## Snake

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# **Chapter 1**

# **Class Index**

## 1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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2 Class Index

# **Chapter 2**

# File Index

## 2.1 File List

Here is a list of all documented files with brief descriptions:

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## **Chapter 3**

## **Class Documentation**

## 3.1 software::game Class Reference

#### **Public Member Functions**

• game (hardware::led\_matrix \_ledMatrix, hardware::joy\_stick \_joyStick)

Construct a new game object.

•  $\sim$ game ()

Destroy the game object.

• void init ()

Should be called shortly after the object is constructed. Initializes the ledMatrix\_ object and the joyStick\_ object by calling their init functions. Unsets all pixels in gameBoard\_. Sets a random inital direction and a random start point for the snake. The random startpoint is in an inner square which is 70% of the game board size. Spawns 2 randomly placed foods on the board.

• bool exec ()

Executes one frame of the game, whereby a frame and a move of the snake is the same cycle. Thus the game speed is controlled by the rate of calling exec. Should be called about every 300 ms for playable results. Returns if the game is lost.

• bool menu ()

Not yet implemented. Should not be used. At current state just returns if the joy stick is pressed.

## 3.1.1 Constructor & Destructor Documentation

#### 3.1.1.1 game()

Construct a new game object.

#### **Parameters**

_ledMatrix	Object for storing the LED information, setting colours and controlling higher graphical functionality.
_joyStick	Object for getting directional information of the connected joy stick.

#### 3.1.2 Member Function Documentation

#### 3.1.2.1 exec()

```
bool software::game::exec ( )
```

Executes one frame of the game, whereby a frame and a move of the snake is the same cycle. Thus the game speed is controlled by the rate of calling exec. Should be called about every 300 ms for playable results. Returns if the game is lost.

#### Returns

true Game can continue.

false Game is lost.

#### 3.1.2.2 menu()

```
bool software::game::menu ( )
```

Not yet implemented. Should not be used. At current state just returns if the joy stick is pressed.

#### Returns

true Joy stick is pressed. false Joy stick is not pressed.

The documentation for this class was generated from the following files:

- · game.hpp
- game.cpp

## 3.2 hardware::joy stick Class Reference

## **Public Types**

```
enum direction {
    noDirection , up , down , left ,
    right }
```

Enum for the possible inputs of the joy stick.

### **Public Member Functions**

```
• joy_stick (uint8_t _buttonPin, uint8_t _vrxPin, uint8_t _vryPin)
```

Construct a new joy stick object.

joy\_stick (joy\_stick &t)

Copy constructor for a new joy stick object.

•  $\sim$ joy\_stick ()

Destroy the joy stick object.

• void init ()

Init function for this object. Need to be called shortly after initialisation.

• direction getDirection ()

Get the current direction of the joy stick.

• bool isPressed ()

Returns if the button is currently pressed.

## 3.2.1 Constructor & Destructor Documentation

#### 3.2.1.1 joy\_stick() [1/2]

Construct a new joy stick object.

#### **Parameters**

_buttonPin	Pin number of the button pin.
_vrxPin	Pin number of the vrx pin.
_vryPin	Pin number of the vry pin.

## 3.2.1.2 joy\_stick() [2/2]

```
\label{eq:continuous_stick} \begin{split} \text{hardware::joy\_stick::joy\_stick (} \\ \text{joy\_stick \& } t \end{split} ) \end{split}
```

Copy constructor for a new joy stick object.

#### **Parameters**

t Object of joy\_stick to copy from.

## 3.2.2 Member Function Documentation

## 3.2.2.1 getDirection()

```
hardware::joy_stick::direction hardware::joy_stick::getDirection ( )
```

Get the current direction of the joy stick.

## Returns

direction Enum of all possible inputs.

#### 3.2.2.2 isPressed()

```
bool hardware::joy_stick::isPressed ( )
```

Returns if the button is currently pressed.

