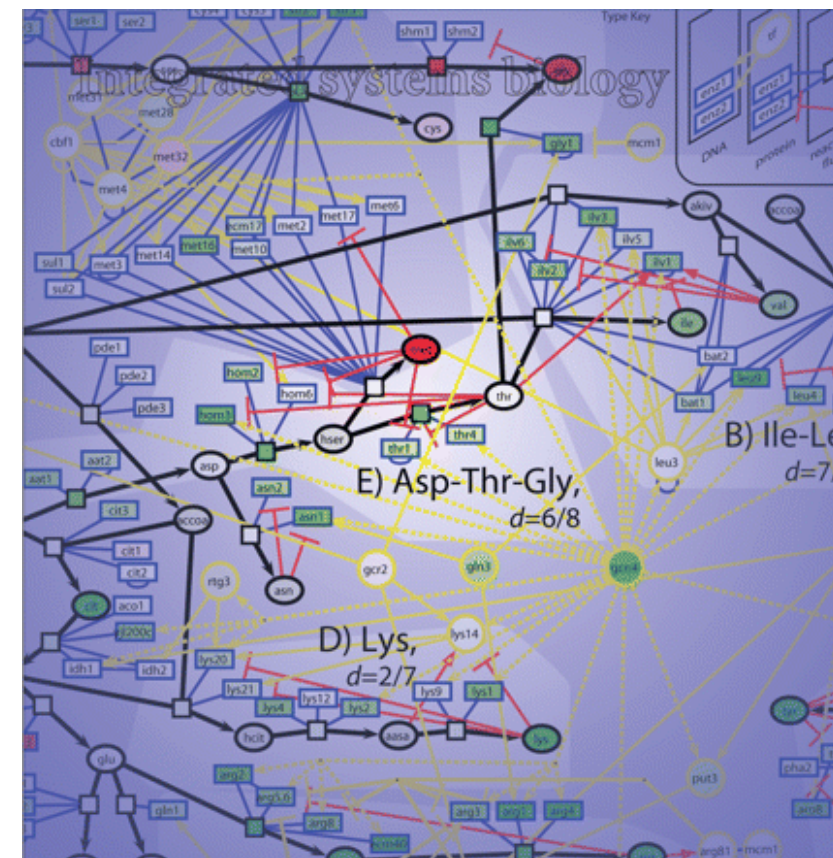


LAYERED SYNTHETIC BIOMOLECULAR SYSTEMS

THOMAS P. PRESCOTT (THOMAS.PRESCOTT@ENG.OX.AC.UK) ANTONIS PAPACHRISTODOULOU
CONTROL GROUP // DEPARTMENT OF ENGINEERING SCIENCE // UNIVERSITY OF OXFORD // UNITED KINGDOM

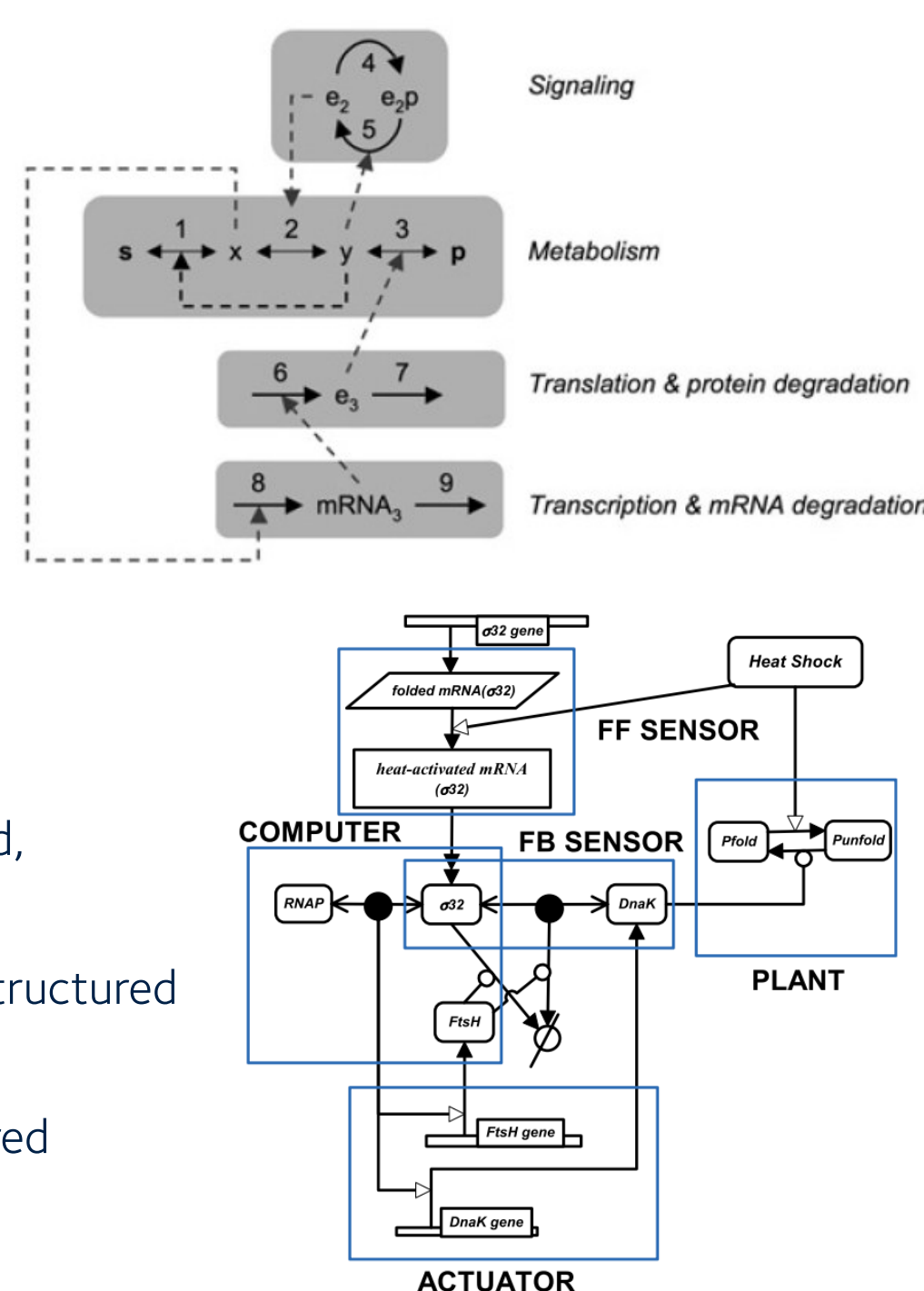
BIOMOLECULAR NETWORKS ARE HIGHLY NONLINEAR, EXTREMELY LARGE SCALE, AND YET ARE EXCEPTIONALLY STRUCTURED



Above: Schematic of complex, integrated, intracellular network [1]

Above right: Biomolecular subnetwork structured through biochemical function [2]

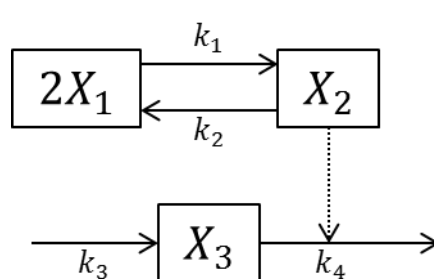
Right: Biomolecular subnetwork structured through system-theoretic function [3]



THE CONCEPT OF LAYERING [4,5] PROVIDES A NEW WAY TO DESCRIBE A BIOLOGICAL SYSTEM'S STRUCTURE

Biological Network ODE Model:

$$\dot{x} = Sv(x)$$



Concentration vector:

$$x = [x_1, x_2, x_3]^T$$

Flux vector:

