

# CS1021 Introduction to Computing I

## 2. ARM Assembly Language

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start

```
MOV    total, a           ; Make the first number the subtotal
ADD    total, total, b     ; Add the second number to the subtotal
ADD    total, total, c     ; Add the third number to the subtotal
ADD    total, total, d     ; Add the fourth number to the subtotal
```

## Pseudocode program from Lecture #1

Adds four numbers together,  $\text{total} = a + b + c + d$

total, a, b, c, and d are stored in memory

Operations (move and add) are performed in CPU

Several memory  $\leftrightarrow$  CPU transfers required

**Accessing memory is slow relative to the speed at which the processor can execute instructions**

`total = total + b`

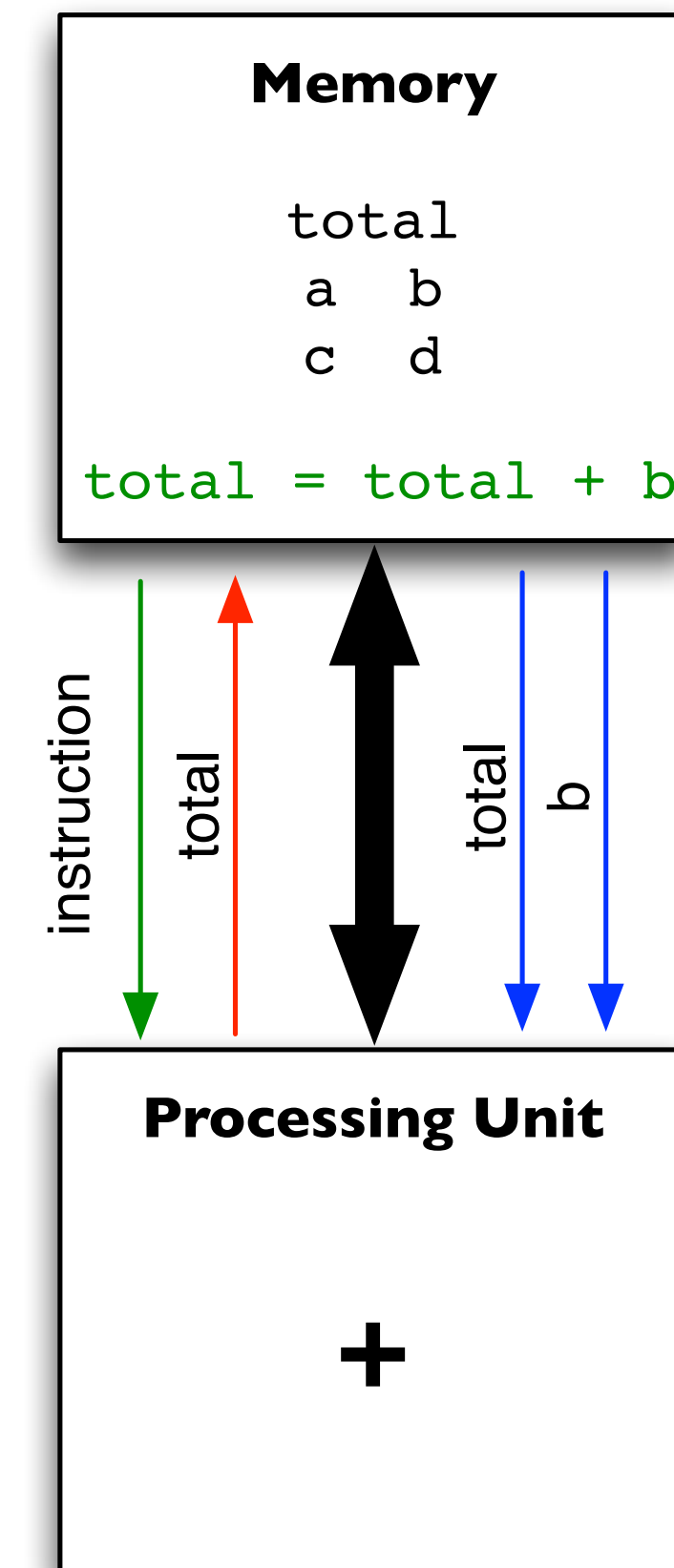
Load instruction from Memory to CPU (ADD total, total, b)

