Robotics

Exercise 1

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1 Matrix equations (4 points)

a) Let X, A be arbitrary matrices, A invertible. Solve for X:

$$XA + A^{\mathsf{T}} = \mathbf{I}$$

b) Let X, A, B be arbitrary matrices, $(C - 2A^{\mathsf{T}})$ invertible. Solve for X:

$$X^{\mathsf{T}}C = [2A(X+B)]^{\mathsf{T}}$$

c) Let $x \in \mathbb{R}^n, y \in \mathbb{R}^d, A \in \mathbb{R}^{d \times n}$. A obviously not invertible, but let $A^T A$ be invertible. Solve for x:

$$(Ax - y)^{\mathsf{T}} A = \mathbf{0}_n^{\mathsf{T}}$$

d) As above, additionally $B \in \mathbb{R}^{n \times n}$, B positive-definite. Solve for x:

$$(Ax - y)^{\mathsf{T}}A + x^{\mathsf{T}}B = \mathbf{0}_{n}^{\mathsf{T}}$$

2 Vector derivatives (5 points)

Let $x \in \mathbb{R}^n$, $y \in \mathbb{R}^d$, $f, g : \mathbb{R}^n \to \mathbb{R}^d$, $A \in \mathbb{R}^{d \times n}$, $C \in \mathbb{R}^{d \times d}$. (Also provide the dimensionality of the results.)

- a) What is $\frac{\partial}{\partial x}x$?
- b) What is $\frac{\partial}{\partial x}[x^{\mathsf{T}}x]$?
- c) What is $\frac{\partial}{\partial x}[f(x)^{\mathsf{T}}f(x)]$?
- d) What is $\frac{\partial}{\partial x}[f(x)^{\mathsf{T}}Cg(x)]$?
- e) Let B and C be symmetric (and pos.def.). What is the minimum of $(Ax y)^T C(Ax y) + x^T Bx$ w.r.t. x?

3 Optimization (3 points)

Given $x \in \mathbb{R}^n$, $f: \mathbb{R}^n \to \mathbb{R}$, we want to find $\operatorname{argmin}_x f(x)$. (We assume f is uni-modal.)

- a) What 1st-order optimization methods (querying f(x), $\nabla f(x)$ in each iteration) do you know?
- b) What 2nd-order optimization methods (querying f(x), $\nabla f(x)$, $\nabla^2 f(x)$ in each iteration) do you know?
- c) What is backtracking line search?