

A nearly correctly-rounded cube root

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This document describes the error analysis of the real cube root function `Cbrt` implemented in `numerics/cbrt.cpp`.

On some abridged root-finding methods

We start with a historical overview of a family of root-finding methods.

In [Fan91a], Lagny first presents the iterations

$$a \mapsto \frac{1}{2}a + \sqrt{\frac{1}{4}a^2 + \frac{b}{3a}}, \quad (1)$$

hereafter the *irrational method*, and

$$a \mapsto a + \frac{ab}{3a^3 + b}, \quad (2)$$

the *rational method*, for the computation of the cube root $\sqrt[3]{a^3 + b}$, mentioning the existence of similar methods for arbitrarily higher powers. In [Fan91b] the above methods are again given, with an outline of the general method for higher powers, and a mention of their applicability to finding roots of polynomials other than $z^p - r$.

That general method is given in detail in [Fan92, p. 19]. Modernizing the notation, the general rule is as follows for finding a root of the monic polynomial of degree $p \geq 2$

$$f(z) := z^p + c_1 z^{p-1} + \dots + c_{p-1} z + c_p =: z^p - R(z)$$

with an initial approximation a .

Separate the binomial expansion of $(x + \frac{1}{2}a)^p$ into alternating sums of degree p and $p - 1$ in z ,

$$S_1 := \sum_{\substack{k=0 \\ 2 \nmid k}}^p \binom{p}{k} x^{p-k} \left(\frac{1}{2}a\right)^k \text{ and } S_2 := \sum_{\substack{k=0 \\ 2 \mid k}}^p \binom{p}{k} x^{p-k} \left(\frac{1}{2}a\right)^k,$$

and consider the following polynomials, of degree p and $p - 1$ in x for almost all a :

$$E_p := S_1 - \frac{1}{2}R\left(x + \frac{1}{2}a\right) \text{ and } E_{p-1} := S_2 - \frac{1}{2}R\left(x + \frac{1}{2}a\right).$$

Let E_{n-1} be the remainder of the polynomial division¹ of E_{n+1} by E_n ; its degree is $n - 1$ for almost all a . The iteration is $a \mapsto x + \frac{1}{2}a$, where x is a root of E_2 for the irrational method, and the root of E_1 for the rational method. Its order is p .

¹While the rest of the method is a straightforward translation, this step bears some explanations; its description in [Fan92] is

De ces deux égalitez, ou prifes féparément, ou comparées enfemble felon la methode des problèmes plus que déterminez tirez en une valeur d' x rationnelle, ou fimplement d'un degré commode.

It is assumed that the reader is familiar with this “comparison according to the method of more-than-determined problems”. While the application of the root-finding method is described in painstaking detail in [Fan33], which outlines the treatment of overdetermined problems, it is perhaps this remark from [Fan97, p. 494] which lays it out most clearly:

Il n'y a rien de nouveau à remarquer fur les Problemes plus que déterminez du quatrième degré. La Regle générale est d'égaliser tout à zero, & de divifer la plus haute équation par la moins élevée, ou l'également élevée l'une par l'autre, continuellement jufques à ce que l'on trouve le refte ou le divifeur le plus fimple.

Modern calculus allows us to give a more straightforward expression for the rational method than was available to Lagny; the proof of the following equivalence will be given at the end of this section.

Proposition. *The iteration of Lagny’s rational method for a polynomial f of degree p is*

$$a \mapsto a + (p - 1) \frac{(1/f)^{(p-2)}(a)}{(1/f)^{(p-1)}(a)}. \quad (3)$$

□

Names

The iteration (3) is a special case of the *Algorithmen* (A_ω^λ) defined by Schröder for an arbitrary polynomial f in [Sch70], equation (69) and p. 350; specifically, it is (A_{p-1}^0). As seen in the proof of the proposition, it is also a special case of Householder’s equation (14) from [Hou70, p. 169], which generalizes it by substituting $\frac{f}{g}$ for f , and letting f be an arbitrary analytic function. The case $g \equiv 1$ is mentioned in theorem 4.4.2, and that expression is given explicitly in [SG01].

For $p = 2$ and f an arbitrary polynomial, (3) is Newton’s method, presented by Wallis in [Wal85, p. 338].

