# SIMD in JavaScript via C++ and Emscripten

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#### **Abstract**

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#### 1. Introduction

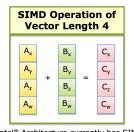
We'll explore the use of Mozilla's Emscripten to compile C++ programs, that has use of SIMD intrinsics or gcc style vector code, into JavaScript. This was recently made possible by the SIMD.JS primitives introduced in JavaScript engine prototypes for Chromium and Firefox as well as extensions to the Emscripten compiler. Emscripten will correctly translate a subset of available C++ SIMD x86 intrinsics into corresponding operations defined in SIMD.JS. The JavaScript benchmarks associated with the SIMD.JS primitives were converted to C++ by hand, and then automatically converted back into JavaScript using the Emscripten compiler.

## 2. SIMD.JS

SIMD is short for Single Instruction, Multiple Data. It refers to CPU instruction level data parallelism. Most modern CPUs have a significant portion of their available instructions dedicated to operating on data in parallel. Typically, those instructions will perform the same operation on elements in short vectors, e.g. vectors of length 4, 8, or 16. Use of these instructions leads to increased performance, because more data processing is achieved with fewer instructions executed, and fewer instructions also means power savings, which is of outmost importance on mobile battery powered devices. Figure 1 shows how four scalar additions are combined into a single operation.

JavaScript is quickly emerging as one of the most popular languages among software developers. It was originally used for simple web page scripting for creating interactive web pages. Around 2008, very efficient and high performance JavaScript engines emerged, e.g. Firefox's TraceMonkey and Chrome's V8 engines. Since then, JavaScript has become a viable language for things beyond just basic web page interactivity, as witnessed by it's use in

Scalar Operation  $\begin{vmatrix} A_x & + & B_x & = & C_x \\ A_y & + & B_y & = & C_y \\ A_z & + & B_z & = & C_z \\ A_w & + & B_w & = & C_w \end{vmatrix}$ 



Intel® Architecture currently has SIMD operations of vector length 4, 8, 16

Figure 1. Replacing four scalar additions with one SIMD addition

large web based applications, such as office applications; e-mail, document processing, etc. Also, large games, which were previously standalone, natively compiled programs, have been ported to JavaScript to run within the browser environment. More recently, JavaScript has been adopted as a server side scripting language (node.js), and lately, JavaScript has found it's way to the mobil platform as a language that offers better portability between the different mobile platforms without sacrificing performance and features. For example, access to platform sensors (location, accelerometers, etc) are accessible from JavaScript via W3C APIs.

Even with the past 7 years of JavaScript performance advances, the desire for better performing JavaScript engines has not lessened, quite the contrary. It's a spiral that keeps on going; better performance leads to more uses, more uses require better performance. Specifically, software that use data parallelism to achieve adequate performance have, so far, been restricted to natively compiled languages, such as C++, because such languages offer ways of utilizing the SIMD instructions available in modern CPUs. JavaScript has only one number type, Number, which is an IEEE-754 floating point number, and JavaScript offers no abstraction primitives for writing algorithms utilizing data paralellism, so it's imperative that this shortcoming is dealt with, such that the next leap in JavaScript performance is made possible. This is what the SIMD.JS proposal addresses.

SIMD.JS is an emerging standard developed collaboratively by Intel, ARM, Mozilla, Google, and Microsoft. It provides low level data types and operations that map well onto the available SIMD instructions of the underlying hardware. Currently, the defined data types and operations are a representative and useful overlap between SIMD types and operations available in most modern CPUs.

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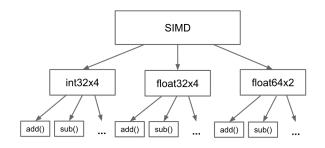


Figure 2. SIMD.JS object hierarchy

```
// function average(data) {
// var sum = SIMD.float32x4.splat(0.0);
// for (var i = 0, l = data.length; i < l; i = i+4) {
// sum = SIMD.float32x4.add(
// sum, SIMD.float32x4.load(data, i));
// var total = sum.x + sum.y + sum.z + sum.w;
// return total/data.length;
// return total/data.length;</pre>
```

Figure 3. SIMD JavaScript code for finding the average of an array of numbers

The SIMD.JS proposal is structured as an object hierarchy, with SIMD being the top level global object. The immediate properties of the SIMD object reflect the data types; int32x4, float32x4, and float64x2. The operations are methods declared as properties on the data type properties as outlined in Figure 2, which shows a portion of the object hierarchy.

