

# Affine Invariant Stochastic Optimization

## Optimization and Big Data 2015

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# Stochastic Optimization

The problem at hand is to find  $\theta_*$  minimizing  $f(\theta)$  when we have samples  $W_\theta$ ; such that,

$$\nabla f(\theta) = E[W_\theta]. \quad (1)$$

A general **Robbins-Monro** iteration takes the form

$$\hat{\theta}_{n+1} = \hat{\theta}_n - \frac{1}{n^\gamma} K_n W_n, \quad (2)$$

where  $W_n$  is a sample of  $W_{\hat{\theta}_n}$ . The **optimal  $K_n$**  is the **inverse of the Hessian of  $f$**  at the optimal  $\theta_*$  and the **optimal  $\gamma$**  is **1**. We follow Bottou and aim to minimize

$$\mathcal{L} = E[f(\hat{\theta}_n) - f(\theta_*)]. \quad (3)$$

# Affine Invariant Optimization

- The optimization procedure  $O$  is **Affine Invariant** if :

$$B \theta_O(f \circ B) = \theta_O(f) . \quad (4)$$

for all lineal transformations  $B : \mathcal{S} \longrightarrow \mathcal{S}$

- A consequence is that the optimization **can not be improved** by a linear transformation of the feature space.
- Second order methods, like the optimal Robbins-Monro, are affine invariant.

# Linear regression approximation of $H^{-1}$ .

Let  $X_n$  and  $Y_n$  be the corresponding  $n \times (p + 1)$  and  $n \times p$  matrices with entries

$$x_k = (\hat{\theta}_k, 1), \quad y_k = W_k,$$

consider the linear regression  $Y = XB$  and denote the first  $p$  rows of a matrix  $M$  by  $\overline{M}$ . We calculate the natural estimators

$$\begin{aligned} B_n &= (X_n^T X_n)^{-1} X_n^T Y, & H_n &= \overline{B_n} \\ G_n &= \overline{B_n}^{-1}, & K_n &= \frac{G_n + G_n^T}{2}, \end{aligned} \tag{5}$$

and use  $K_n$  as our  $H^{-1}$  estimator and  $\gamma = 0.6$ .

- The estimator is  $\bar{\theta}_n = \frac{1}{n}(\hat{\theta}_1 + \dots + \hat{\theta}_n)$ , **Polyak averaging**

Similar algorithms (with  $\gamma = 1$  and no Polyak averaging) were analyzed by **Lai and Robbins in 1981**, with no numerical simulations. This optimization is **Affine invariant**.

# Online update

We use the *online update*

$$\begin{aligned} s_{n+1} &= \frac{1}{1 + x_{n+1} P_n x_{n+1}^T} \\ u_{n+1} &= s_{n+1} \overline{P_n x_{n+1}^T} \\ v_{n+1} &= y_{n+1} - x_{n+1} B_n \\ t_{n+1} &= \frac{1}{1 + v_{n+1} G_n u_{n+1}} \\ G_{n+1} &= G_n - t_{n+1} G_n u_{n+1} v_{n+1} G_n \\ B_{n+1} &= B_n + s_{n+1} P_n x_{n+1}^T v_{n+1} \\ P_{n+1} &= P_n - s_{n+1} P_n x_{n+1}^T x_n P_n^T \end{aligned} \tag{6}$$

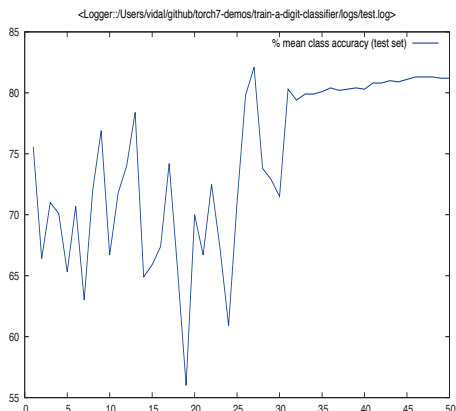
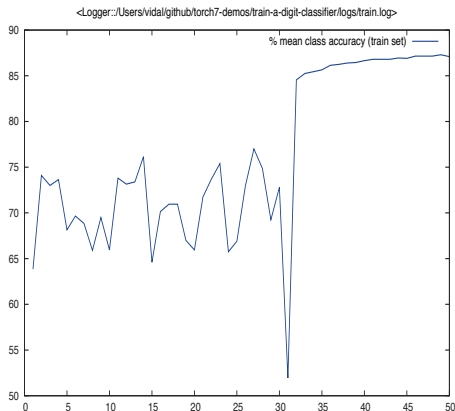
- $P_n = (X_n^T X_n)^{-1}$  is the **precision matrix**.
- $O(p^2)$  **completely parallelizable** operations .

