Introduction to Optimization Theory Homework Assignment 4

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ILO Ex. 8.5

Proof

(a)⇒(b)

If P is full-dimensional, there exists an interior point \boldsymbol{x} s.t. $\boldsymbol{x} \in P$ and all the constraints are not active at \boldsymbol{x} , i.e., $\boldsymbol{A}\boldsymbol{x} > \boldsymbol{b}$.

(b)⇒(c)

Suppose not, i.e., all the extreme points lie on the same hyperplane. Let d be a vector which is vertical to the hyperplane, since the polyhedra is the convex hull of all extreme points, for any $\lambda \in \mathbb{R}$, we have $x + \lambda d \notin P$, which means at least one constraint is active at x and we get a contradiction.

(c)⇒(a)

If there are n+1 extreme points of P that do not lie on a common hyperplane, note that the convex hull of the extreme points is a subset of the polyhedra, and the convex hull has positive volume, which means the polyhedra is full-dimensional.

CO Ex. 3.4

Proof

$$\int_0^1 f(x+\lambda(y-x))d\lambda \le \int_0^1 ((1-\lambda)f(x)+\lambda f(y))d\lambda$$

$$= f(x) + (f(y)-f(x)) \int_0^1 \lambda d\lambda$$

$$= f(x) + \frac{1}{2}(f(y)-f(x))$$

$$= \frac{f(x)+f(y)}{2}.$$

CO Ex. 3.7

Suppose not. There exists \mathbf{x}, \mathbf{y} s.t. $f(\mathbf{x}) \neq f(\mathbf{y})$. WLOG, assume $f(\mathbf{x}) < f(\mathbf{y})$. The function f is convex indicates that $g(t) = f(\mathbf{x} + t(\mathbf{y} - \mathbf{x}))$ is convex, which means $g(t) > (g(1) - g(0))t + g(0), \forall t > 1$. Notice that $g(1) = f(\mathbf{y}) > f(\mathbf{x}) = g(0)$, which means (g(1) - g(0))t + g(0) is unbounded. Therefore, g is unbounded, which leads to a contradiction.

CO Ex. 3.11

Proof

For any $\boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^n$, we have

$$f(\boldsymbol{y}) \geq f(\boldsymbol{x}) + (\nabla f(\boldsymbol{x}))^T (\boldsymbol{y} - \boldsymbol{x}) \geq f(\boldsymbol{y}) + (\nabla f(\boldsymbol{y}))^T (\boldsymbol{x} - \boldsymbol{y}) + (\nabla f(\boldsymbol{x}))^T (\boldsymbol{y} - \boldsymbol{x}).$$

Decrease by f(y) in both sides, we get

$$(\nabla f(\boldsymbol{y}) - \nabla f(\boldsymbol{x}))^T (\boldsymbol{y} - \boldsymbol{x}) \ge 0.$$

The converse is false. Consider

$$g(\mathbf{x}) = g([x_1, x_2]^T) = [2x_1, 2x_1 + 2x_2]^T.$$

Note that

$$(\boldsymbol{x} - \boldsymbol{y})^T \begin{bmatrix} 2 & 0 \\ 2 & 2 \end{bmatrix} (\boldsymbol{x} - \boldsymbol{y}) = (\boldsymbol{x} - \boldsymbol{y})^T \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} (\boldsymbol{x} - \boldsymbol{y}) > 0, \forall \boldsymbol{x} \neq \boldsymbol{y},$$

in that

$$\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

is a positive definite matrix. Therefore, $g(\mathbf{x})$ is monotone. However, there doesn't exist a f s.t. $\nabla f = g$ in that

$$\frac{\partial^2 f}{\partial x_1 \partial x_2} = 0, \frac{\partial^2 f}{\partial x_2 \partial x_1} = 2,$$

which is contradictory to that f is differentiable.

CO Ex. 3.12

Proof

Let $A = \{(\boldsymbol{x},t)^T : t \geq f(\boldsymbol{x})\}$, $B = \{(\boldsymbol{x},t)^T : g(\boldsymbol{x}) \geq t\}$. We know A and B are convex sets since f is convex and g is concave. By separating hyperplane theorem, we know there exists a hyperplane $\{(\boldsymbol{x}^T,t)^T : (\boldsymbol{x}^T,t)\boldsymbol{y}=b\}$ separating two convex sets, i.e. $\forall \boldsymbol{a} \in A, \boldsymbol{a}^T\boldsymbol{y} > b$ and $\forall \boldsymbol{a} \in B, \boldsymbol{a}^T\boldsymbol{y} < b$.

