

Contrastive learning

Background

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Scope: self-supervised representation learning

- No labels
- To extract features (representations)

Why?



Labeled data



Unlabeled data

Motivation



How? Let us classify the following images into 2 categories



- Every instance image has its own feature/representation
- Can we learn representation by discriminating instances?

<https://billsberryfarm.com/produce/peaches/>

<https://www.applesfromny.com/varieties/jonagold/>

<https://www.heb.com/static-page/apple-varieties>

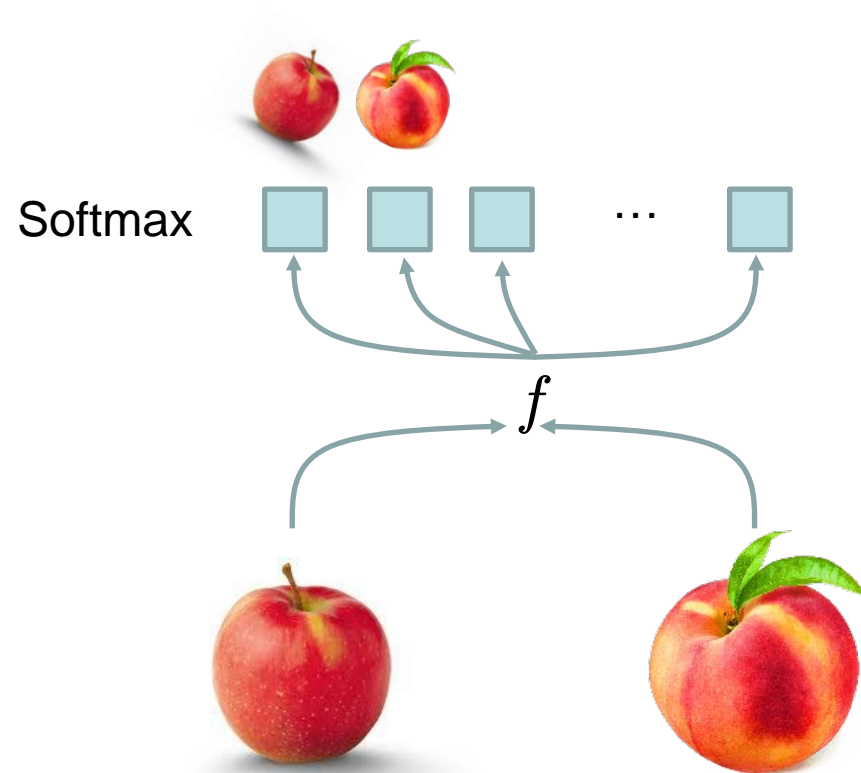
<https://www.freshpoint.com/archive/commodity-stone-fruits-peach-yellow/>



Motivation



A naïve idea: train a classifier to classify N images into N categories.



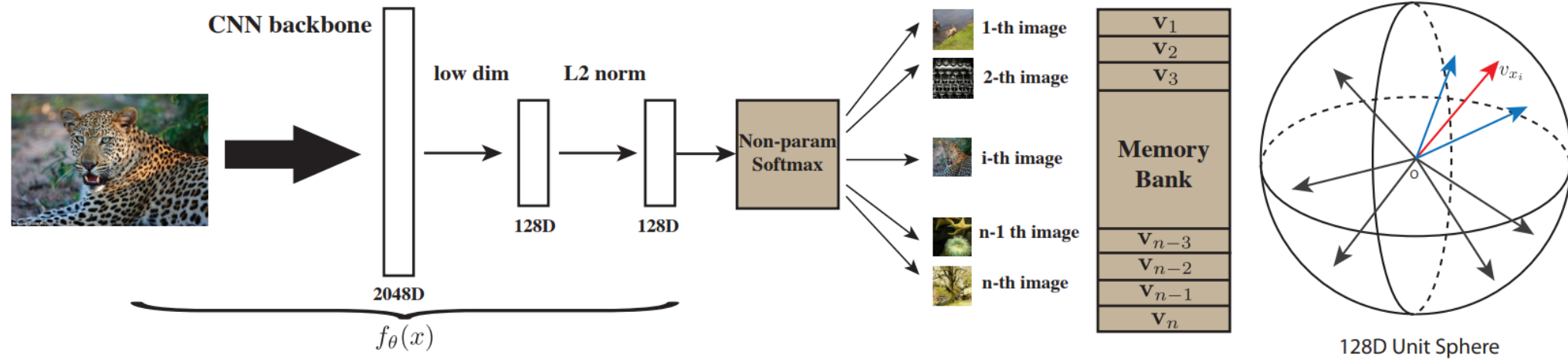
Impractical, too many categories.



