [1.13928996e-01]
- [-1.66893413e-04]
- [1.03208993e-04]
- [-2.82583843e-03]
- [-7.89217798e-03]
- [1.00009227e-01]
- [1.26884114e-01]
- [8.70739844e-02]
- [-7.96800731e-03]
- [1.26324463e-01]
- [-8.64521680e-03]
- [8.22516265e-03]
- [8.33284832e-03]
- [-1.49250053e-03]
- [1.04531467e-01]
- [-5.49454095e-02]
- [-5.04784629e-01]
- [-6.03148133e-01]
- [-5.42216092e-01]
- [-8.68303776e-02]
- [-1.01235509e-01]
- [-4.00631428e-02]
- [-1.82916343e-01]
- [-1.57450974e-01]
- [-1.57461345e-01]
- [-3.31899524e-02]
- [-2.19121397e-01]
- [-1.21212780e-01]
- [-1.50719643e-01]
- [-3.17441940e-01]
- [-5.16519710e-01]
- [-7.04471007e-01]
- [-1.74282968e-01]
- [-2.94654995e-01]
- [-3.22575897e-01]
- [-2.04434693e-01]
- [-2.10897088e-01]
- [-2.89744943e-01]
- [-3.16507697e-01] [-1.85709000e-01]
- [-2.39403248e-01]

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[-7.22723858e-01]
      [-1.55335009e-01]
      [-2.59883583e-01]
      [-6.32948875e-02]
      [-7.34488368e-02]
      [-1.68464541e-01]
      [-6.61159158e-02]
      [-7.24911379e-01]
      [-1.65027440e-01]
      [ 1.08559132e-02]
      [-4.14290428e-02]
      [-1.98863804e-01]
      [-1.50630474e-01]
      [ 1.33534372e-01]
      [-7.14180321e-01]
      [-6.89361997e-01]
      [ 3.32126141e-01]]
[29]: print(history.history.keys())
     dict_keys(['loss', 'val_loss'])
[31]: loss_train = history.history['loss']
      loss_val = history.history['val_loss']
      epochs = range(1,101)
      plt.plot(epochs, loss_train, 'g', label='Training loss')
      plt.plot(epochs, loss_val, 'b', label='validation loss')
      plt.title('Training and Validation loss')
      plt.xlabel('Epochs')
      plt.ylabel('Loss')
      plt.legend()
      plt.show()
```



[]: