Python and Numerical Methods

Physics Simulation

Objectives

- Python Ecosystem
- Performance Tests
- Examples 2D simulation

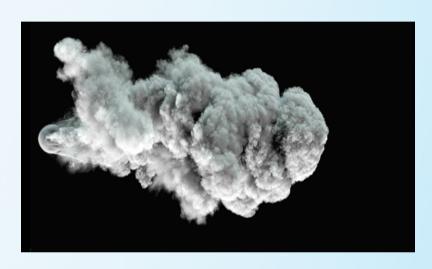
Concepts

Physics Simulation

Physics Simulation

Basic Concepts





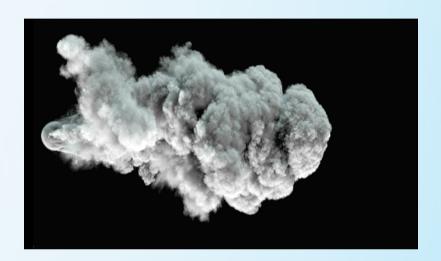


Physics Simulation

Basic Concepts



Point / Navier Stokes



Cell / Navier Stokes



Triangles / Hookes Law

Prototype

- N-dimensional array
- Apply function on multiple data (array)
- Easy to code, do not re-invent the wheel
- Fast to evaluate a simulation
- Open Source

Prototype

- N-dimensional array
- Apply function on multiple data (array)
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- Open Source

C++ is fast but bad for prototyping... Lets find something else!

Python Ecosystem

Numerical Methods





- N-dimensional array
- Memory alignment

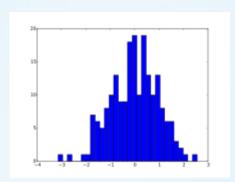


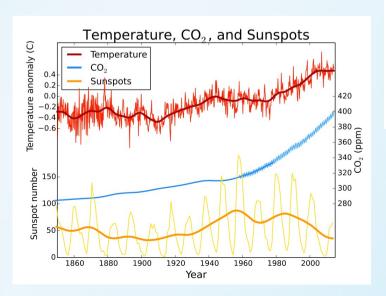


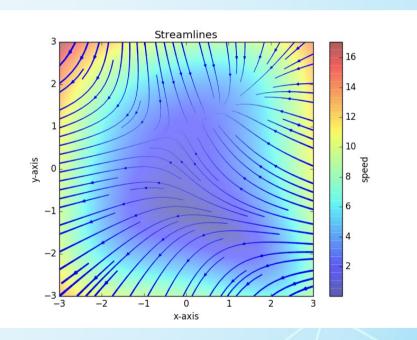
- Optimization
- Linear Algebra
- Signal Processing
- **ODE Solver**









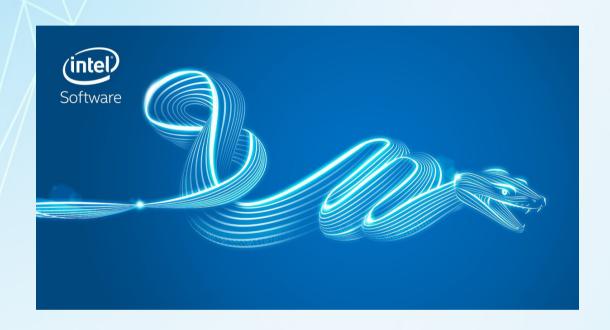






- Translates Python functions to optimized machine code at runtime
- CPU and GPU support





Accelerate compute-intense applications—including numeric, scientific, data analytics, machine learning-that use NumPy, SciPy

Performance Tests

1D-Array Test

Numba Introduction

Objectives

- . Update random array with function
- . Test Numba

```
def create_data(N):
    return np.random.rand(N)
```

```
def function(value):
    return math.sqrt(math.tan(value) * value * math.cos(value))
```

```
def run(array):
    for i in range(array.shape[0]):
        array[i] = function(array[i])
    return array
```

	Standard	Numba	Numba Parallel
1e6	0.295 sec		
1e7	3.01 sec		
1e8	29.50 sec		
1e9	-		

1D-Array Test

Numba Introduction

Objectives

- . Update random array with function
- . Test Numba

def create_data(N):

```
return np.random.rand(N)

@njit
def function(value):
```

return math.sqrt(math.tan(value) * value * math.cos(value))

@njit

```
def run(array):
    for i in range(array.shape[0]):
        array[i] = function(array[i])
    return array
```

	Standard	Numba	Numba Parallel
1e6	0.295 sec	0.009 sec	
1e7	3.01 sec	0.069 sec	
1e8	29.50 sec	0.689 sec	
1e9	-	10.939 sec	