For $p = 3$ and f an arbitrary polynomial, it is Halley’s rational method, given in [Hal94, pp. 142–143] in an effort to generalize² Lagny’s (2). It is usually simply known as Halley’s method, as the irrational method—which likewise generalizes Lagny’s irrational method for $p = 3$ while retaining constant order as the degree changes—has comparatively fallen into obscurity; see [ST95].

Considering, as remarked by [Sch70, p. 334], that a method can often be generalized from arbitrary polynomials or rational functions to arbitrary analytic functions, we call the iteration (3)

- Newton’s method when $p = 2$, for arbitrary f ;
- Lagny’s rational method when $p > 2$ and f is a polynomial of degree p ;
- Halley’s (rational) method when $p = 3$ and f is not a polynomial of degree 3;
- the Lagny–Schröder method of order p otherwise.

We do not simply call this last case “Schröder’s method”, as it is only a special case of the methods defined in [Sch70], so that the expression would be ambiguous.

Note that we avoid the name “Householder’s method” which appears in [SG01] and ulterior works, as it is variably used to refer to either (3) or to a method from a different family, namely φ_{p+1} from [Hou70, p. 168], equation (7), taking $\Gamma_{p+1} \equiv 0$ in the resulting iteration; φ_3 is³ the iteration given in section 3.0.3 of [SG01]. As mentioned by Householder, both of those were described by Schröder a century prior anyway: Householder’s (7) is Schröder’s (18) from [Sch70, p. 327].

Bibliographic note

Our foray into the history of these methods was prompted by finding the “historical background” section of [ST95] while looking for a reference for Halley’s method: it is mentioned therein that this method, as applied to the cube root, is due to Lagny.

²Lagny’s method is general, in that an iteration is given for any polynomial, albeit one whose order changes with the degree. However, while he refers to its results—and even corrects a misprint therein—, Halley did not have access to a copy of [Fan92].

Has Regulas, cum nondum librum videram, ab amico communicatas habui

and it appears that said friend communicated only the formulæ for the cube and fifth root, as opposed to the general method and its proof, as Halley writes

[...] *D. de Lagny* [...] qui cum totus fere fit in eliciendis Potestatum purarum radicibus, præfertim Cubicâ, pauca tantum eaque perplexa nec fatis demonstrata de affectarum radicum extractione fubjungit.

or, about Lagny’s irrational method for the fifth root,

Author autem nullibi inveniendi methodum ejufve demonstrationem concedit, etiamfi maxime defiderari videatur [...].

Being unaware of this generality, Halley sets out to generalize (1) and (2) to arbitrary polynomials, and does so by keeping the order constant.

³We are grateful to Peter Barfuss for this observation.

Searching for Lagny's work led us to the historical note [Can61], wherein a note by the editors Terquem and Gerono reads

Naturellement, en mathématiques, séjour des propositions irréfragables, identiques en toute langue, en tout pays, ces rencontres ne peuvent manquer d'être assez fréquentes; nulle part les plagiats *effectifs* sont si rares, et les plagiats *apparents* si communs que dans la science exacte par excellence; mais les signaler est un devoir, un service rendu à l'histoire scientifique.

The editors then quote a letter by Prouhet, wherein he gives a reference to [Fan92].

Lagny's work proved far more extensive than we expected: besides the above root finding methods for arbitrary polynomials, it contains an error analysis, and even a discussion of the principles of performance analysis based on a decomposition in elementary operations on decimal digits.

We observed that the higher-order examples corresponded to the well-known higher order method attributed to Householder in [SGo1]. Looking for properties of these methods in [Hou70] so as to prove that observation, we found that they are attributed to Schröder therein. As mentioned in the translator's note to the English translation [SS93] of [Sch70] by Stewart,

A. S. Householder used to claim you could evaluate a paper on root finding by looking for a citation of Schröder's paper. If it was missing, the author had probably rediscovered something already known to Schröder.

It is quite possible that the irrational method could be expressed using Schröder's methods in one way or another, but while the result would probably be more convenient, it is unlikely to be something well-known, as irrational methods are far less popular nowadays.