**Opensource** machine learning library in **Lua** (scripting) maintained by Idiap Research Institute, NYU and NEC Laboratories America.

- Supports CUDA and OpenMP
- Recent neural networks, like **Dropout**, are implemented.
- Many optimization methods are implemented.

# MNIST

- Convolutional neural network with 4,000 parameters.
- Minimize negative log likelihood
- We run experiments in Tesla K40, provided by NVIDIA.
- We can not increase the number of parameters because we run out of memory.



# Low rank approximation (Matthew Brand)

Given the *thin SVD* decomposition  $G = USV^T$ , with  $S \in M_{r \times r}$ , find the decomposition of the **rank one update**

$$G + ab^T = \bar{U} \bar{S} \bar{V}^T, \quad \bar{S} \in M_{(r+1) \times (r+1)},$$

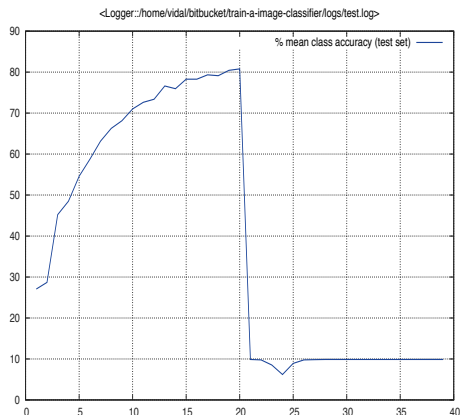
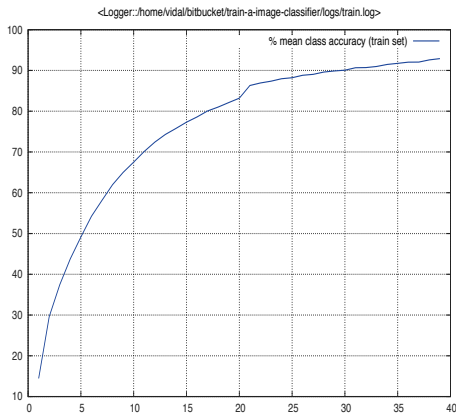
with the steps

$$\begin{aligned} m &= U^T a; & p &= a - Um, & R_a &= \|p\|; & P &= R_a^{-1} p, \\ n &= V^T b; & q &= b - Vn, & R_b &= \|q\|; & Q &= R_b^{-1} q, \\ K &= \begin{bmatrix} S + mn^T & \|q\| m \\ \|p\| n^T & \|p\| \|q\| \end{bmatrix}, & K &= U' S' V'^T \\ \bar{U} &= [U \ P] U'; & \bar{S} &= S'; & \bar{V} &= [V \ Q] V' \end{aligned}$$



# CIFAR-10

- Convolutional neural network with **Dropout** and **9,000,000 parameters**
- Minimize **negative log likelihood**
- We run experiments in **Tesla K40**. Thank you again **NVIDIA !**.
- **Accuracy increases only on the test set**. Conclusion: even with Dropout, we have **overfitting** in the model.



- Jose Vidal Alcala Burgos, Optimizing the exercise boundary for the holder of an American option over a parametric family, Ph.D. Thesis, ProQuest (2012).

<http://gradworks.umi.com/35/24/3524127.html>

- Code for the *affine invariant* algorithm is available at <https://github.com/vidalalcala/sopt-ols>
- Code for MNIST is available at <https://bitbucket.org/vidalalcala/affine-invariant-sopt>
- Code for CIFAR *affine invariant* is available at <https://bitbucket.org/vidalalcala/train-a-image-classifier> with password.