We've modelled the semantics of the SIMD types and operations as a polyfill ¡REF¿. This allows programmers to experiment without using a JavaScript engine that natively supports SIMD.JS. The polyfill also serves as documentation for the semantics and interfaces. It will also reflect the current state of the proposal. The proposal is under active development and changes are likely to happen as the proposal is being refined and moves forward through the approval process.

As an example use case, Figure 3 shows the SIMD JavaScript code for computing the average of an array of floating point numbers. The numbers are held in a Float32Array typed array; data. The benefit of using SIMD operations, for computing the average, is that four numbers can be added in one operation, thereby reducing the number of iterations by a factor of 4, and achieving an equivalent speedup.

The optimizing Just-In-Time (JIT) compiler in our Chrome/V8 SIMD enabled prototype is able to produce the code in Figure 4 for the body of the loop. The code shows how the compiler is able to utilize 128-bit SIMD registers (xmm) to hold the value of sum and to use the addps instruction for adding 4 single precision numbers in one instruction. The details for this code snippet are as follows:

line 1-2: Check the loop index, i, against the upper bound and exit the loop if upper bound is encountered. eax holds the loop index and edx holds the upper bound.

line 3-4: Check to enable the JavaScript engine to abort the execution, if the loop has been running for too long. It will prevent a user program from hanging the browser.

line 5-11: Bounds check for the SIMD\_float32x4\_load operation. eax holds the index and ecx holds the upper bound.

line 12: Load the 4 32-bit float values. edi holds the base address of the data. The reason the index is multiplied by 2 and not

```
1 371 cmp eax, edx
2 373 jnl 440 (270629B8)
3 379 cmp esp,[0x645e9c]
4 385 jc 445 (270629BD)
5 391 mov esi,eax
6 393 shl esi.1
7 396 add esi,0x10
8 399 mov ebx,ecx
9 401 shl ebx,1
10 404 cmp esi.ebx
11 406 ja 499 (270629F3)
12 412 movups xmm2, [edi+eax*2]
13 416 movaps xmm3, xmm1
14 419 addps xmm3,xmm2
15 422 mov ebx, eax
16 424 add ebx,0x8
17 427 jo 504 (270629F8)
18 433 movaps xmm1,xmm3
19 436 mov eax, ebx
20 438 jmp 371 (27062973)
```

Figure 4. JIT compiler generated code for the for loop in the average function

4 is the fact that V8 represents integers in bits 1-31, so the value in eax is already holding the value of the index variable times 2.

line 13-14: Add the four 32-bit float values.

line 15-17: increment the loop index by 4. Since the integer representation used by V8 is done in bits 1-31 the actual value added is 8. The overflow checks is there to ensure that the result can still be represented in 31 bits, if not the representation is switched to a boxed floating point number.

line 18: Move the result of the SIMD add operation, to the xmm1 register, which holds the value of sum.

line 19-20: Move the new loop index value to it's proper register and jump back to the top of the loop.

For more details on how the JIT compilers operate see ¡REF<sub>i</sub>.

#### 2.1 The Future of SIMD.JS

The proposal has been presented to TC39, the JavaScript language standard committee, and was unanimously approved for stage 1 in 2014. Stage 1 is the proposal stage. It indicates that the need has been justified, and an outline for a solution has been accepted. It does not mean that this is the final proposal.

The focus, so far, has been on identifying types and operations that can be effectively implemented on all relevant CPU architectures. We realize that CPUs have destinct features that are useful and it will make sense to expose such features to the JavaScript programmer. This will most likely be done via architecture specific extensions to the SIMD object, e.g. SIMD.x86.\*

SIMD.JS is currently being refined and prepared for the next stages of approval, and we expect this to be part of the EcmaScript 7 standard (ES7). EcmaScript 5 is the current JavaScript standard. EcmaScript 6 is slated for a mid-2015 release. ES6 is a major overhaul of the JavaScript language and a substantial set of new features were added, as reflected by the size of the language specification document. The ES5 specification document is roughly 300 pages, whereas the ES6 specification is roughly double that. Most browsers have already implemented most of the ES6 features.

