

# Project On Parameterization

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Noam Aigerman, Yaron Lipman (2015)

Orbifold Tutte Embeddings

*ACM Transactions on Graphics (TOG) - Proceedings of ACM SIGGRAPH Asia 2015, 34(6)*



Noam Aigerman, Yaron Lipman (2016)

Hyperbolic Orbifold Tutte Embeddings

*ACM Transactions on Graphics (TOG) - Proceedings of ACM SIGGRAPH Asia 2016, 35(6)*



Rohan Sawhney, Keenan Crane (2017)

Boundary First Flattening

*ACM Transactions on Graphics (TOG) (Under Review)*

# Overview

- ① Project Overview
- ② Orbifold Tutte Embedding
- ③ Boundary First Flattening

# Project Components

## **Orbifold Embedding**

Generalization of Tutte embedding to sphere-type mesh.

I explore two kinds of background geometry: Euclidean and hyperbolic.

## **Boundary First Flattening**

Based on differential geometry.

Conformal map.

Handle curvature and conformal factors directly.

With cone technique, can be generalize to meshes with slices.

## Tutte Embedding

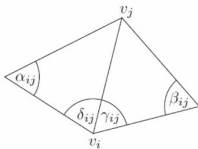
The embedding problem is the following full-rank linear system:

$$\sum_{v_j \in N(v_i)} w_{ij}(z_j - z_i) = 0, \quad v_i \in V - B$$

$$z_i = z_i^0, \quad v_i \in B$$

where  $w > 0$ .

**Harmonic Map:**  $w_{ij} = \frac{\cot \alpha_{ij} + \cot \beta_{ij}}{2}$



# Tutte Embedding Equivalence

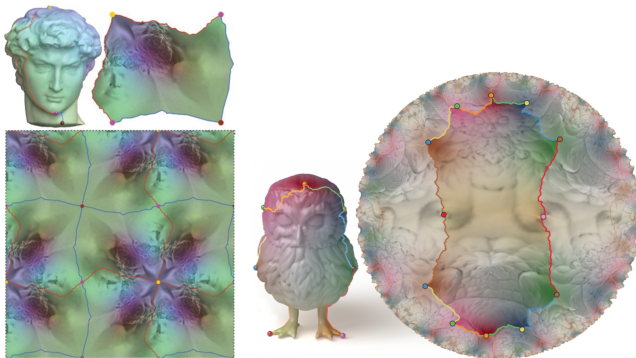
$$\begin{aligned} \min_{\Phi} \quad & E(z) = \frac{1}{2} \sum_{(i,j) \in E} w_{ij} d(z_i, z_j)^2 \\ \text{s.t.} \quad & z_i = z_i^0, \quad v_i \in B \end{aligned}$$

# Orbifold

Tiled space defined by a basic tile.

Points differed by a transition between copies are equivalence.

Transition: rigid motions.



# Euclidean Orbifold Tutte Embedding

Select some cones and cut the mesh into a disk, we solve:

For  $v_i \in \bar{V} - \bar{B}$ :

$$\sum_{v_j \in N(v_i)} w_{ij}(z_j - z_i) = 0$$

For  $(v_i, v_{i'})$  boundary pair,

$$\sum_{v_j \in N(v_i)} w_{ij}(z_j - z_i) + \sum_{v_j \in N(v_{i'})} w_{i'j} R_{i'i}(z_j - z_{i'}) = 0$$
$$R_{i'i} z_{i'} - z_i = t_{ii'}$$

For  $v_i \in \bar{C}$ ,

$$z_i = z_i^0$$



# Hyperbolic Tutte Embedding

$$\begin{aligned} & \min_{\phi} E(z), \\ \text{s.t. } & z_i = m_{i'i}(z_{i'}), \quad v_i \in \bar{B} - \bar{C} \\ & z_i = z_i^0, \quad v_i \in \bar{C} \end{aligned}$$

