

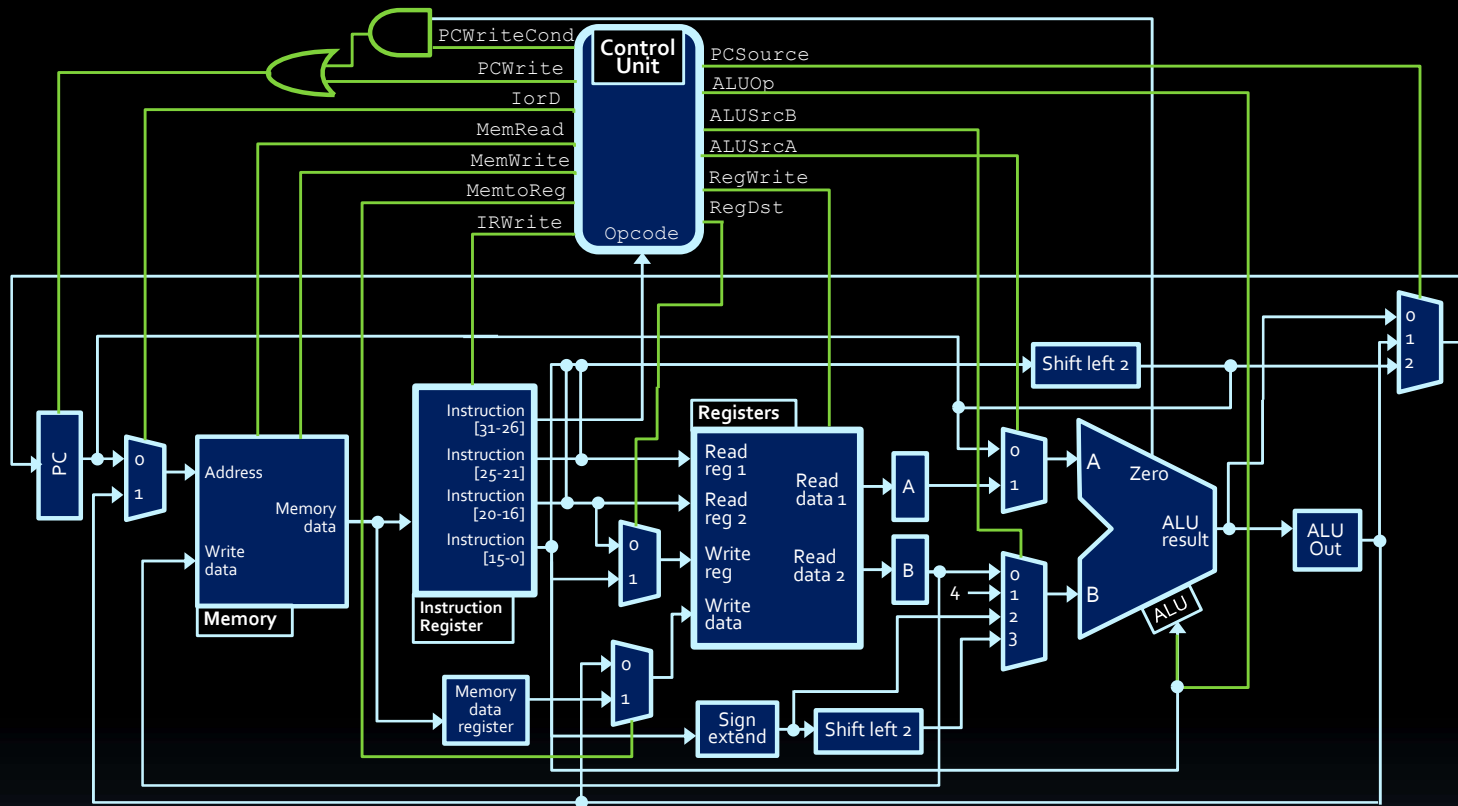


# Week 9 Review





# Question #1



- Given the datapath above, what signals would the control unit turn on and off in order to add \$t1 to \$t2 and store the result in \$t7?