#### 3. Emscripten

Emscripten is a compiler that compiles C/C++ programs into JavaScript. It is based on the clang/LLVM compiler infrastructure ¡REF¿. The compiler is the brainchild of Alon Zakai of Mozilla.

As an example of how it works, we'll look at the generated JavaScript code resulting from compilign a simple C function.

```
// float averageScalar(float *a, uint32_t length) {
   float sum = 0.0f;
   for (uint32_t j = 0, 1 = length; j < 1; j = j + 4) {
      sum = sum + (*(a++));
   }
   return sum/length;
   }
}</pre>
```

Figure 5. Scalar C code for the average function

```
// function _averageScalar($a, $length) {
    a = a \mid 0;
    $length = $length | 0;
3
    var $a$addr$06 = 0, $add = 0.0, $j$05 = 0,
        sum 01csa = 0.0, sum 04 = 0.0, sp = 0;
.5
6
    sp = STACKTOP;
    if (($length | 0) == 0)
7
      \sum_{0.05}
8
    else {
10
      $a$addr$06 = $a;
11
      j$05 = 0;
      sum 04 = 0.0;
12
      while (1) {
13
14
        $add = $sum$04 + +HEAPF32[$a$addr$06 >> 2];
        j$05 = j$05 + 4 | 0;
15
        if (($j$05 >>> 0 < $length >>> 0)) {
16
          $sum$0$1cssa = $add;
17
          break:
18
19
        } else {
20
         a^{0} = a^{0} + 4 \mid 0:
21
         sum = add;
22
      }
23
24
2.5
    STACKTOP = sp;
    return +($sum$0$lcssa / +($length >>> 0));
26
```

**Figure 6.** JavaScript code generated by Emscripten for the averageScalar function

We'll again use a function that computes the average of float numbers. Figure 5 shows the input C program.

The Emscripten compiler command is similar to the clang compiler command, and takes most of the same options. The following command will generate optimized JavaScript code shown in Figure 6:

```
$ emcc -02 -g average-scalar.c
```

This example shows how Emscripten manages to map a staticly typed language (C) with pointers to a dynamically typed language without pointers (JavaScript).

Memory is modelled as overlayed typed arrays. In this example when the pointer \*a is used to fetch from memory the corresponding JavaScript code is +HEAPF32[\$a\$addr\$06 >> 2] (line 14). HEAPF32 is a global JavaScript typed array declared as follows:

```
var buffer = new ArrayBuffer(TOTAL_MEMORY);
HEAP8 = new Int8Array(buffer);
HEAP16 = new Int16Array(buffer);
HEAP32 = new Int32Array(buffer);
HEAPU8 = new Uint8Array(buffer);
HEAPU16 = new Uint16Array(buffer);
HEAPU32 = new Uint32Array(buffer);
HEAPF32 = new Float32Array(buffer);
HEAPF64 = new Float64Array(buffer);
```

All of these typed arrays are views on the same array buffer, so they all access the same physical memory. Notice that the index expression '\$a\$addr\$06 >> 2' is shifted right by 2. This is be-

Figure 7. SIMD C code with intrinsics for the average function

cause \$a\$addr\$06 is a byte address, and elements in the HEAPF32 are 4 bytes each.

To enable the JavaScript JIT compilers to generate efficient code two type coercision tricks are used.

For integers and pointers the 'expr | 0' is used to guarantee that the type of the resulting expression is a 32-bit integer. JavaScript semantics of the the bitwise | expression dictate that the resulting expression is a 32-bit integer. A side effect of pointers being 32-bit integers is that compiled C/C++ programs are restricted to a 32-bit address space.

For floating point numbers, the unary '+' operator is applied, because JavaScript semantics dictate that the resulting expression is a floating point number.

Emscripten has been successfully used to compiler very large C/C++ code bases (+100K lines of code). For example both Epic's and Unity's game engines have been ported, using Emscripten ¡REF¿. Game engines are one example of software that will have optional implementations of performance critical portions of the code implemented using SIMD features. Since, JavaScript hasn't had a way of utilizing these powerful low level SIMD features of the CPU, Emscripten has not been able to compile these highly tuned implementations of the performance critical sections of the code. However, with the introduction of SIMD.JS, Emscripten will now be able to take full advantage of those. The next section covers how this is accomplished.

