

Week 5: Evaluating niche-based distribution models

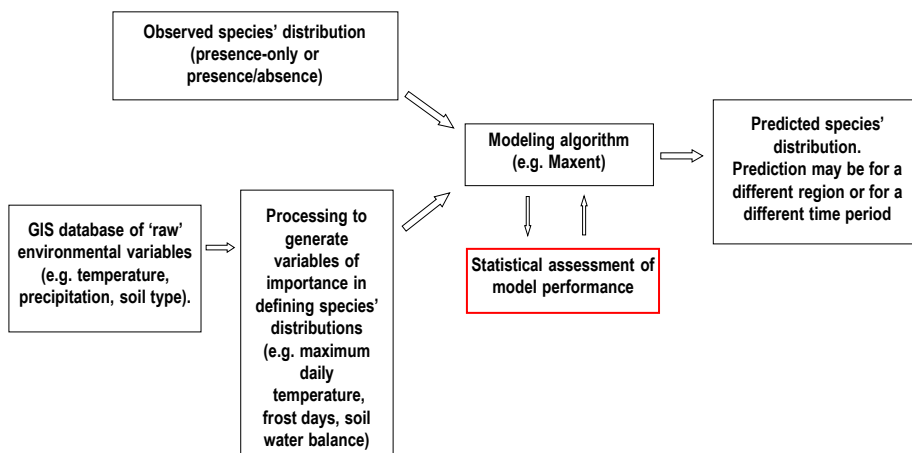
Peter Galante

Outline:

1. Maxent model tuning
 2. Model validation
 3. Model evaluation
 4. Evaluation statistics
 5. Model complexity and advanced considerations
- (thanks to Richard Pearson, Rob Anderson, and Mary Blair for content)

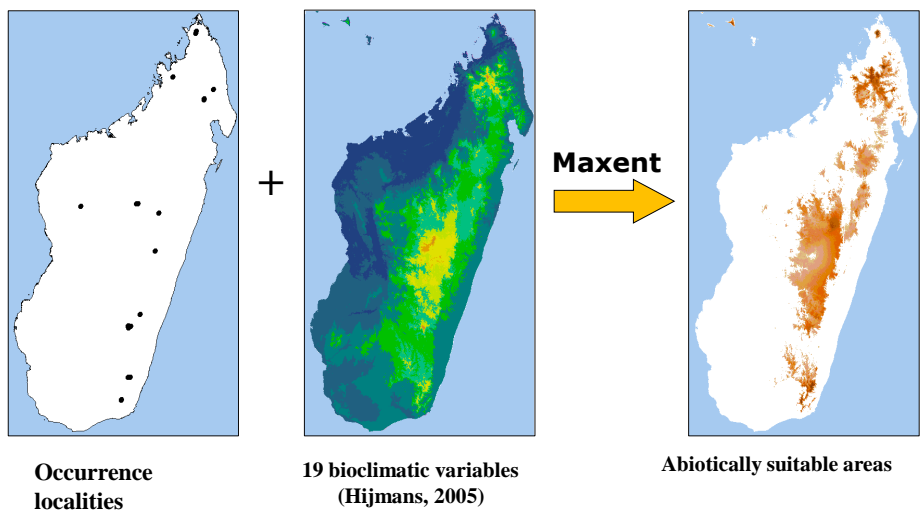
1

Flow diagram detailing the main steps required for building and validating a correlative species distribution model



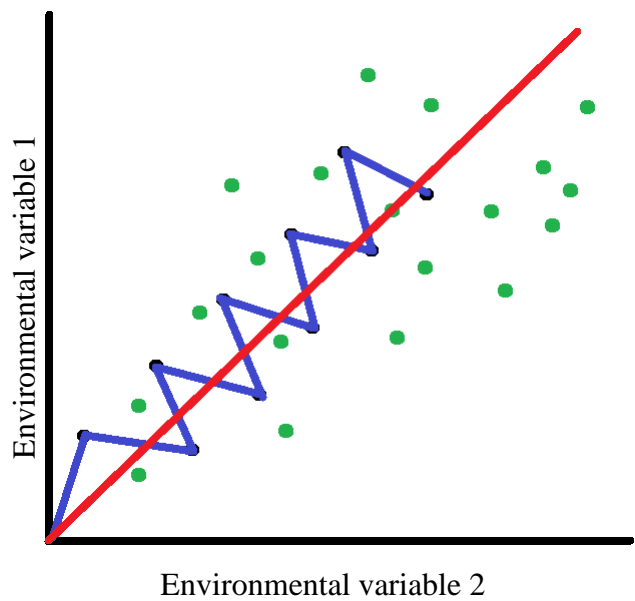
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Niche Models