Prouhet's letter in [Can61] ends with these words:

Tout cela est fort abrégé; mais qui nous délivrera des méthodes abrégées, qui n'en finissent pas?



Proof of the proposition

We now prove the above proposition, which, substituting the definition of Lagny's rational method, is that

$$x + \frac{1}{2}a = a + (p-1) \frac{(1/f)^{(p-2)}(a)}{(1/f)^{(p-1)}(a)} =: \psi(a)$$

if x is the root of E_1 .

Proof. Let $E_p = d_0x^p + \dots + d_p$, $E_{p-1} = e_0x^{p-1} + \dots + e_{p-1}$. As shown in [Hou70, pp. 52–54], the polynomial remainders E_k are given up to a constant factor by [Hou70, p. 19] equation (23), *i.e.*, for some α ,

$$\frac{E_k}{\alpha_k} = \det \begin{pmatrix} (E_p)_{p-1-k} \\ (E_{p-1})_{p-k} \end{pmatrix},$$

where the expression on the right-hand side is the *bigradient* defined in [Hou68] (3.2)

or [Hou70, p. 19] (20),

$$\frac{E_k}{\alpha_k} = \det \begin{pmatrix} d_0 & d_1 & d_2 & \cdots & d_{2(p-k)-3} & x^{p-k-2}E_p \\ & d_0 & d_1 & \cdots & d_{2(p-k)-4} & x^{p-k-3}E_p \\ & & \ddots & & \vdots & \\ \mathbf{0} & & & d_0 & d_1 & \cdots & d_{p-k-1} & x^0 E_p \\ & & & & e_0 & \cdots & e_{p-k-2} & x^0 E_{p-1} \\ & & & & \ddots & & \vdots & \\ & & e_0 & \cdots & e_{2(p-k)-4} & x^{p-k-2}E_p \\ & e_0 & e_1 & \cdots & e_{2(p-k)-4} & x^{p-k-2}E_p \\ e_0 & e_1 & e_2 & \cdots & e_{2(p-k)-3} & x^{p-k-1}E_p \end{pmatrix} =: \det \mathbf{E}_k,$$

where $d_n := 0$ for $n > p$, and $e_n := 0$ for $n > p-1$.

In particular, for $k = 1$,

$$\mathbf{E}_1 = \begin{pmatrix} d_0 & d_1 & d_2 & \cdots & d_{p-3} & d_{p-2} & d_{p-1} & d_p & & \mathbf{0} & x^{p-3}E_p \\ & d_0 & d_1 & \cdots & d_{p-4} & d_{p-3} & d_{p-2} & d_{p-1} & d_p & & x^{p-4}E_p \\ & & \ddots & & & & & & & \ddots & \vdots \\ & & & d_0 & d_1 & d_2 & & \cdots & & d_{p-2} & x^0 E_p \\ & & & & e_0 & e_1 & & \cdots & & e_{p-3} & x^0 E_{p-1} \\ & & & & \ddots & & & & & \ddots & \vdots \\ & & e_0 & \cdots & e_{p-5} & e_{p-4} & e_{p-3} & e_{p-2} & e_{p-1} & & x^{p-5}E_{p-1} \\ & e_0 & e_1 & \cdots & e_{p-4} & e_{p-3} & e_{p-2} & e_{p-1} & & & x^{p-4}E_{p-1} \\ e_0 & e_1 & e_2 & \cdots & e_{p-3} & e_{p-2} & e_{p-1} & & & \mathbf{0} & x^{p-3}E_{p-1} \end{pmatrix}.$$

Observe that, since the value of x used in the rational method is the root of E_1 , for that value of x , $\det \mathbf{E}_1 = 0$, i.e., \mathbf{E}_1 is singular.

Lemma (Left as an exercise to the reviewer). *The matrix \mathbf{E}_1 is singular if and only if $\mathcal{C}(x + \frac{1}{2}a)$ is singular, where*

$$\mathcal{C}(\Psi) := \begin{pmatrix} \Psi - a & c_0 & & \mathbf{0} \\ -1 & c_1 & c_0 & \\ 0 & c_2 & & \ddots \\ \vdots & \vdots & \ddots & c_0 \\ 0 & c_{p-1} & \cdots & c_2 & c_1 \end{pmatrix}$$

and $c_0 := 1$.

