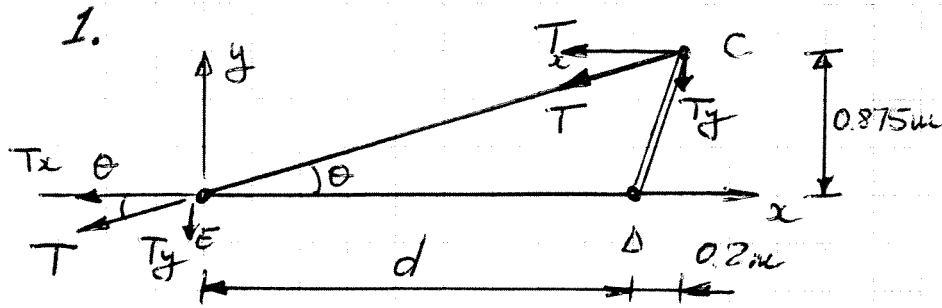


# CIV 100F: SOLUTIONS TO ASSIGNMENT No.2

1.



Force  $\vec{T}$ , i.e. the tension in cable CE, can be resolved into its rectangular components,  $\vec{T}_x$  and  $\vec{T}_y$ , and can also be applied at E since  $\vec{T}$  is a sliding vector. Hence, the moment

of  $\vec{T}$  about point D will be given by only the y component of  $\vec{T}$  since the line of action of  $T_x$  passes through point D, i.e. the moment arm is zero.

$$\therefore M_D = (T \sin \theta) d, \text{ where } \sin \theta = \frac{0.875}{\sqrt{(d+0.2)^2 + (0.875)^2}}$$

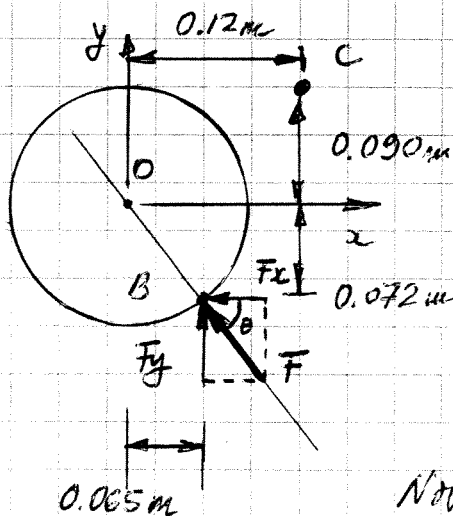
$$\text{Point } 960 = (d)(2400) \frac{0.875}{\sqrt{(d+0.2)^2 + (0.875)^2}}$$

Req'd moment to rotate the post about D      Force in the cable

$$\therefore \sqrt{(d+0.2)^2 + (0.875)^2} = 2.1875d, \text{ or } d^2 + 0.4d + 0.04 + 0.7656 = 4.785d$$

$$\therefore 3.7852d^2 - 0.4d - 0.8056 = 0 \quad \therefore \underline{d_{\min} = 0.517 \text{ m}}$$

2.



The line of action of  $\vec{F}$  is line OB, and  $\vec{F}$  can also be resolved into its rectangular components

$$d_{OB} = \sqrt{(65)^2 + (72)^2} = 97 \text{ mm}, \quad \cos \theta = \frac{65}{97} \text{ and } \sin \theta = \frac{72}{97}$$

$$\therefore F_x = F \cos \theta = (485) \frac{65}{97} = 325 \text{ N}$$

$$F_y = F \sin \theta = (485) \frac{72}{97} = 360 \text{ N}$$

$$\text{Now, } M_C = -F_x d_y - F_y d_x =$$

$$= -(325)(0.072 + 0.005) - (360)(0.12 - 0.065) = -(325)(0.077) - (360)(0.055) =$$

$$= -72.45 \text{ Nm}$$

$$\therefore \underline{M_C = 72.5 \text{ Nm}}$$

$$3. d_{AB} = \sqrt{(24-0)^2 + (16-(-8))^2 + (-18-10)^2} = 44 \text{ m} \quad \underline{2}$$

Assume an imaginary force  $\vec{F}$  acting at point A and directed from A to B. Then,

$$\vec{F} = F \hat{\lambda}_{AB} = \frac{F}{44} (24\vec{i} + 24\vec{j} - 28\vec{k}) = \frac{F}{11} (6\vec{i} + 6\vec{j} - 7\vec{k}).$$

By definition, the moment of  $\vec{F}$  about C is  $\vec{M}_C = \vec{r}_{CA} \times \vec{F}$ , and its magnitude:  $M_C = |\vec{r}_{CA} \times \vec{F}| = Fd$ , where

$$\vec{r}_{CA} = 3\vec{i} - 10\vec{j} + (10-a)\vec{k}$$

$$\therefore \vec{M}_C = \frac{F}{11} \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 3 & -10 & (10-a) \\ 6 & 6 & -7 \end{vmatrix} = \frac{F}{11} \{ [70 - 6(10-a)]\vec{i} + [6(10-a) + 21]\vec{j} + [18 + 60]\vec{k} \} = \frac{F}{11} \{ [10 + 6a]\vec{i} + [81 - 6a]\vec{j} + 78\vec{k} \}.$$