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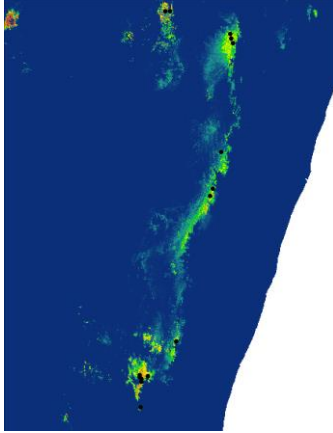
Model Complexity vs. Generality



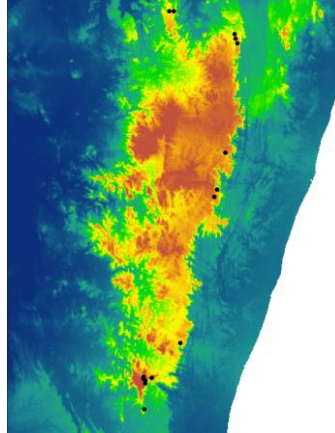
4

Model Selection

Complex



Simple



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Model Tuning

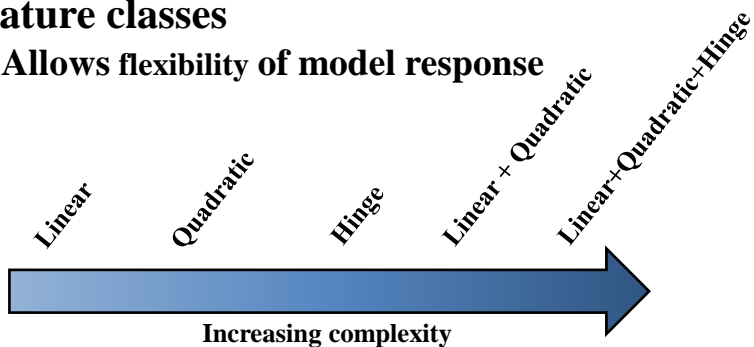
Two settings in Maxent (in ENMeval):

Regularization multiplier:

Increasing regularization increases penalties on model complexity $0 \rightarrow ?$

Feature classes

Allows flexibility of model response



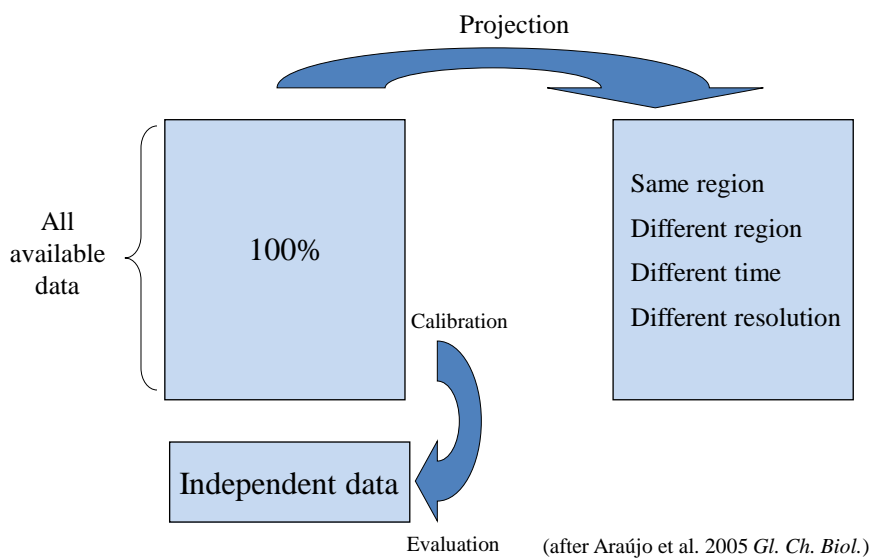
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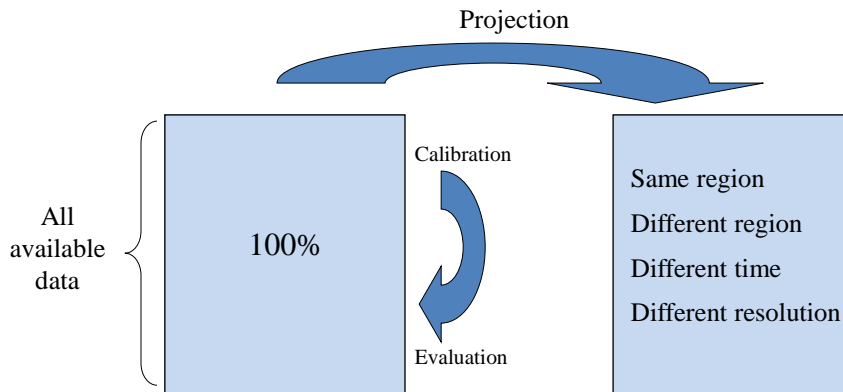
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Model calibration and evaluation strategies: independent validation



