

CSCI 2270

Data Structures and Algorithms

Binary Trees and Binary Search Trees

Elizabeth White

elizabeth.white@colorado.edu

Office hours: ECCS 112/128

Wed 9:30am-11:30am

Thurs 10am-11am

Administrivia

Read Trees chapter, pp.507-535

In lab this week, you'll write insert and count for the binary search tree class. You'll have a lot of code supplied already.

Destroying a binary tree

```
void tree_clear(binary_tree_node<ItemType>*& root_ptr) {  
    binary_tree_node<ItemType>* child;  
    if (root_ptr != nullptr)  
    {  
        child = root_ptr->left( );  
        tree_clear( child );  
        child = root_ptr->right( );  
        tree_clear( child );  
        delete root_ptr;  
        root_ptr = nullptr;  
    }  
}
```

Copying a binary tree

```
binary_tree_node<ItemType>* tree_copy(const
    binary_tree_node<ItemType>* root_ptr) {
    binary_tree_node<ItemType> *l_ptr, *r_ptr;
    if (root_ptr == nullptr) return nullptr;
    else {
        l_ptr = tree_copy( root_ptr->left( ) );
        r_ptr = tree_copy( root_ptr->right( ) );
        return new binary_tree_node<ItemType>
            (root_ptr->data( ), l_ptr, r_ptr);
    }
}
```


Binary tree node access

In bintree.h, you have methods to get at the data and the children:

```
ItemType& data( ) { return data_field; }  
binary_tree_node*& left( ) { return left_field; }  
binary_tree_node*& right( ) { return right_field; }
```

Notice, please, that each of these returns a reference. This means that we can assign to them. THIS IS WEIRD.

```
root_ptr->left() = new binary_tree_node(entry);  
root_ptr->data() = 2;
```

Inserting an Item

```
void BSTreeBag<ItemType>::insert(const ItemType& entry)
```

2 cases:

empty tree (easy to find where the Item goes)

non-empty tree: walk a pointer from the root to a leaf

```
    binary_tree_node<ItemType> *cursor;
```

```
    cursor = root_ptr;
```

```
    bool done = false;
```

```
    while (!done)
```

```
    {
```

```
        // find where this entry goes
```

```
    }
```

Inserting an Item

```
void BSTreeBag<ItemType>::insert(const ItemType& entry)
    cursor = root_ptr; bool done = false;
    while (!done) {
        if (entry <= cursor->data()) {
            // if cursor's left child is nullptr, add entry:
            cursor->left() = new
binary_tree_node<ItemType> (entry); done = true;
            // else keep looking
            cursor = cursor->left();
        }
        // else look in the right subtree
    }
}
```


Counting Items

```
unsigned int BSTreeBag<ItemType>::count(const ItemType&
target) const
{
    unsigned int answer = 0;
    binary_tree_node<ItemType> *cursor;
    while (cursor != nullptr)
    {
        // check if cursor has the target as its data
        // if so, count answer up
        // set cursor to the right child and look for more
    }
}
```

Removing Items

Inserting is easy, removing is hard

Reason: we need to keep the tree kosher after removals

2 cases:

- we're removing a node with no left subtree

 - we delete this node and move the right subtree
up into its spot

- we're removing a node with a left subtree

 - we find the maximum node in our left subtree,
delete that node,

 - and copy its data to the node we wanted to delete

Trees offer the chance for $\log(n)$ performance if you're lucky

For a binary search tree of n nodes,

Search: $O(\log n)$ average, $O(n)$ worst case

Insert: $O(\log n)$ average, $O(n)$ worst case

Remove: $O(\log n)$ average, $O(n)$ worst case

Traverse: $O(n)$

Another tree ADT, the B-tree, ensures that the tree is perfectly balanced (and even full); this guarantees the $O(\log n)$ performance, worst case