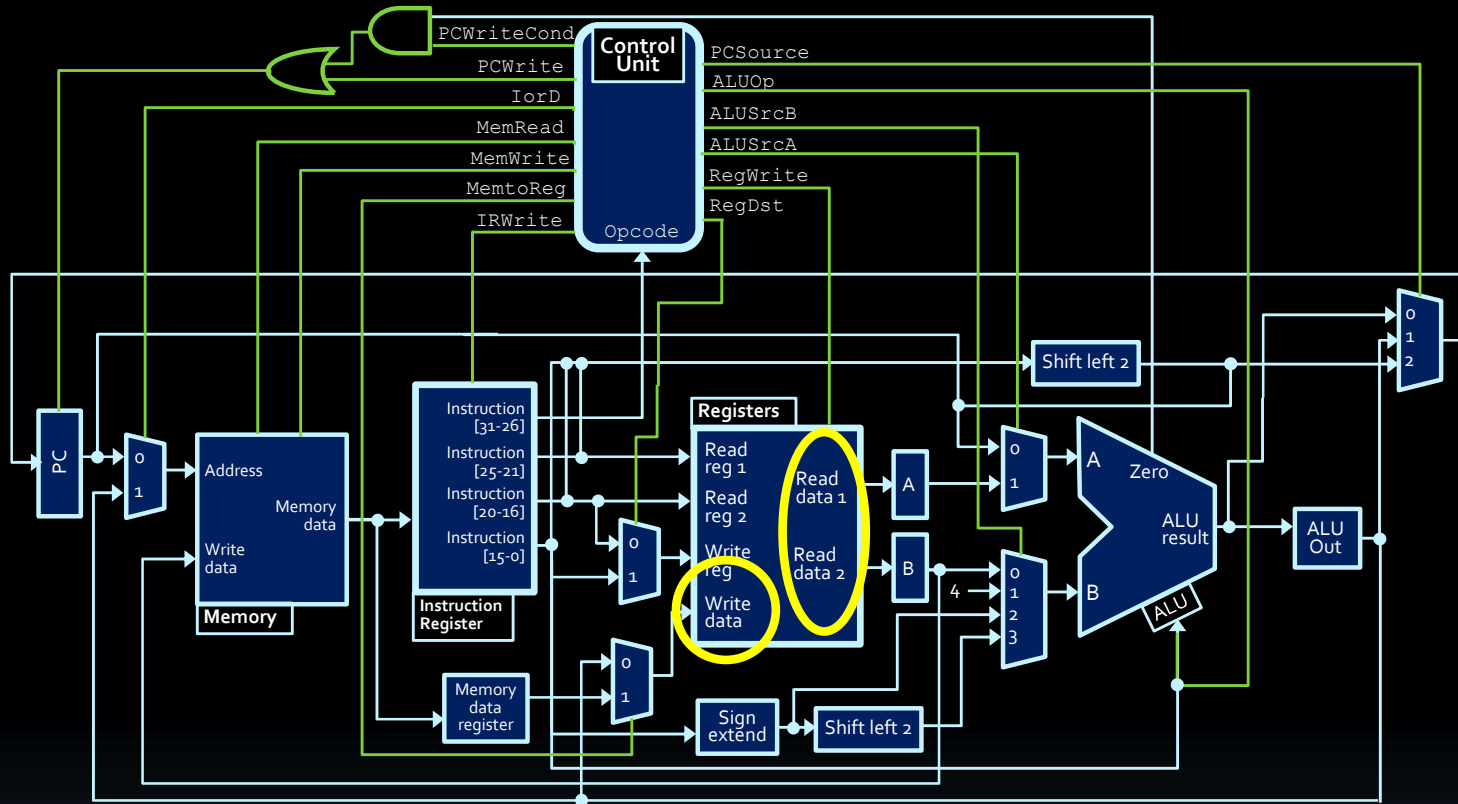


# Basic approach

1. Figure out the data source(s) and destination.
2. Determine the path of the data.
3. Deduce the signal values that cause this path:
  - a) Start with `Read` & `Write` signals (at most one can be high at a time).
  - b) Then, mux signals along the data path.
  - c) Non-essential signals get an `X` value.



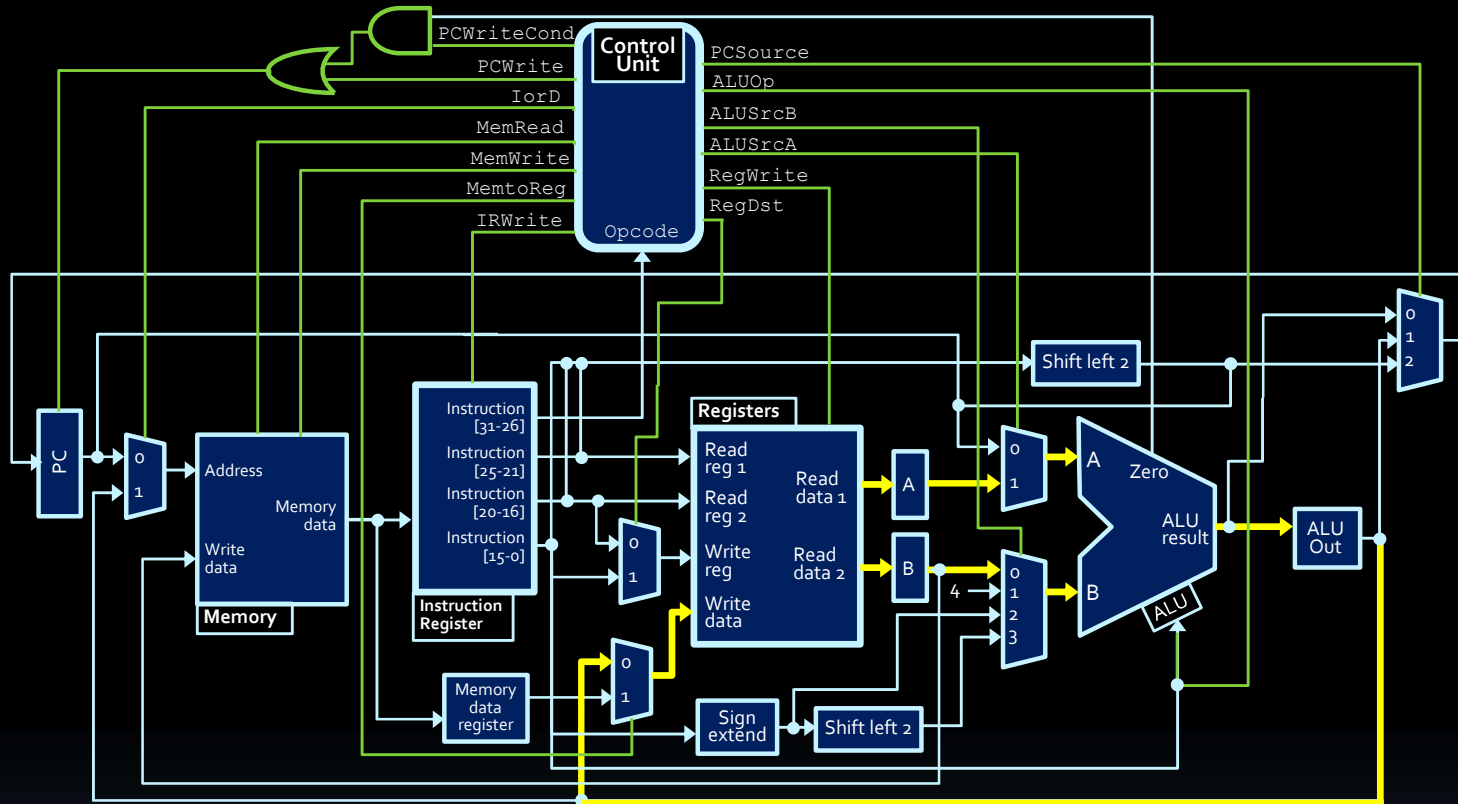
# Question #1 (cont'd)



- Step #1: Data source and destination
  - Data starts in register block.
  - Data goes to register block.