$$\therefore M_C^2 = \left(\frac{F}{11}\right)^2 [(10+6a)^2 + (81-6a)^2 + 78^2] = (Fd)^2, \text{ hence}$$

$$d^2 = \frac{1}{121} [(10+6a)^2 + (81-6a)^2 + (78)^2]$$

To calculate  $d_{min}$ , find the derivative of  $d^2$  and equal it to 0:

$$\frac{d(d^2)}{da} = \frac{1}{121} [2(10+6a)(6) + 2(81-6a)(-6)] = 0, \text{ or}$$

$$(10+6a) - (81-6a) = 0 \quad \therefore \underline{a = 5.92 \text{ m}}$$

$$4. BA = \sqrt{(-3)^2 + (3)^2 + (-1.5)^2} = 4.5 \text{ m and}$$

$$BD = \sqrt{(-0.08)^2 + (0.38)^2 + (0.16)^2} = 0.42 \text{ m}$$

$$(a) \vec{T}_{BA} = \frac{\vec{T}_{BA}}{4.5} (-3\vec{i} + 3\vec{j} - 1.5\vec{k}) = \frac{\vec{T}_{BA}}{3} (-2\vec{i} + 2\vec{j} - \vec{k}) \quad \left( \begin{array}{l} \text{From: } \vec{T}_{BA} = \vec{\lambda}_{BA} T_{BA} \\ \vec{\lambda}_{BA} = \frac{\vec{BA}}{BA} \end{array} \right)$$

$$\vec{\lambda}_{BD} = \frac{\vec{BD}}{BD} = \frac{1}{0.42} (-0.08\vec{i} + 0.38\vec{j} + 0.16\vec{k}) = \frac{1}{21} (-4\vec{i} + 19\vec{j} + 8\vec{k})$$

$$\cos \theta = \frac{\vec{T}_{BA} \cdot \vec{\lambda}_{BD}}{T_{BA} \cdot 1} = \frac{(-2)(-4) + (2)(19) + (-1)(8)}{3(21)} = 0.60317$$

$$\therefore \underline{\theta = 52.9^\circ}$$

$$(b) (T_{BA})_{BD} = \vec{T}_{BA} \cdot \vec{\lambda}_{BD} = T_{BA} (1) \cos \theta =$$

$$= (540)(0.60317) \text{ N}$$

$$\therefore \underline{(T_{BA})_{BA} = 326 \text{ N}}$$

$$5. \vec{M}_O = \vec{r}_{OA} \times \vec{F}, \quad \vec{r}_{OA} = [(-0.1)\vec{i} + (0.275)\vec{j} - (0.675)\vec{k}] \text{ m}$$

$$\text{Also, } \vec{F} = F[(\cos\theta)(\cos\phi)\vec{i} - \sin\theta\vec{j} + (\cos\theta)(\sin\phi)\vec{k}] \text{ N}$$

$$\text{Hence, } M_O = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -0.1 & 0.275 & -0.675 \\ (\cos\theta)(\cos\phi) & -\sin\theta & (\cos\theta)(\sin\phi) \end{vmatrix} =$$

$$= F[(0.275(\cos\theta)(\sin\phi) - 0.675(\sin\theta))\vec{i} + (-0.675(\cos\theta)(\cos\phi) + 0.1(\cos\theta)(\sin\phi))\vec{j} + (0.1(\sin\theta) - 0.275(\cos\theta)(\cos\phi))\vec{k}] \text{ Nm}$$

$$\text{So that: } M_x = F[0.275(\cos\theta)(\sin\phi) - 0.675(\sin\theta)] \quad (1)$$

$$M_y = F[-0.675(\cos\theta)(\cos\phi) + 0.1(\cos\theta)(\sin\phi)] \quad (2)$$

$$M_z = F[0.1(\sin\theta) - 0.275(\cos\theta)(\cos\phi)] \quad (3)$$

$$\text{From (1): } (\cos\theta)(\sin\phi) = \frac{1}{0.275} \left( \frac{M_x}{F} + 0.675 \sin\theta \right) \quad (4)$$

$$\text{From (3): } (\cos\theta)(\cos\phi) = \frac{1}{0.275} \left( 0.1 \sin\theta - \frac{M_z}{F} \right) \quad (5)$$

Substituting (4) and (5) into (2):

$$M_y = F \left\{ -0.675 \left[ \frac{1}{0.275} \left( 0.1 \sin\theta - \frac{M_z}{F} \right) \right] + 0.1 \left[ \frac{1}{0.275} \left( \frac{M_x}{F} + 0.675 \sin\theta \right) \right] \right\}$$

$$M_y = F \left\{ \left[ \frac{-0.0675}{0.275} \sin\theta + \frac{0.675 M_z}{0.275 F} \right] + \left[ \frac{0.1}{0.275} \frac{M_x}{F} + \frac{0.0675}{0.275} \sin\theta \right] \right\}$$

$$= \frac{1}{0.275} (0.675 M_z + 0.1 M_x) = \frac{1}{0.275} [(0.675)(-81) + (0.1)(-77)]$$

$$\therefore \underline{M_y = -227 \text{ N}\cdot\text{m}}$$