Computational Fabrication (Fall, 2017)

Prof. Shinjiro Sueda

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#### 3D Scanning Report (Assignment #3a)

#### 1. Introduction

• Team Member: Ying Wang, Yura Hwang

• Used Device: Microsoft Kinect V1

• O/S: Microsoft Windows

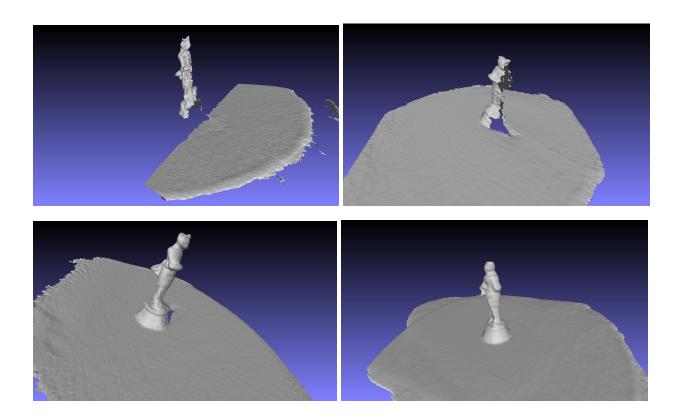
• Software Version: Kinect Fusion Explorer-WPF

## 2. Scanning Difficulties

• Statue of Baron



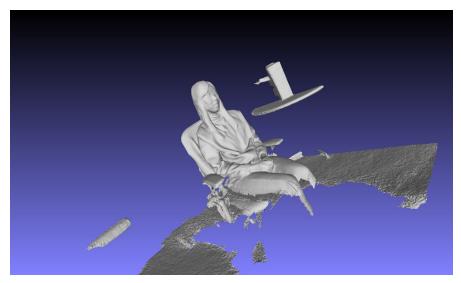
- Statue of Baron (from one of Miyazaki's films)
- Small sized, with various subtle details
- Fairly easy to scan (small scanning range)
- However most details were lost during the scanning process (whiskers, cane, top hat, etc.)
- Very hard to adjust distance and depth along with parameters
  - Often produce an indistinguishable 'lump'
  - Team's need for bigger objects for scans

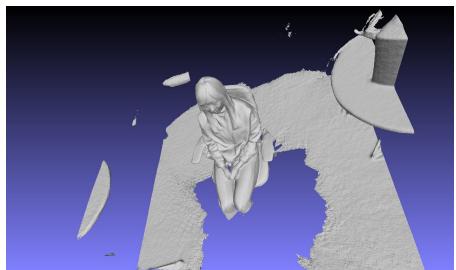


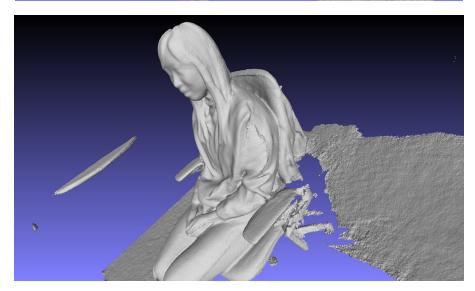
#### Ourselves

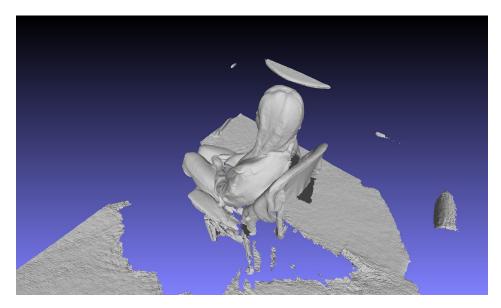
- Inspired by our need for bigger objects for scans
- If stayed motionless (seated), the outcome was decent
- If it was an unstable pose (standing on one leg) the outcome was also unstable, resulting in more holes and cracked surfaces
- Nevertheless, both outcomes contained holes in blind spots (spaces between torso, spots between hair and neck, wrinkles from clothes)
- Harder to scan, compared to Statue of Baron (large scanning range)
- Lots of parts were being cut off, and the system would crash or freeze easily in the middle of scanning process
- Too many unnecessary scans from background

# > Ying



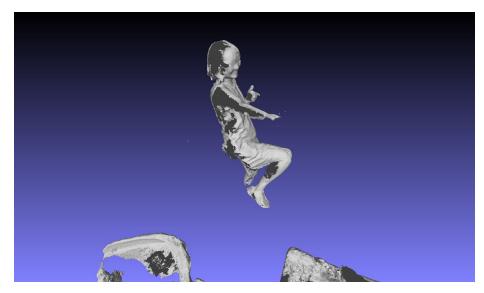


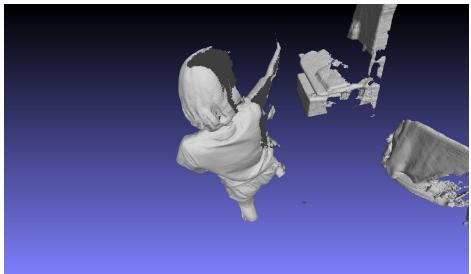




> Yura

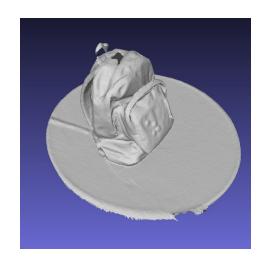


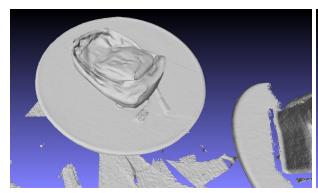


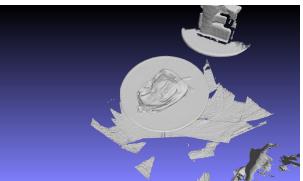




- Backpack
- Inadvertently scanned a backpack
- Great outcome which was unexpected!
- Decided to choose it as our final object