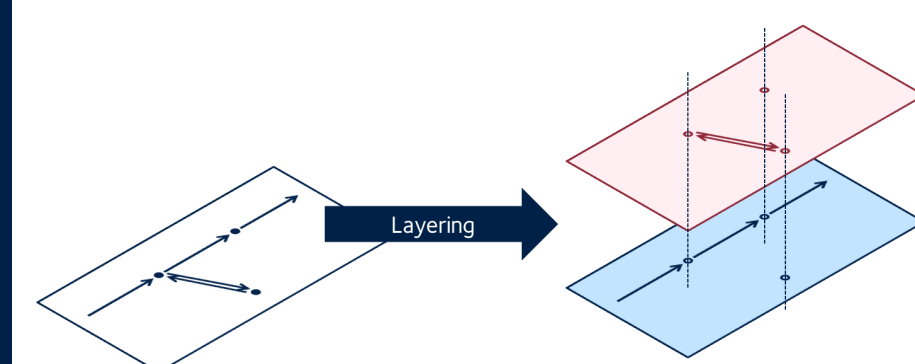
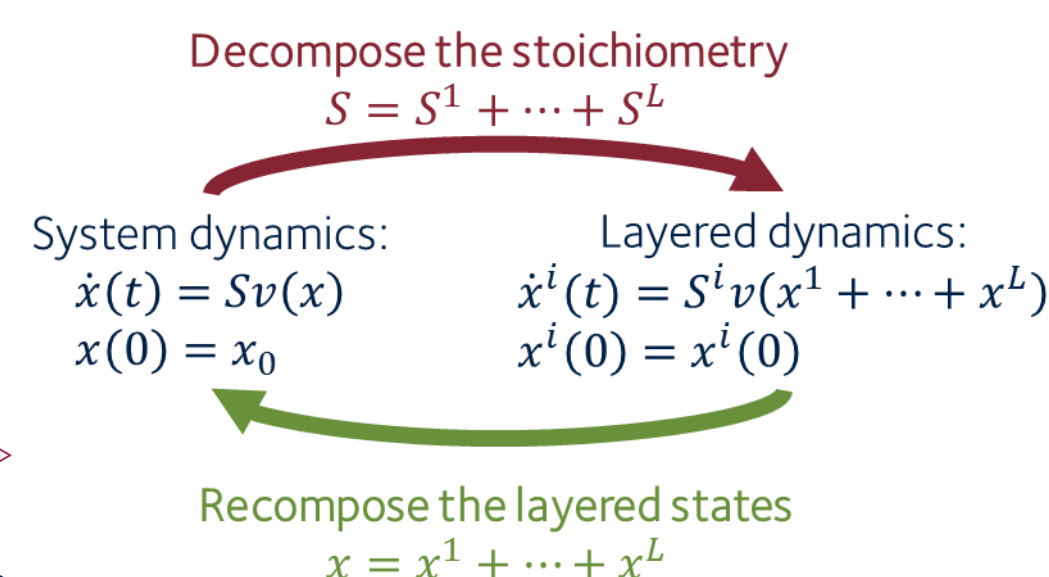
$$v(x) = [k_1(x_1)^2, k_2x_2, k_3, k_4x_2x_3]^T$$

Stoichiometric matrix:

$$S = \begin{bmatrix} -2 & 2 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

Traditional concept of modular decomposition concentrates on a simultaneous partition of the reaction-species sets into interconnected sub-networks. Assumes a partition of the state space of the dynamics.

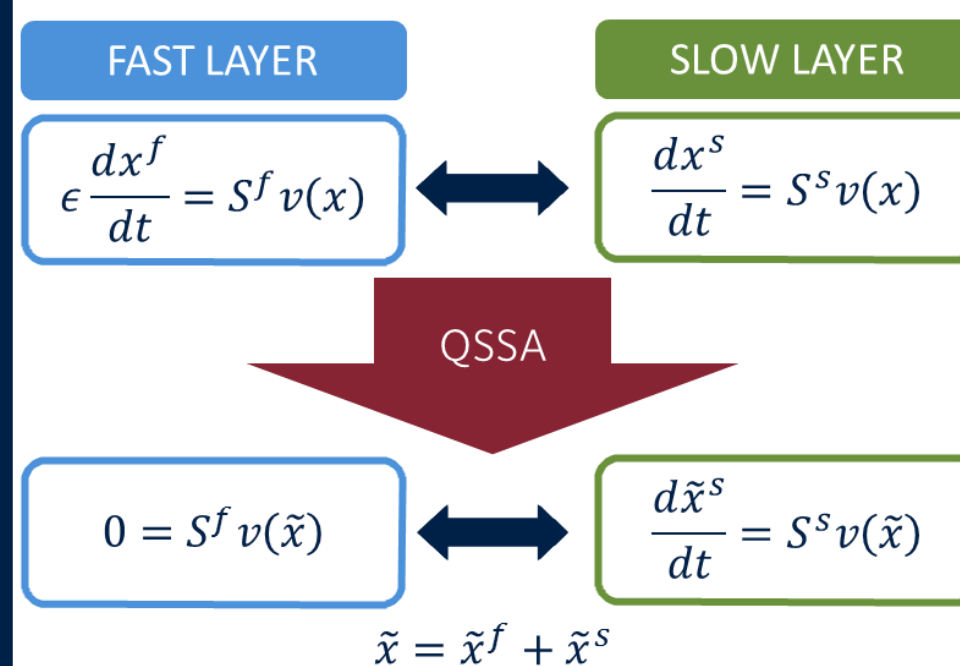
We have instead proposed a new approach, termed **layering**, that considers the contribution of each subsystem to all species. Subsystem dimensions are defined by matrix ranks.