#### Returns

```
true Button is pressed. false Button is not pressed.
```

The documentation for this class was generated from the following files:

- · joy\_stick.hpp
- · joy\_stick.cpp

## 3.3 hardware::led matrix Class Reference

#### **Public Types**

enum colorPixel { obstacle = CRGB::Red , tail = CRGB::Yellow , food = CRGB::Green , head = CRGB::Blue }

Enumeration of the default colors for every game pixel.

## **Public Member Functions**

• led\_matrix ()

Construct a new led matrix object.

led\_matrix (led\_matrix &t)

Copy construct for a new led matrix object.

∼led\_matrix ()

Destroy the led matrix object.

• void init ()

Init function for this object. Need to be called shortly after initialisation.

void setPixel (uint16\_t x, uint16\_t y, colorPixel color)

Set the color from the default colors of a coordinate.

void setPixel (uint16\_t x, uint16\_t y, uint32\_t color)

Set the color of a coordinate.

void unsetPixel (uint16\_t x, uint16\_t y)

Unsets the pixel by setting the color value to 0 making the LED black.

void printText (const char \*text, int16\_t x, int16\_t y, CRGB::HTMLColorCode color, bool wrap)

Print text on the led matrix. Uses FastLED Neomatrix library. Text could wrap and scroll.

void setBrightness (uint8\_t brightn)

Set the brightness of the led matrix.

• void outputMatrix ()

Outputs the content of the leds\_ array to the physical led matrix.

• void clearMatrix ()

Clears the content in leds\_ matrix. If this should take effect on the physical matrix, outputMatrix() should be called aferwards.

#### **Protected Attributes**

• uint8\_t brightness\_ {40}

Brightness of the leds on the matrix. Should not be too low, to avoid weird side effects. Too high values could also lead to weird side effects or just not working matrix, due to not enough power delivery.

• bool initailized\_ {false}

Is set true, when init() is called.

• CRGB leds\_ [NUM\_LEDS]

Matrix of CRGB objects for setting the color values of the LEDs.

FastLED\_NeoMatrix \* matrix\_

Object of the FastLED Neomatrix library for controlling LEDs. This is used for higher graphical functionality like scrolling text for example.

#### 3.3.1 Constructor & Destructor Documentation

#### 3.3.1.1 led\_matrix()

```
\label{led_matrix::led_matrix} \begin{tabular}{ll} hardware::led\_matrix ::led\_matrix & t \end{tabular} \end{tabular}
```

Copy construct for a new led matrix object.

#### **Parameters**

```
t Object to copy from.
```

#### 3.3.2 Member Function Documentation

#### 3.3.2.1 printText()

Print text on the led matrix. Uses FastLED Neomatrix library. Text could wrap and scroll.

#### **Parameters**

text	Character array of the text to print.
Х	TODO where is the starting point?
У	TODO
color	TODO what does this option?
wrap	If true, text wraps around edges.

## 3.3.2.2 setBrightness()

Set the brightness of the led matrix.

#### **Parameters**

brightn	Brightness to set.
---------	--------------------

## 3.3.2.3 setPixel() [1/2]

Set the color from the default colors of a coordinate.

#### **Parameters**

X	X value of the coordinate to set.
У	Y value of the coordinate to set.
color	Default color enum.

## 3.3.2.4 setPixel() [2/2]

Set the color of a coordinate.

#### **Parameters**

X	X value of the coordinate to set.
У	Y value of the coordinate to set.
color	Color value.

## 3.3.2.5 unsetPixel()

Unsets the pixel by setting the color value to 0 making the LED black.

#### **Parameters**

Χ	X value of the coordinate to set.
У	Y value of the coordinate to set.

The documentation for this class was generated from the following files:

- led\_matrix.hpp
- · led\_matrix.cpp

## 3.4 hardware::pixelCoordinate Struct Reference

## **Public Member Functions**

```
• bool increaseX ()
```

Increases the x\_ value by 1, but not higher than the MATRIX\_HEIGHT.

• bool increaseY ()

Increases the y\_ value by 1, but not higher than the MATRIX\_WIDTH.

