

## CS2010: ALGORITHMS AND DATA STRUCTURES

### Lecture 14: Binary Search Trees (2)

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## 3.2 BINARY SEARCH TREES

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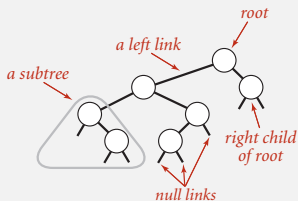
- *BSTs*
- *ordered operations*
- *deletion*

# Binary search trees

**Definition.** A BST is a **binary tree** in **symmetric order**.

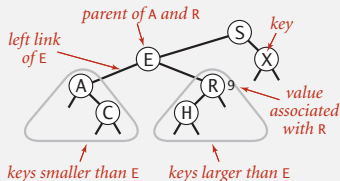
A binary tree is either:

- Empty.
- Two disjoint binary trees (left and right).



**Symmetric order.** Each node has a key, and every node's key is:

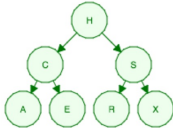
- Larger than all keys in its left subtree.
- Smaller than all keys in its right subtree.



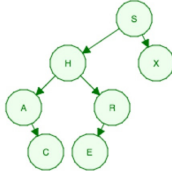
# QUIZ

Q: Which of the following are Binary Search Trees? Why?

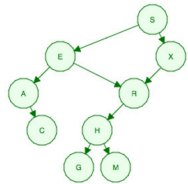
(1)



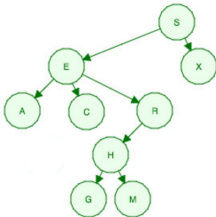
(2)



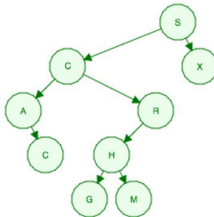
(3)



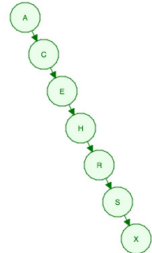
(4)



(5)



(6)



## ST implementations: summary

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implementation	guarantee		average case		operations on keys
	search	insert	search hit	insert	
sequential search (unordered list)	$N$	$N$	$\frac{1}{2} N$	$N$	<code>equals()</code>
binary search (ordered array)	$\lg N$	$N$	$\lg N$	$\frac{1}{2} N$	<code>compareTo()</code>
BST	$N$	$N$	$1.39 \lg N$	$1.39 \lg N$	<code>compareTo()</code>



Why not shuffle to ensure a (probabilistic) guarantee of  $4.311 \ln N$ ?



## 3.2 BINARY SEARCH TREES

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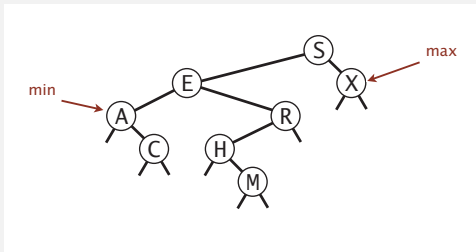
- *BSTs*
- *ordered operations*
- *deletion*

## Minimum and maximum

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**Minimum.** Smallest key in table.

**Maximum.** Largest key in table.



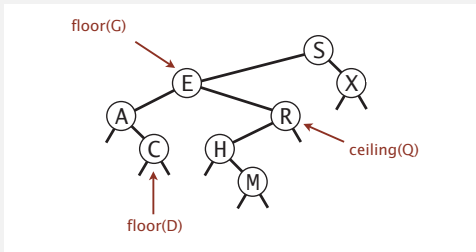
Q. How to find the min / max?

# Floor and ceiling

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**Floor.** Largest key  $\leq$  a given key.

**Ceiling.** Smallest key  $\geq$  a given key.



**Q.** How to find the floor / ceiling?



# Computing the floor

**Case 1.** [ $k$  equals the key in the node]

The floor of  $k$  is  $k$ .

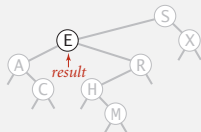
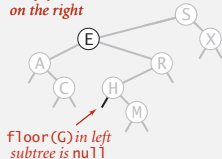
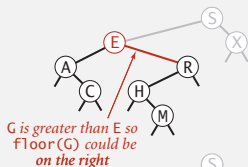
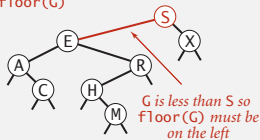
**Case 2.** [ $k$  is less than the key in the node]

The floor of  $k$  is in the left subtree.