WE CAN CHOOSE A LAYERED DECOMPOSITION BASED ON TIMESCALE SEPARATION [6]

Reaction rates often separate in scale; this in turn implies a natural decomposition of the columns of S . Traditional singular perturbation techniques require transformations to find fast and slow variables. By layering, these are automatically uncovered in terms of the original, physical, variables.

$$\dot{x} = \frac{1}{\epsilon} S^f v(x) + S^s v(x) \text{ with } \epsilon \ll 1$$



Original dynamics:

$$\dot{x} = \frac{1}{\epsilon} S^f v(x) + S^s v(x)$$

Approximated dynamics:

$$\dot{\tilde{x}} = (I + M^f(\tilde{x})) S^s v(\tilde{x})$$

The key result of [6] is given to the left. The system dynamics are a projection of the slow dynamics, defined by the formula:

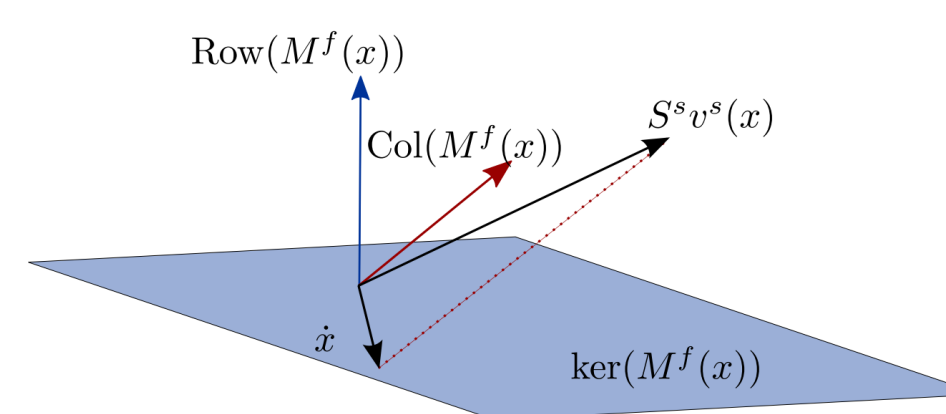
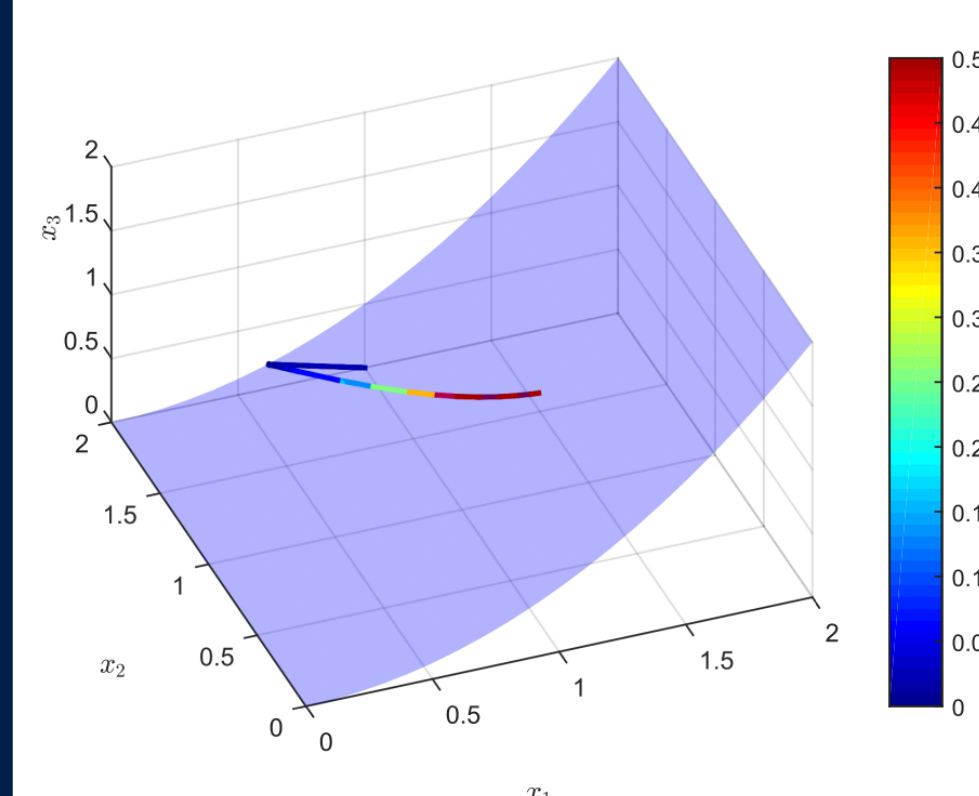
$$M^f(x) = -U^f (C^f v'(x) U^f)^{-1} C^f v'(x)$$