Proof. Observe that:

- since $\det \mathbf{E}_1$ is a polynomial of degree 1, all terms divisible by x^2 must cancel out in the Laplace expansion of that determinant on the last column, the determinant is equal to

$$\pm \delta_1 x E_p \mp \delta_2 E_p \pm \delta_3 E_{p-1} \mp \delta_4 x E_{p-1},$$

where the δ_i are determinants of real matrices;

- by the same reasoning, only the linear and constant terms of the polynomials remain in the above expression, which simplifies to

$$\pm \delta_1 d_p x \mp \delta_2 (d_{p-1} x + d_p) \pm \delta_3 (e_{p-2} x + e_{p-1}) \mp \delta_4 e_{p-1} x;$$

- $E_p - E_{p-1} = S_1 - S_2$, which, by Lagny's *theoreme fondamental* [Fan92, p. 17], is $(x - \frac{1}{2}a)^p$.

The proof is a calculation. \square

The proposition follows from the lemma and theorem 4.4.2 from [Hou70, p. 169]: $\psi(a)$ is Householder's (14) with $g \equiv 1$; for that value of g , theorem 4.4.2 states that (14) is the solution of (12) from the same page, which is $\det \mathcal{C}(\psi(a)) = 0$. By the lemma, for the value of x in Lagny's rational method, $x + \frac{1}{2}a$ solves that equation. \square

Computing a real cube root

We now turn to the computation in `numerics/cbrt.cpp`.

Overview

The general approach to compute the cube root of $y > 0$ is the same as the one described in [KB01]:

1. integer arithmetic is used to get an initial quick approximation q of $\sqrt[3]{y}$;
2. a root finding method is used to improve that to an approximation ξ with a third of the precision;
3. ξ is rounded to a third of the precision, resulting in the rounded approximation x whose cube x^3 can be computed exactly;
4. a single high order iteration of a root finding method is used to get the final result.

Notation

We define the fractional part as $\text{frac } a := a - \lfloor a \rfloor \in [0, 1[$, regardless of the sign of a .

The quantities $p \in \mathbb{N}$ (precision in bits) and $\text{bias} \in \mathbb{N}$ are defined as in IEEE 754-2008.

We use capital Latin letters fixed-point numbers involved in the computation, and $A > 0$ for the normal floating-point number $a > 0$ reinterpreted as a binary fixed-point number with $p - 1$ bits after the binary point⁴,

$$\begin{aligned} A &:= \text{bias} + \lfloor \log_2 a \rfloor + \text{frac}(2^{-\lfloor \log_2 a \rfloor} a) \\ &= \text{bias} + \lfloor \log_2 a \rfloor + 2^{-\lfloor \log_2 a \rfloor} a - 1, \end{aligned}$$

and *vice versa*,

$$a := 2^{\lfloor A \rfloor - \text{bias}} (1 + \text{frac } A).$$

This corresponds to [KB01]'s $B + K + F$.

For both fixed- and floating-point numbers, given $\alpha \in \mathbb{R}$, we write $\llbracket \alpha \rrbracket$ for the nearest representable number (rounding ties to even). For fixed-point numbers, we write $\llbracket \alpha \rrbracket_0$ for directed rounding towards 0 to the fixed-point precision (as in division implemented with integer division). We write the unit roundoff $u := 2^{-p}$, and, after [Higham2002], $\gamma_n := \frac{nu}{1-nu}$.

To quote [Tre97], “If rounding errors vanished, 95% of numerical analysis would remain”. While we keep track of rounding errors throughout, they are of very little importance until the last step; when it is convenient to solely study the truncation error, we work with ideal quantities affected with a prime, which correspond to their primeless counterparts by removal of all intervening roundings.

Except in the section on rescaling, the input y and all intervening floating-point numbers are taken to be normal; the rescaling performed to avoid overflows also avoids subnormals.

