

MEMORANDUM

October 22, 2025

TO: Dr. Arthur Erdman

FROM: Peyton Lettau, Sebastian Hondl, John Robinson, Will McConnell

SUBJECT: Progress Report 1 - Miniature Tabletop Greenhouse Mechanism Design

DATE: October 22, 2025

EXECUTIVE SUMMARY

This memorandum summarizes the progress on the miniature tabletop greenhouse mechanism design project. Through systematic type synthesis and patent analysis, we have identified the Watt I six-bar mechanism as the optimal topology for path generation. The work demonstrates the inadequacy of four-bar solutions for the given constraints and establishes a clear path forward for dimensional synthesis and prototype development.

PROBLEM STATEMENT

The project addresses the challenge of designing a mechanism for a miniature tabletop greenhouse that can simultaneously open both top and front panels while meeting strict spatial constraints. A greenhouse creates a controlled microclimate by admitting short-wave solar radiation while slowing heat loss, raising temperature and humidity to support plant growth. In miniature formats, these same principles are compressed to a smaller area, but certain criteria become more difficult to maintain due to scaling effects.

Design Requirements

Key requirements include:

- Single-degree-of-freedom motion with one user input
- Compact tabletop dimensions (18" × 18" × 24")
- Support for 5 lb panels with smooth motion
- Mechanism must not extend beyond greenhouse silhouette when closed
- Enable access to plants from both top and front faces simultaneously
- The opening above the enclosure must be >90% of the depth of the enclosure

- Allow front and top of the enclosure to be positioned at any position between open and close and remain in place
- Fold the top and front panels above the enclosure, creating unobstructed access for plant maintenance

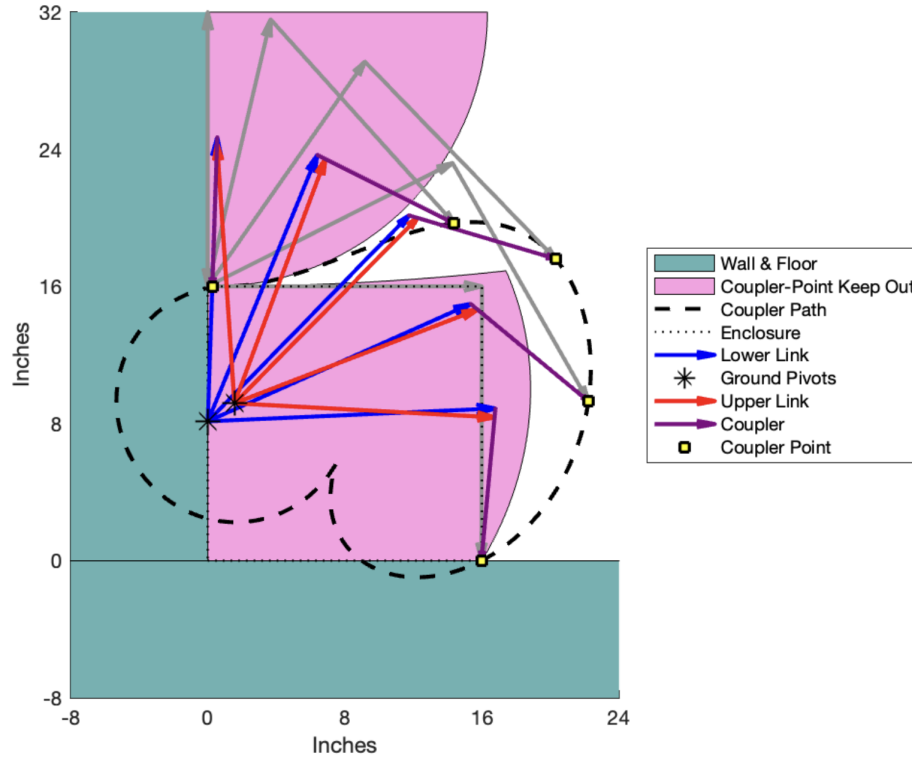


Figure 1: Coupler point analysis for mechanism path generation

PATENT ANALYSIS

Analysis of existing solutions revealed significant scaling challenges. Common access solutions range from simple to engineered approaches. Low-tech options include clothes and cold-frame-style hinged lids, sliding or lift-off clear panels, roll-up soft sides, zipper covers, and magnetic or hook-and-loop closures. More refined mechanisms add hold-open features and controllable venting: front-hinged or top-hinged lids with friction hinges or gas springs; scissor-link or four-bar "pop-top" lids that lift and translate to clear the aperture; rack-and-pinion or cam-assisted lift for precise positioning; and side-access tambour doors for tight spaces.