• bool decreaseX ()

Decreases the  $x_value$  by 1, but not less than 0.

• bool decreaseY ()

Decreases the y\_ value by 1, but not less than 0.

#### **Public Attributes**

- uint8\_t x\_
- uint8\_t **y**\_

#### 3.4.1 Member Function Documentation

#### 3.4.1.1 decreaseX()

```
bool hardware::pixelCoordinate::decreaseX ( )
```

Decreases the  $x_{-}$  value by 1, but not less than 0.

#### Returns

true New value is not out of matrix dimension.

false New value is out of matrix dimension.

#### 3.4.1.2 decreaseY()

```
bool hardware::pixelCoordinate::decreaseY ( )
```

Decreases the y\_ value by 1, but not less than 0.

#### Returns

true New value is not out of matrix dimension. false New value is out of matrix dimension.

## 3.4.1.3 increaseX()

```
bool hardware::pixelCoordinate::increaseX ( )
```

Increases the x\_ value by 1, but not higher than the MATRIX\_HEIGHT.

#### Returns

true New value is not out of matrix dimension MATRIX\_HEIGHT. false New value is out of matrix dimension MATRIX\_HEIGHT.

## 3.4.1.4 increaseY()

```
bool hardware::pixelCoordinate::increaseY ( )
```

Increases the y\_value by 1, but not higher than the MATRIX\_WIDTH.

#### Returns

true New value is not out of matrix dimension MATRIX\_WIDTH. false New value is out of matrix dimension MATRIX\_WIDTH.

The documentation for this struct was generated from the following files:

- · led\_matrix.hpp
- led\_matrix.cpp

## 3.5 software::snake Class Reference

#### **Public Member Functions**

• snake ()

Construct a new snake object.

•  $\sim$ snake ()

Destroy the snake object.

• void init (hardware::pixelCoordinate coord, hardware::joy\_stick::direction dir)

Init function for this object. Need to be called shortly after initialisation. The start coordinate and start direction is set by this method.

void move (hardware::pixelCoordinate coord)

Move the snake on coordinate. Add the new coordinate and deletes the tail coordinate of the snake.

void grow (hardware::pixelCoordinate coord)

Grows the snake to the coordinate. Add the new coordinate, but does not delete the tail coordinate.

hardware::pixelCoordinate getHeadCoord ()

Get the coordinate of the snake head.

hardware::pixelCoordinate getTailCoord ()

Get the coordinate of the snake tail.

• hardware::joy\_stick::direction getDirection ()

Get the direction of the snake.

void setDirection (hardware::joy\_stick::direction dir)

Set the direction object of the snake. Can not be no direction, must be up, right, lef or down.

uint8\_t getSnakeLength ()

Get the length of the snake, the number of coordinates in the deque.

## 3.5.1 Member Function Documentation

### 3.5.1.1 getDirection()

```
\verb| hardware::joy_stick::direction| software::snake::getDirection| ( )
```

Get the direction of the snake.

Returns

hardware::joy\_stick::direction Direction of the snake.

#### 3.5.1.2 getHeadCoord()

```
hardware::pixelCoordinate software::snake::getHeadCoord ( )
```

Get the coordinate of the snake head.

Returns

hardware::pixelCoordinate Coordinate of the head.

#### 3.5.1.3 getSnakeLength()

```
uint8_t software::snake::getSnakeLength ( )
```

Get the length of the snake, the number of coordinates in the deque.

#### Returns

uint8 t Length of the snake.

## 3.5.1.4 getTailCoord()

```
hardware::pixelCoordinate software::snake::getTailCoord ( )
```

Get the coordinate of the snake tail.

#### Returns

hardware::pixelCoordinate Coordinate of the tail.

#### 3.5.1.5 grow()

Grows the snake to the coordinate. Add the new coordinate, but does not delete the tail coordinate.