Load total from Memory to CPU

Load b from Memory to CPU

Compute `total + b`

Store total from CPU to Memory



**Processors use small fast internal storage to temporarily store values – called registers**

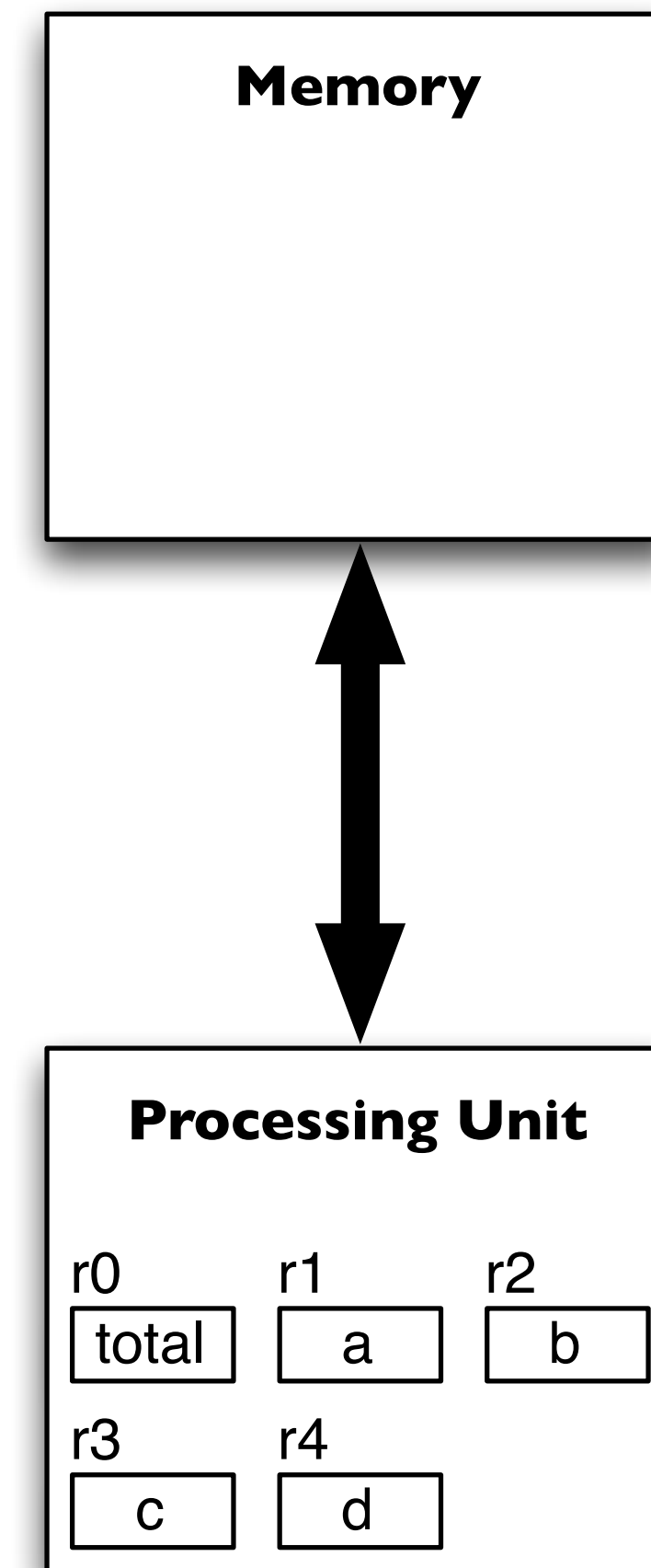
ARM has 16 word-size registers

Labelled r0, r1, ..., r15

r15 is special – the Program Counter

r13 and r14 are normally used for special purposes

you should avoid using r13...r15 (for now ...)



A program (any program, originally written using any language) is composed of a sequence of machine code instructions that are stored in memory

Instructions determine the operations performed by the processor (e.g. add, move, multiply, subtract, compare, ...)