Detailed Patent Analysis

Patent 1 - Portable Greenhouse (Koziol, 1974 [1]): This patent represents a practical full-scale greenhouse solution using a different opening and closing system. While effective at full size, scaling this design down presents significant operational challenges. The plurality of covered sides becomes more complex to operate when the greenhouse is positioned on a desk, and the mechanism components become proportionally smaller and more difficult to manipulate.

Patent 2 - Full-Scale Greenhouse Covering (Jaderloon Company, 1999 [2]): This design functions to keep out rainwater using cable systems, rotating shafts, and tension drums that require very precise alignment. While effective at full scale, these systems are not feasible for small-scale applications. Scaling down would make parts more fragile, expensive, and difficult to assemble. Additionally, the tension in cables does not scale proportionally when reduced to smaller sizes, leading to inadequate performance or excessive complexity.

Patent 3 - Greenhouse Window Mechanism (Bom, 1978 [3]): This patent shows an opening and closing mechanism for greenhouse windows that demonstrates potential scalability to the current project. The mechanism relies on rigid bars and rotational joints, making it more suitable for adaptation to small-scale applications. The triangular guide-bar linkage coordinates multiple vents with stable geometry, offering promise for synchronized, multi-panel tabletop access.

DESIGN PROCESS

Solution Approach Options

The design problem can be formulated through multiple approaches:

1. **Path Generation:** A point on the front panel is selected as the coupler point, and a linkage is synthesized to guide this point through a series of precision positions while maintaining the front panel attachment through a pivot connection.
2. **Motion Synthesis:** The top and front panels are linked within the mechanism, and the mechanism is synthesized based on the angular and positional relationships of the front panel throughout its range of motion.

Selected Solution Approach

For this project, the path generation approach was selected as the primary design methodology. Initial work attempted to synthesize a four-bar linkage for this task, but analysis indicates that a satisfactory four-bar solution is unlikely to exist within the given constraints. However, it appears probable that an effective solution can be achieved using linkages with additional degrees of freedom, such as six-bar or eight-bar mechanisms.

TECHNICAL APPROACH

Type Synthesis Process

Following Erdman and Sandor (1990) methodology [4], we applied Gruebler’s equation $F = 3(n - 1) - 2f_1 - f_2$ for planar mechanisms. Initial four-bar analysis ($n = 4$, $f_1 = 4$) revealed no feasible solutions within spatial constraints. This necessitated exploration of six-bar mechanisms ($n = 6$, $f_1 = 7$).

Four-Bar Analysis

Initial synthesis attempts demonstrated that four-bar linkages cannot simultaneously satisfy the spatial constraints—ground pivots must be located at the base within 8 cm height with maximum

25 cm separation—and achieve the required door motion with translation through three precision positions. The compact greenhouse envelope combined with ground pivot placement restrictions resulted in no feasible four-bar solutions.

Six-Bar Mechanism Development

Using the equation $n - (F + 3) = T + 2Q + 3P$ for link types, where T , Q , and P represent ternary, quaternary, and pentagonal links respectively, we find that $6 - (1 + 3) = 2$ for our six-bar, single-DOF mechanism. The standard kinematic link set solution (KLSS) comprises 2 ternary links and 4 binary links, providing the foundation for mechanism topology development.

Systematic enumeration of basic kinematic chains (BKC) from this KLSS, with application of the degree-of-freedom distribution criterion to eliminate configurations containing zero-freedom subchains, yields two valid BKC: the Watt chain, characterized by two ternary links sharing a common connection, and the Stephenson chain, where the ternary links are separated by binary links.