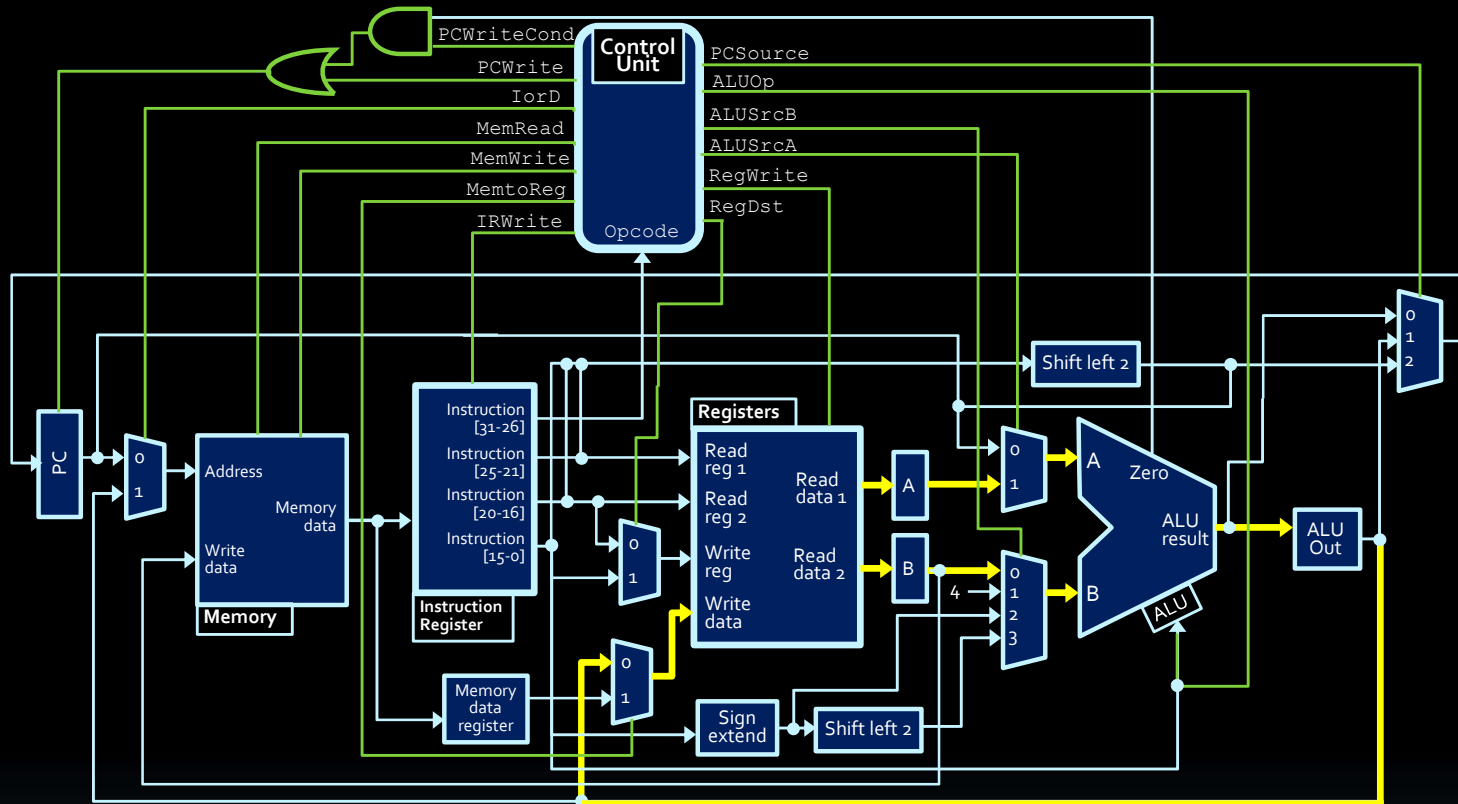
# Question #1 (cont'd)



- Step #2: Determine the path of the data
  - ▣ Data needs to go through the ALU before heading back into the register file.



# Question #1 (cont'd)



- Step #3a: Read & Write signals
  - Only RegWrite needs to be high.
  - PCWrite, PCWriteCond, MemRead, MemWrite, IRWrite would be low.