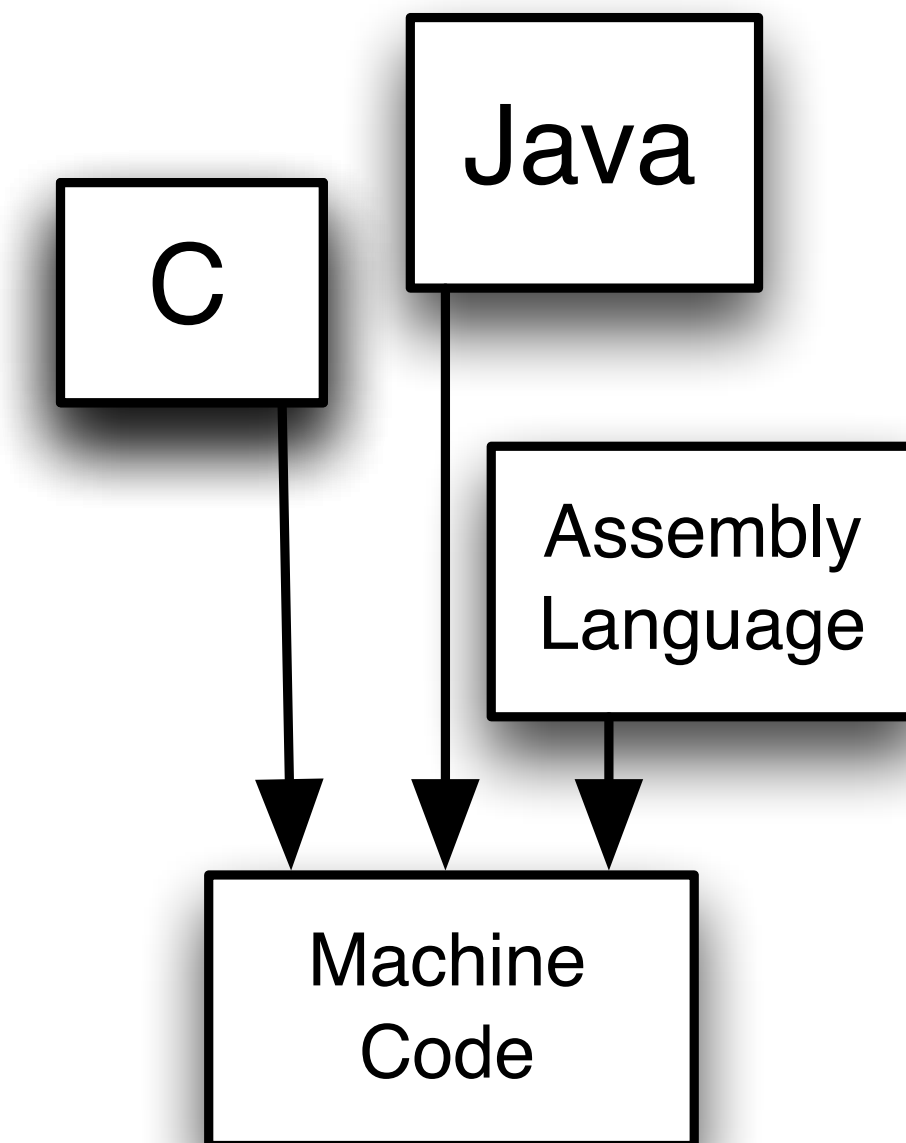
A single instruction is composed of

- an operator (instruction)

- zero, one or more operands

Each instruction and its operands are encoded using a 32-bit value

e.g. 0xE0810002 is the machine that causes the processor to add the values in r1 and r2 and store the result in r0



Writing programs using machine code is possible ...