**Case 3.** [ $k$  is greater than the key in the node]

The floor of  $k$  is in the right subtree  
(if there is any key  $\leq k$  in right subtree);  
otherwise it is the key in the node.

finding floor( $G$ )



# Computing the floor

```
public Key floor(Key key)
{
    Node x = floor(root, key);
    if (x == null) return null;
    return x.key;
}

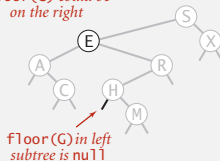
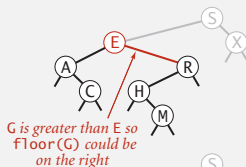
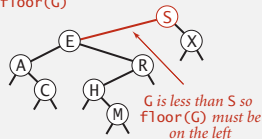
private Node floor(Node x, Key key)
{
    if (x == null) return null;
    int cmp = key.compareTo(x.key);

    if (cmp == 0) return x;

    if (cmp < 0) return floor(x.left, key);

    Node t = floor(x.right, key);
    if (t != null) return t;
    else return x;
}
```

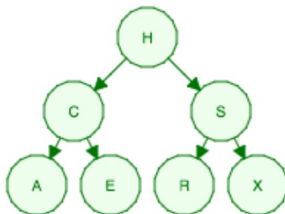
finding floor(G)



## RANK AND SELECT

→ **rank(Key k)**: how many keys less than k?

→ **select(int n)**: what key has rank n?

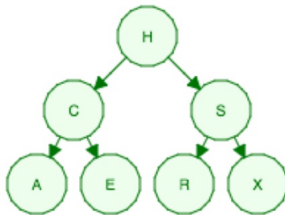


→ Q: what is the rank of 'S'?

## RANK AND SELECT

→ **rank(Key k)**: how many keys less than k?

→ **select(int n)**: what key has rank n?

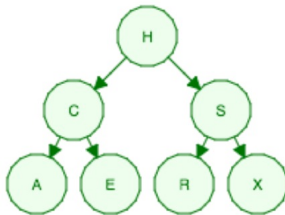


→ **Q**: what is the rank of 'S'?     5 (5 keys less than 'S' in the tree)

## RANK AND SELECT

→ **rank(Key k)**: how many keys less than k?

→ **select(int n)**: what key has rank n?



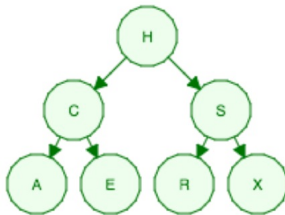
→ Q: what is the rank of 'S'?     5 (5 keys less than 'S' in the tree)

→ Q: what key has rank 4?

## RANK AND SELECT

→ **rank(Key k)**: how many keys less than k?

→ **select(int n)**: what key has rank n?



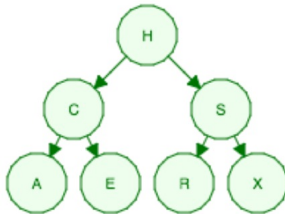
→ Q: what is the rank of 'S'?      5 (5 keys less than 'S' in the tree)

→ Q: what key has rank 4?      'R' (4 keys less than 'R' in the tree)

## RANK AND SELECT

→ **rank(Key k)**: how many keys less than k?

→ **select(int n)**: what key has rank n?



→ Q: what is the rank of 'S'?      5 (5 keys less than 'S' in the tree)

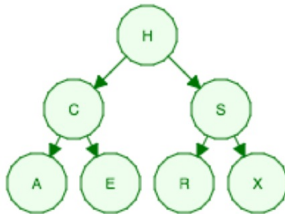
→ Q: what key has rank 4?      'R' (4 keys less than 'R' in the tree)

→ Q: what is the rank of 'Q' ('Q' is not in the tree)?

## RANK AND SELECT

→ **rank(Key k)**: how many keys less than k?

→ **select(int n)**: what key has rank n?