#### 4. Compiling C++ with SIMD intrinsics

Figure 7 shows a typical SIMD implementation of the average function in C, using x86 SIMD intrinsics.

The \_m128 type holds 4 32-bit float numbers. The \_mm\_\*\_ps function calls are the SIMD intrinsics, which operates on single precision \_m128 values. For example, the \_mm\_add\_ps intrinsic maps to the x86 addps instruction, which adds 4 32-bit float numbers in one operation. This allows the iteration count to be reduced by a factor of 4 resulting in an equivalent speedup.

The resulting JavaScript produced by Emscripten is shown in Figure 8.

The JavaScript code in Figure 8 might appear extensive at first look, however, it is very similar to the handwritten version of the function from Figure 3. The while loop starting at line 15 corresponds to the for loop from the C program. Implementing a for loop as a while loop takes a bit more code. The important thing to notice here is the use of the SIMD\_float32x4\_add and SIMD\_float32x4\_load SIMD.JS operations. The use of '.' instead of '.' is because Emscripten have created single identifier versions for all the SIMD.JS primitives.

It's important to note that use of CPU specific intrinsics makes the C version of the code target specific, i.e. it will only execute on x86 CPUs, whereas the resulting JavaScript code will execute on all architectures supported by the underlying SIMD enabled JavaScript engine.

```
// function _averageIntrin($a, $length) {
  2
                 a = a \mid 0;
                 $length = $length | 0;
                 var $add$i = SIMD_float32x4(0, 0, 0, 0),
  5
                                 $j$09 = 0,
                                 \sum_{sum x 4 0 slcssa} = SIMD_float 32x 4(0, 0, 0, 0),
  6
                                 \sum_{0,0} \sum_{0,0} SIMD_{10} = 
                                sp = 0;
  8
                 sp = STACKTOP;
  9
10
                 if (($length | 0) == 0)
                         $sumx4$0$1cssa = SIMD_float32x4_splat(Math_fround(0));
11
12
                 else {
                        5599 = 0:
13
                         $sumx4$010 = SIMD_float32x4_splat(Math_fround(0));
14
15
                         while (1) {
16
                                     $add$i =
                                            SIMD_float32x4_add(
17
18
                                                    $sumx4$010,
19
20
                                     $i$09 = $i$09 + 4 | 0;
                                     if (($j$09 >>> 0 < $length >>> 0)) {
21
22
                                            $sumx4$0$lcssa = $add$i;
23
                                            break:
24
                                           else $sumx4$010 = $add$i;
25
26
                 STACKTOP = sp;
27
28
                 return +((+$sumx4$0$lcssa.w + (+$sumx4$0$lcssa.z +
29
                                         (+$sumx4$0$lcssa.x + +$sumx4$0$lcssa.y))) /
                                        +($length >>> 0));
30
31 }
```

Figure 8. Emscripten generated SIMD JavaScript code for the averageIntrin function

```
1 typedef float floatx4 __attribute__ ((vector_size(16)));
2 float averageVectorSize(float *a, uint32_t length) {
3    floatx4 sumx4 = {0.0f, 0.0f, 0.0f, 0.0f};
4    floatx4 *ax4 = (floatx4 *)a;
5    for (uint32_t j = 0, 1 = length; j < 1; j = j + 4) {
6        sumx4 = sumx4 + *(ax4++);
7    }
8    return (sumx4[0] + sumx4[1] +
9        sumx4[2] + sumx4[3])/length;
10 }</pre>
```

Figure 9. SIMD C code with vector\_size for the average function

Use of non target specific SIMD code in C is possible via the gcc vector\_size attribute. Emscripten also supports compiling such code. A non target specific version of the average function is shown in Figure 9. The generated JavaScript code is virtually identical to the code resulting from the C code using intrinsics. If possible, developers should be encouraged to write their SIMD code using this more universal syntax.

#### 5. Benchmarks

We've created a set of benchmark kernels. The kernels are written in both C++ and JavaScript. Each kernel will have both a scalar implementation and a SIMD implementation.

