



## 5. 投影向量( Projection )



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This is also an optimization problem. Are you familiar with this equation?1.

$$x^* = (A^T A)^{-1} A^T Y$$

### 1. Projection a Vector $b$ onto a line

$p$  is the vector from the origin to the closest points;  $a$  is the line direction;

So,

$$p = \hat{x}a, e = b - p$$

which is perpendicular to  $p, a$ .

Thus,

$$\begin{aligned} a * (b - \hat{x}a) &= 0 \\ \Rightarrow a * b &= \hat{x} * a * a \\ \Rightarrow \hat{x} &= \frac{a * b}{a * a} \\ \Rightarrow p &= \frac{a^T b}{a^T a} a = \frac{a * b}{\|a\|^2} a \end{aligned}$$

### 2. Projection onto a Subspace

Suppose  $V$  is a subspace of  $R^m$  with basis  $a_1, \dots, a_n$ . The projection of  $b$  onto  $V$  is the vector in  $V$  closest to  $b$ . This projection vector  $p$ , will be by definition a linear combination of the basis vectors of  $V$ :



If  $A$  is a matrix with column vectors  $a_1, \dots, a_n$  and  $\hat{x}$  is a vector with components  $\hat{x}_1, \dots, \hat{x}_n$ , the  $p = A\hat{x}$ . This error vector, the vector that points from  $p$  to  $b$ , will be  $e = b - p = b - A\hat{x}$ . This error vector will be perpendicular to the subspace  $V$ , which is equivalent to being perpendicular to the basis vectors  $a_1, \dots, a_n$ . Stated mathematically, this is

$$\begin{aligned} a_1^T(b - A\hat{x}) &= 0, \\ a_n^T(b - A\hat{x}) &= 0 \end{aligned}$$

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We can write all of the above in matrix form:

$$A^T(b - A\hat{x}) = 0$$

This in turn can be written as

$$A^T A \hat{x} = A^T b$$

If  $A^T A$  is invertible we can solve for  $\hat{x}$  to get:

$$\hat{x} = (A^T A)^{-1} A^T b$$

Now, the projection vector  $p$  is the vector  $A\hat{x}$ , so

$$p = A(A^T A)^{-1} A^T b$$

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In general, to calculate the projection of any vector onto the space  $W$  we multiply the vector by the projection matrix

$$P = A(A^T A)^{-1} A^T$$

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