→ Q: what is the rank of 'S'?      5 (5 keys less than 'S' in the tree)

→ Q: what key has rank 4?      'R' (4 keys less than 'R' in the tree)

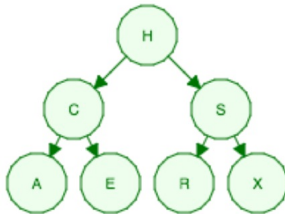
→ Q: what is the rank of 'Q' ('Q' is not in the tree)?      4 (4 keys in the tree are less than 'Q')



## RANK AND SELECT

→ **rank(Key k)**: how many keys less than k?

→ **select(int n)**: what key has rank n?



→ Q: what is the rank of 'S'?      5 (5 keys less than 'S' in the tree)

→ Q: what key has rank 4?      'R' (4 keys less than 'R' in the tree)

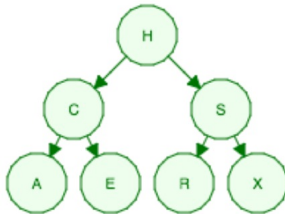
→ Q: what is the rank of 'Q' ('Q' is not in the tree)?      4 (4 keys in the tree are less than 'Q')

→ Q: what key has rank 7?

## RANK AND SELECT

→ **rank(Key k)**: how many keys less than k?

→ **select(int n)**: what key has rank n?



→ Q: what is the rank of 'S'?      5 (5 keys less than 'S' in the tree)

→ Q: what key has rank 4?      'R' (4 keys less than 'R' in the tree)

→ Q: what is the rank of 'Q' ('Q' is not in the tree)?      4 (4 keys in the tree are less than 'Q')

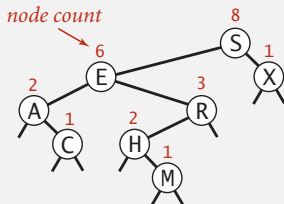
→ Q: what key has rank 7?      no key in the tree has this rank (no key has 7 keys smaller than it in the tree)

## Rank and select

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Q. How to implement `rank()` and `select()` efficiently?

A. In each node, we store the number of nodes in the subtree rooted at that node; to implement `size()`, return the count at the root.



## BST implementation: subtree counts


```
private class Node
{
    private Key key;
    private Value val;
    private Node left;
    private Node right;
    private int count;
}
```



number of nodes in subtree


```
public int size()
{ return size(root); }
```

```
private int size(Node x)
{
    if (x == null) return 0;
    return x.count;
}
```



ok to call  
when x is null

```
private Node put(Node x, Key key, Value val)
{
    if (x == null) return new Node(key, val, 1);
    int cmp = key.compareTo(x.key);
    if (cmp < 0) x.left = put(x.left, key, val);
    else if (cmp > 0) x.right = put(x.right, key, val);
    else if (cmp == 0) x.val = val;
    x.count = 1 + size(x.left) + size(x.right);
    return x;
}
```

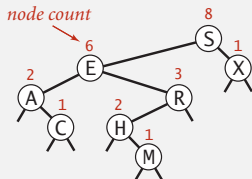


initialize subtree  
count to 1

# Rank

Rank. How many keys  $< k$ ?

Easy recursive algorithm (3 cases!)



```
public int rank(Key key)
{ return rank(key, root); }

private int rank(Key key, Node x)
{
    if (x == null) return 0;
    int cmp = key.compareTo(x.key);
    if (cmp < 0) return rank(key, x.left);
    else if (cmp > 0) return 1 + size(x.left) + rank(key, x.right);
    else if (cmp == 0) return size(x.left);
}
```

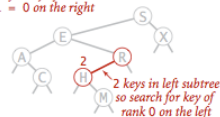
# SELECT

Select. Find the key with rank  $n$ .

```
public Key select(int n) {
    if (n < 0 || n >= size()) return null;
    Node x = select(root, n);
    return x.key;
}

private Node select(Node x, int n) {
    if (x == null) return null;
    int t = size(x.left);
    if (t > n) return select(x.left, n);
    else if (t < n) return select(x.right, n-t-1);
    else return x;
}
```