Assume $\mathbf{y} = (\mathbf{z}^T, y_0)^T$ (WLOG, assume $y_0 > 0$), $\forall (\mathbf{x}^T, t)^T \in A$, we have $\mathbf{x}^T \mathbf{z} + ty_0 > b \Leftrightarrow -\frac{\mathbf{z}^T}{y_0} \mathbf{x} - \frac{b}{y_0} < t$. Therefore, $-\frac{\mathbf{z}^T}{y_0} \mathbf{x} - \frac{b}{y_0} < f(\mathbf{x}), \forall \mathbf{x}$, i.e., $f(\mathbf{x})$ is lower bounded by the affine function.

CO Ex. 5.15

Proof

Since $f_i(\boldsymbol{x})$ is convex, $\forall \boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^n, \lambda \in (0,1)$, we have $f_i(\lambda \boldsymbol{x} + (1-\lambda)\boldsymbol{y}) \leq \lambda f_i(\boldsymbol{x}) + (1-\lambda)f_i(\boldsymbol{y})$. Since $h_i(\boldsymbol{x})$ is increasing and convex, we have

$$h_i(f_i(\lambda \boldsymbol{x} + (1-\lambda)\boldsymbol{y})) \le h_i(\lambda f_i(\boldsymbol{x}) + (1-\lambda)f_i(\boldsymbol{y})) \le \lambda h_i(f_i(\boldsymbol{x})) + (1-\lambda)h_i(f_i(\boldsymbol{y})).$$

Therefore, $h_i(f_i(\boldsymbol{x}))$ is convex, which means $\phi(\boldsymbol{x}) = f_0(\boldsymbol{x}) + \sum h_i(f_i(\boldsymbol{x}))$ is convex.

Since $\tilde{\boldsymbol{x}}$ minimizes ϕ , we have $\nabla \phi(\tilde{\boldsymbol{x}}) = \nabla f_0(\tilde{\boldsymbol{x}}) + \sum h_i'(f_i(\tilde{\boldsymbol{x}}))\nabla f_i(\tilde{\boldsymbol{x}}) = 0$. Let $\lambda_i = h_i'(f_i(\tilde{\boldsymbol{x}}))$, we have $\lambda_i > 0$ in that h_i is increasing. Therefore, $\boldsymbol{\lambda}$ is dual feasible, i.e., $g(\boldsymbol{\lambda}) = f_0(\tilde{\boldsymbol{x}}) + \sum \lambda_i f_i(\tilde{\boldsymbol{x}})$ is a lower bound to the primal problem.

CO Ex. 5.31

Proof

Since f_i is convex, we have $f_i(\mathbf{x}^*) + \nabla f_i(\mathbf{x}^*)^T(\mathbf{x} - \mathbf{x}^*) \leq f_i(\mathbf{x}) \leq 0$. Therefore,

$$egin{aligned} 0 &\geq \sum_{i=1}^m \lambda_i^* (f_i(oldsymbol{x}^*) +
abla f_i(oldsymbol{x}^*)^T (oldsymbol{x} - oldsymbol{x}^*)) \ &= \sum_{i=1}^m \lambda_i^* f_i(oldsymbol{x}^*) + \lambda_i^*
abla f_i(oldsymbol{x}^*)^T (oldsymbol{x} - oldsymbol{x}^*) \ &= \sum_{i=1}^m \lambda_i^*
abla f_i(oldsymbol{x}^*)^T (oldsymbol{x} - oldsymbol{x}^*) \ &= -
abla f_0(oldsymbol{x}^*) (oldsymbol{x} - oldsymbol{x}^*), \end{aligned}$$

which is equivalent to $\nabla f_0(\boldsymbol{x}^*)(\boldsymbol{x}-\boldsymbol{x}^*) \geq 0$.

CO Ex. 9.1

(a)

Proof

Since P is not semi-definite positive, there exists \mathbf{x}_0 s.t. $\mathbf{x}_0^T P \mathbf{x}_0 < 0$. Let $\mathbf{x} = k \mathbf{x}_0$, $f(\mathbf{x}) = \frac{1}{2} k^2 \mathbf{x}_0^T P \mathbf{x}_0 + k \mathbf{q}^T \mathbf{x}_0 + r$, which is obviously unbounded below.

(b)

Proof

Rewrite q as $q_0 + v$ s.t. $q_0 \in \text{Col}(P), v \perp \text{Col}(P)$, i.e., Pv = 0. Let x = kv, we have

$$f(\boldsymbol{x}) = k\boldsymbol{q}^T\boldsymbol{v} + r = k\boldsymbol{v}^T\boldsymbol{v} + r = k\|\boldsymbol{v}\|_2^2 + r,$$

which is unbounded below.