for the full rank matrices defining $S^f = U^f C^f$

$$\begin{aligned} \dot{x} &= \begin{bmatrix} -1 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} k_1 x_1 / \epsilon \\ k_{-1} x_2 / \epsilon \\ k_2 x_2 \\ k_{-2} x_3 \end{bmatrix} \\ S^f &= \begin{bmatrix} -1 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\ S^s &= \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix} \end{aligned}$$

TIMESCALE SEPARATION IMPLIES THAT THE BIOCHEMICAL NETWORK DYNAMICS PROCEED ACCORDING TO ADDITIONAL NONLINEAR CONSERVATION CONSTRAINTS [7]

The projection of the slow dynamics given above implies that the approximated dynamics are always orthogonal to the row space of $M^f(x)$, which varies with the state.

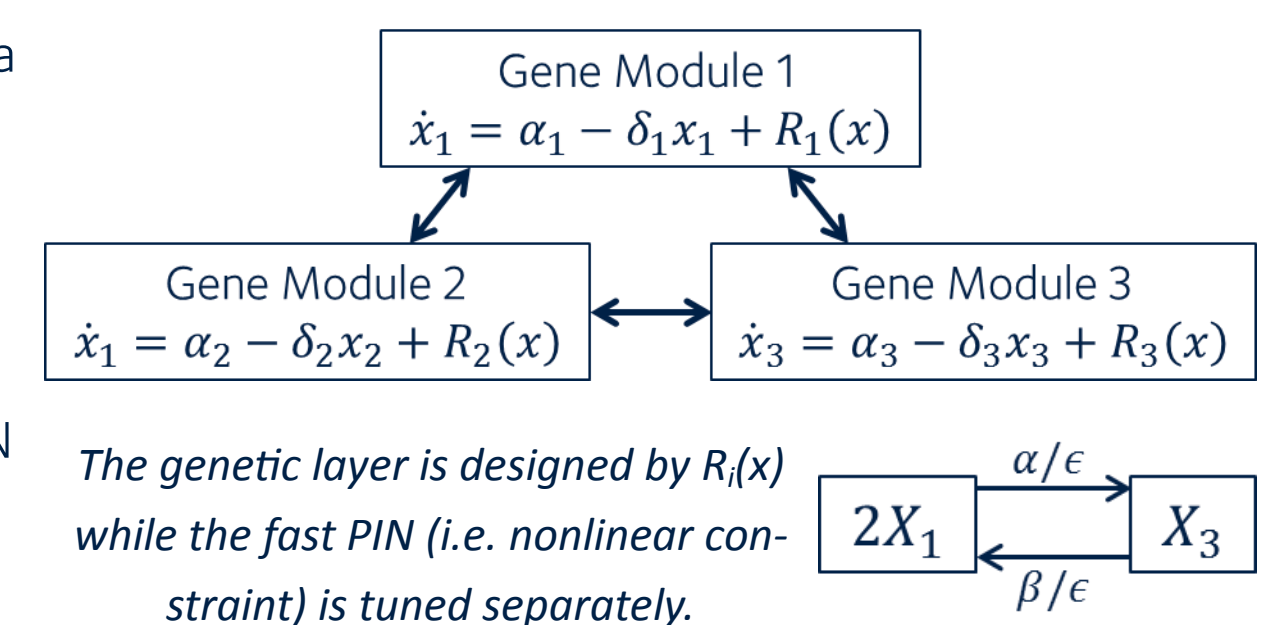


The nonlinear conservation $x_3 = kx_1^2$ is not implied by the empty left null space of the full system's stoichiometric matrix:

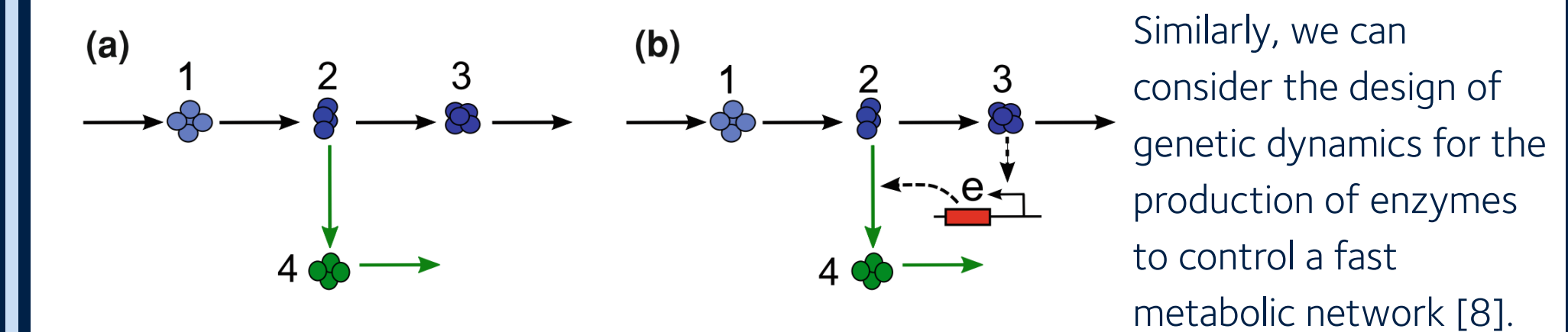
$$S = \begin{bmatrix} 1 & 0 & 0 & -2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

THIS HAS IMPLICATIONS FOR DESIGNING SYNTHETIC BIOMOLECULAR NETWORKS ACROSS MULTIPLE TIMESCALES

Consider the layered design of a gene regulatory network whose transcription factors participate in a fast protein interaction network.



- What constraints can the PIN implement?
- How to design the genetic interactions (dynamics) together with the PIN (constraints) for the network to achieve the desired behaviour with the required performance?



- Nonlinear constraints defined by enzyme-dependent (quasi-) steady states of the metabolic network
- Slower, genetic dynamics can be externally driven by modulating metabolic influxes
- Where should the metabolic network be tuned through redesign of metabolic parameters (constraint design)? Where should the genetic network be constructed and tuned (design of dynamics)?

CONCLUSIONS AND FUTURE WORK

- Through layered decomposition we have formulated the QSS approximation of a timescale separated system as a state-dependent projection of the slow dynamics, written in terms of the fast layer's stoichiometric structure and kinetic form.
- We can thus approximate complex dynamics in high dimension into lower-dimensional dynamics, yet remain embedded in the original state space.
- The design of fast dynamics can thus implement tuneable, nonlinear static constraints into a synthetic biomolecular network.
- Conversely, when investigating natural networks, the dynamics on one, fast, timescale define nonlinear static constraints on other, slower timescales, on which dynamics have evolved to perform biological functionalities.
- Consider also layered decomposition without timescale separation, or in other dynamical systems. How can the decomposition of dynamics be interpreted as a decomposition into multiple functionalities and constraints on the entire set of original system variables?