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Model calibration and evaluation strategies: resubstitution

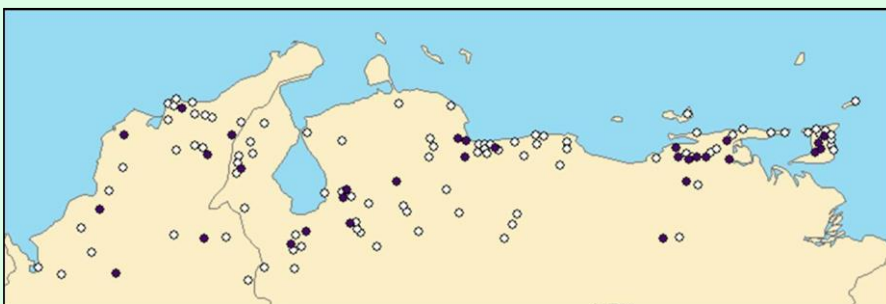


(after Araújo et al. 2005 *Gl. Ch. Biol.*)

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Random subsets

random split-sample approach: easy test, cannot detect overfitting to bias

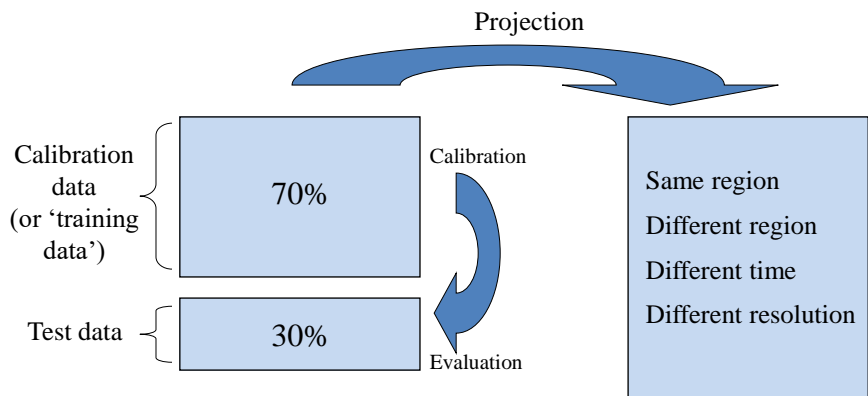


White: calibrate the model

Black: evaluate the model

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Model calibration and evaluation strategies: data splitting