1D-Array Test

Numba Introduction

Objectives

- . Update random array with function
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```
def create_data(N):
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@njit
```

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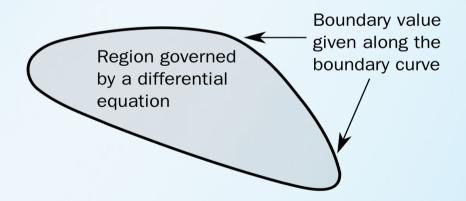
```
@njit(parallel=True)
def run(array):
    for i in prange(array.shape[0]):
        array[i] = function(array[i])
    return array
```

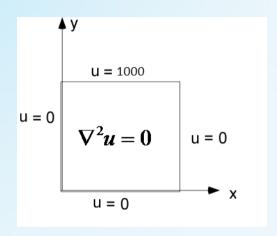
	Standard	Numba	Numba Parallel
1e6	0.295 sec	0.009 sec	0.002 sec
1e7	3.01 sec	0.069 sec	0.016 sec
1e8	29.50 sec	0.689 sec	0.165 sec
1e9	-	10.939 sec	1.681 sec

Boundary value problem

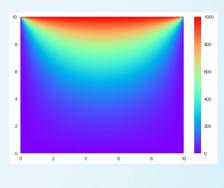
Objectives

- . Solve Laplace's Equation
- . CPU / GPU
- . Stencil operations



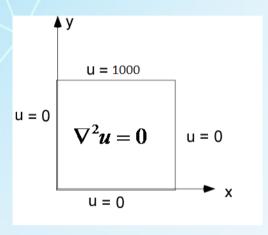


Problem



Solution

Boundary value problem

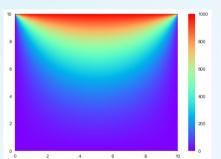


Solve a linear system Au = b

A: sparse matrix [N², N²]

u : unknown [N^2] b : zero vector [N^2]

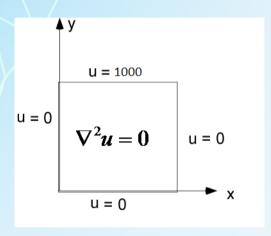
N : number of values along on axis (x, y)

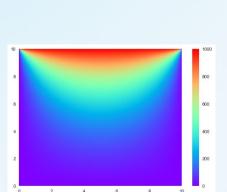




Solve Au = b with Jacobi Iterative Method

Boundary value problem





olve a linear system Au = b

A: sparse matrix [N^2, N^2]

u : unk. own [N^2]

b : zero v ctor [N^2]

N : number of alugalong on axis (x, y)



Solve Au = b with Jacobi Iterate Method

```
def create_domain(N):
  values = zeros((num_nodes, num_nodes), np.float)
  values[num nodes-1:num nodes] = 1000.0
def iteration(x, next_x):
  num_dof_x = x.shape[0]
  num_dof_y = x.shape[1]
  for i in range(1, num_dof_x - 1):
     for j in range(1, num_dof_y - 1):
       next_x[i][j] = (x[i - 1][j] +
                     x[i + 1][j] +
                     x[i][j - 1] +
                     x[i][i + 1]) * 0.25
```

	Standard	Numba	Numba Parallel	Numba Cuda
64x64 2000 iter				
128x128 10000 iter.				
256x256 50000 iter.				
512x512 250000 iter.				

```
def create_domain(N):
    values = zeros((num_noc
    values[num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:num_nodes-1:
```

```
def iteration(x, next_x):
    num_dof_x = x.shape[0]
    num_dof_y = x.shape[1]
```

	Standard	Numba	Numba Parallel	Numba Cuda
64x64 2000 iter	9.696 sec			
128x128 10000 iter.	-			
256x256 50000 iter.	-			
512x512 250000 iter.	-			

```
def create_domain(N):
  values = zeros((num_nodes, num_nodes), np.float)
  values[num nodes-1:num nodes] = 1000.0
@njit
def iteration(x, next_x):
  num dof x = x.shape[0]
  num_dof_y = x.shape[1]
  for i in range(1, num_dof_x - 1):
     for j in range(1, num_dof_y - 1):
       next_x[i][j] = (x[i - 1][j] +
                     x[i + 1][j] +
                     x[i][j - 1] +
                     x[i][j + 1]) * 0.25
```

	Standard	Numba	Numba Parallel	Numba Cuda
64x64 2000 iter	9.696 sec	0.007 sec		
128x128 10000 iter.	-	0.133 sec		
256x256 50000 iter.	-	2.459 sec		
512x512 250000 iter.	-	50.343 sec		