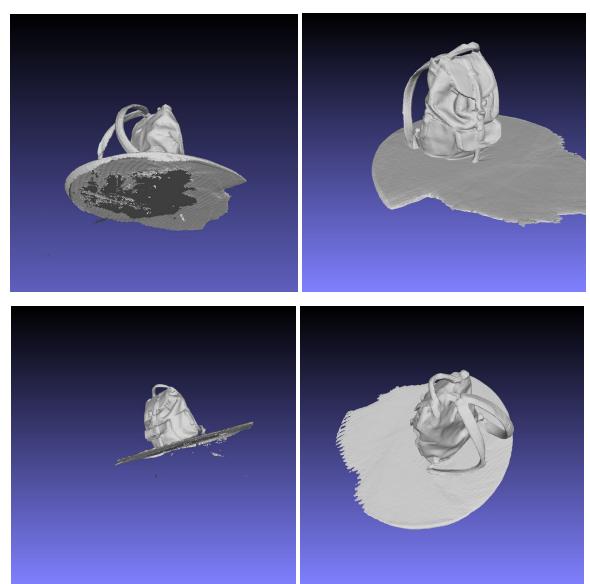




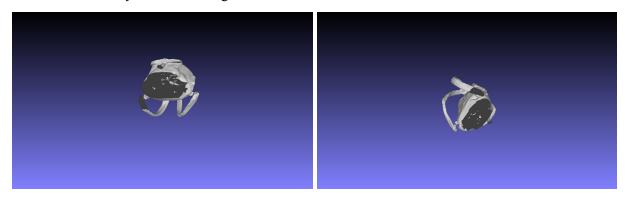


- Our final resort
- Appropriate size (about 17 inches)
- Included number of details (wrinkles, pockets, belts, etc.) which was appropriate for scanning
- Temporarily encountered an error after Poisson Surface Reconstruction (generated strange hole at the bottom), but we were able to get a correct outcome by overgoing Mesh-Clean Up stages from the beginning

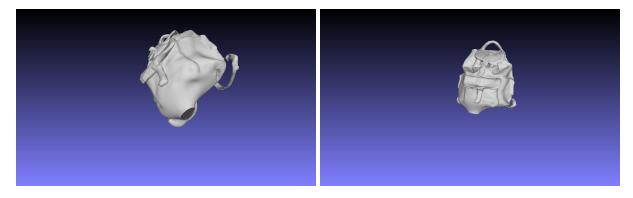
## > Raw



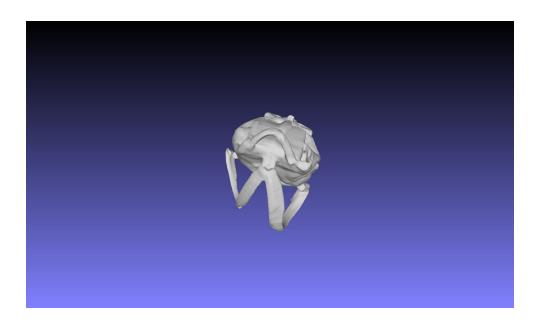
## > Unnecessary Vertices/Triangles Removed

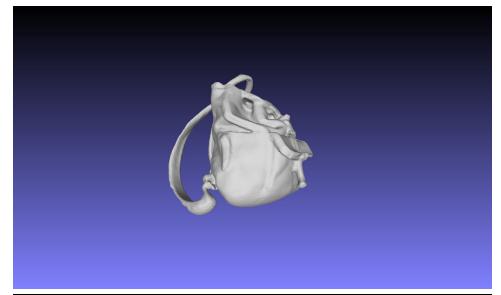


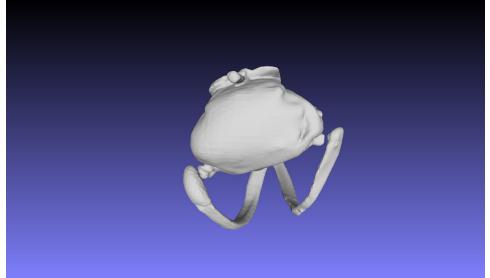
## > Poisson Error

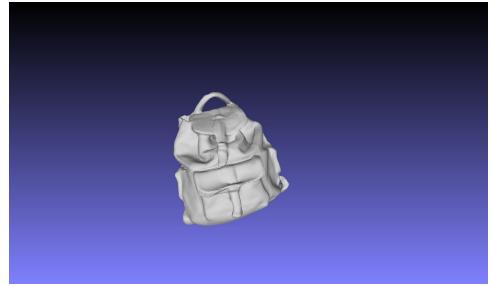


## 3. Final Results









## 4. Final Comments

- Had a great fun scanning various objects
- Learned scanning process could be affected by various factors which we normally considered not important (depth, distance, details, sizes, etc.)
- Learned not every scanning process was automated--there came a time that user's control was essential to get a more desired outcome (such as cleaning up the vertices manually )