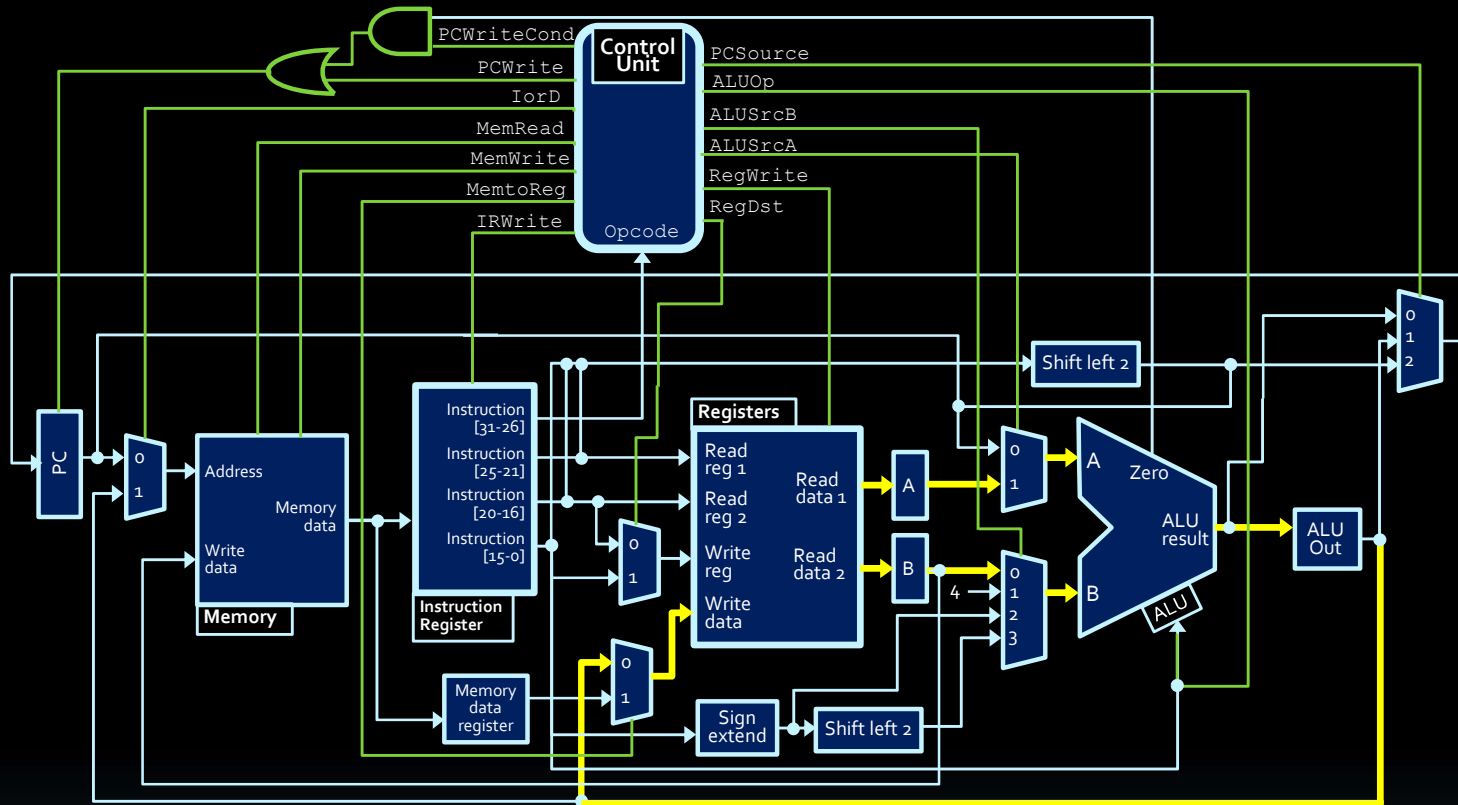


- Step #3b: Data path signals

- Muxes before ALU:  $ALUSrcA \rightarrow 1, ALUSrcB \rightarrow 00$ .
- $ALUOp \rightarrow 001$  (Add)
- Mux before registers:  $MemToReg \rightarrow 0$



# Question #1 (cont'd)



- Step #3c: Non-essential signals
  - No writing to PC: PCSource  $\rightarrow$  X.
  - No reading from memory: IorD  $\rightarrow$  X.