```
def create_domain(N):
  values = zeros((num_nodes, num_nodes), np.float)
  values[num nodes-1:num nodes] = 1000.0
@njit(parallel=True)
def iteration(x, next_x):
  num_dof_x = x.shape[0]
  num_dof_y = x.shape[1]
  for i in prange(1, num_dof_x - 1):
     for j in range(1, num_dof_y - 1):
       next_x[i][j] = (x[i - 1][j] +
                     x[i + 1][j] +
                     x[i][j - 1] +
                     x[i][j + 1]) * 0.25
```

	Standard	Numba	Numba Parallel	Numba Cuda
64x64 2000 iter	9.696 sec	0.007 sec	0.012 sec	
128x128 10000 iter.	-	0.133 sec	0.131 sec	
256x256 50000 iter.	-	2.459 sec	1.401 sec	
512x512 250000 iter.	-	50.343 sec	19.872 sec	

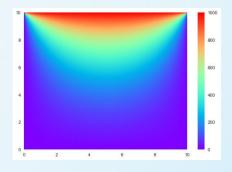
Boundary value problem

```
def create_domain(N):
    values = zeros((num_nodes, num_nodes), np.float)
    values[num_nodes-1:num_nodes] = 1000.0
```

@cuda.jit

	Standard	Numba	Numba Parallel	Numba Cuda
64x64 2000 iter	9.696 sec	0.007 sec	0.012 sec	0.34 sec
128x128 10000 iter.	-	0.133 sec	0.131 sec	1.21 sec
256x256 50000 iter.	-	2.459 sec	1.401 sec	5.56 sec
512x512 250000 iter.	-	50.343 sec	19.872 sec	27.30 sec

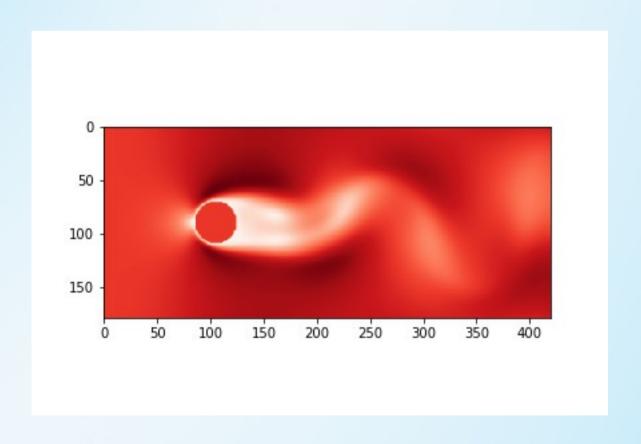
Stencil Operations		Standard	Numba	Numba Parallel	Numba Cuda
8.192.000	64x64 2000 iter	9.696 sec	0.007 sec	0.012 sec	0.34 sec
163.840.000	128x128 10000 iter.	-	0.133 sec	0.131 sec	1.21 sec
3.276.800.000	256x256 50000 iter.	-	2.459 sec	1.401 sec	5.56 sec
65.536.000.000	512x512 250000 iter.	-	50.343 sec	19.872 sec	27.30 sec



Examples

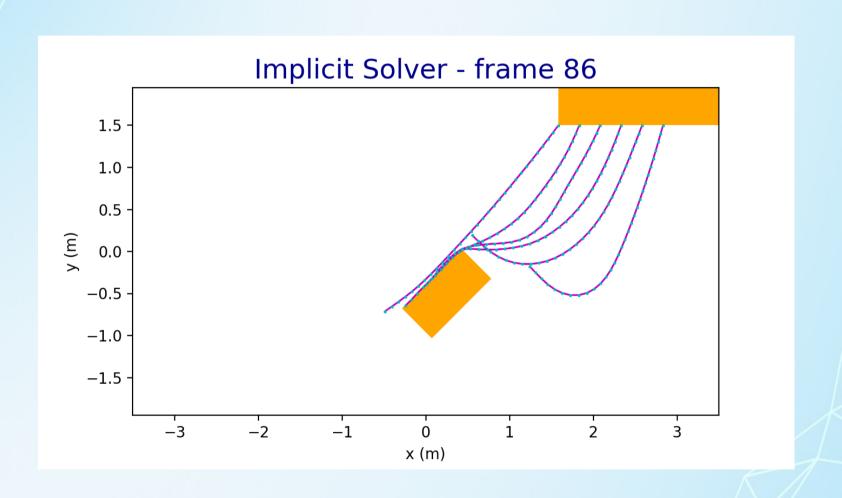
2D - Fluid Simulation

Lattice Boltzmann



2D - Elastic Deformation

FEM - Implicit Solver



Conclusion

- Fail Fast Development is an iterative process
- Focus more on problem-solving and developing interesting programs

Next Step

- 2D => 3D
- More complex examples
- Debugging / Profiling / Testing