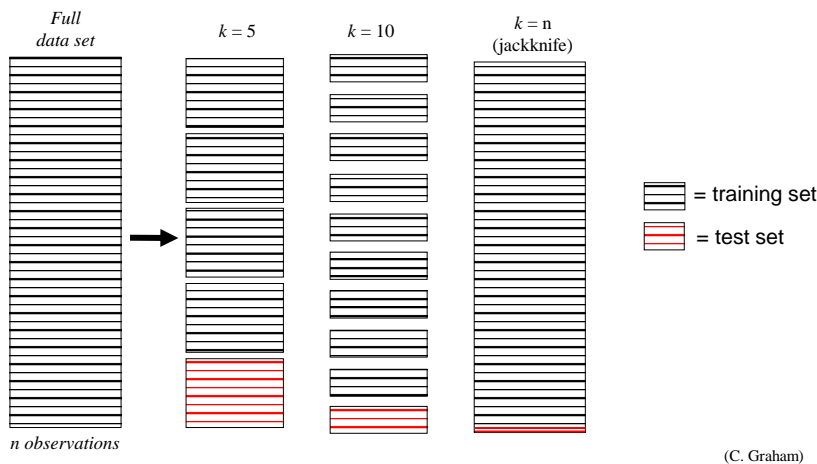


(after Araújo et al. 2005 *Gl. Ch. Biol.*)

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Model calibration and evaluation strategies: cross validation/ k -fold partitioning

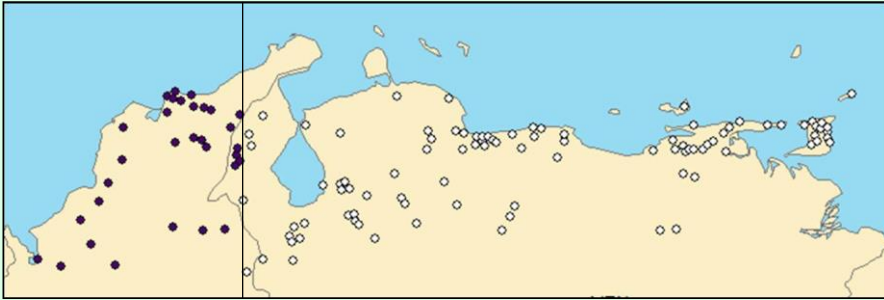
1. Split data randomly into k roughly equal-sized parts. Take turns using each part as a test set and the other $k - 1$ parts for model training.
2. Compute test statistic each time. Cross-validation estimate of predictive performance is the average of the k tests.



(C. Graham)

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Spatial subsets

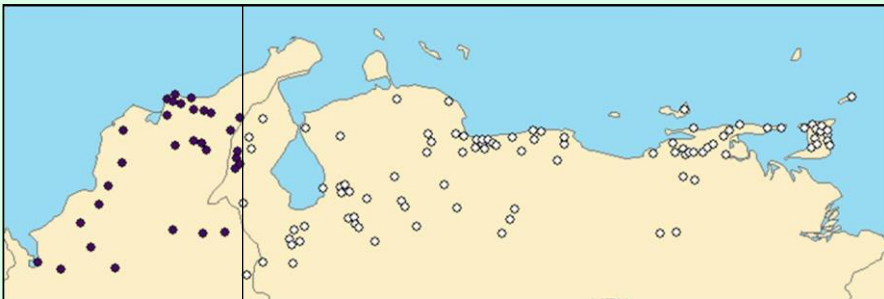


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Spatial subsets



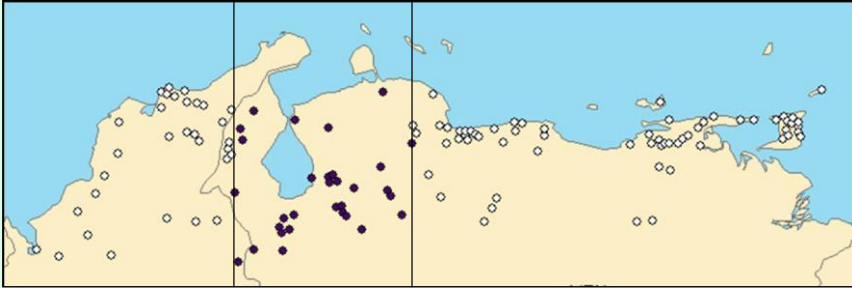
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Radosavljevic & Anderson 2014

