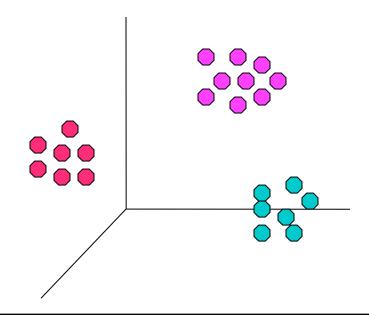
## **Data Mining**

## Introduction to Clustering

### Mauro Sozio

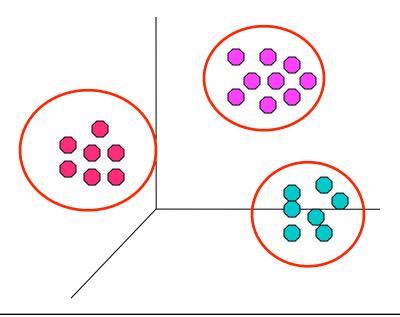
some slides from Tan, Steinbach, Kumar, Introduction to Data Mining

Finding groups of objects such that the objects in a group will be similar (or related) to one another and different from (or unrelated to) the objects in other groups



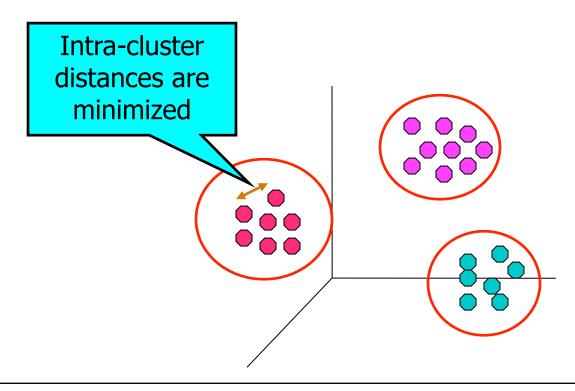
Mauro Sozio

Finding groups of objects such that the objects in a group will be similar (or related) to one another and different from (or unrelated to) the objects in other groups

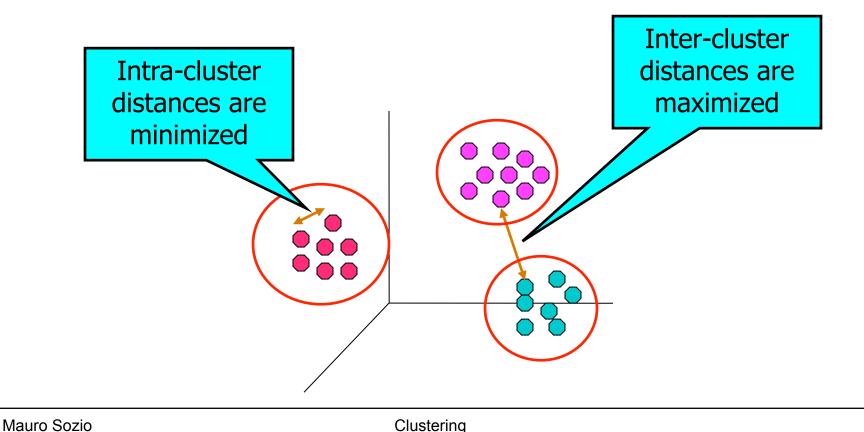


Mauro Sozio

Finding groups of objects such that the objects in a group will be similar (or related) to one another and different from (or unrelated to) the objects in other groups



Finding groups of objects such that the objects in a group will be similar (or related) to one another and different from (or unrelated to) the objects in other groups



Monday, March 27, 17

## **Applications of Cluster Analysis**

Clustering

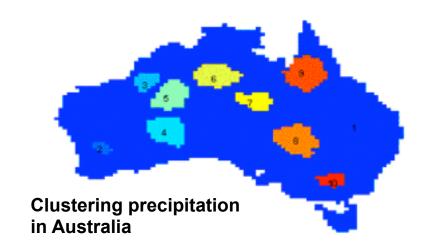
### Understanding

 Group related documents for browsing, group genes and proteins that have similar functionality, or group stocks with similar price fluctuations

	Discovered Clusters	Industry Group
1	Applied-Matl-DOWN,Bay-Network-Down,3-COM-DOWN, Cabletron-Sys-DOWN,CISCO-DOWN,HP-DOWN, DSC-Comm-DOWN,INTEL-DOWN,LSI-Logic-DOWN, Micron-Tech-DOWN,Texas-Inst-Down,Tellabs-Inc-Down, Natl-Semiconduct-DOWN,Oracl-DOWN,SGI-DOWN, Sun-DOWN	Technology1-DOWN
2	Apple-Comp-DOWN,Autodesk-DOWN,DEC-DOWN, ADV-Micro-Device-DOWN,Andrew-Corp-DOWN, Computer-Assoc-DOWN,Circuit-City-DOWN, Compaq-DOWN, EMC-Corp-DOWN, Gen-Inst-DOWN, Motorola-DOWN,Microsoft-DOWN,Scientific-Atl-DOWN	Technology2-DOWN
3	Fannie-Mae-DOWN,Fed-Home-Loan-DOWN, MBNA-Corp-DOWN,Morgan-Stanley-DOWN	Financial-DOWN
4	Baker-Hughes-UP,Dresser-Inds-UP,Halliburton-HLD-UP, Louisiana-Land-UP,Phillips-Petro-UP,Unocal-UP, Schlumberger-UP	Oil-UP

#### Summarization

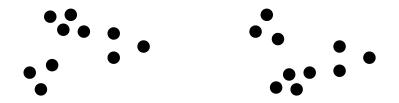
 Reduce the size of large data sets



Mauro Sozio

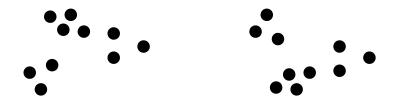
- Supervised classification
  - Have class label information
- Simple segmentation
  - Dividing students into different registration groups alphabetically, by last name
- Results of a query
  - Groupings are a result of an external specification
- Graph partitioning
  - Some mutual relevance and synergy, but areas are not identical

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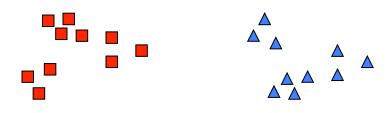


How many clusters?

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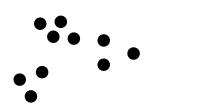


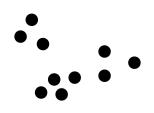
How many clusters?

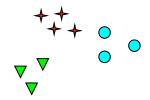


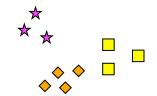
Two Clusters

Mauro Sozio



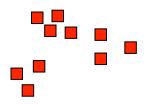


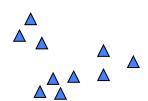




How many clusters?