#### **Parameters**

coord New coordinate to add.	
------------------------------	--

#### 3.5.1.6 init()

Init function for this object. Need to be called shortly after initialisation. The start coordinate and start direction is set by this method.

#### **Parameters**

coord	Starting coordinate.
dir	Starting direction.

## 3.5.1.7 move()

Move the snake on coordinate. Add the new coordinate and deletes the tail coordinate of the snake.

#### **Parameters**

coord New coordinate to add.

## 3.5.1.8 setDirection()

Set the direction object of the snake. Can not be no direction, must be up, right, lef or down.

#### **Parameters**

dir New direction to set.

The documentation for this class was generated from the following files:

- · snake.hpp
- snake.cpp

## **Chapter 4**

## **File Documentation**

## 4.1 game.hpp

```
00001 #ifndef __game_header_included__
00002 #define __game_header_included_
00003
00004 #include <string>
00005
00006 #include "snake.hpp"
00007 #include "led_matrix.hpp"
00008 #include "joy_stick.hpp"
00009
00010 namespace software {
00011
00012 class game {
00013
       private:
00019
          enum gameMode {
            easy,
normal,
00020
00022
00023
          } ;
00028
          enum pixelType {
00029
            unset,
             snakeHead,
00030
00031
            snakeTail,
00032
            food,
00033
            obstacle
00034
00035
00036
          //std::array<std::array<pixelType, MATRIX_WIDTH>, MATRIX_HEIGHT> gameBoard_;
00042
          pixelType gameBoard_[MATRIX_WIDTH][MATRIX_HEIGHT];
00047
           hardware::led_matrix ledMatrix_;
00052
           hardware::joy_stick joyStick_;
00057
           software::snake snake_;
00062
           gameMode currentGameMode_{gameMode::normal};
00067
          uint8_t numberOfFood_{0};
00068
00075
           void setPixel(hardware::pixelCoordinate coord, pixelType type);
00083
          bool isPixelFree(hardware::pixelCoordinate coord);
00091
           bool isPixelFood(hardware::pixelCoordinate coord);
00099
          bool isPixelObstacle(hardware::pixelCoordinate coord);
bool isPixelSnake(hardware::pixelCoordinate coord);
00107
00114
          pixelType getPixelType(hardware::pixelCoordinate coord);
00120
           void loseGame();
00129
           void spawnFood(const uint8_t &number);
00142
          bool makeMove();
00143
00144
        public:
          game(hardware::led_matrix _ledMatrix, hardware::joy_stick _joyStick);
00153
00158
           ~game();
00169
          void init();
00179
          bool exec();
00187
          bool menu();
00188 };
00189 }
00190
00191 #endif // __game_header_included__
```

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## 4.2 joy\_stick.hpp

```
00001 #ifndef __joy_stick_header_included__
00002 #define __joy_stick_header_included_
00003 #include <sys/_stdint.h>
00004 #include <Arduino.h>
00005
00006 namespace hardware {
00007
00008 class joy_stick {
00009
       private:
00010
          // pins
          const uint8_t buttonPin_;
00022
          const uint8_t vrxPin_;
00028
          const uint8_t vryPin_;
00029
          // resolution
00030
          const uint16_t centerPoint_{2047};
00038
00048
          const uint16_t centerDetectRadius_{1000};
00049
00050
00056
          bool initialized_{false};
00057
          bool isOutOfDetectBand(const int32_t &val);
00068
00078
          bool isOutOfDetectRadius(uint32_t x, uint32_t y);
08000
00088
          joy_stick(uint8_t _buttonPin, uint8_t _vrxPin, uint8_t _vryPin);
00094
           joy_stick(joy_stick &t);
00099
          ~joy_stick();
00100
          enum direction {
00106
            noDirection,
00107
00108
            down,
00109
            left.
00110
            right
00111
00112
00118
          void init();
00124
          direction getDirection();
00131
          bool isPressed();
00132 };
00133 }
00135 #endif // __joy_stick_header_included__
```