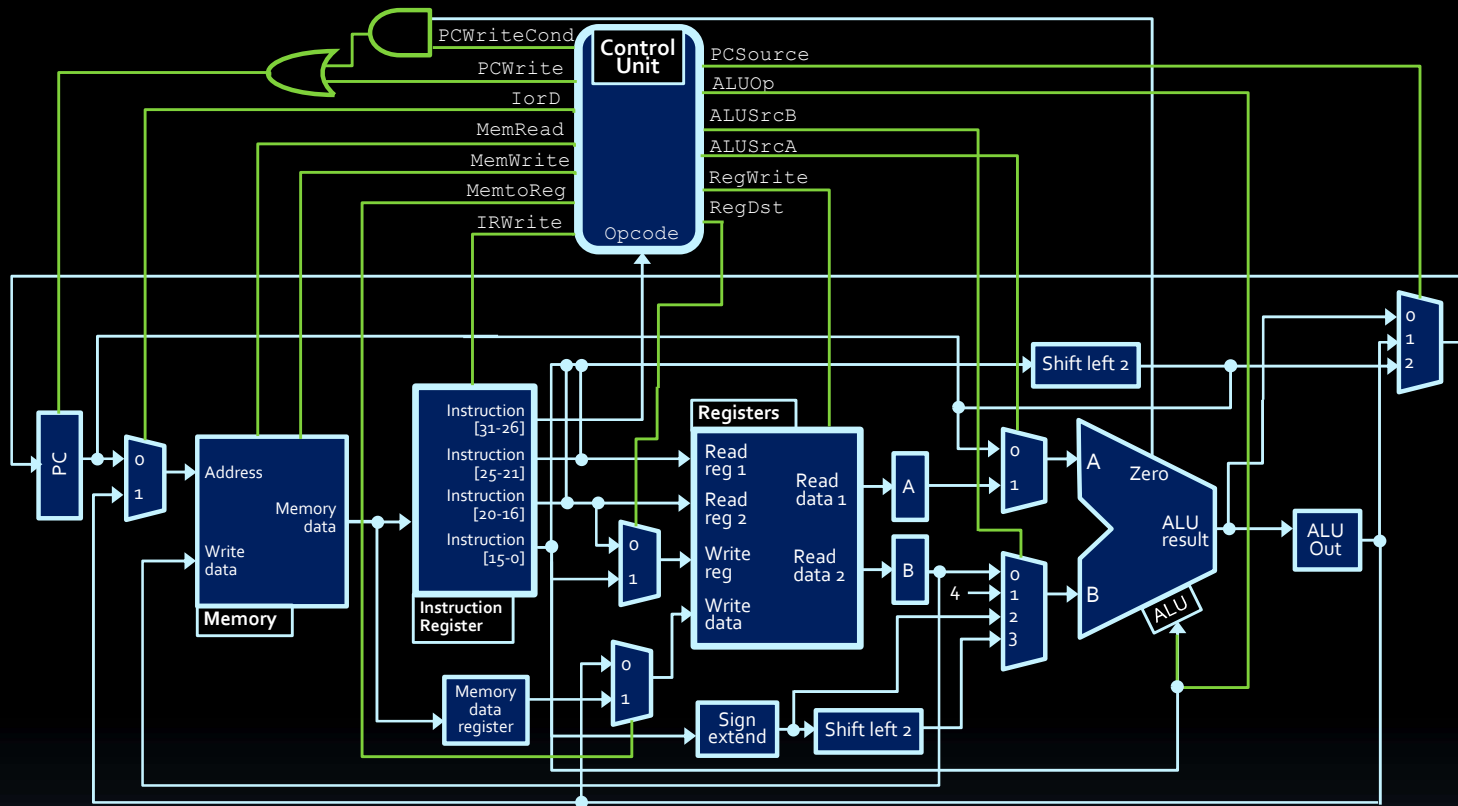


# Question #1 (cont'd)

- PCWrite = 0
  - PCWriteCond = 0
  - IorD = X
  - MemRead = 0
  - MemWrite = 0
  - MemToReg = 0
  - IRWrite = 0
  - PCSource = X
  - ALUOp = 001
  - ALUSrcA = 1
  - ALUSrcB = 00
  - RegWrite = 1
  - RegDst = 1
- Note: RegDst rule
    - ▣ high for 3-register operations
    - ▣ low for 2-register operations



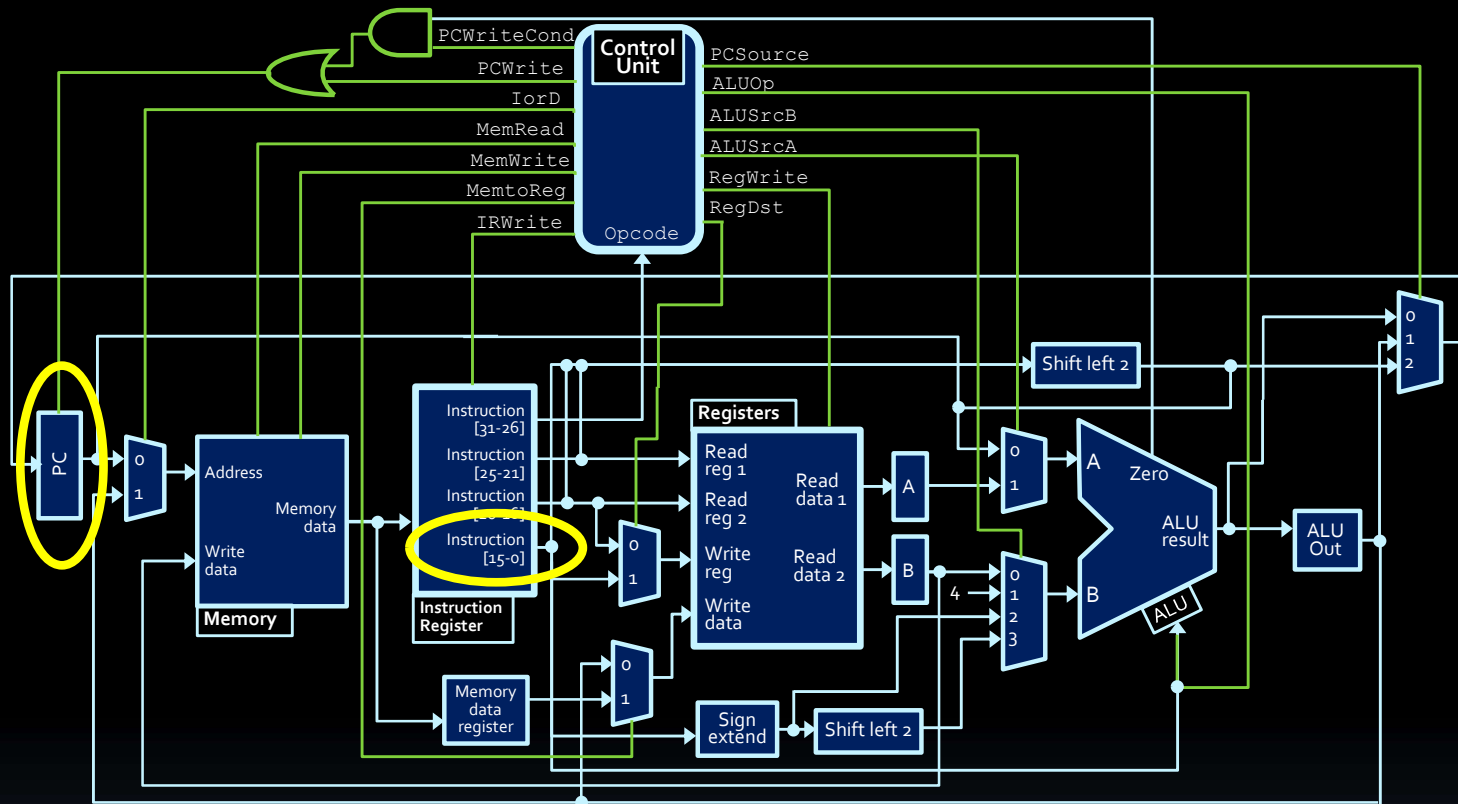
# Question #2



- Given the datapath above, what signals would the control unit turn on and off in order to add 100 to the program counter?



