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## The Experiment Report of *Machine Learning*

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**SCHOOL:** SCHOOL OF SOFTWARE ENGINEERING

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# Recommender System Based on Matrix Decomposition

**Abstract**—This report introduces my work in lab5, where I built a recommending system based on matrix factorization and optimized it using the strategy of stochastic gradient descent.

## I. INTRODUCTION

THE recommender system has been developed as an independent discipline for nearly twenty years but not yet has a precise definition. Several strategies have been proposed in the way to constructing a more accurate and more useful model, such as Content-based Algorithm, Item-based Collaborative Filtering Algorithm and Matrix Factorization Algorithm. In this lab, we will work on a Matrix Factorization model, which put the observed samples in a sparse matrix and try to decompose it through introducing a new parameter  $K$ , which tries to identify the potential features of each user and each item. The main goals of the lab are completely generating a movie recommender system and cultivate engineering ability under a small dataset.

## II. METHODS AND THEORY

Before constructing a recommender system using matrix factorization, there are some concepts we need to introduce. A matrix  $R \in \mathbb{R}^{m \times n}$  is a sparse rating matrix for  $m$  users and  $n$  items (movies in this case). An observed samples  $r_{u,i}$  (means the rate of user  $u$  towards item (movie)  $i$ ) will be represented as a specific value in  $R$ . In the matrix factorization method we use, we will try to decompose  $R$  into two matrices  $P \in \mathbb{R}^{m \times k}$  and  $Q \in \mathbb{R}^{k \times n}$  where  $k$  denotes potential features for each user and movie.

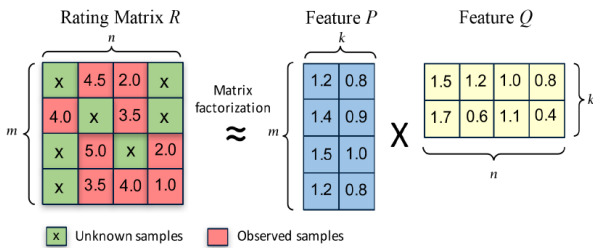


Fig. 1. An illustration of matrix factorization ( $m=4$ ,  $n=4$ ,  $k=2$ ).

After confirming the basic skeleton of our model, the next step is to determine how we evaluate the goodness of it and the way we optimize it. A naive loss function is squared error loss:

$$L(r_{u,i}, \hat{r}_{u,i}) = (r_{u,i} - \hat{r}_{u,i})^2 \quad (1)$$

Besides, there are two ways to minimize the loss on our

lab guidance alternate least squares optimization (ALS) and stochastic gradient descent method (SGD). I chose SGD as my strategy to optimize, because it is a simple and scalable to large-scale datasets way compared to ALS.

In stochastic gradient descent, we define the loss function as below:

$$L = \sum_{u,i \in \Omega} (r_{u,i} - p_u^T q_i)^2 + \lambda_p \|p_u\|^2 + \lambda_q \|q_i\|^2 \quad (2)$$

$r_{u,i}$  denotes the actual rating of user  $u$  for item  $i$ .  $\Omega$  denotes the set of observed samples from rating matrix  $R$ .  $\lambda_p$  and  $\lambda_q$  are regularization parameters to avoid overfitting. In order to minimize the loss and update our matrices  $P$  and  $Q$ , we randomly pick an observed sample  $r_{u,i}$  in the sparse matrix  $R$  and there are two other important formulas which we use to calculate gradients:

$$\frac{\partial L}{\partial p_u} = E_{u,i}(-q_i) + \lambda_p p_u \quad (3)$$

$$\frac{\partial L}{\partial q_i} = E_{u,i}(-p_u) + \lambda_q q_i \quad (4)$$

In the equations above,  $p_u$  denotes the  $u$ th user's column vector while  $q_i$  denotes the  $i$ th movie's column vector. They both have shape  $k \times 1$ .

The following step is to update the feature matrices  $P$  and  $Q$  with learning rate  $\alpha$  making use of the gradients we computed:

$$p_u = p_u + \alpha \frac{\partial L}{\partial p_u} \quad (5)$$

$$q_i = q_i + \alpha \frac{\partial L}{\partial q_i} \quad (6)$$

We will repeat the steps above until the loss converge.

## III. EXPERIMENTS

### A. Dataset

In this lab we Utilize the 'MovieLens-100k dataset' which Consists 10,000 comments from 943 users out of 1682 movies. At least, each user comment 20 videos. Users and movies are numbered consecutively from number 1 respectively. The data is sorted randomly.

### B. Implementation

Firstly, I decided to use `u1.base` as my train data and `u1.test` as my test data, then I read the data set to generate my matrix  $R$  and fill 0 for null values. According to the principle that  $k \ll \min(m, n)$ , I finally chose  $k = 50$ ,  $\lambda_p = 0.5$ ,  $\lambda_q = 0.5\alpha = 0.01$  as my input hyperparameters. To

perform stochastic gradient descent, I randomly selected an observed sample  $r_{u,i}$  from observed set, then calculated the gradient  $\frac{\partial l}{\partial p_u}$ ,  $\frac{\partial l}{\partial q_i}$  to the loss function. Next, I updated the feature matrices P and Q with learning rate  $\alpha$  and gradient using formula (5) (6). I repeated the above processes until convergence.

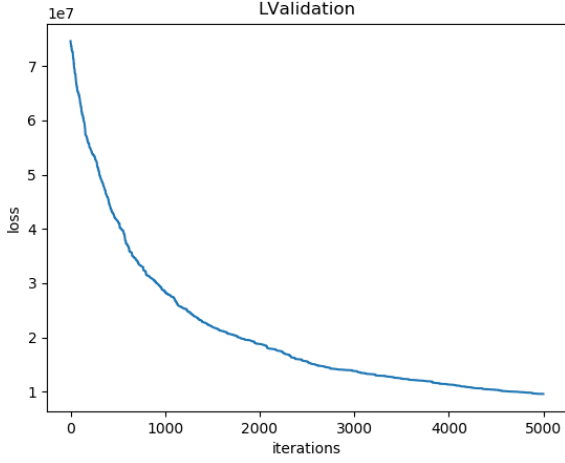


Fig. 2. The change of Lvalidation.

#### IV. CONCLUSION

To summarize, I feel this lab very inspiring and beneficial for me. Instead of reading and deriving the theory and formulas in books and slices, it offers us a practical way to practise machine learning.