Memory bank

Non-Parametric Instance Discrimination

We reduce the dimension of classifications



We want to learn $\mathbf{v} = f_{\theta}(x)$ subject to $\|\mathbf{v}\| = 1$

Non-parametric softmax $P(i|\mathbf{v}) = \frac{\exp(\mathbf{v}_i^T \mathbf{v} / \tau)}{\sum_{j=1}^n \exp(\mathbf{v}_j^T \mathbf{v} / \tau)}$

Loss $J(\theta) = - \sum_{i=1}^n \log P(i|f_{\theta}(x_i))$

Motivation

Can we incorporate more semantic info? Let us classify the following images into 2 categories



What are the attributes to distinguish between these two types of objects

- Shape? Yes
- Texture? Yes
- Color? Maybe
- Orientation? No
- Image size? No
- Location? No

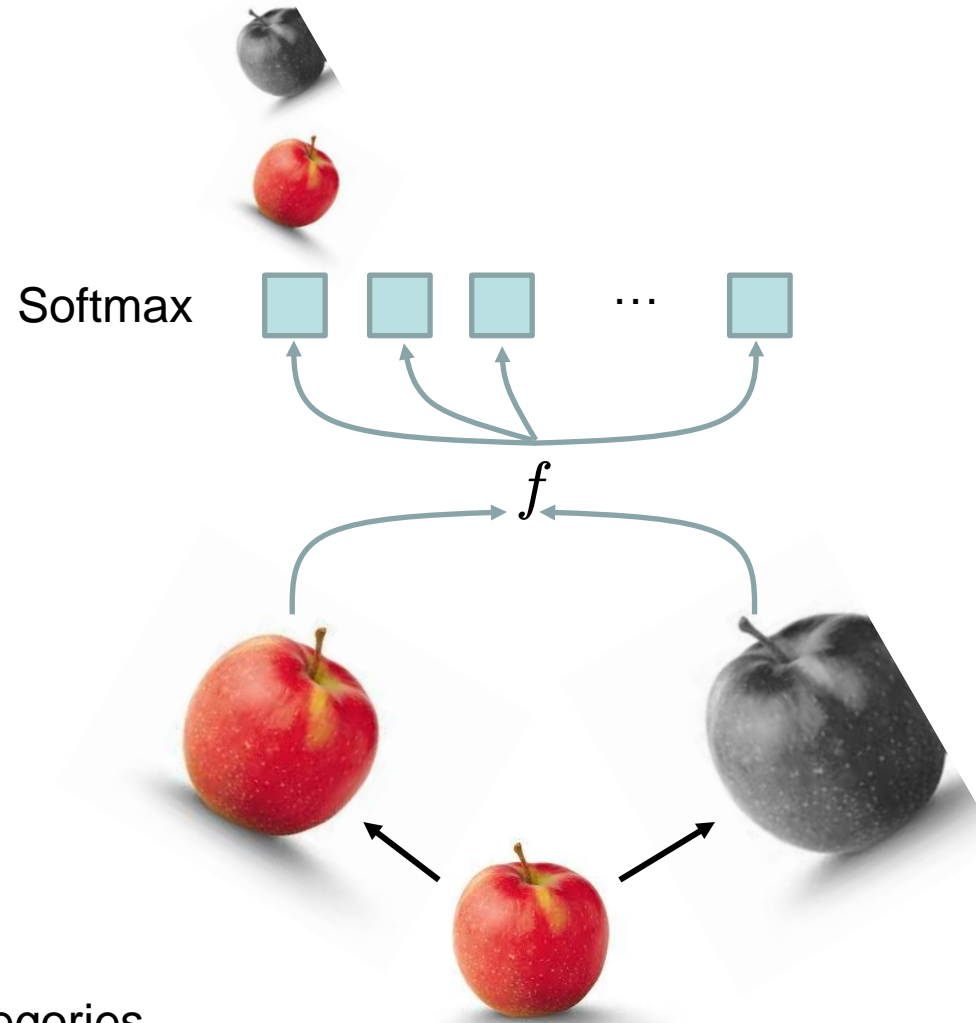
The *views* are generated from 2 *images* by **data augmentation**

