Mean Probability to Lose a Track for Behavior Policies 0: myopic, innov. 4: myopic, prob. 0.35 1: non-myopic, innov. 5: non-myopic, prob. 2: myopic, innov. & RI 6: myopic, prob. & RI Mean probability to lose a track 3: non-myopic, innov, & RI 7: non-myopic, prob. & RI 0.30 0.25 0.20 0.15 0.10 0.05 0.00 Training episodes