... but not practical

Instead, we write programs using assembly language

Instructions are expressed using mnemonics

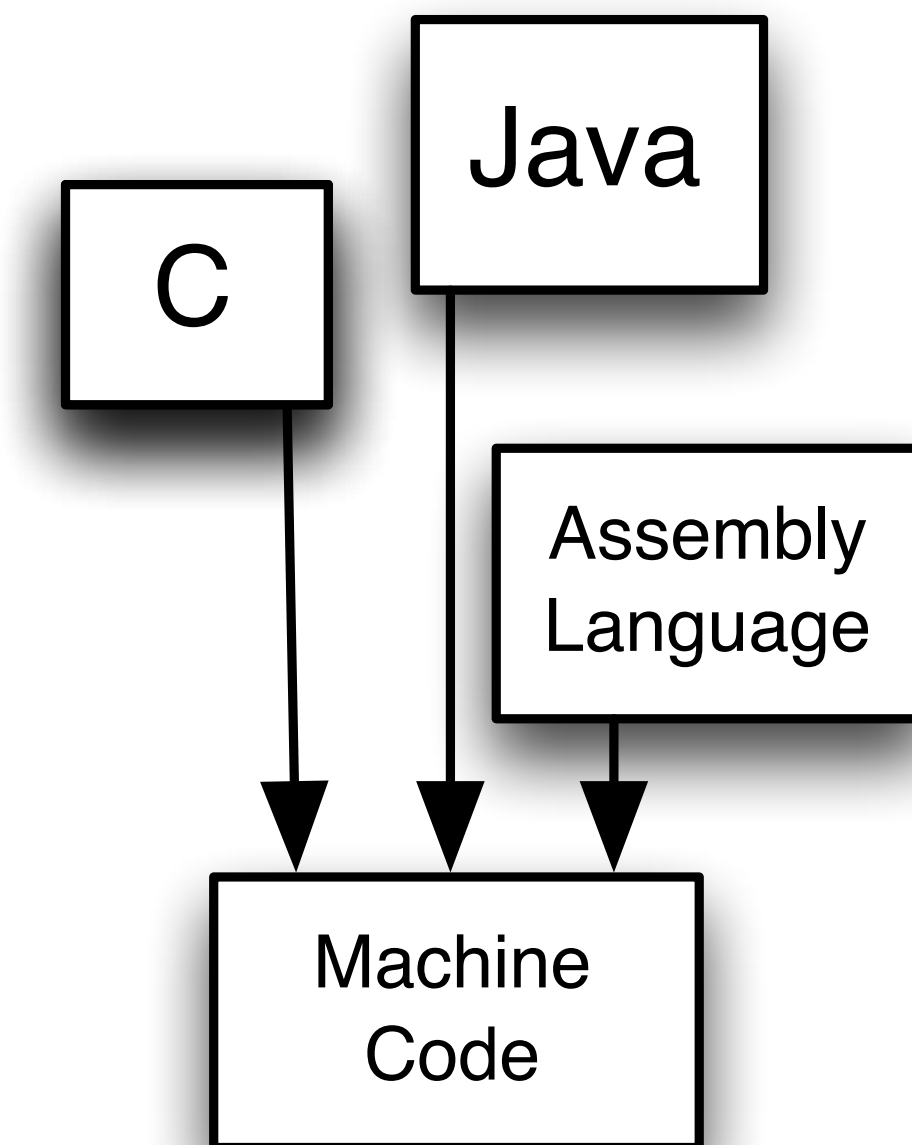
e.g. the word “ADD” instead of the machine code 0xE08

e.g. the expression “r2” to refer to register number two

Assembly language must still be translated into machine code

Done using a program called an assembler

Machine code produced by the assembler is stored in memory and executed by the processor



# Demo Program - ARM Assembly Language

7

start

```
MOV    r0, r1           ; Make the first number the subtotal
ADD    r0, r0, r2        ; Add the second number to the subtotal
ADD    r0, r0, r3        ; Add the third number to the subtotal
ADD    r0, r0, r4        ; Add the fourth number to the subtotal
```

stop B stop



# Demo Program – Machine Code

1	00000000		AREA	Demo, CODE, READONLY
2	00000000		IMPORT	main
3	00000000		EXPORT	start
4	00000000			
5	00000000	start		
6	00000000	E1A00001	MOV	r0, r1
7	00000004	E0800002	ADD	r0, r0, r2
8	00000008	E0800003	ADD	r0, r0, r3
9	0000000C	E0800004	ADD	r0, r0, r4
10	00000010			
11	00000010	EAFFFFFE		
		stop	B	stop
12	00000014			
13	00000014		END	

line #

instruction  
address

machine code  
instructions

original  
assembly language



# Machine Code and Assembly Language

Every ARM machine code instruction is 32-bits long

32-bit instruction word must encode

operation (instruction)