- Know the “category” of views without label
- Train the network to discard unneeded attributes

Motivation



Another naïve idea: train a classifier to classify N images (unlimited views) into N categories.

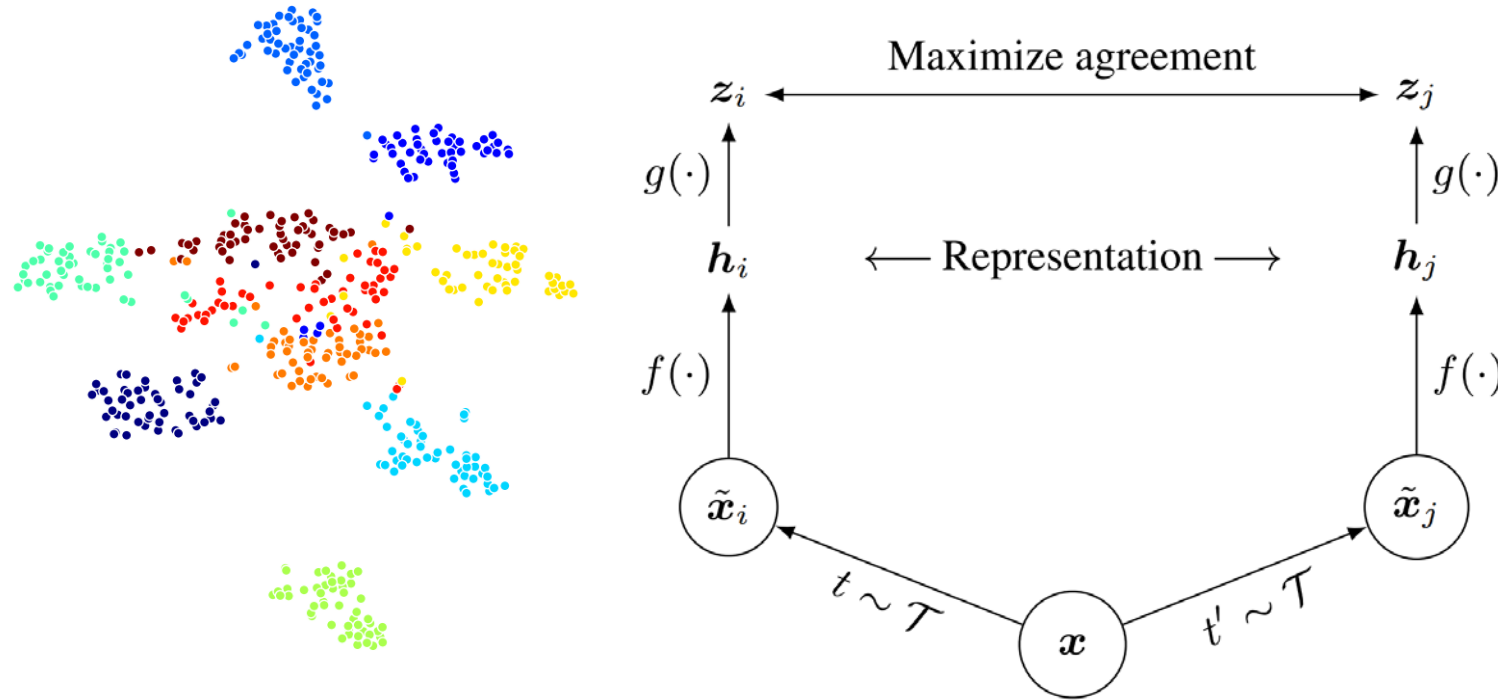


Impractical, too many categories.