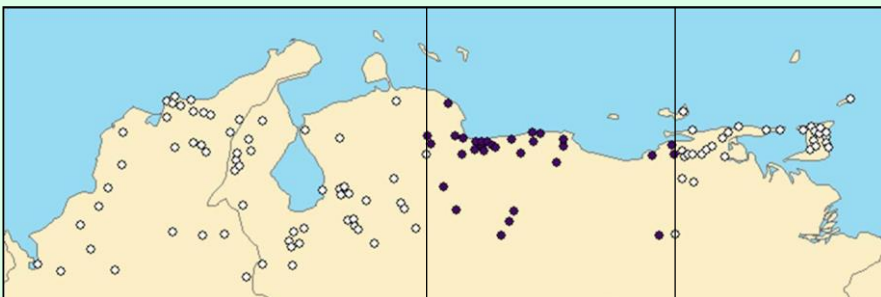
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Bin B for evaluation



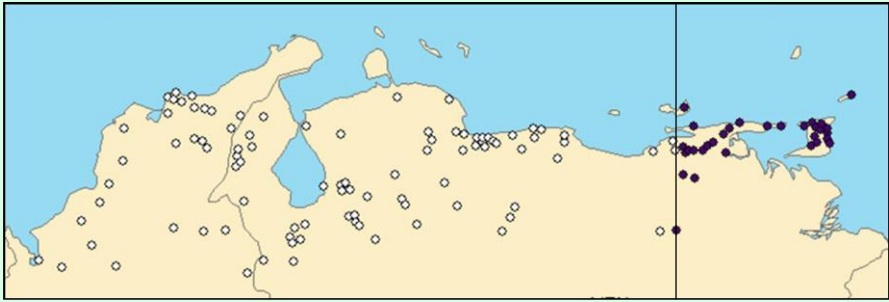
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Bin C for evaluation

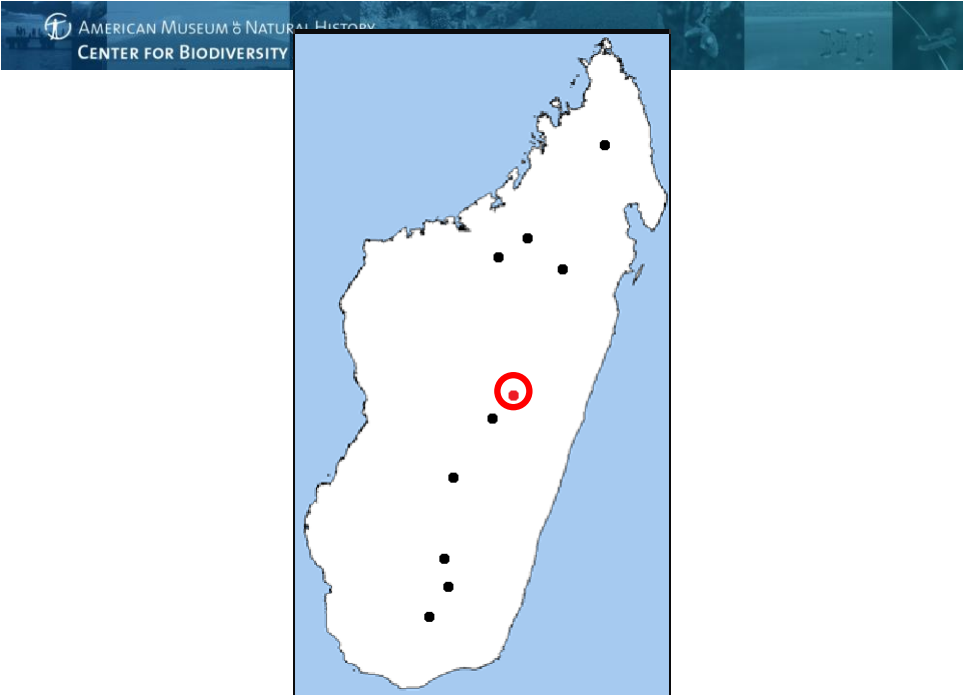


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Bin D for evaluation



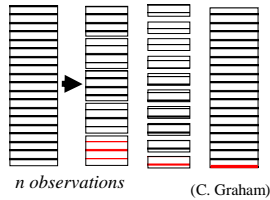
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Model calibration and evaluation strategies: cross validation/ k -fold partitioning

1. Split data randomly into k roughly equal-sized parts. Take turns using each part as a test set and the other $k - 1$ parts for model training.
2. Compute test statistic each time. Cross-validation estimate of predictive performance is the average of the k tests.