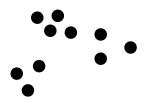
Six Clusters

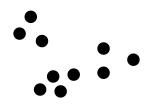


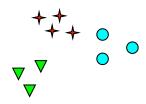


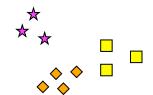
Two Clusters

Mauro Sozio



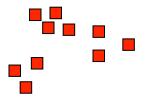


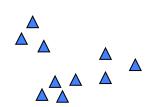


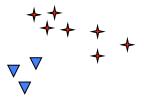


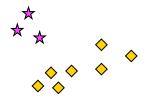
How many clusters?

Six Clusters









Two Clusters

Four Clusters

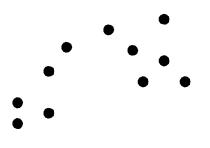
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## **Types of Clusterings**

- A clustering is a set of clusters
- Important distinction between hierarchical and partitional sets of clusters
- Partitional Clustering
  - A division data objects into non-overlapping subsets (clusters) such that each data object is in exactly one subset
- Hierarchical clustering
  - A set of nested clusters organized as a hierarchical tree

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# **Partitional Clustering**



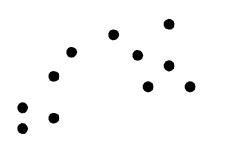
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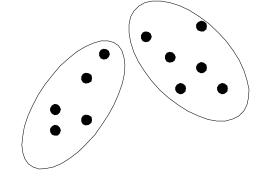
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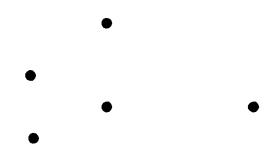
#### **Original Points**

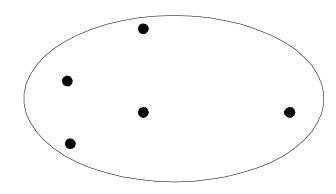
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# **Partitional Clustering**







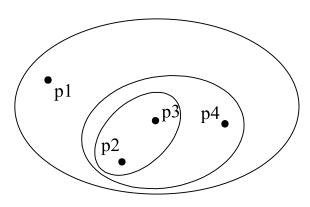


**Original Points** 

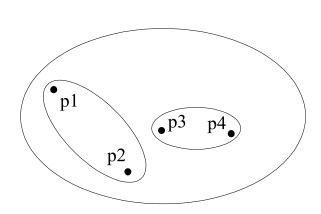
A Partitional Clustering

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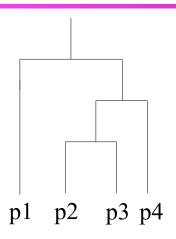
## **Hierarchical Clustering**



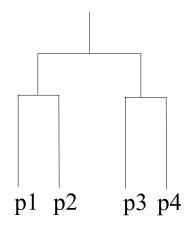
**Traditional Hierarchical Clustering** 



**Non-traditional Hierarchical Clustering** 



**Traditional Dendrogram** 



**Non-traditional Dendrogram** 

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### **Other Distinctions Between Sets of Clusters**

### Exclusive versus non-exclusive

- In non-exclusive clusterings, points may belong to multiple clusters.
- Can represent multiple classes or 'border' points

### Fuzzy versus non-fuzzy

- In fuzzy clustering, a point belongs to every cluster with some weight between 0 and 1
- Weights must sum to 1
- Probabilistic clustering has similar characteristics

### Partial versus complete

- In some cases, we only want to cluster some of the data
- Heterogeneous versus homogeneous
  - Cluster of widely different sizes, shapes, and densities

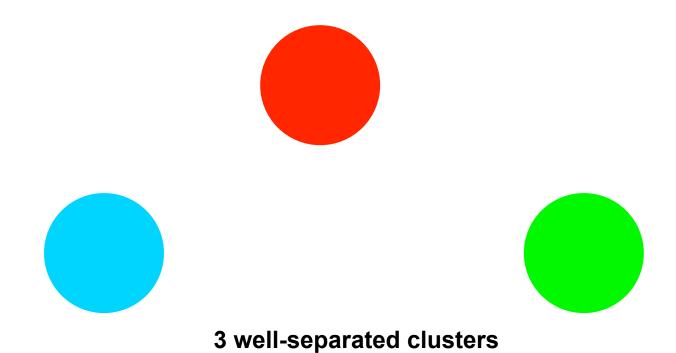
## **Types of Clusters**

- Well-separated clusters
- Center-based clusters
- Contiguous clusters
- Density-based clusters
- Property or Conceptual
- Described by an Objective Function

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### **Types of Clusters: Well-Separated**

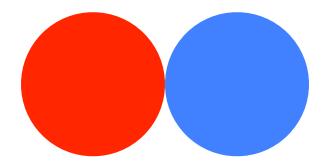
- Well-Separated Clusters:
  - A cluster is a set of points such that any point in a cluster is closer (or more similar) to every other point in the cluster than to any point not in the cluster.

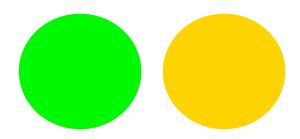


### **Types of Clusters: Center-Based**

### Center-based

- A cluster is a set of objects such that an object in a cluster is closer (more similar) to the "center" of a cluster, than to the center of any other cluster
- The center of a cluster is often a centroid, the average of all the points in the cluster, or a medoid, the most "representative" point of a cluster



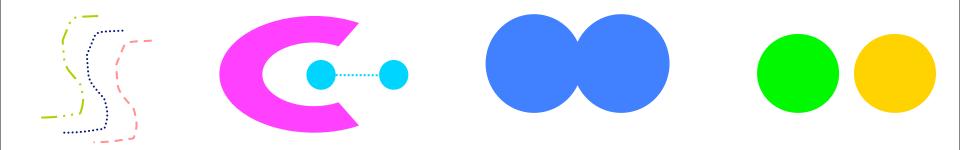


#### 4 center-based clusters

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## **Types of Clusters: Contiguity-Based**

- Contiguous Cluster (Nearest neighbor or Transitive)
  - A cluster is a set of points such that a point in a cluster is closer (or more similar) to one or more other points in the cluster than to any point not in the cluster.

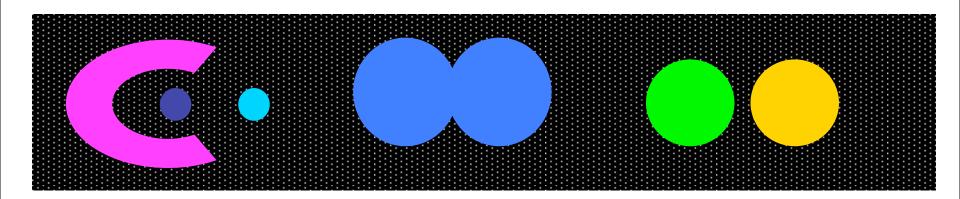


#### 8 contiguous clusters

## **Types of Clusters: Density-Based**

### Density-based

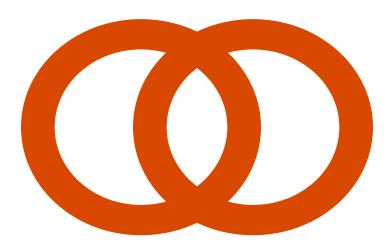
- A cluster is a dense region of points, which is separated by low-density regions, from other regions of high density.
- Used when the clusters are irregular or intertwined, and when noise and outliers are present.