1 Quick approximation

The quick approximation q is computed using fixed-point arithmetic as

$$Q := C + \left\lfloor \frac{Y}{3} \right\rfloor_0,$$

⁴The implementation uses integers (obtained by multiplying the fixed-point numbers by 2^{p-1}). For consistency with [KB01] we work with fixed-point numbers here. Since we do not multiply fixed point numbers together, the expressions are unchanged.

where the fixed-point constant C is defined as⁵

$$C := \left\lceil \frac{2 \text{bias} - \Gamma}{3} \right\rceil$$

for some $\Gamma \in \mathbb{R}$.

Let $\varepsilon := \frac{q}{\sqrt[3]{y}} - 1$, so that $\sqrt[3]{y}(1 + \varepsilon) = q$; the relative error of q as an approximation of $\sqrt[3]{y}$ is $|\varepsilon|$. Considering Y , Q , q , and ε as functions of y , we have

$$\begin{aligned} Y(8y) &= Y(y) + 3, \\ Q(8y) &= Q(y) + 1, \\ q(8y) &= 2q(y), \\ \varepsilon(8y) &= \varepsilon(y), \end{aligned}$$

so that the properties of ε need only be studied on some interval of the form $[\eta, 8\eta[$.

Pick $\eta := 2^{\lfloor \Gamma \rfloor}$, and $y \in [\eta, 8\eta[= [2^{\lfloor \Gamma \rfloor}, 2^{\lfloor \Gamma \rfloor + 3}[$, so that $\log_2 y \in [\lfloor \Gamma \rfloor, \lfloor \Gamma \rfloor + 3[$. Let $k := \lfloor \log_2 y \rfloor - \lfloor \Gamma \rfloor$; note that $k \in \{0, 1, 2\}$. Let $f := \text{frac}(2^{-\lfloor \log_2 y \rfloor} y) \in [0, 1[$. Up to at most 3 half-units in the last place from rounding (2 from the directed rounding of the division by three and 1 from the definition of C), we have

$$\begin{aligned} Q &\approx Q' := \text{bias} + \frac{\lfloor \log_2 y \rfloor}{3} + \frac{\text{frac}(2^{-\lfloor \log_2 y \rfloor} y) - \Gamma}{3}, \\ &= \text{bias} + \frac{\lfloor \Gamma \rfloor + k}{3} + \frac{f - \Gamma}{3}, \\ &= \text{bias} + \frac{k + f - \text{frac } \Gamma}{3}. \end{aligned}$$

Since $k \in [0, 2]$, the numerator $k + f - \text{frac } \Gamma$ lies in $] -1, 3[$. Further, it is negative only if $k = 0$, so that

$$\begin{aligned} \lfloor Q' \rfloor &= \begin{cases} \text{bias} - 1 & \text{if } k = 0 \text{ and } \text{frac } \Gamma > \text{frac}(2^{-\lfloor \Gamma \rfloor} y), \\ \text{bias} & \text{otherwise,} \end{cases} \text{ and} \\ \text{frac } Q' &= \begin{cases} 1 + \frac{f - \text{frac } \Gamma}{3} & \text{if } k = 0 \text{ and } \text{frac } \Gamma > f, \\ \frac{k + f - \text{frac } \Gamma}{3} & \text{otherwise.} \end{cases} \end{aligned}$$

Accordingly, for the quick approximation q , we have, again up to at most 3 half-units in the last place,

$$q \approx q' = \begin{cases} 1 + \frac{f - \text{frac } \Gamma}{3} & \text{if } k = 0 \text{ and } \text{frac } \Gamma > f, \\ 1 + \frac{k + f - \text{frac } \Gamma}{3} & \text{otherwise,} \end{cases}$$

With $\sqrt[3]{y} = 2^{\frac{\lfloor \Gamma \rfloor + k}{3}} \sqrt[3]{1 + f}$, we can define

$$\varepsilon' := \frac{q'}{\sqrt[3]{y}} - 1,$$

which we can express piecewise as a function of f and k . This gives us a bound on the relative error,

$$|\varepsilon| \leq |\varepsilon'| (1 + 3u).$$

The values $\Gamma = 0.1009678$ and $\varepsilon < 3.2\%$ from [KBo1] may be recovered by choosing Γ minimizing the maximum of $|\varepsilon'|$ over $y \in [\eta, 8\eta[$, or equivalently,

$$\Gamma_{\text{Kahan}} := \operatorname{argmin}_{\Gamma \in \mathbb{R}} \max_{y \in [\eta, 8\eta[} |\varepsilon'| = \operatorname{argmin}_{\Gamma \in \mathbb{R}} \max_{(f, k)} |\varepsilon'|$$

where the maximum is taken over $(f, k) \in [0, \text{frac } \Gamma[\times \{0\} \cup [0, 1[\times \{1, 2\}$,

$$= \operatorname{argmin}_{\Gamma \in \mathbb{R}} \max_{(f, k) \in \mathcal{E} \cup \mathcal{L}} |\varepsilon'|,$$