finding select(3)  
the key of rank 3



Selection in a BST

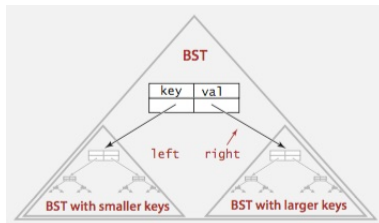
# TREE TRAVERSALS

**Task:** Process all nodes of the tree.

**Purpose:** To print all nodes, to add all nodes in a datastructure (e.g. queue), etc.

## Three kinds of traversals:

- **inorder:** for each node:
  1. traverse the left subtree
  2. **process the node**
  3. traverse the right subtree
- **preorder:** for each node:
  1. **process the node**
  2. traverse the left subtree
  3. traverse the right subtree
- **postorder:** for each node:
  1. traverse the left subtree
  2. traverse the right subtree
  3. **process the node**

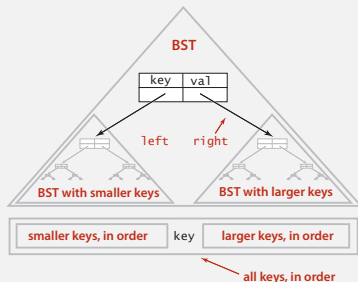


# Inorder traversal

- Traverse left subtree.
- Enqueue key.
- Traverse right subtree.

```
public Iterable<Key> keys()
{
    Queue<Key> q = new Queue<Key>();
    inorder(root, q);
    return q;
}

private void inorder(Node x, Queue<Key> q)
{
    if (x == null) return;
    inorder(x.left, q);
    q.enqueue(x.key);
    inorder(x.right, q);
}
```




**Property.** Inorder traversal of a BST yields keys in ascending order.



## BST: ordered symbol table operations summary

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	sequential search	binary search	BST
search	$N$	$\lg N$	$h$
insert	$N$	$N$	$h$
min / max	$N$	1	$h$
floor / ceiling	$N$	$\lg N$	$h$
rank	$N$	$\lg N$	$h$
select	$N$	1	$h$
ordered iteration	$N \log N$	$N$	$N$



$h$  = height of BST  
(proportional to  $\log N$   
if keys inserted in random order)

Worst case:  $h = O(N)$

order of growth of running time of ordered symbol table operations



## 3.2 BINARY SEARCH TREES

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- *BSTs*
- *ordered operations*
- *deletion*

## ST implementations: summary

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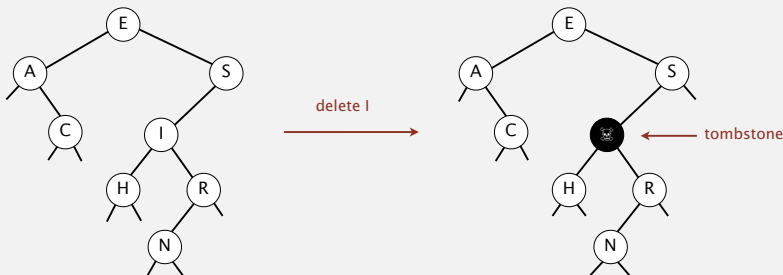
implementation	guarantee			average case			ordered ops?	operations on keys
	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	$N$	$N$	$N$	$\frac{1}{2} N$	$N$	$\frac{1}{2} N$		<code>equals()</code>
binary search (ordered array)	$\lg N$	$N$	$N$	$\lg N$	$\frac{1}{2} N$	$\frac{1}{2} N$	✓	<code>compareTo()</code>
BST	$N$	$N$	$N$	$1.39 \lg N$	$1.39 \lg N$	???	✓	<code>compareTo()</code>

Next. Deletion in BSTs.

## BST deletion: lazy approach

To remove a node with a given key:

- Set its value to null.
- Leave key in tree to guide search (but don't consider it equal in search).



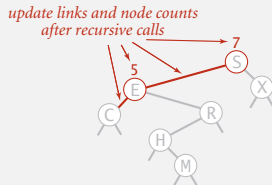
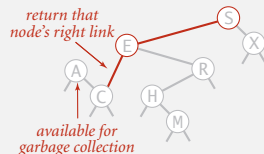
**Cost.**  $\sim 2 \ln N'$  per insert, search, and delete (if keys in random order), where  $N'$  is the number of key-value pairs ever inserted in the BST.