#### 6 density-based clusters

### **Types of Clusters: Conceptual Clusters**

- Shared Property or Conceptual Clusters
  - Finds clusters that share some common property or represent a particular concept.



#### 2 Overlapping Circles

# **Clustering Algorithms**

- K-means
- K-means++
- Hierarchical clustering

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### **K-means Clustering**

**Input**: integer k>0, set S of points in the euclidean space

Output: A (partitional) clustering of S

- 1. Select k points in S as the initial centroids
- Repeat until the centroids do not change
   Form k clusters by assigning points to the closest centroids
   For each cluster recompute its centroid

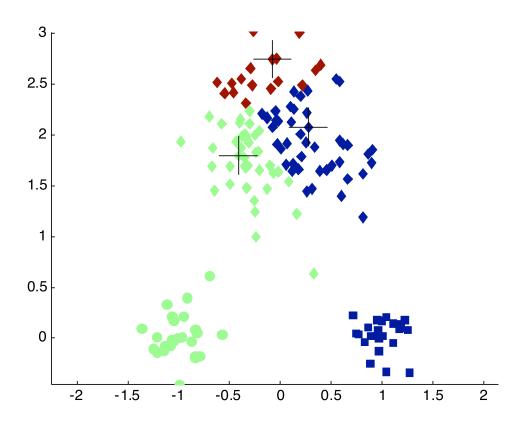
### **K-means Clustering**

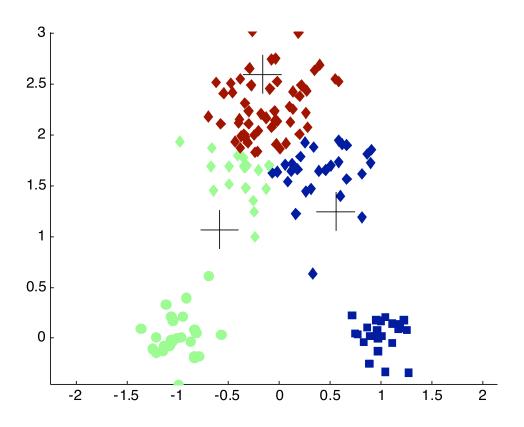
**Input**: integer k>0, set S of points in the euclidean space

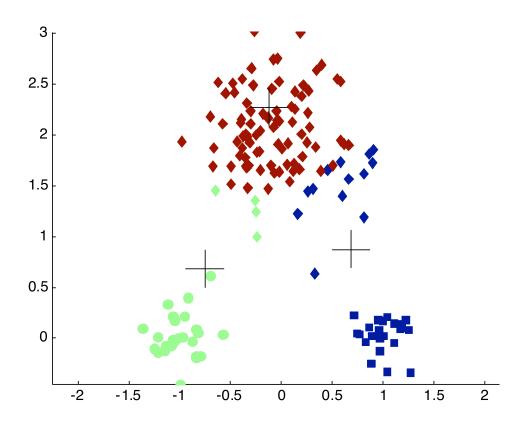
Output: A (partitional) clustering of S

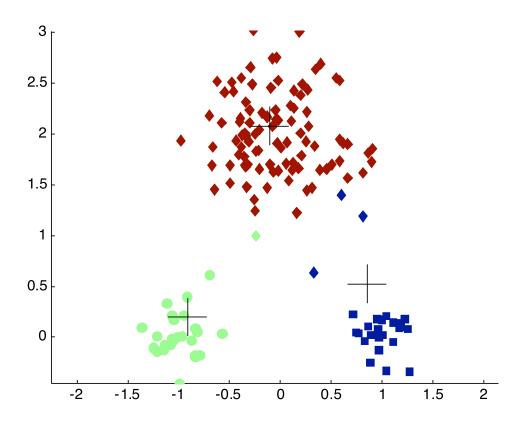
- 1. Select k points in S as the initial centroids
- Repeat until the centroids do not change
   Form k clusters by assigning points to the closest centroids
   For each cluster recompute its centroid
- Initial centroids are often chosen randomly.
- Centroids are often the mean of the points in the cluster.
- 'Closeness' is measured by Euclidean distance, cosine similarity, correlation, etc.

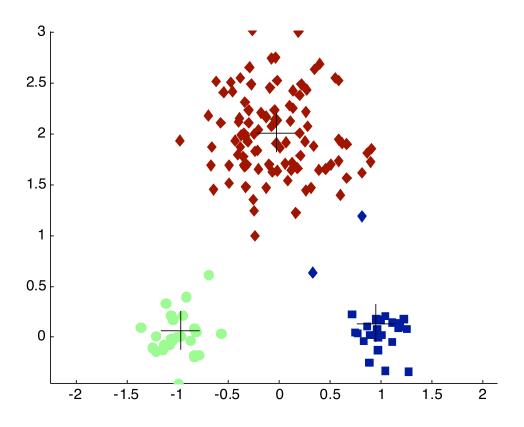
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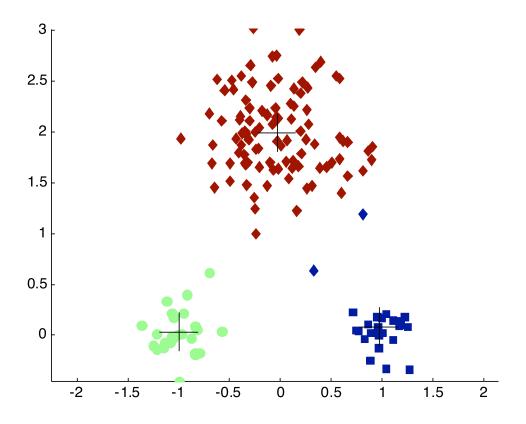