⁵Note that there is a typo in the corresponding expression $C := (B - 0.1009678)/3$ in [KBo1]; a factor of 2 is missing on the bias term.

where $\mathcal{E} := \{(\frac{\Gamma}{2}, 0)\} \cup \{(0, k) \mid k \in \{0, 1, 2\}\}$ is the set of the endpoints of the intervals whereon q' is piecewise affine, and $\mathcal{L} := \{(\frac{k - \frac{\Gamma}{2}}{2}, k) \mid k \in \{1, 2\}\}$ are the local extrema.

The values are more precisely⁶

$$\Gamma_{\text{Kahan}} \approx 0.10096\,78121\,55802\,88786\,36993\,42643\,55358\,06489\,88235\,75289$$

with

$$\max_y |\varepsilon'| \approx 0.03155\,46327\,73624\,80606\,11789\,73328\,17135\,58940\,02093\,40816,$$

leading to $C_{\text{Kahan}} = {}_{16}2\text{A9F}\,7625\,3119\,\text{D328} \cdot 2^{-52}$ for IEEE 754-2008 binary64. However, as we will see in the next section, this value does not optimize the final error, so it is not the one that we use.

2 Getting to a third of the precision

We use a single iteration of Lagny's rational method to compute ξ ,

$$\xi := \left\| q - \frac{\left\| \left(\left\| \left(\left\| q^2 \right\| q \right) - y \right) q \right\| \right\|}{\left\| 2 \left\| \left\| q^2 \right\| q \right\| + y \right\|} \right\|.$$

Note that the subtraction in the numerator is exact by Sterbenz's lemma.

Let $\Delta := \frac{\xi}{\sqrt[3]{y}} - 1$ and

$$\xi' = q' - \frac{(q'^3 - y)q'}{2q'^3 + y},$$

so that, up to rounding errors,

$$\Delta \approx \Delta' := \frac{\xi'}{\sqrt[3]{y}} - 1.$$

With $q' = \sqrt[3]{y}(1 + \varepsilon')$, we can express Δ' using the transformation of the relative error error by one step of Lagny's rational method on the cube root,

$$\Delta' = \frac{2\varepsilon'^3 + \varepsilon'^4}{3 + 6\varepsilon' + 6\varepsilon'^2 + 2\varepsilon'^3}.$$

If q' is computed using $\Gamma = \Gamma_{\text{Kahan}}$, we get

$$\begin{aligned} \max_y |\Delta'| &\approx 0.00002196, \\ \log_2 \max_y |\Delta'| &\approx -15.47. \end{aligned}$$

However, Γ_{Kahan} , which minimizes $\max_y |\varepsilon|$, does not minimize $\max_y |\Delta'|$. This is because while Δ' is monotonic as a function of ε' , it is not odd: positive errors are reduced more than negative errors are, so that the minimum is attained for a different value of Γ . Specifically, we have

$$\begin{aligned} \Gamma_L &:= \operatorname{argmin}_{\Gamma \in \mathbb{R}} \max_y |\Delta'| \\ &\approx 0.09918\,74615\,29855\,99525\,66149\,20761\,31234\,34720\,23067\,92759 \end{aligned}$$

with

$$\max_y |\varepsilon'| \approx 0.03103\,20521\,29929\,93577\,08166\,75859\,02139\,33719\,41389\,93269,$$

but

$$\max_y |\Delta'| \approx 0.00002\,08686\,35536\,39593\,48770\,92008\,39844\,10254\,14831\,61229.$$

The corresponding fixed-point constant is $C_L := {}_{16}2\text{A9F}\,7893\,782\text{D}\,\text{A1CE} \cdot 2^{-52}$ for binary64.