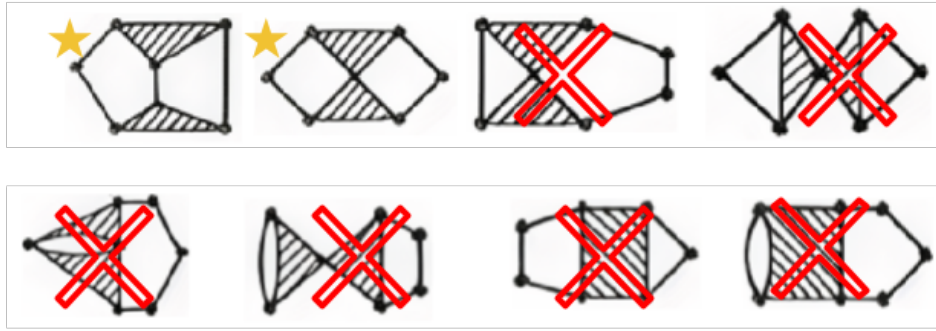


Figure 2: Six-bar mechanism topology options

Topology Selection

Five topological variations were evaluated: Watt I, Watt II, Stephenson I, Stephenson II, and Stephenson III. The critical differentiator was ground pivot accessibility. Watt II, Stephenson II, and Stephenson III require ternary ground links with three ground pivots, which cannot be accommodated on the compact greenhouse base structure.

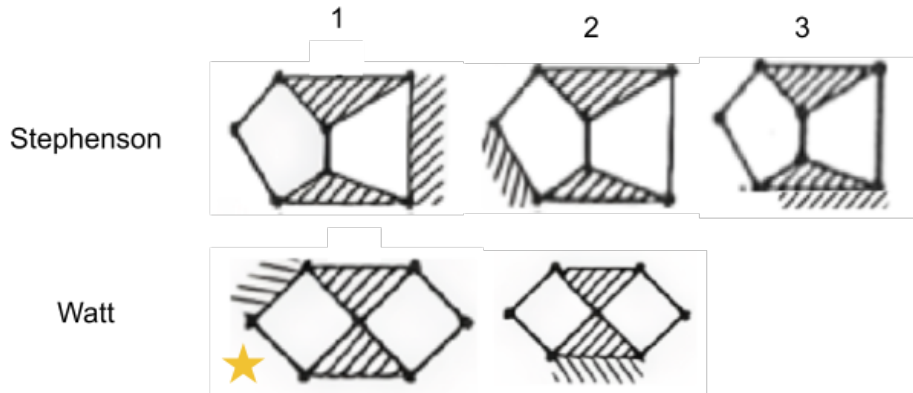


Figure 3: Stephenson and Watt chain configurations

SOLUTION SELECTION

The Watt I configuration emerged as optimal, providing:

- Two accessible ground pivots (15-20 cm separation)
- Compact dual-loop structure with 8-20 cm link lengths
- Favorable transmission angle characteristics
- Single-degree-of-freedom motion with one input

All seven joints are specified as revolute (pin) joints for manufacturing simplicity. The configuration positions the binary link connected to ground pivot G_A as the input crank, guiding the door panel through three precision positions: closed, ventilation, and fully open.

RESULTS AND ANALYSIS

The systematic type synthesis process has successfully identified the Watt I six-bar mechanism as the optimal topology for the greenhouse application. This configuration provides:

- Two accessible ground pivots positioned at the front base edge
- Compact dual-loop structure with appropriate link lengths
- Favorable transmission angle characteristics
- Single-degree-of-freedom motion with one input
- Spatial compatibility within the greenhouse envelope

The selected configuration positions the binary link connected to ground pivot G_A as the input crank, accessible for external user interaction while the mechanism guides the door panel through the three precision positions: closed, ventilation, and fully open.

FUTURE WORK

The next phase of the project will focus on:

- **Dimensional synthesis:** Detailed design of the Watt I mechanism with specific link lengths and joint positions
- **Optimization:** Optimization of link lengths and joint positions to achieve optimal performance

CONCLUSION

The systematic type synthesis process has successfully identified the Watt I six-bar mechanism as the optimal solution for the greenhouse application. This configuration provides the necessary design flexibility while meeting all spatial constraints and performance requirements. The work establishes a clear foundation for dimensional synthesis and prototype development.

Prepared by: Project Team

Date: October 22, 2025

References

- [1] L. L. Koziol, “Portable greenhouse,” 1974. Google Patents.
- [2] I. Jaderloon Company, “Covering mechanism for a greenhouse,” 1999. Google Patents.
- [3] P. L. J. Bom, “Greenhouse window actuating mechanism,” 1978. Google Patents.
- [4] A. G. Erdman and G. N. Sandor, *Mechanism Design: Analysis and Synthesis*, vol. 1. Englewood Cliffs, NJ: Prentice Hall, 2nd ed., 1990.