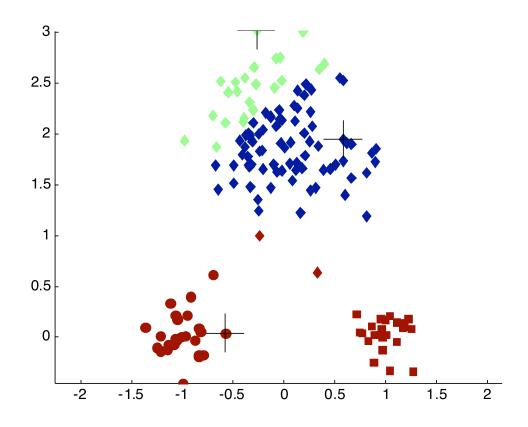


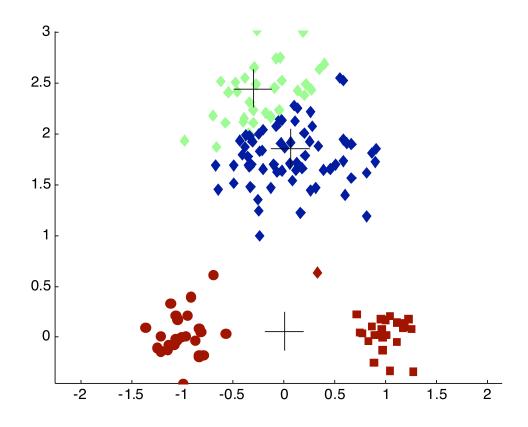


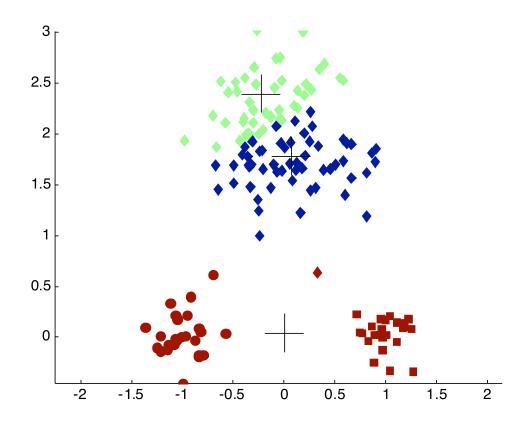


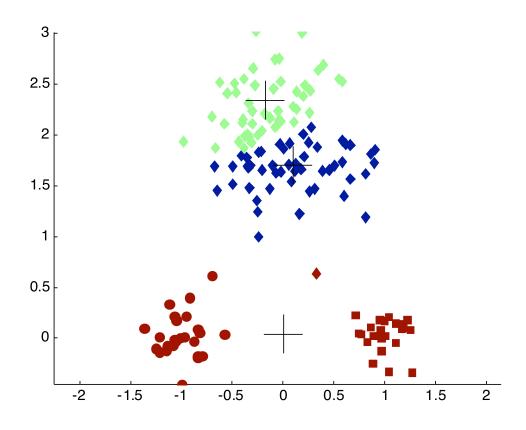


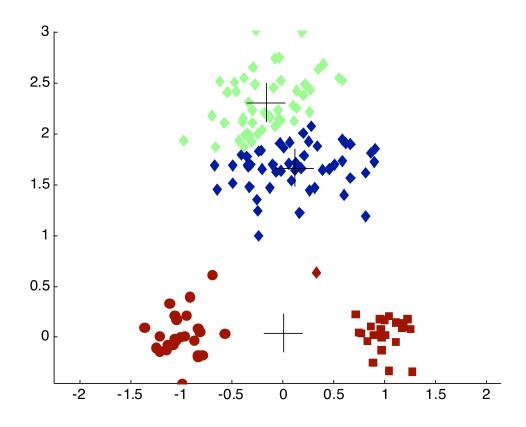




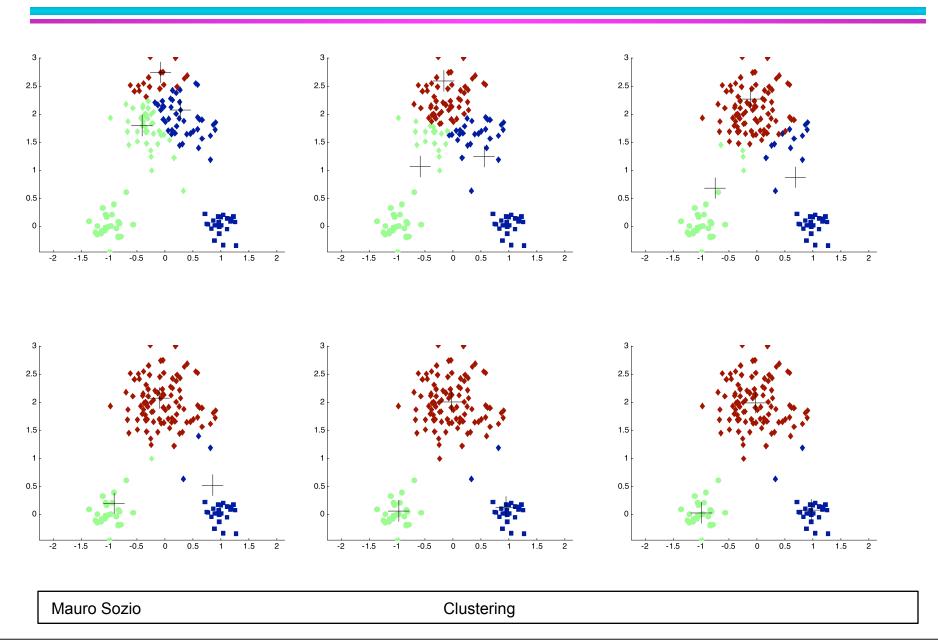






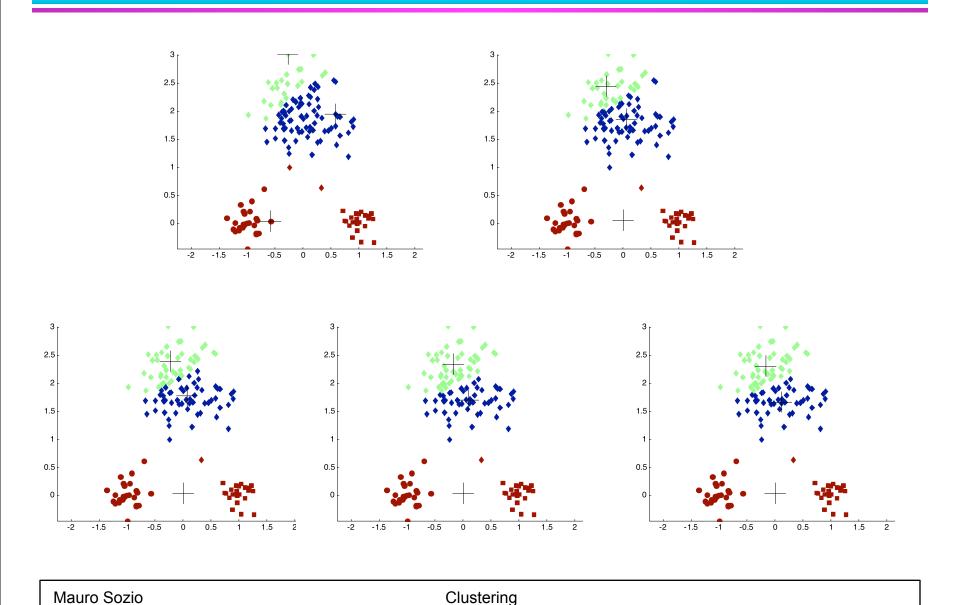


## **Importance of Choosing Initial Centroids**



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## **Importance of Choosing Initial Centroids ...**



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## **Problems with Selecting Initial Points**

- Input: k sets of points, n/k points per set.
- Points in a same set are very close, while points in different sets are far apart.
- If we don't select 1 point per set, doesn't work!

Prob. = 
$$\frac{\left(\frac{n}{k}\right)^k}{\binom{n}{k}} \approx \frac{k!}{k^k}$$

For example, if K = 10, then probability =  $10!/10^{10} = 0.00036$ .