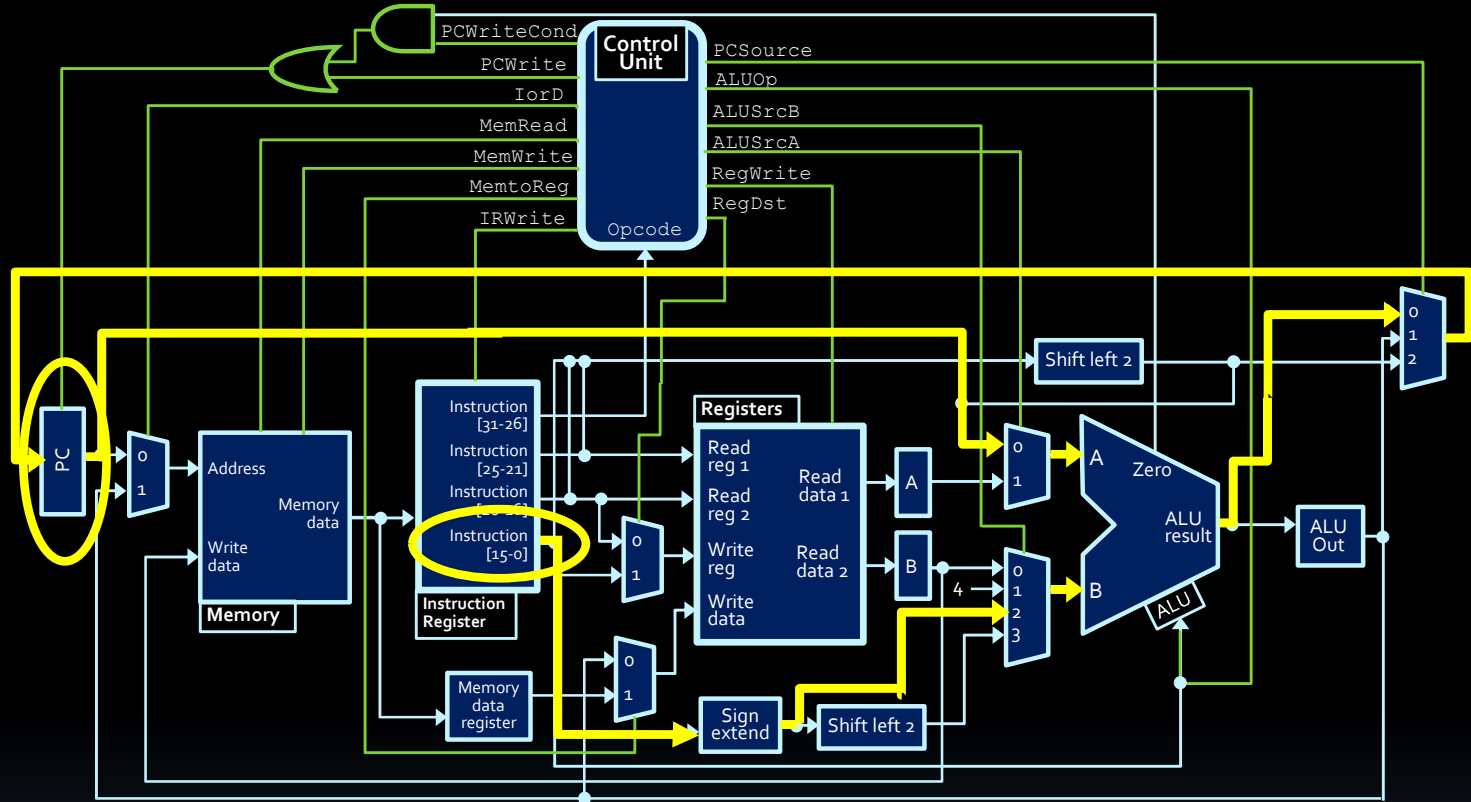
# Question #2



- Step #1: Source and destination.
  - Program counter is both source and destination.
  - Immediate value from instruction is other source.



# Question #2



- Step #2: Path between source and destination.



## Question #2 (cont'd)

- **Read / Write signals:**
  - PCWrite high, all others low.
    - PCWriteCond is X, when PCWrite is high.
- **Datapath signals:**
  - ALUSrcA  $\rightarrow$  0
  - ALUSrcB  $\rightarrow$  2 (100 is an immediate value; needs to come from the instruction)
  - PCSource  $\rightarrow$  0
- **Non-essential signals:**
  - IorD, MemToReg, RegDst