The gradient of the energy is given by

$$\nabla_{z_i} E = \sum_{j \in N_i} w_{ij} \nabla_{z_i} d^2(z_i, z_j) + \sum_{j \in N_{i'}} w_{i'j} \nabla_{z_i} d^2(z_i, m_{i'i}(z_j))$$

# Poisson Problems

Dirichlet-type condition:

$$\begin{aligned}\Delta a &= \phi && \text{on } M \\ a &= g, && \text{on } \partial M\end{aligned}\tag{1}$$

Riemann-type condition:

$$\begin{aligned}\Delta a &= \phi && \text{on } M \\ \frac{\partial a}{\partial n} &= h, && \text{on } \partial M\end{aligned}\tag{2}$$

Discrete version (Riemann):

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{BI} & A_{BB} \end{bmatrix} \begin{bmatrix} a_I \\ a_B \end{bmatrix} = \begin{bmatrix} \phi_I \\ \phi_B - h \end{bmatrix}\tag{3}$$

# Conversion between Dirichlet and Riemann

Given  $h$ , we simply solve the Poisson equation and set

$$g = \Lambda_{\phi}^* h = a_B, \quad (4)$$

Given  $g$ , we can convert it to  $h$  by

$$h = \Lambda_{\phi} g = \phi_B - A_{IB}^T A_{II}^{-1} (\phi_I - A_{IB} g) - A_{BB} g \quad (5)$$

## Cherrier Formula

For a conformal map  $f : M \rightarrow \tilde{M}$ , we have

$$\begin{aligned}\Delta u &= K - e^{2u} \tilde{K} \quad \text{on } M \\ \frac{\partial u}{\partial n} &= k - e^u \tilde{k} \quad \text{on } \partial M\end{aligned}\tag{6}$$

where  $u$  is conformal factor,  $K, \tilde{K}$  are Gauss curvature of the source surface and the target surface,  $k, \tilde{k}$  is geodesic curvature of the source surface and the target surface.

## Discrete Cherrier Formula

$$\begin{aligned} Au &= \Omega - \tilde{\Omega} \quad \text{on } \text{Int } M \\ h &= k - \tilde{k} \quad \text{on } \partial M \end{aligned} \tag{7}$$

where  $\Omega_i = 2\pi - \sum_{ijk \in F} \theta_i^{jk}$  defined on interior vertices,  
 $k_i = \pi - \sum_{ijk \in F} \theta_i^{jk}$  defined on boundary vertices, which is the exterior angle at  $v_i$ . Note that  $\Omega$  is defined to be zero at boundary vertices.

## Algorithm

The pipeline of the BFF algorithm is as follows:

1) If boundary conformal factor  $u$  is known, we compute boundary target  $k$  by:

$$\tilde{k} = k - \Lambda_{\Omega} u.$$

If target boundary  $\tilde{k}$  is known, we compute boundary conformal factor  $u$  by::

$$u = \Lambda_{\Omega}^*(k - \tilde{k}).$$

2) Define new boundary edge lengths as:

$$l_{ij}^* = e^{\frac{u_i + u_j}{2}} l_{ij}.$$

With  $\tilde{k}$ , which is exterior angles, we can integrate these two data into a closed loop.

3) Extend the loop into interior conformally.

## Loop Integration

In step 2, usually, directly integrating  $\tilde{k}$  over  $l_{ij}^*$  won't give a closed loop, we should change edge length a little. So we solve the following quadratic optimization problem:

$$\begin{aligned} \min_{\tilde{l}} \quad & ||\tilde{l} - l^*||_2^2 \\ \text{s.t.} \quad & \sum_{ij \in \partial M} \tilde{l}_{ij} \tilde{T}_{ij} \end{aligned} \tag{8}$$

# Conformal Interpolation

Two choice:

- 1) Use harmonic map on both components
- 2) Use harmonic map on one componet, and minimize conformal energy on the other component. Linear problem.



## Video Demo

GitHub: xuan-li

(<https://github.com/xuan-li/GraphicsProject>)