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# **Evaluating K-means Clusterings**

Most common measure is Sum of Squared Error (SSE):

$$SSE = \sum_{i=1}^{K} \sum_{x \in C_i} dist^2(m_i, x)$$

- where x is a point in cluster C<sub>i</sub> and m<sub>i</sub> is the centroid of cluster C<sub>i</sub>
- Given two clusterings, we can choose the one with smallest error
- Decreasing K might decrease SSE. However, good clusterings with small K might have a lower SSE than poor clusterings with higher K.

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# K-means always terminates

- Theorem: K-means with euclidean distance as a measure of closeness always terminates.
- Proof (sketch): 1) the number of possible clusterings is finite (< n^k) 2) it can be shown that SSE strictly decreases. From 2) it follows that we cannot yield twice the same clustering. Hence, in the worst case we produce all possible clusterings.
- Observe that we need both 1) and 2).

#### **Solutions to Initial Centroids Problem**

- Multiple runs (helps but low success probability)
- Sample and use hierarchical clustering to determine initial centroids
- Select more than k initial centroids and then select among these initial centroids
- Postprocessing
- K-Means++

## **Handling Empty Clusters**

- Basic K-means algorithm can yield empty clusters. (Exercise)
- Several strategies:
  - Pick the points that contributes most to SSE and move them to empty cluster.
  - Pick the points from the cluster with the highest SSE
  - If there are several empty clusters, the above can be repeated several times.

# **Updating Centers Incrementally**

In the basic K-means algorithm, centroids are updated after all points are assigned to a centroid

- An alternative is to update the centroids after each assignment (incremental approach)
  - + Never get an empty cluster
  - Introduces an order dependency
  - More expensive

## **Pre-processing and Post-processing**

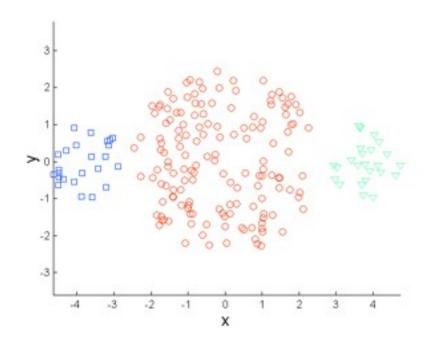
- Pre-processing
  - Normalize the data
  - Eliminate outliers
- Post-processing
  - Eliminate small clusters that may represent outliers
  - Split 'loose' clusters, i.e., clusters with relatively high SSE
  - Merge clusters that are 'close' and that have relatively low SSE

#### **Limitations of K-means**

- K-means has problems when clusters are of differing
  - Sizes
  - Densities
  - Non-globular shapes
- K-means has problems when the data contains outliers.

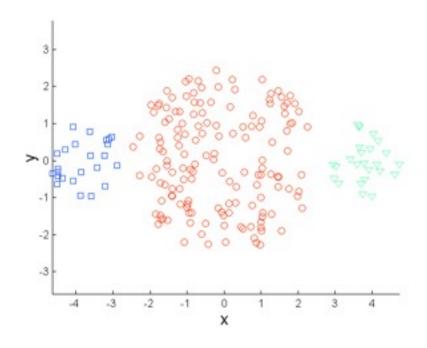
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## **Limitations of K-means: Differing Sizes**



**Original Points** 

## **Limitations of K-means: Differing Sizes**

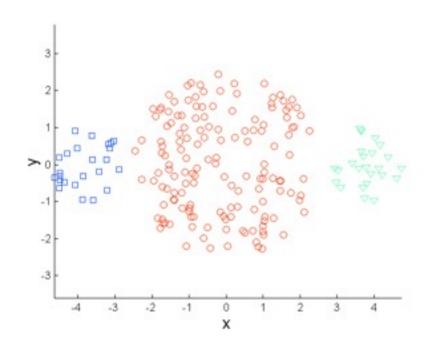


**Original Points** 

K-means (3 Clusters)

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## **Limitations of K-means: Differing Sizes**

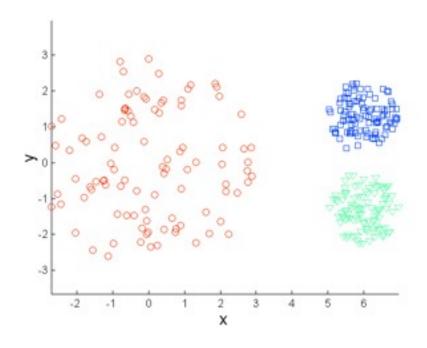


N 0 X

**Original Points** 

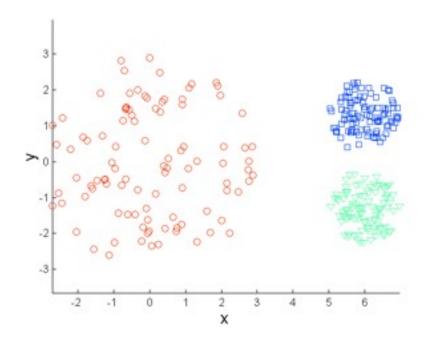
K-means (3 Clusters)

## **Limitations of K-means: Differing Density**



**Original Points** 

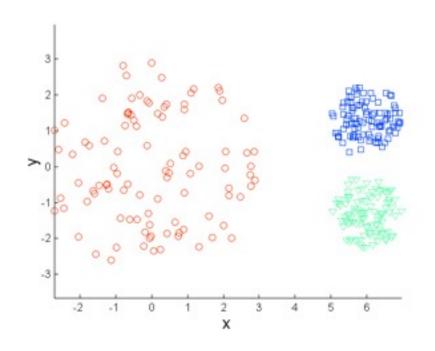
## **Limitations of K-means: Differing Density**

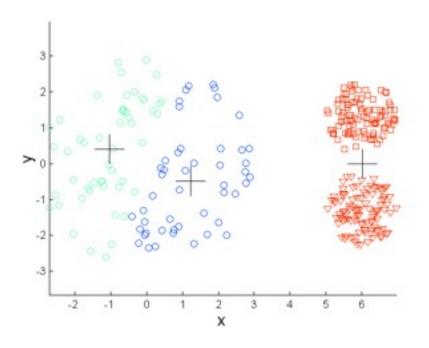


**Original Points** 

K-means (3 Clusters)

## **Limitations of K-means: Differing Density**

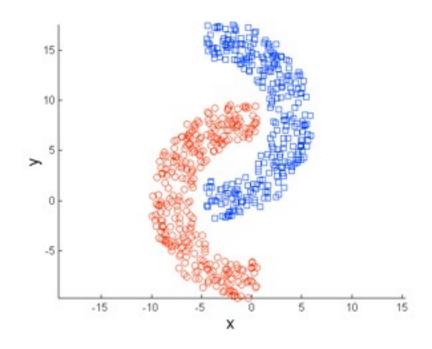




**Original Points** 

K-means (3 Clusters)