**Unsatisfactory solution.** Tombstone (memory) overload.

## Deleting the minimum

### To delete the minimum key:

- Go left until finding a node with a null left link.
- Replace that node by its right link.
- Update subtree counts.



```
public void deleteMin()
{ root = deleteMin(root); }

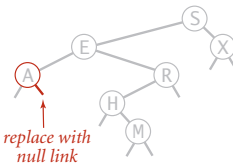
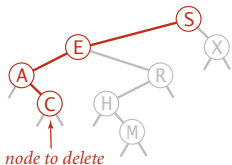
private Node deleteMin(Node x)
{
    if (x.left == null) return x.right;
    x.left = deleteMin(x.left);
    x.count = 1 + size(x.left) + size(x.right);
    return x;
}
```

# Hibbard deletion

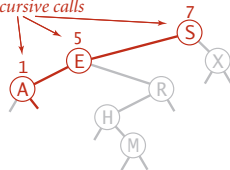
To delete a node with key  $k$ : search for node  $t$  containing key  $k$ .

**Case 0.** [0 children] Delete  $t$  by setting parent link to null.

deleting C



update counts after recursive calls

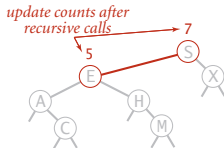
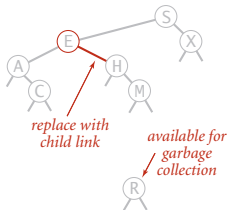
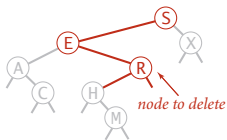


# Hibbard deletion

To delete a node with key  $k$ : search for node  $t$  containing key  $k$ .

Case 1. [1 child] Delete  $t$  by replacing parent link.

deleting R







## Hibbard deletion: Java implementation

---

```
public void delete(Key key)
{ root = delete(root, key); }

private Node delete(Node x, Key key) {
    if (x == null) return null;
    int cmp = key.compareTo(x.key);
    if (cmp < 0) x.left = delete(x.left, key);
    else if (cmp > 0) x.right = delete(x.right, key);
    else {
        if (x.right == null) return x.left;
        if (x.left == null) return x.right;

        Node t = x;
        x = min(t.right);
        x.right = deleteMin(t.right);
        x.left = t.left;

    }
    x.count = size(x.left) + size(x.right) + 1;
    return x;
}
```

search for key

no right child

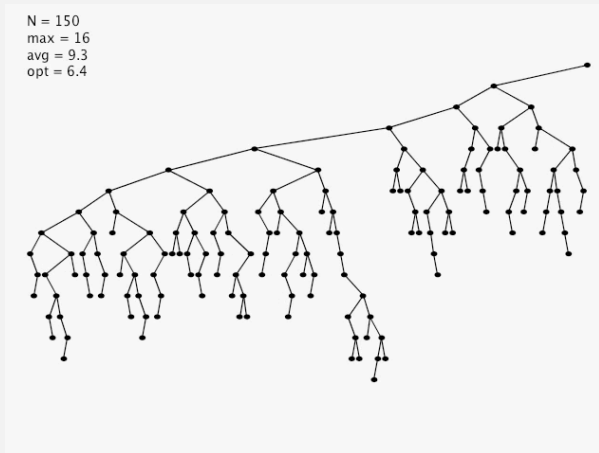
no left child

replace with successor

update subtree counts

## Hibbard deletion: analysis

Unsatisfactory solution. Not symmetric.



Surprising consequence. Trees not random (!)  $\Rightarrow \sqrt{N}$  per op.

Longstanding open problem. Simple and efficient delete for BSTs.

## ST implementations: summary

---

implementation	guarantee			average case			ordered ops?	operations on keys
	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	$N$	$N$	$N$	$\frac{1}{2} N$	$N$	$\frac{1}{2} N$		equals()
binary search (ordered array)	$\lg N$	$N$	$N$	$\lg N$	$\frac{1}{2} N$	$\frac{1}{2} N$	✓	compareTo()
BST	$N$	$N$	$N$	$1.39 \lg N$	$1.39 \lg N$	$\sqrt{N}$	✓	compareTo()

other operations also become  $\sqrt{N}$   
if deletions allowed

Next lecture. Guarantee logarithmic performance for all operations.