all the required instruction operands

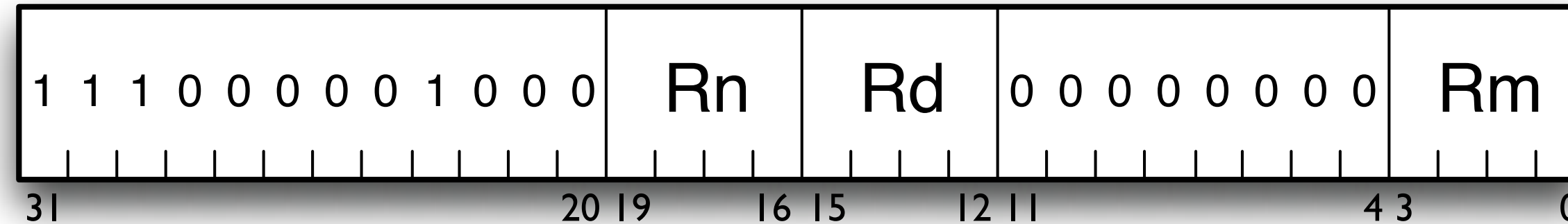
Example – add `r0, r0, r2`

## Destination Operand

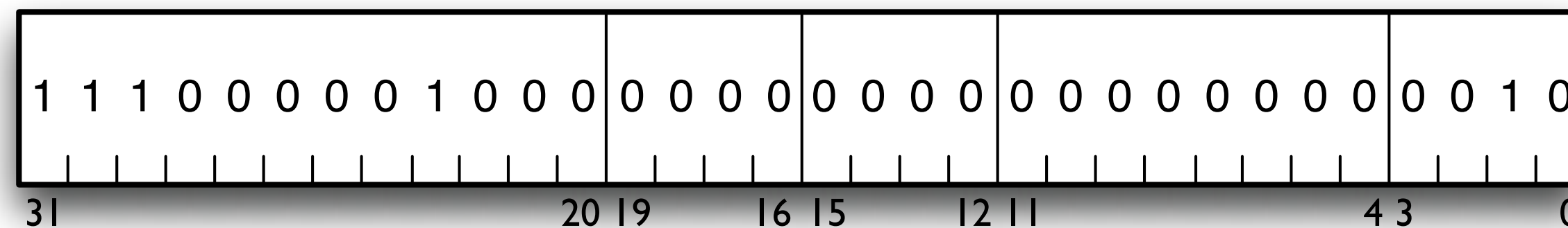
