

## BCT 2410: Seminar Presentations

### Final Report Guidelines

*This is what you should include in your final report for seminar presentations:*

- A cover page containing the following:
  - The title; your topic
  - Your name and registration number
  - Course code and course name
  - Date of submission (06.12.2021)
- An abstract that provides a summary of your report (150 to 250 words)
- A clear introduction of your topic and the objectives
- The objectives should be listed i) objective 1..... ii) objective 2
- The body section details your content : this should be well organized, see below

#### **1 Introduction**

##### **1.1 Robotics**

##### **1.1.1 Socially Assistive Robots**

- A conclusion section
- Include a final section “Reflections”: in this section reflect on your work, and on the materials you examined and indicate the lessons you have learned

*Very Important: Take note of this:*

- The document should be well formatted, and easy to read (select a good font and size)
- Spell check and grammar check your text
- All content in your document should be well referenced: For references and citations adhere to the following guidelines:
  - In the references section, provide complete information (follow standards: see APA or the IEEE Citation Style Guide. These can easily be found at various locations on the WWW)
  - In the text, include precise references to relevant sources. Basically, it should be clear to the reader what the source is of every piece of text:
    - a literal quotation (enclosed by quotation marks, the text should make clear what the purpose of the quote is);
    - a rephrasing of text from one or more sources (provide references)
    - your own contribution ; your arguments based on the research you have done
    - All the figures /tables should be well labelled and referenced

*Some examples of referencing following APA:*

Prior work in human-robot interaction has shown that gaze can help build effective interactions between humans and robots (Admoni and Scassellati, 2017; Broz, Lehmann, Nakano, and Mutlu, 2012; Ruhland et al., 2015).

Admoni et al. (2016) demonstrated how to achieve effective interactions with robots using nonverbal in various domains, for example, robot tutors, robot therapists, and robot coaches.

Huang and Mutlu (2013) developed a toolkit to generate useful social behavior for robots to achieve positive outcomes in an educational setting.

*The document should be 5 to 10 pages including a final page with a listing of references*

*Submit your document to [eunice.njeri@jkuat.ac.ke](mailto:eunice.njeri@jkuat.ac.ke)*