## 4.3 led\_matrix.hpp

```
00001 #ifndef __led_matrix_header_included__
00002 #define __led_matrix_header_included_
00004 #include <Adafruit_GFX.h>
00005 #include <FastLED_NeoMatrix.h>
                                     // official FastLed 3.6.0 release doesnt work (missing uno r4 minima
00006 #include <FastLED.h>
     support)
                                     // #1523 from facchinm (bit buggy but works) (04.12.2023) -->
     https://github.com/FastLED/FastLED/tree/0398b9a99901d00044de82led86e8537995f561b
00008 #ifndef PSTR
00009 #define PSTR // Make Arduino Due happy
00010 #endif
00011
00012 #define COLOR_ORDER
                                     //GRB
                                              breaks if changed
00013 #define CHIPSET
                             WS2812B //WS2812B breaks if changed
00014 #define LED PIN
00015 #define MATRIX_WIDTH 16
00016 #define MATRIX_HEIGHT 16
00017 #define NUM_LEDS
                             (MATRIX_HEIGHT * MATRIX_WIDTH)
00019
00020 namespace hardware {
00021
00022 struct pixelCoordinate {
00023 uint8_t x_;
        uint8_t y_;
00031
        bool increaseX();
00038
        bool increaseY();
00045
       bool decreaseX();
00052
       bool decreaseY();
00053 };
00055 inline bool operator==(const pixelCoordinate& first, const pixelCoordinate& second) {
```

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```
return (first.x_ == second.x_) && (first.y_ == second.y_);
00057 }
00058
00059 class led matrix {
00060
         protected:
00068
            uint8_t brightness_{40};
            bool initailized_{false};
00078
            CRGB leds_[NUM_LEDS];
00085
            FastLED_NeoMatrix *matrix_;
00086
00087
         public:
00092
            led_matrix();
            led_matrix(led_matrix &t);
00098
00103
            ~led_matrix();
00108
            enum colorPixel{
00109
               obstacle = CRGB::Red,
                       = CRGB::Yellow,
00110
               tail
                         = CRGB::Green,
00111
               food
                         = CRGB::Blue
00112
              head
00113
            };
00119
            void init();
00120
            //#### visualisation functions #####
00121
            //##### Visualisation functions #####
void setPixel(uint16_t x, uint16_t y, colorPixel color);
void setPixel(uint16_t x, uint16_t y, uint32_t color);
void unsetPixel(uint16_t x, uint16_t y);
void printText(const char *text, int16_t x, int16_t y,
00129
00137
00156
00157
                                CRGB::HTMLColorCode color, bool wrap);
00163
            void setBrightness(uint8_t brightn);
00168
            void outputMatrix();
00174
            void clearMatrix();
00175 };
00176 }
00177
00178 #endif // __led_matrix_header_included__
```

## 4.4 snake.hpp

```
00001 #ifndef __snake_header_included_
00002 #define __snake_header_included_
00003
00004 #include <deque>
00005 #include <algorithm>
00006 #include "led_matrix.hpp"
00007 #include "joy_stick.hpp"
80000
00009 namespace software {
00010 class snake {
00011 private:
00017
          std::deque<hardware::pixelCoordinate> snake_;
00023
          hardware::joy_stick::direction snakeDirection_;
00028
          bool initialized_{false};
00036
          bool contains(const hardware::pixelCoordinate &coord);
00037
00038
        public:
00043
          snake();
00048
           ~snake();
00057
          void init(hardware::pixelCoordinate coord,
00058
                     hardware::joy_stick::direction dir);
00065
          void move(hardware::pixelCoordinate coord);
00072
          void grow(hardware::pixelCoordinate coord);
00078
          hardware::pixelCoordinate getHeadCoord();
00084
          hardware::pixelCoordinate getTailCoord();
          hardware::joy_stick::direction getDirection();
00097
           void setDirection(hardware::joy_stick::direction dir);
00104
          uint8_t getSnakeLength();
00105 };
00106 }
00107
00108 #endif // __snake_header_included__
```

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