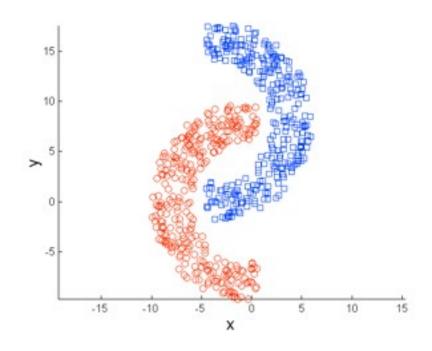
## **Limitations of K-means: Non-globular Shapes**



**Original Points** 

Mauro Sozio

## **Limitations of K-means: Non-globular Shapes**

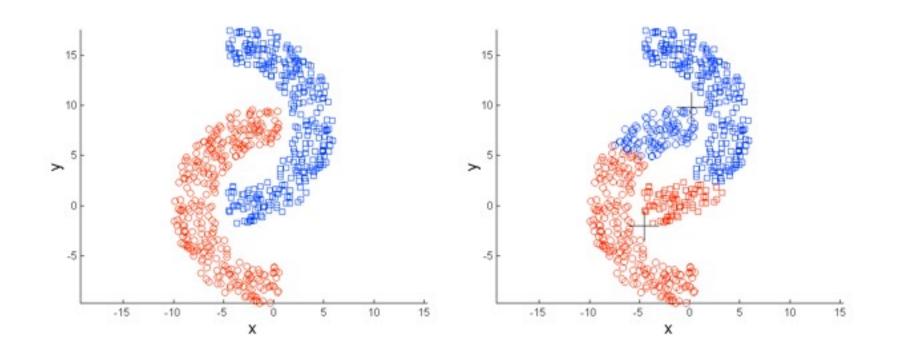


**Original Points** 

K-means (2 Clusters)

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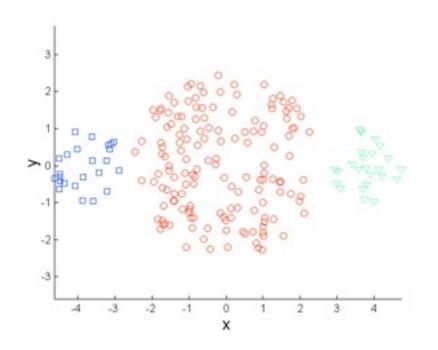
#### **Limitations of K-means: Non-globular Shapes**

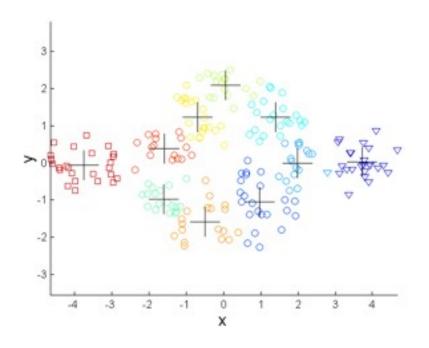


**Original Points** 

K-means (2 Clusters)

#### **Overcoming K-means Limitations**





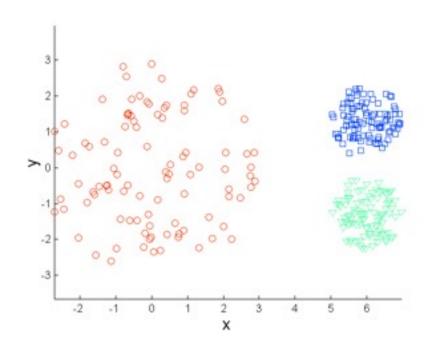
**Original Points** 

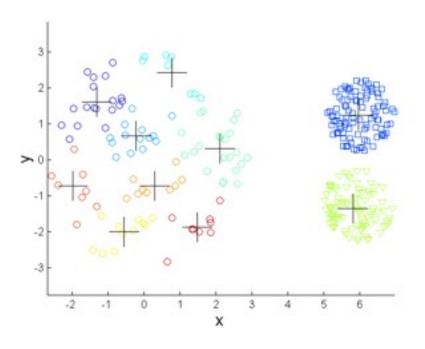
**K-means Clusters** 

One solution is to use many clusters.

Find parts of clusters, but need to put together.

## **Overcoming K-means Limitations**

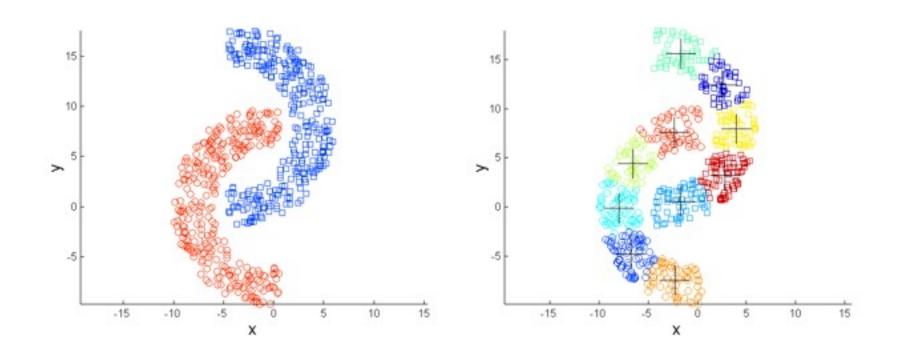




**Original Points** 

**K-means Clusters** 

## **Overcoming K-means Limitations**

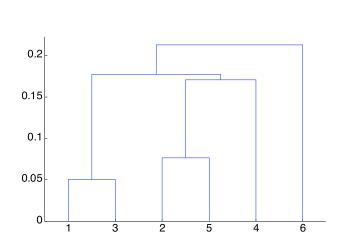


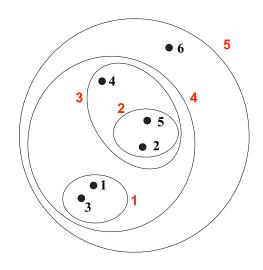
**Original Points** 

**K-means Clusters** 

# **Hierarchical Clustering**

- Produces a set of nested clusters organized as a hierarchical tree
- Can be visualized as a dendrogram
  - A tree like diagram that records the sequences of merges or splits





# **Strengths of Hierarchical Clustering**

- Do not have to assume any particular number of clusters
  - Any desired number of clusters can be obtained by 'cutting' the dendogram at the proper level
- They may correspond to meaningful taxonomies
  - Example in biological sciences (e.g., animal kingdom, phylogeny reconstruction, ...)