Rd

# Source Operands

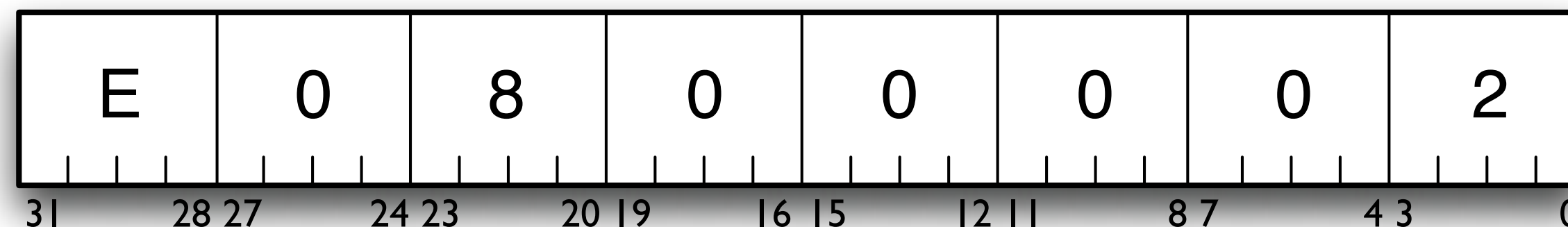
## Rn, Rm



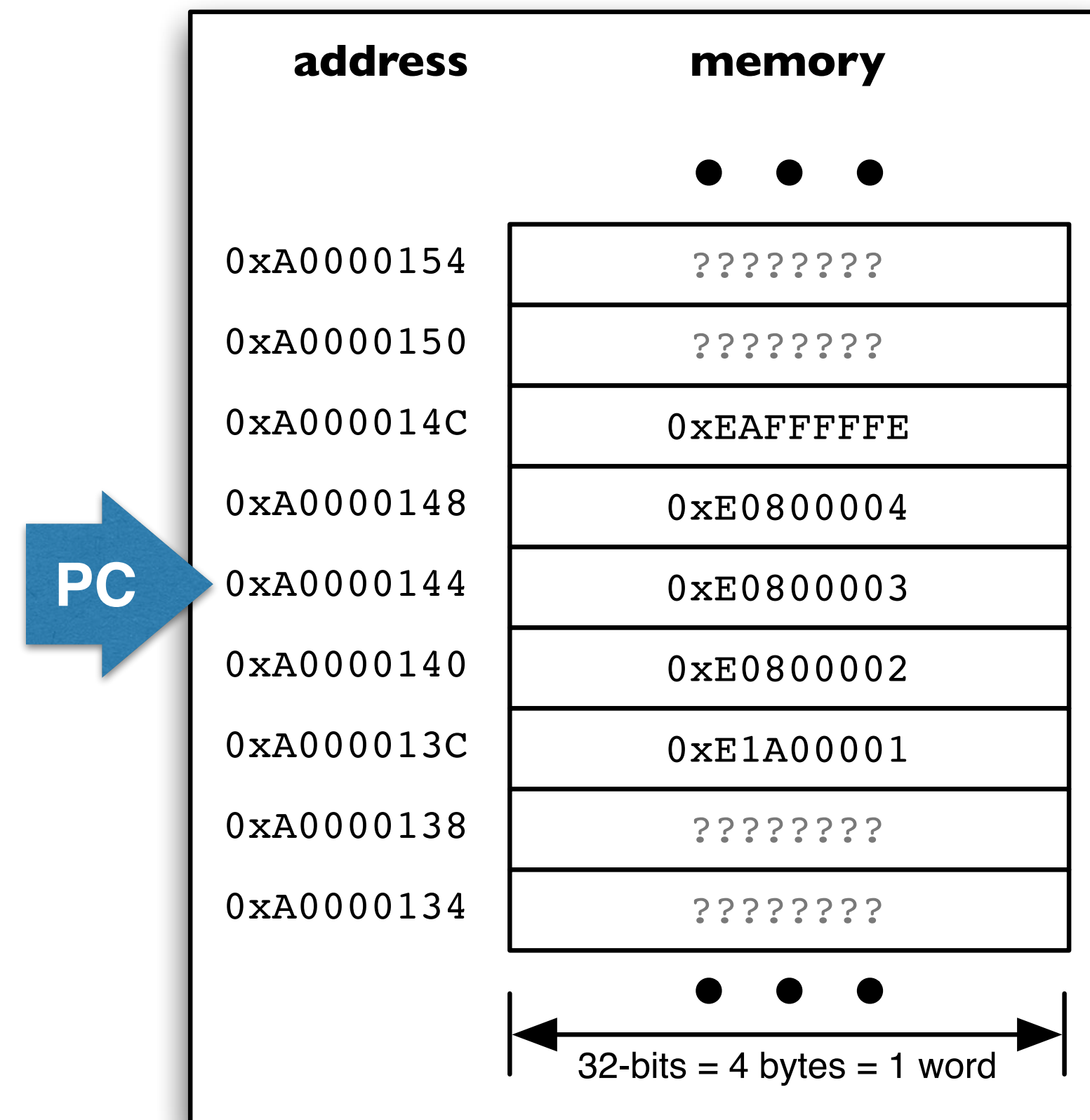
add instruction template  
**ADD Rd, Rn, Rm**