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Each Feature Class and
Regularization
Multiplier combination

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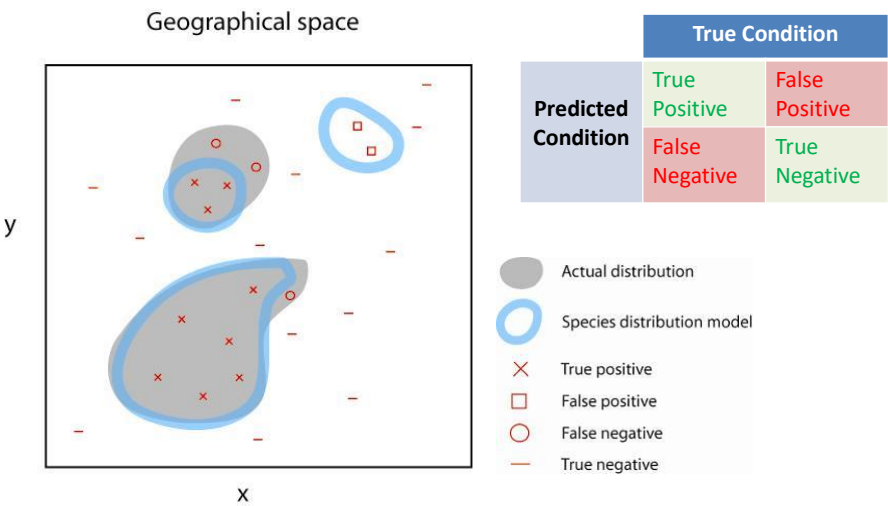


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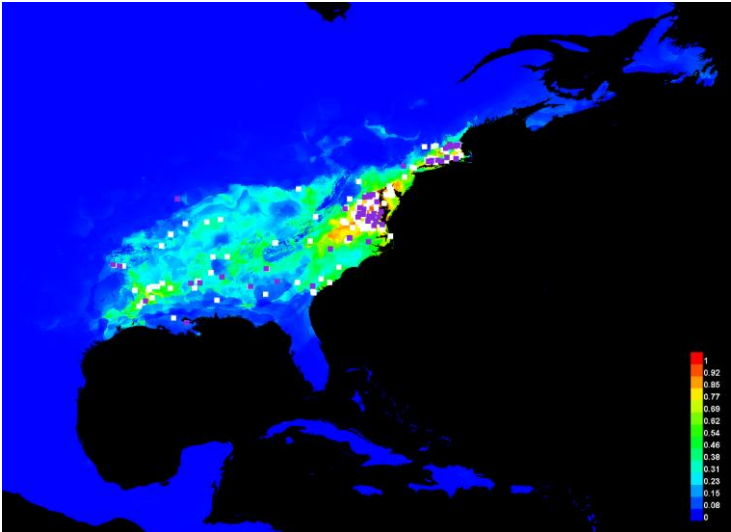
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The four types of results that are possible when testing a distribution model



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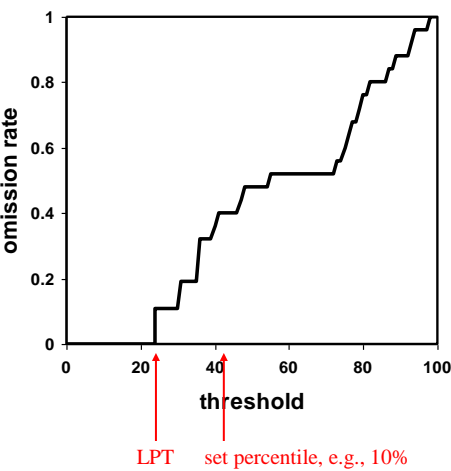
‘Continuous’ model output