⁶These may be computed formally, but the expressions are unwieldy.

TODO(egg): Δ' accounts for half of the excess above correct rounding in the final bound; consider using either a higher order iteration or Lagny's irrational formula. Also consider optimizing the constants in the method, as in [Can18]; in the rational method of order 3 there are none to optimize.

Rounding error analysis. It is fairly clear that Δ' dominates the rounding error in $\Delta \approx \Delta'$; for the sake of completeness we quantify this.

Since we have a cancellation in the numerator, a little bit of care is needed to bound those errors. As mentioned above, q approximates q' to a relative error of at most $3u < \gamma_3$. The sum in the denominator

$$d := \llbracket 2\llbracket \llbracket q^2 \rrbracket q \rrbracket + y \rrbracket$$

has positive terms, so its relative error with respect to $d' := 2q'^3 + y$ is readily bounded,

$$\frac{d}{d'} - 1 < \gamma_{3 \cdot 3 + 3} = \gamma_{12}.$$

The cancelling difference $b := \llbracket \llbracket q^2 \rrbracket q \rrbracket - y$ differs from $b' := q'^3 - y$ by at most

$$\delta := q'^3 \gamma_{3 \cdot 3 + 2} = q'^3 \gamma_{11},$$

and the numerator $\llbracket bq \rrbracket$ from $b'q'$ by at most

$$((b' + \delta)q'(1 + \gamma_3))(1 + \gamma) - b'q' = (1 + \gamma_4)\delta q' + \gamma_4 b'q'.$$

We can bound the relative error of the correction term,

$$\begin{aligned} \left| \frac{\llbracket \llbracket bq \rrbracket \rrbracket}{\frac{b'q'}{d'}} - 1 \right| &< \frac{\frac{b'q' + (1 + \gamma_4)\delta q' + \gamma_4 b'q'}{d'(1 - \gamma_{12})}}{\frac{b'q'}{d'}} - 1 = \frac{1 + \frac{(1 + \gamma_4)\delta}{b'} + \gamma_4}{(1 - \gamma_{12})} - 1 \\ &= \frac{(1 + \gamma_4)\delta}{(1 - \gamma_{12})b'} + \frac{\gamma_4 + \gamma_{12}}{(1 - \gamma_{12})} \end{aligned}$$

3 Rounded approximation

The number x is obtained from ξ by zeroing all but the most significant $\lfloor \frac{p}{3} \rfloor$ bits of its significand. The resulting relative error

$$\left| \frac{x}{\xi} - 1 \right|$$

is greatest when the zeroed bits are all 1 and the remaining bits (except for the leading 1) are all 0; this is the case when the significand of ξ is $1 + 2^{-\lfloor \frac{p}{3} \rfloor + 1} - 2^{1-p}$, in which case that of x is 1.

The relative error arising from $\xi \mapsto x$ is thus at most

$$1 - \frac{1}{1 + 2^{-\lfloor \frac{p}{3} \rfloor + 1} - 2^{1-p}} < 2^{-\lfloor \frac{p}{3} \rfloor + 1},$$

2^{-16} in binary64.

4 High order iteration

We use one iteration of the Lagny–Schröder method of order 6:

$$r := \left\llbracket x - \frac{\llbracket \llbracket x(x^3 - y) \rrbracket \llbracket \llbracket \llbracket 5x^3 \rrbracket + \llbracket 17y \rrbracket x^3 \rrbracket + \llbracket 5y^2 \rrbracket \rrbracket}{\llbracket \llbracket \llbracket 7x^3 \rrbracket + \llbracket 42y \rrbracket \llbracket x^6 \rrbracket \rrbracket + \llbracket \llbracket 30x^3 \rrbracket + 2y \rrbracket \llbracket y^2 \rrbracket \rrbracket} \right\rrbracket,$$

Where x^3 is exact thanks to the trailing 0s of x , $\llbracket x^6 \rrbracket$ is correctly-rounded because it is computed as the square of x^3 , and $x^3 - y$ is exact by Sterbenz's lemma.

TODO(egg): consider order 5; the truncation error is dominated by the rounding error here.

References

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