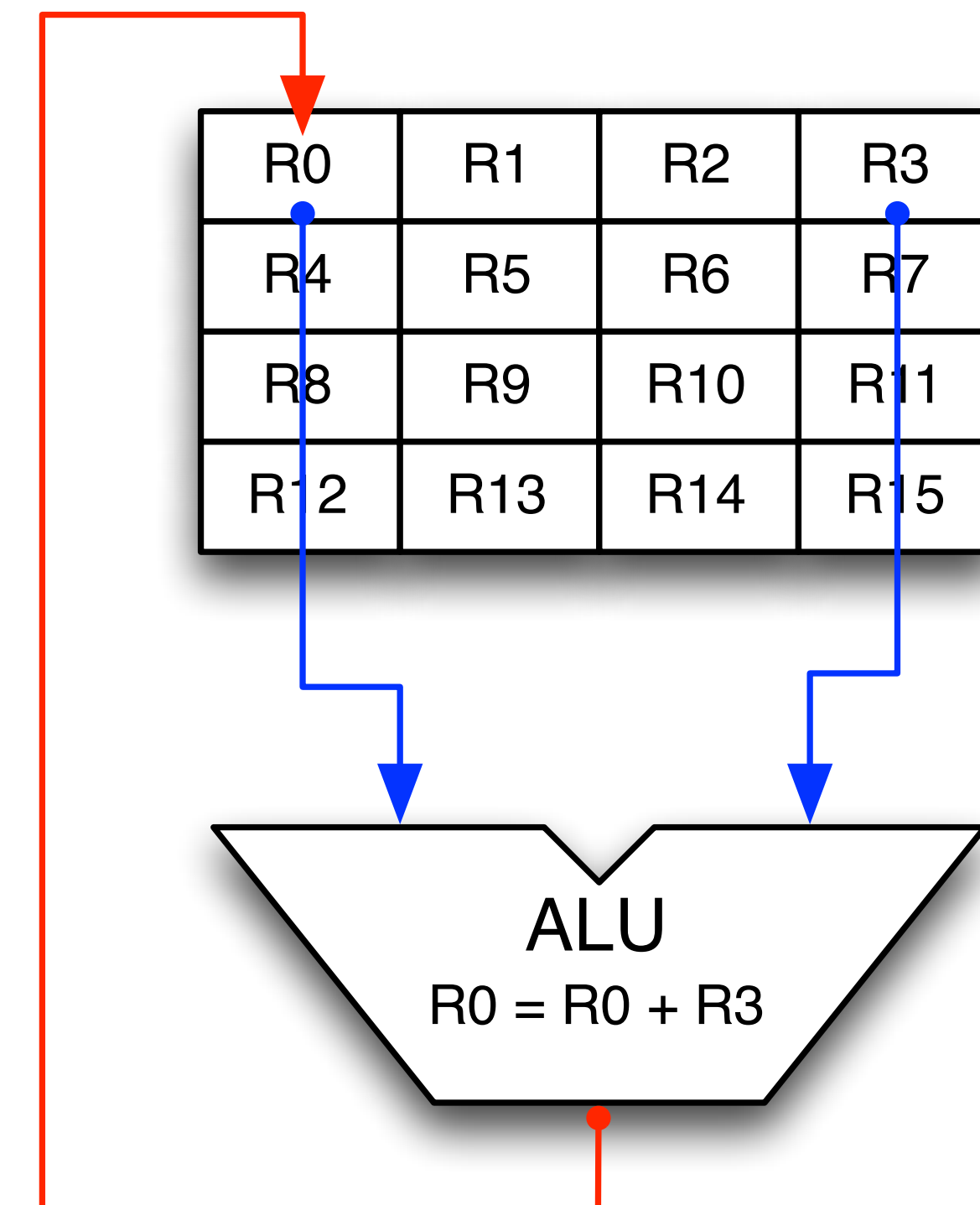
machine code binary



machine code hexadecimal



**0xE0800003**  
**operation:** add  
**source Rn:** R0  
**source Rm:** R3  
**destination:** R0



**Fetch** next instruction from memory at the address contained in the Program Counter (PC / R15)

PC is advanced to next instruction (PC = PC + 4)

Machine Code instruction is **decoded** to determine operation and source / destination operands

Instruction is **executed**. (In this example the ALU adds the values in R0 and R3, storing the result back in R0.)



Start Debug session



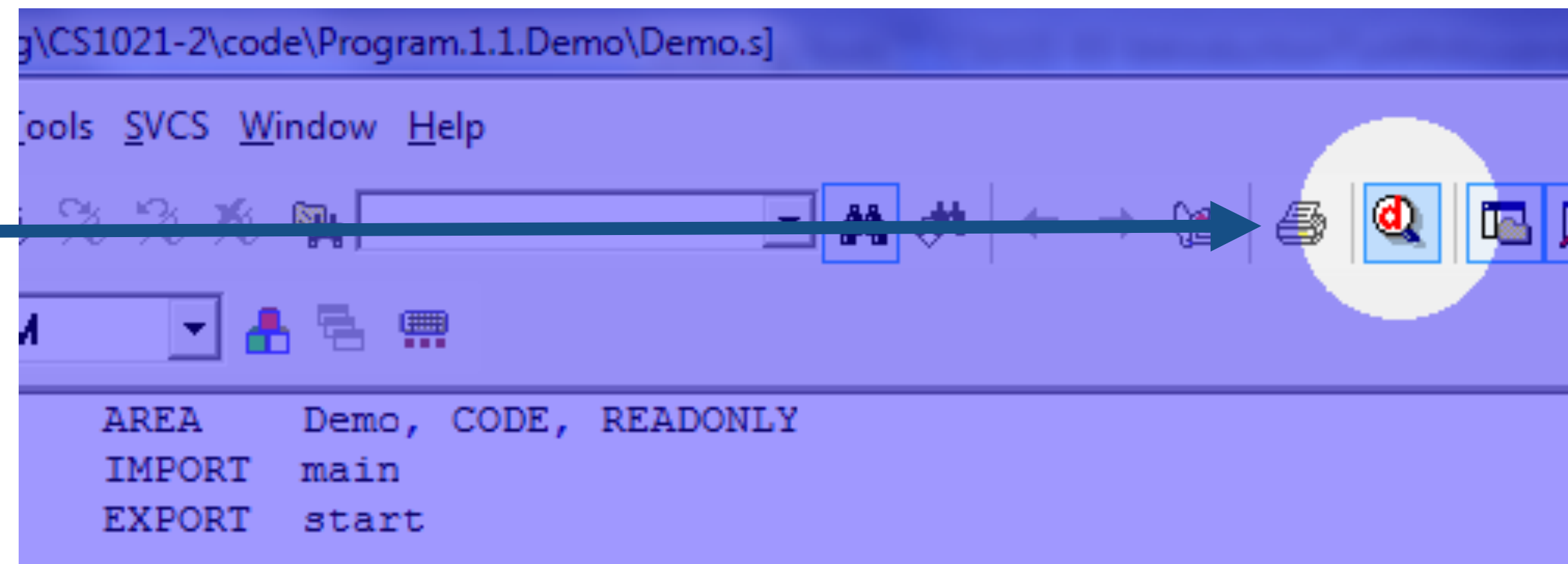
Assembled program  
(Machine Code) loaded  
into memory as pre-  
defined address