SimCLR

- Use data augmentation to generate views
- Measure the distance between representations
- Cluster representations of views



First define distance by inner product

$$\text{sim}(\mathbf{u}, \mathbf{v}) = \mathbf{u}^\top \mathbf{v} / \|\mathbf{u}\| \|\mathbf{v}\|$$

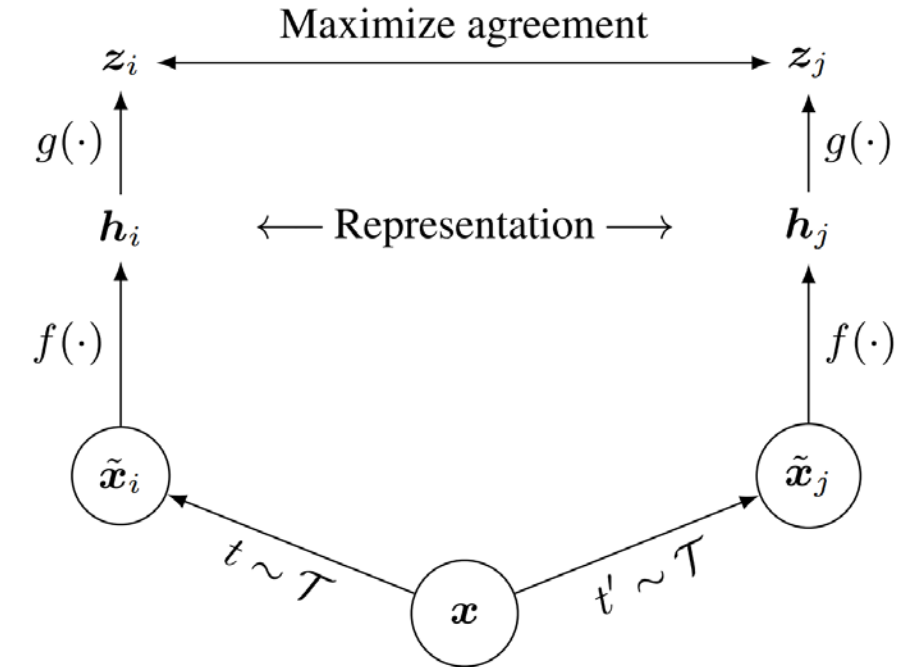
Then define loss function by distance

For a positive pair of views i, j (from the same image)

$$\ell_{i,j} = -\log \frac{\exp(\text{sim}(\mathbf{z}_i, \mathbf{z}_j)/\tau)}{\sum_{k=1}^{2N} \mathbb{1}_{[k \neq i]} \exp(\text{sim}(\mathbf{z}_i, \mathbf{z}_k)/\tau)} \quad \text{InfoNCE}$$

To make this work, we need

- Large batch size (256-8192 in the paper)
- Various data augmentation techniques



Data augmentation used in SimCLR



(a) Original



(b) Crop and resize



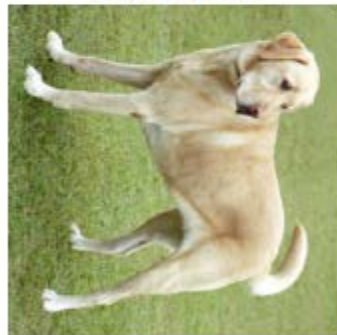
(c) Crop, resize (and flip)



(d) Color distort. (drop)