# **Hierarchical Clustering**

- Two main types of hierarchical clustering
  - Agglomerative:
    - Start with the points as individual clusters
    - At each step, merge the closest pair of clusters until only one cluster (or k clusters) left
  - Divisive:
    - Start with one, all-inclusive cluster
    - ◆ At each step, split a cluster until each cluster contains a point (or there are k clusters)
- Traditional hierarchical algorithms use a similarity or distance matrix
  - Merge or split one cluster at a time

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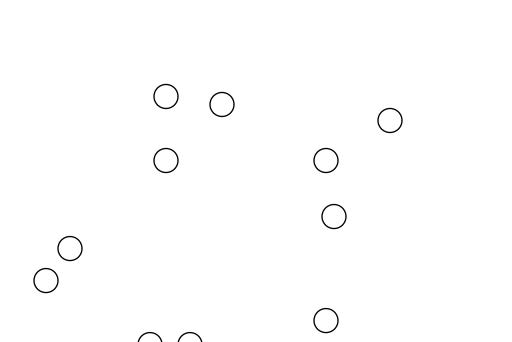
# **Agglomerative Clustering Algorithm**

- Most popular hierarchical clustering technique
- Algorithm:
  - 1. Let each data point be a cluster
  - Compute the distance matrix n x n
  - 2. Repeat
  - 3. Merge the two closest clusters
  - 4. Update distance matrix
  - **5. Until** only a single cluster remains

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## **Starting Situation**

Start with clusters of individual points and a distance matrix n x n



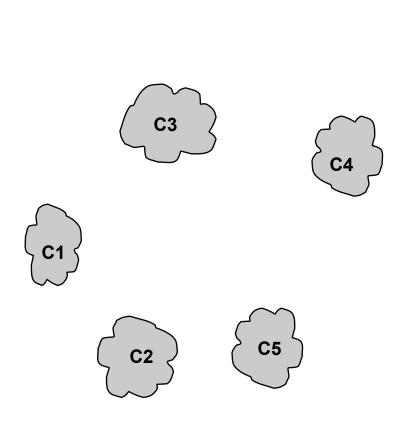
	<b>p1</b>	<b>p2</b>	рЗ	p4	р5	<u>L</u>
<b>p1</b>						
<b>p2</b>						
<u>p2</u> <u>p3</u>						
<u>p4</u> p5						
•						

Distance Matrix

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#### **Intermediate Situation**

After some merging steps, we have some clusters



	C1	C2	С3	C4	<b>C5</b>
<b>C1</b>					
<b>C2</b>					
<b>C3</b>					
C4					
<b>C5</b>					

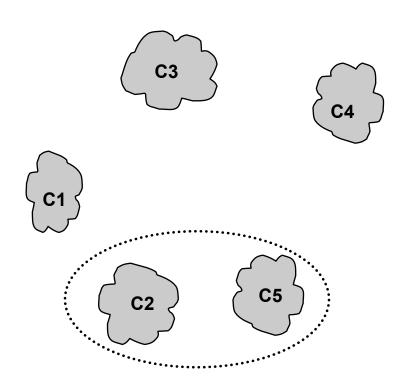
**Distance Matrix** 

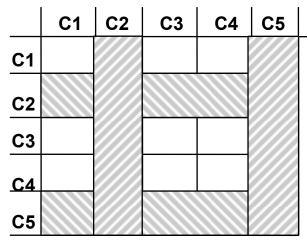
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#### **Intermediate Situation**

We want to merge the two closest clusters (C2 and C5) and

update the distance matrix.

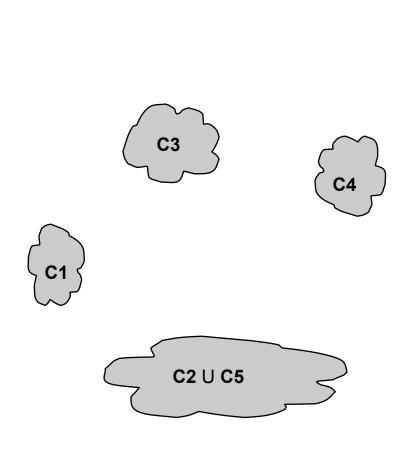




**Distance Matrix** 

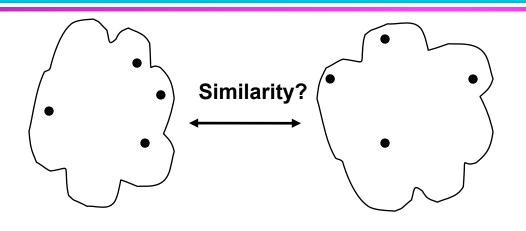
# **After Merging**

The question is "How do we update the distance matrix?"



			<b>C2</b> U		
		C1	U <b>C5</b>	C3	C4
	<b>C1</b>		?		
<b>C2</b> U	<b>C5</b>	?	?	?	?
	<b>C3</b>		?		
	<u>C4</u>		?		

**Distance Matrix** 

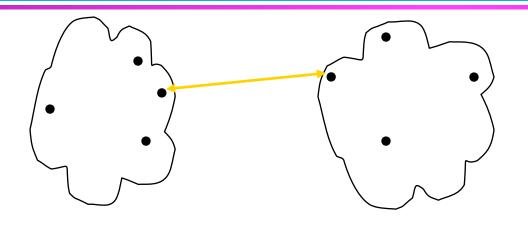


	p1	p2	р3	p4	<b>p</b> 5	<u>.</u> .
p1						
<b>p2</b>						
р3						
<b>p4</b>						
р5						

- MIN
- **I** MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

**Distance Matrix** 

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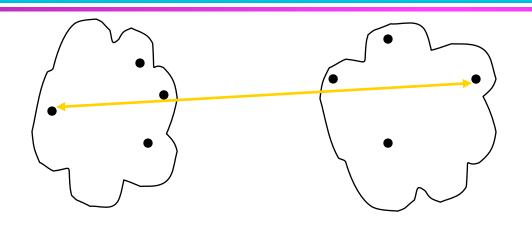


	<b>p1</b>	<b>p2</b>	р3	p4	<b>p</b> 5	<u>L</u> .
<b>p1</b>						
p2						
рЗ						
<b>p4</b>						
р5						

**Distance Matrix** 

- MIN
- MAX
- **Group Average**
- **Distance Between Centroids**
- Other methods driven by an objective function
  - Ward's Method uses squared error

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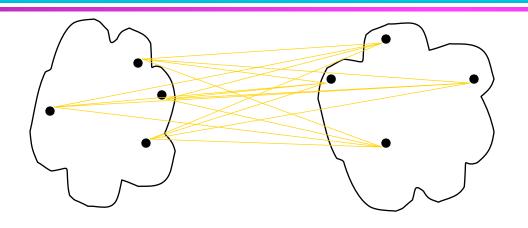


	p1	<b>p2</b>	р3	p4	<b>p</b> 5	<u>.</u> .
р1						
p2						
рЗ						
<b>p4</b>						
р5						

- MIN
- I MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

**Distance Matrix** 

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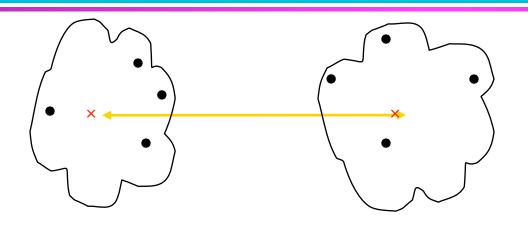


	<b>p1</b>	<b>p2</b>	рЗ	p4	<b>p</b> 5	<u> </u>
p1						
p2						
р3						
<b>p4</b>						
p5						
_						