Program Counter (PC /  
R15) set to same pre-  
defined address



Fetch-Decode-Cycle  
resumes



address	memory
	• • •
0xA0000154	????????
0xA0000150	????????
0xA000014C	0xEAFFFFF
0xA0000148	0xE0800004
0xA0000144	0xE0800003
0xA0000140	0xE0800002
0xA000013C	0xE1A00001
0xA0000138	????????
0xA0000134	????????
	• • •
	32-bits = 4 bytes = 1 word

What happens  
when we reach the  
end of our  
program?

Write a ARM Assembly Language program to swap the contents of registers R0 and R1

## Register Operands

```
ADD  R0, R1, R2  
MOV  R5, R2
```

Register Operand

Often want to use constant values, instead of registers

e.g. move the value 0 (zero) into register R3

```
MOV  R0, #0
```

e.g. set  $R1 = R2 + 1$

```
ADD  R1, R2, #1
```

Immediate Operands



Write an ARM Assembly Language program to compute  $4x^2+3x$  if  $x$  is stored in R1. Store the result in R0.

```
start
    MUL    r0, r1, r1        ; result = x * x
    LDR     r2, =4           ; tmp = 4
    MUL    r0, r2, r0        ; result = 4 * x * x

    LDR     r2, =3           ; tmp = 3
    MUL    r2, r1, r2        ; tmp = x * tmp

    ADD     r0, r0, r1        ; result = result + tmp

stop    B      stop
```

cannot use MUL to multiply by a constant value

MUL Rx, Rx, Ry produces unpredictable results

R1 is unmodified by our program ... which may be something we want ... or maybe we don't care

```
...  
LDR    r2, =3                ; tmp = 3  
MUL    r2, r1, r2            ; tmp = x * tmp  
...
```

Note use of operand **=3**

Move constant value 3 into register R2

**L**oad **R**egister instruction can be used to load any 32-bit signed constant value into a register

```
...  
LDR    r4, =0xA000013C       ; r4 = 0xA000013C  
...
```

Note use of **=x** syntax instead of **#x** with LDR instruction

Cannot fit large constant values in a 32-bit MOV instruction  
(Remember: all ARM instructions are 32-bit words)

```
MOV    r0, #0x4FE8
```

```
error: A1510E: Immediate 0x00004FE8 cannot be represented by 0-255 and a rotation
```

LDR is a “pseudo-instruction” that simplifies the implementation of a word-around for this limitation

For small constant values, the Assembler quietly replaces the LDR instruction with a simple MOV instruction

```
LDR    r0, =7
```

```
6 00000000 E3A00007      LDR          r0, =7
```

```
MOV    r0, #7
```

```
6 00000000 E3A00007      MOV          r0, #7
```

Assembler transparently implements the work-around for us for large constant values

Provide meaningful comments and assume someone else will be reading your code

```
MUL    r2, r1, r2           ; r2 = r1 * r2
```



```
MUL    r2, r1, r2           ; tmp = x * tmp
```



Break your programs into small pieces separated by white space

While starting out, keep programs simple

Pay attention to initial values in registers (and memory)