(e) Color distort. (jitter)



(f) Rotate $\{90^\circ, 180^\circ, 270^\circ\}$



(g) Cutout



(h) Gaussian noise

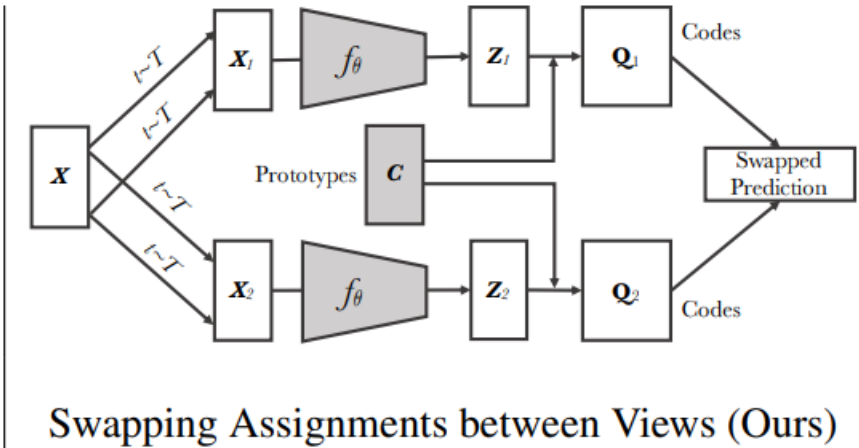
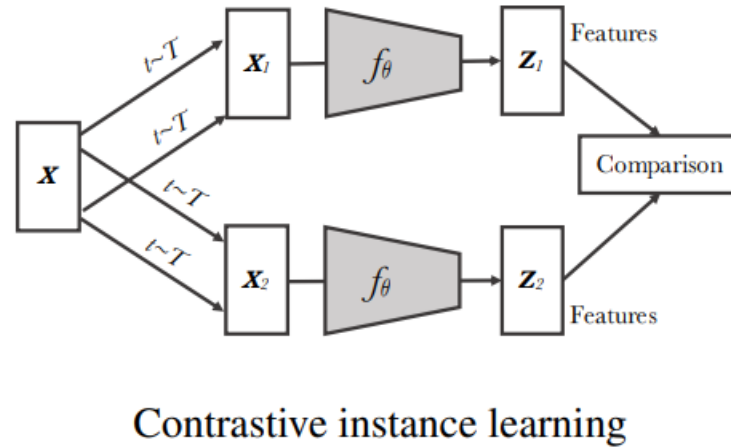
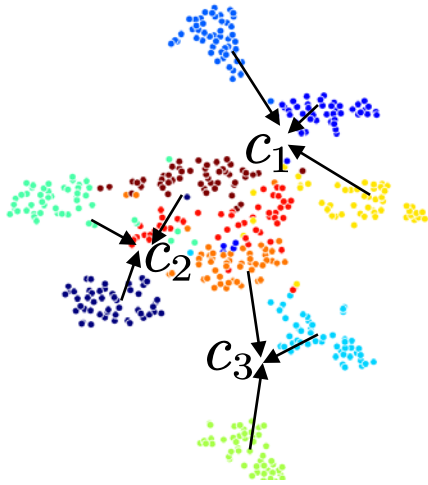