The C++ SIMD implementation is done using x86 intrinsics. The C++ kernels are compiled with both the C++ clang compiler and with the Emscripten compiler. This gives us a basis for comparing SIMD/Scalar speedups for both C++ and JavaScript as well as C++/JavaScript performance differences. For the JavaScript execution we've used our two SIMD enabled JavaScript engines; V8 and SpiderMonkey.

The benchmarks are written such that each kernel operation is executed as many times as it takes for it to run in about a second. This guarantees that the optimizing JavaScript JIT compilers kick in, which is essential for optimimal performance.

The benchmark kernels we've collected performance data for are:

- AverageFloat32x4: Average 10,000 32-bit float number. This
  the kernel for the example used throughout the previous examples.
- Mandelbrot: Compute how many iterations it takes for z(i+1) = z(i)\*\*2 + c to diverge for seed point c = (0.01, 0.01). Divergence is determined by  $z^**2 > 4$ . This seed point never diverges, so the loop always runs up to the maximum of iterations allowed. The maximum number of iterations for this kernel is set to 100. The scalar version of the kernel will compute the iteration count of the scalar version of the SIMD version will compute the iteration count for four seedpoints. As an example of how all the benchmark kernels are structured we've shown the handwritten JavaScript and C++ version of this kernel in Figure 11 and Figure 10.
  - MatrixMultiplication: Multiply two 4x4 matrices. For each element in the resulting 4x4 matrix, 4 scalar multiplications and 3 scalar additions are required. The SIMD version will rearrange the source data, using a shuffle operation, and compute an entire row in the result matrix with 4 SIMD multiplies and 3 SIMD additions.
  - VertexTransform: Multiply a 4x4 matrix with a 4 element vector. This is a common CPU side operation for creating projection matrices for webGL shaders. Typically, it's used to compute a transformation for a point in 3D space, e.g. rotation around an axis. For each element in the resulting 4 element vector, 4 scalar multiplies and 3 scalar additions must be computed. The SIMD version will compute all 4 elements, using SIMD multiplies and adds, thereby reducing the number of multiply and add instructions. Some shuffling is required to get the input data into the right lanes.
  - MatrixTranspose: Transpose a 4x4 matrix. This is also a common operation, when doing vector/matrix algebra. Rows are made into columns. The scalar kernel, simply moves the 16 elements around one by one. The SIMD version uses 8 shuffle operations
  - MatrixInverse: Compute the inverse of a 4x4 matrix. This is a complex operation, involving hundreds of multiples and add operations. There are several different ways of computing the inverse of a matrix. Here we have chosen a method called the Cramer rule ¡REF¡. This kernel is the most compute intensive.

The sources for the C++ benchmarks can be found here: ¡REF¿, and the sources for the handwritten JavaScript benchmarks can be found here: ¡REF;

#### 6. Results

We've collected performance results for these combinations:

- Natively compiled C++
- Handwritten JavaScript executed with V8
- Handwritten JavaScript executed with SpiderMonkey
- Emscripten produced JavaScript from C++ implementation executed with V8
- Emscripten produced JavaScript from C++ implementation executed with SpiderMonkey

```
1 __m128i mandelx4(__m128 c_re4, __m128 c_im4,
                     uint32_t max_iterations) {
 2
 3
    _{\rm m}128 \ z_{\rm re4} = c_{\rm re4};
 4
    _{-m128} z_{im4} = c_{im4};
    __m128 four4 = _mm_set_ps1(4.0f);
 .5
    _{\rm _{m}128} two4 = _{\rm _{mm_{set_{ps1}(2.0f)};}
    __m128i count4 = _mm_set1_epi32(0);
     __m128i one4 = _mm_set1_epi32(1);
    uint32_t i;
    for (i = 0; i < max_iterations; ++i) {</pre>
10
       _m128 z_re24 = _mm_mul_ps(z_re4, z_re4);
11
       __m128 z_im24 = _mm_mul_ps(z_im4, z_im4);
12
13
       _{\rm m}128~{\rm mi4} =
14
        _mm_cmple_ps(_mm_add_ps(z_re24, z_im24), four4);
       if (_mm_movemask_ps(mi4) == 0)
15
16
         break:
17
       __m128 new_re4 = _mm_sub_ps(z_re24, z_im24);
       _m128 new_im4 = _mm_mul_ps(_mm_mul_ps(two4, z_re4), z_im4);
18
      z_re4 = _mm_add_ps(c_re4, new_re4);
19
       z_im4 = _mm_add_ps(c_im4, new_im4);
20
21
       count4 = _mm_add_epi32(
         count4, _mm_and_si128(_mm_castps_si128(mi4), one4));
22
23
24
    return count4;
25 };
```