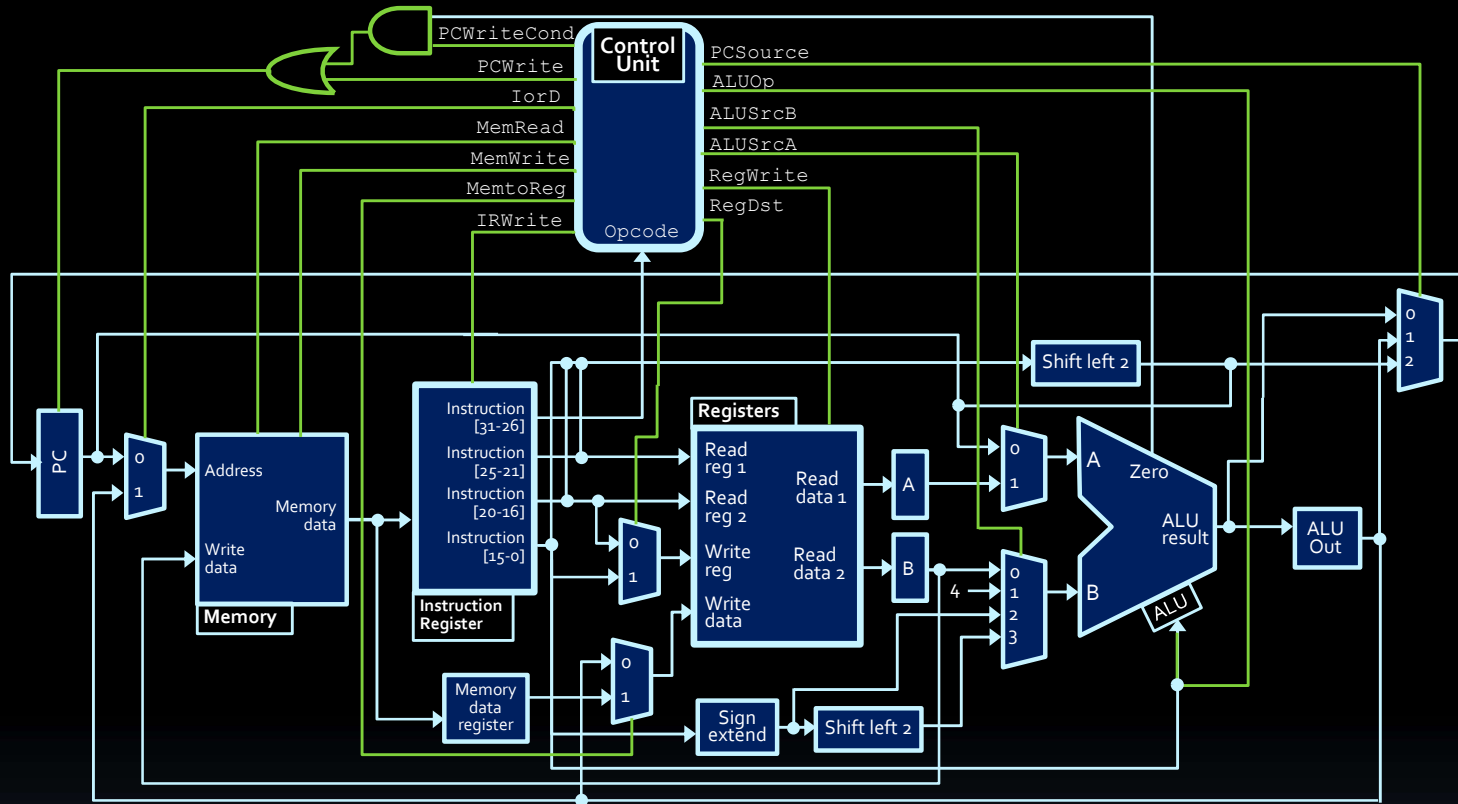


## Question #2 (cont'd)

- PCWrite = 1
- PCWriteCond = X
- IorD = X
- MemRead = 0
- MemWrite = 0
- MemToReg = X
- IRWrite = 0
- PCSource = 0
- ALUOp = 001
- ALUSrcA = 0
- ALUSrcB = 10
- RegWrite = 0
- RegDst = X