(i) Gaussian blur



(j) Sobel filtering

SwAV: use given number of clusters/categories



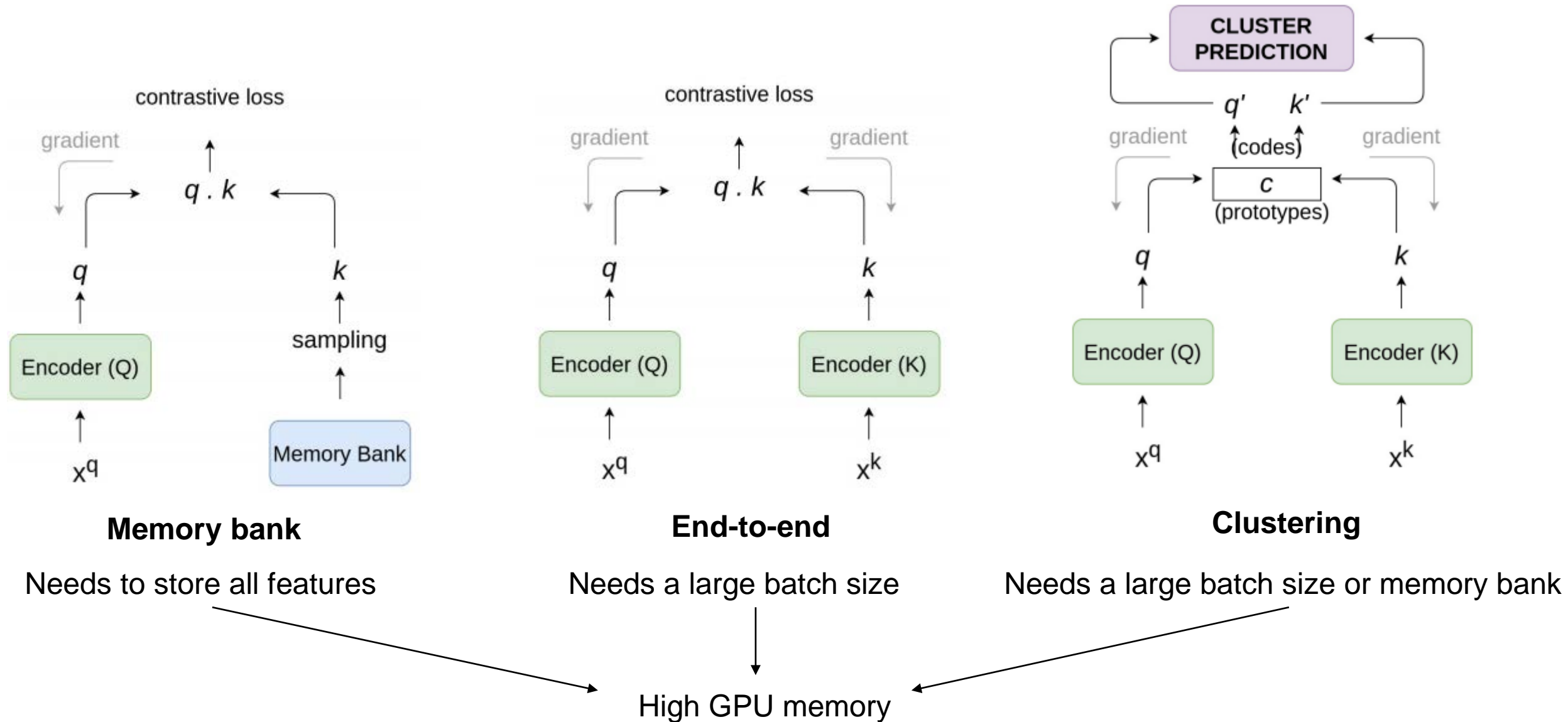
$$\text{Loss} = -\frac{1}{N} \sum_{n=1}^N \sum_{s,t \sim \mathcal{T}} \left[\frac{1}{\tau} \mathbf{z}_{nt}^\top \mathbf{C} \mathbf{q}_{ns} + \frac{1}{\tau} \mathbf{z}_{ns}^\top \mathbf{C} \mathbf{q}_{nt} - \log \sum_{k=1}^K \exp \left(\frac{\mathbf{z}_{nt}^\top \mathbf{c}_k}{\tau} \right) - \log \sum_{k=1}^K \exp \left(\frac{\mathbf{z}_{ns}^\top \mathbf{c}_k}{\tau} \right) \right]$$

To avoid trivial solution, \mathcal{Q} is regularized by complicated constraints

- High entropy
- Equal partition of images by prototypes (clusters)

A large batch size or memory bank is needed

Brief summary



Thank you