- MIN
- **MAX**
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

**Distance Matrix** 

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	p1	p2	рЗ	p4	р5	<u>.</u> .
<b>p1</b>						
<b>p2</b>						
р3						
<b>p4</b>						
p4 p5						
_						

- MIN
- I MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective
  - function
    - Ward's Method uses squared error

Clustering

**Distance Matrix** 

#### **Hierarchical Clustering: Problems and Limitations**

- Once a decision is made to combine two clusters, it cannot be undone
- No objective function is directly minimized
- Different schemes have problems with one or more of the following:
  - Sensitivity to noise and outliers
  - Difficulty handling different sized clusters and convex shapes
  - Breaking large clusters

# **Cluster Validity**

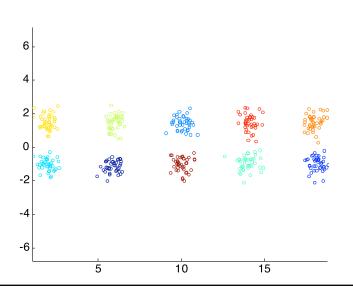
- For cluster analysis, the analogous question is how to evaluate the "goodness" of the resulting clusters?
- But "clusters are in the eye of the beholder"!
- Then why do we want to evaluate them?
  - To avoid finding patterns in noise
  - To compare clustering algorithms
  - To compare two sets of clusters
  - To compare two clusters

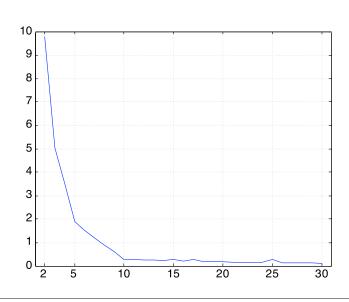
## **Measures of Cluster Validity**

- Numerical measures that are applied to judge various aspects of cluster validity, are classified into the following three types.
  - External Index: Used to measure the extent to which cluster labels match externally supplied class labels.
    - Entropy
  - Internal Index: Used to measure the goodness of a clustering structure without respect to external information.
    - Sum of Squared Error (SSE)
  - Relative Index: To compare two different clusterings or clusters.
    - ◆ An external or internal index is used for this function, e.g., SSE or entropy
- Sometimes these are referred to as criteria instead of indices

#### **Internal Measures: SSE**

- Clusters in more complicated figures aren't well separated
- Internal Index: Used to measure the goodness of a clustering structure without respect to external information
  - SSE
- SSE is good for comparing two clusterings or two clusters (average SSE).
- Can also be used to estimate the number of clusters





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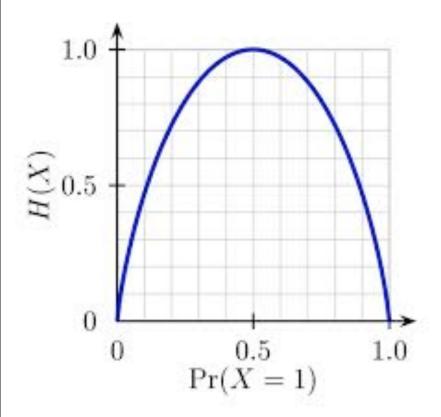
# **Entropy: definition**

Given a discrete random variable X with possible value {1,..,n} entropy is defined as

$$H(X) = -\sum_{i=1}^{n} P(X=i) \log_2 P(X=i)$$

I Entropy measure how **uncertain** is an event, the larger the entropy the more uncertain is the event

# **Entropy: intuition**



Entropy of a binary variable.

#### Examples:

- 1. entropy of unbiased coin vs biased coin?
- 2. entropy of a dice roll?
- 3. Probability distribution:  $P(X=c_i) = \text{probability of finding}$ character  $c_i$  in a text document. Easier to compress a document when entropy is high or low?

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#### **External Measures of Cluster Validity: Entropy**

Table 5.9. K-means Clustering Results for LA Document Data Set

Cluster	Entertainment	Financial	Foreign	Metro	National	Sports	Entropy	Purity
1	3	5	40	506	96	27	1.2270	0.7474
2	4	7	280	29	39	2	1.1472	0.7756
3	1	1	1	7	4	671	0.1813	0.9796
4	10	162	3	119	73	2	1.7487	0.4390
5	331	22	5	70	13	23	1.3976	0.7134
6	5	358	12	212	48	13	1.5523	0.5525
Total	354	555	341	943	273	738	1.1450	0.7203

Topics={Entertainment, Financial, Metro,...}= $\{1,2,3,...k\}$   $p_{ij}$ = Probability that an element of cluster j belongs to topic i. E.g.  $p_{13}$ =1/685

For a cluster j better to have higher or lower entropy?

#### **External Measures of Cluster Validity: Entropy**

Table 5.9.	K-means Clustering	Results for LA	Document Data Set
------------	--------------------	----------------	-------------------

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Total	354	555	341	943	273	738	1.1450	0.7203

m<sub>j</sub>= size of cluster j, m=number of docs.

Entropy and purity of a cluster

$$e_j = -\sum_{i=1}^{\kappa} p_{ij} \log p_{ij}$$
 purity<sub>j</sub> = max<sub>i</sub>  $p_{ij}$ 

Entropy and purity of a clustering:

$$\sum_{j} \frac{m_{j}}{m} e_{j}$$
  $\sum_{j} \frac{m_{j}}{m} purity_{j}$ 

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## **Final Comment on Cluster Validity**

"The validation of clustering structures is the most difficult and frustrating part of cluster analysis.

Without a strong effort in this direction, cluster analysis will remain a black art accessible only to those true believers who have experience and great courage."

Algorithms for Clustering Data, Jain and Dubes

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#### k-means++

#### Algorithm 1 k-means++(k) initialization.

- 1:  $\mathcal{C} \leftarrow$  sample a point uniformly at random from X
- 2: while  $|\mathcal{C}| < k$  do
- 3: Sample  $x \in X$  with probability  $\frac{d^2(x,C)}{\phi_X(C)}$
- 4:  $\mathcal{C} \leftarrow \mathcal{C} \cup \{x\}$
- 5: end while

where:

$$d(x,C) = \min_{c \in C} d(x,c), \quad \Phi_X(C) = \sum_{x \in X} d^2(x,C)$$

 $d^2(x,C)$  measures how "good" is the clustering for point x. Points that are *relatively* far away from "their" centroids will be selected with higher probability.

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#### K-means ++

- K-means++:
  - Initialize the centroids as in Algorithm 1
  - Run K-means algorithm to improve the clustering.

Theorem: Let C\_KM++ be the clustering produced by the K-means++ algorithm, let C\_opt be an optimal clustering (with minimum SSE among all possible clusterings). Then, SSE(C\_KM++) <= 8\*(In k + 2)\*SSE(C\_opt), on expectation (average).

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## **Algorithms**

- K-means:
  - no guarantees on the quality of the solution
  - it always terminates
  - running time could be exponential but it is OK in practice
- K-means++
  - it always terminates
  - O(log k)-approximation on the quality of the solution.
  - In practice the advantage is noticeable for large k

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