**Figure 10.** C++ SIMD Mandelbrot kernel

```
// function mandelx4(c_re4, c_im4, max_iterations) {
    var z re4 = c re4:
2
3
    var z_im4 = c_im4;
    var four4 = SIMD.float32x4.splat(4.0);
    var two4 = SIMD.float32x4.splat(2.0);
.5
    var count4 = SIMD.int32x4.splat(0);
    var one4 = SIMD.int32x4.splat(1);
8
    for (var i = 0; i < max_iterations; ++i) {</pre>
      var z_re24 = SIMD.float32x4.mul(z_re4, z_re4);
9
      var z_im24 = SIMD.float32x4.mul(z_im4, z_im4);
10
11
      var mi4 = SIMD.float32x4.lessThanOrEqual(
12
                   SIMD.float32x4.add(z_re24, z_im24), four4);
      // check if all 4 values are greater than 4.0
13
      if (mi4.signMask === 0x00)
14
15
        break:
16
      var new_re4 = SIMD.float32x4.sub(z_re24, z_im24);
      var new_im4 = SIMD.float32x4.mul(
17
        SIMD.float32x4.mul(two4, z_re4), z_im4);
18
19
      z_re4 = SIMD.float32x4.add(c_re4, new_re4);
      z_im4 = SIMD.float32x4.add(c_im4, new_im4);
20
21
      count4 = SIMD.int32x4.add(
22
        count4, SIMD.int32x4.and (mi4, one4));
23
    return count4;
25 }
```

Figure 11. JavaScript SIMD Mandelbrot kernel

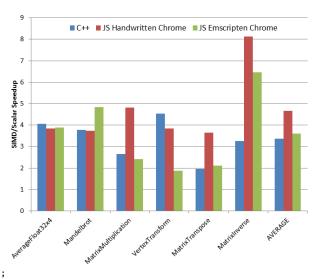


Figure 12. SIMD vs. Scalar relative speedups

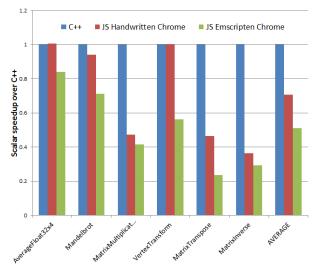


Figure 13. Scalar C++ vs. Javascript relative performance

#### 6.1 SIMD vs. Scalar

Figure 12 shows the relative SIMD vs. Scalar performance of the five combinations. Greater than 1 means that the kernel ran that the SIMD kernel ran that much faster than the corresponding scalar kernel.

#### 6.2 Scalar C++ vs. JavaScript

Figure 13 shows the relative scalar C++ vs. JavaScript performance for each of the five combinations. Less than 1 means that the JavaScript kernel ran that much slower than the corresponding C++ kernel.

#### 6.3 SIMD C++ vs. JavaScript

Figure 14 shows the relative SIMD C++ vs. JavaScript performance for each of the five combinations. Less than 1 means that the JavaScript kernel ran that much slower than the corresponding C++ kernel.

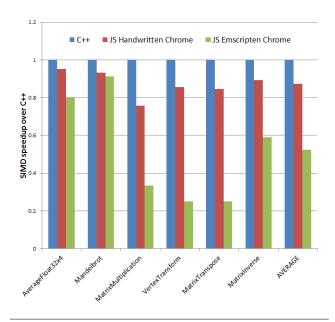


Figure 14. SIMD C++ vs. Javascript relative performance

# 7. Summary

# A. Appendix Title

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# Acknowledgments

Acknowledgments, if needed.

#### References

[1] P. Q. Smith, and X. Y. Jones. ...reference text...