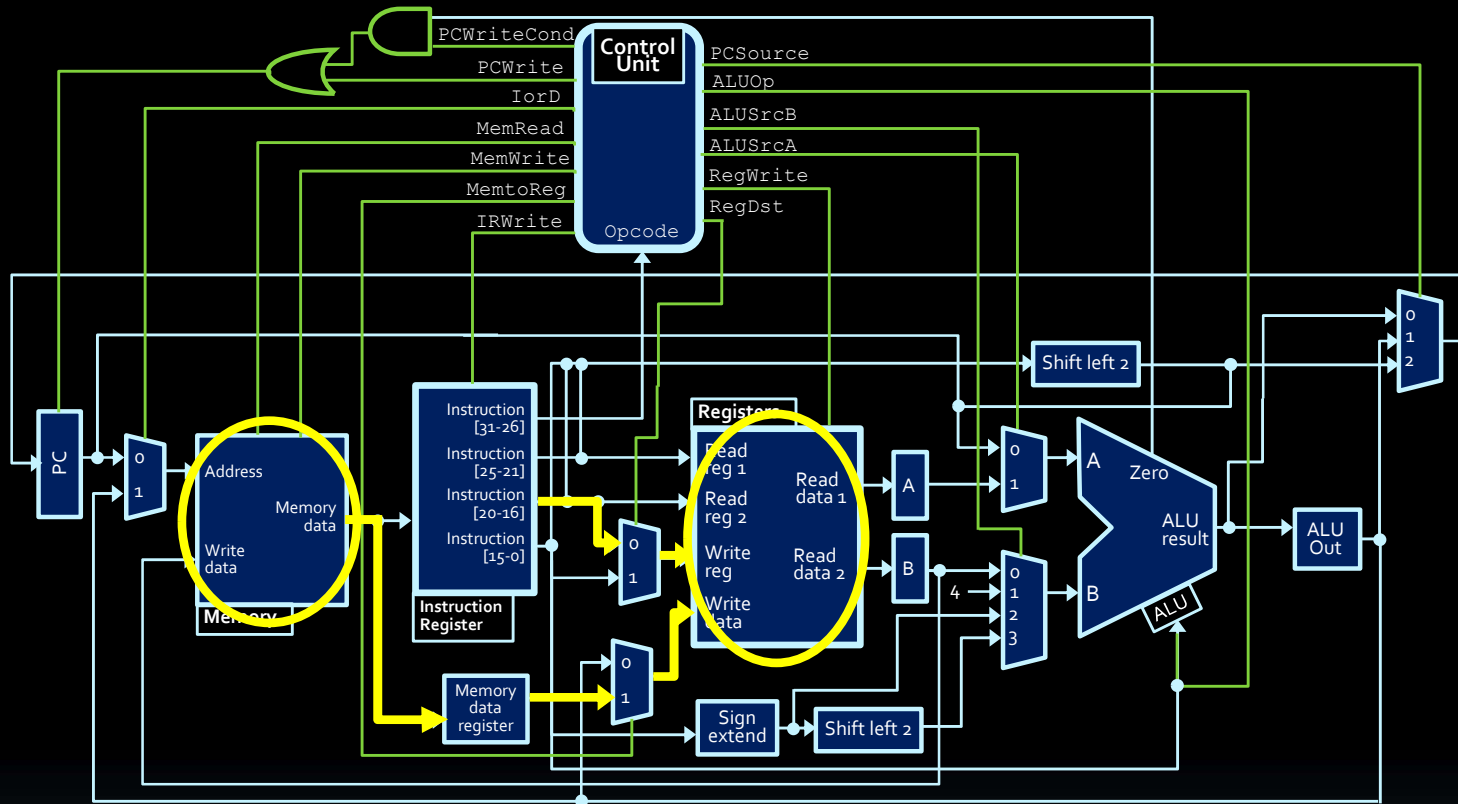
# Question #3



- Given the datapath above, what signals would the control unit turn on and off in order to load a memory value into  $\$t0$ ?



# Question #3



- Loading a memory value into  $\$t0$ 
  - Step #1: Determine source and destination.
  - Step #2: Path between source and destination.
- Note: This assumes that the address of this memory location has already been sent to the memory unit as part of a previous instruction.



## Question #3 (cont'd)

- **Read / Write signals:**
  - RegWrite and MemRead high, all others low.
- **Datapath signals:**
  - MemToReg  $\rightarrow$  1
  - RegDst  $\rightarrow$  0
- **Non-essential signals:**
  - IorD, PCSource, AluSrcA, AluSrcB



## Question #3 (cont'd)

- PCWrite = 0
- PCWriteCond = 0
- IorD = X
- MemRead = 1
- MemWrite = 0
- MemToReg = 1
- IRWrite = 0
- PCSrc = X
- ALUOp = XXX
- ALUSrcA = X
- ALUSrcB = XX
- RegWrite = 1
- RegDst = 0

Note: The highlighted signals will have values if you choose to extend the hold of the memory address for the duration of the load operation.



# Question #4

- What are the following assembly language instructions doing?

```
sub $t7, $t0, $t1
```



Subtract register `$t1` from `$t0` and placing the result into `$t7`

```
andi $t7, $t0, 15
```



Bitwise AND between register `$t0` and `15` (`1111`), with the result placed into register `$t7`

```
sra $t2, $t1, 2
```



Arithmetic shift of register `$t1` two bits to the right, with the result stored in `$t2`

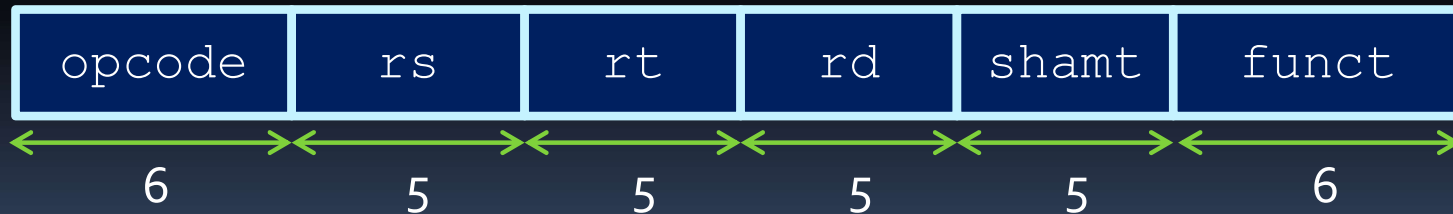


## Question #5

- How do you translate the following assembly language instruction into machine code?

```
add $t7, $t0, $t1
```

R-type instruction!





# Question #5

```
add $t7, $t0, $t1
```

## ■ Step #1: The opcode

- Arithmetic operations start with six 0's, and have the function identifier at the end.

```
000000 sssss ttttt ddddd xxxxx 100000
```

## ■ Step #2: The register values

- Remember that \$t0 does not translate to register 0
- The temporary registers start at register 8, so \$t0 → 8, \$t1 → 9 and \$t7 → 15

```
000000 01000 01001 01111 xxxxx 100000
```







# Week 10 lab

- What lab?
- Just the project today.



# The final destination

- Things to note for the project report:
  - Tell us what you learned.
    - Get up-close and personal ☺
  - Clarity.
- Sections are vital.
  - Introduction
    - Why this project?
  - Methods
    - What did you do (include figures)
  - Results
    - How did it go?
  - Discussion
    - Did it work?
    - What did you learn specifically?
    - What would you do different?
  - Conclusion
  - Appendix
    - code, schematics, etc.