Maxent model for the marbled salamander

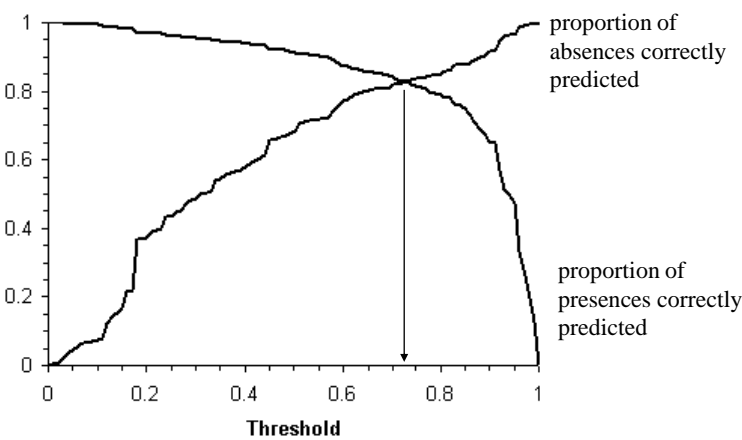
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Selecting a threshold with presence-only data



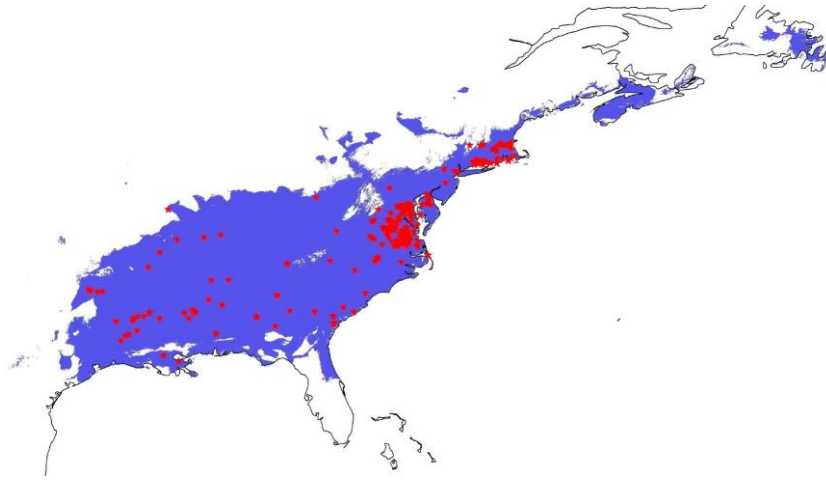
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Selecting a threshold with presence/absence data



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Thresholded model output



Maxent model for the marbled salamander with threshold applied

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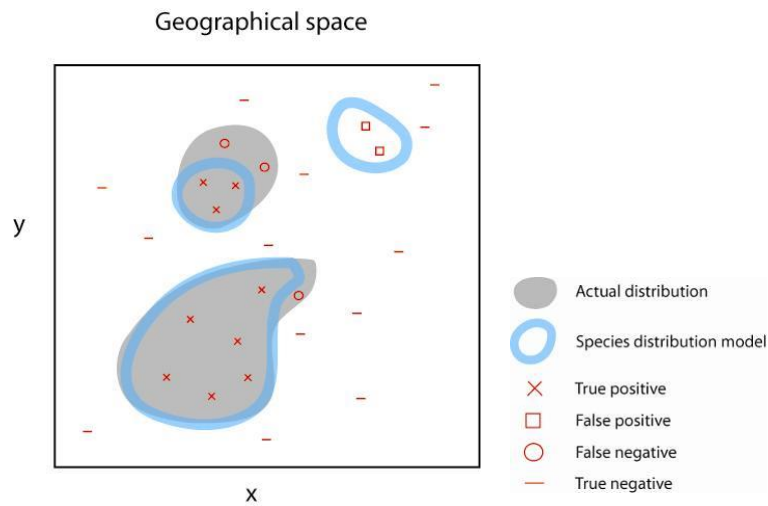


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The four types of results that are possible
when testing a distribution model



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Presence-absence confusion matrix

	<i>Recorded present</i>	<i>Recorded (or assumed) absent</i>
<i>Predicted present</i>	a (true positive)	b (false positive)
<i>Predicted absent</i>	c (false negative)	d (true negative)

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Presence-only test statistics

