

Comparative Architectures

Source

- IB Architecture / Computer Design
- IB Compiler Construction
- II Advanced Computer Architecture / Comparative Architectures
- Computer architecture: a quantitative approach
 - Hennessy, J.L. & Patterson, D.A (2011)

Analogue and digital

- What are the advantages and disadvantages of analogue computers over their digital counterparts?

	analogue (oscilloscope)	digital computer
feature	continuous values / physical data	discrete values / binary system
speed	slow	fast
memory capacity	low or limited	large
reliable / accurate	no (checksum)	yes
usage, arch	complicated	easy
result	voltage signals	computer screen
energy	current -- power-hungry	lower power
reprogram	wirable	reconfigurable
communication	radio signal (speed)	bus, wire (1/10 speed of light)

Relationship: Analog = Quantize [0,255] saturated by Max \implies Digital

Digital computer system comes from analog and the conversion has a cost.

Digital one has repeatable complex components, Inductor.

Modern Compiler

Key takeaway from translator (interpreter) shown in Compiler Lecture,

- Divide from single into two stages
 - Compile (inspect)
 - Interpret (compute)

- Divide from single into two stacks (memories)

- instruction stack / IM

PUSH, POP, MK_PAIR

- data value stack / DM

- Separation of the two memories (Instruction and Data)
 - allows for simultaneous access
 - an instruction can be read while a data memory is read or written in the same cycle.
 - Motivation for pipeline and multi-issue *superscalar* (Instruction level parallelism)
 - more difficult with a unified cache/memory.
 - instruction memory is read-only and has less circuitry.
 - has no dirty bits, no write back, etc
 - the IM and DM can have different associativity

Flynn's Taxonomy

Based on parallelism on instruction and data streams, the first four kinds listed below

SISD

- A simple processor

MISD

- Used for redundancy
 - Flight control system, error-detection

SIMD

- Vector processing
 - Vector registers each hold several data items
 - Vector operations (add, multiple)
- Energy-efficient, data level parallelism

MIMD

- Multicore, standard general purpose CPUs

Extra: SIMT

- each thread has *separate state* (registers and memory)
 - e.g. stack pointer (sp)
- data level parallelism

Processor	T0	T1	T2	T3	Note
instruction	---S---	Fetch	Decode	---S---	Shared
memory	---S---	Shared	Memory	---S---	Shared
thread states	Regs 0	Regs 1	Regs 2	Regs 3	
- each contain 32 floats vector Regs 12 Regs 13 Regs 14 Regs 15	hide latency when stall
processing	ALU0	ALU31	single 32-value vector operation

Architectures comparison

Source: Classifying Instruction Set Architectures (Textbook **A.2**)

Architecture	Accumulator	Stack	Register File
operands: from memory and	acc + 3 = 4	top of the stack	rs1, rs2 (disjoint), rd orthogonal needs less
instruction density	shortest less mem space	concise (short instr)	longer
von Neumann bottleneck (Mem bus)	worse for mem (RTT) mem bus 2x CPU ⇔ 2x frequency	store imm in stack (near) If stack is full, memory	store in cache (nearer) fast mem access ⇔ higher frequency
caching	hard to predict	predictable	in the middle
power consumption	less few memory accesses	less for control few memory accesses	most multi-issue
multi-issue	0	0	Yes
performance	Calculator ENIAC	razer printer, compiler(JVM) Hard for queue, list, swap	modern CPU IC best

Addressing and cache

	virtual addressing	physical addressing
index / hit time	fast, check within offset permission check TLB later	slow, wait translation south bridge hw (address space)

	virtual addressing	physical addressing
address after context switch	same virtual for different physical addresses	different physical addresses
prefetchable	Yes	no (update rather than cache)
aliasing (different virtual)	yes (coherence problems)	No
others	homonyms problem (different physical if not flush)	network package (last bit) not write mergeable (two core write)

Depending on the index and tag addressing mode:

- VIPT, VIVT, PIPT, PIVT cache