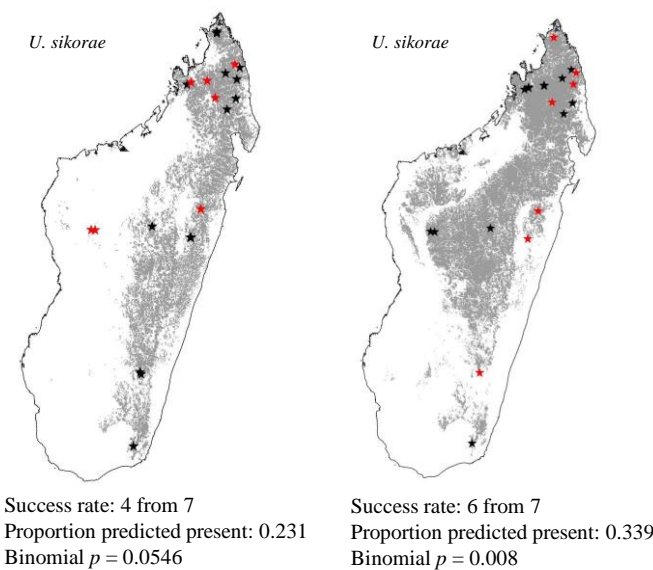
	<i>Recorded present</i>	<i>Recorded (or assumed) absent</i>
<i>Predicted present</i>	a (true positive)	b (false positive)
<i>Predicted absent</i>	c (false negative)	d (true negative)

Proportion of observed presences correctly predicted (or ‘sensitivity’, or ‘true positive fraction’):

$$a/(a + c)$$

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Presence-only test statistics:
testing for statistical significance



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Presence-absence test statistics

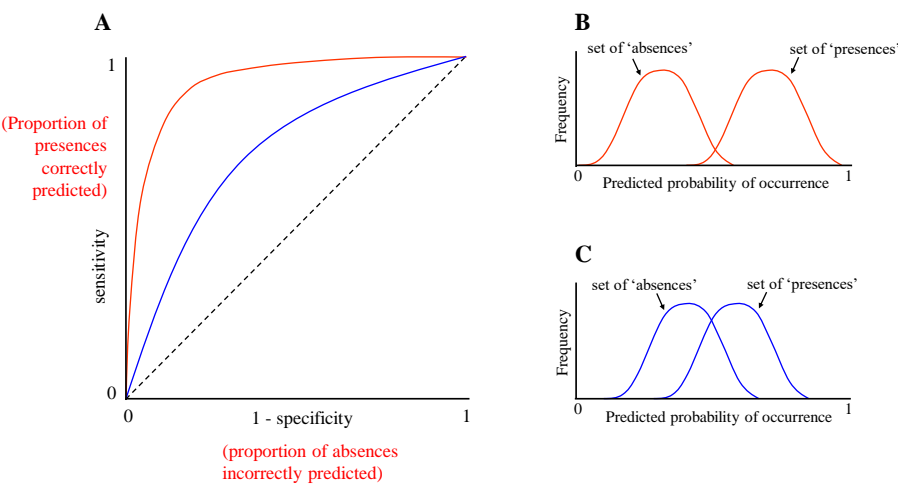
	<i>Recorded present</i>	<i>Recorded (or assumed) absent</i>
<i>Predicted present</i>	a (true positive)	b (false positive)
<i>Predicted absent</i>	c (false negative)	d (true negative)

Proportion of observed presences correctly predicted (or ‘sensitivity’):
 $a/(a + c)$

Proportion of observed absences correctly predicted (or ‘specificity’):
 $d/(b + d)$

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The Receiver Operating Characteristic (ROC) Curve



(check out: <http://www.anaesthetist.com/mnm/stats/roc/Findex.htm>)

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So, what is a ‘good’ result?

Some subjective guidelines (after Swets 1988 *Science*) :

- 0.5 – 0.7: poor discrimination
- 0.7 – 0.9: reasonable discrimination
- 0.9 – 1.0: very good discrimination

However, note that the Maxent software generates AUC statistics using ‘background’ rather than absence data, so the maximum achievable AUC score is <1 (see Phillips et al. 2006).

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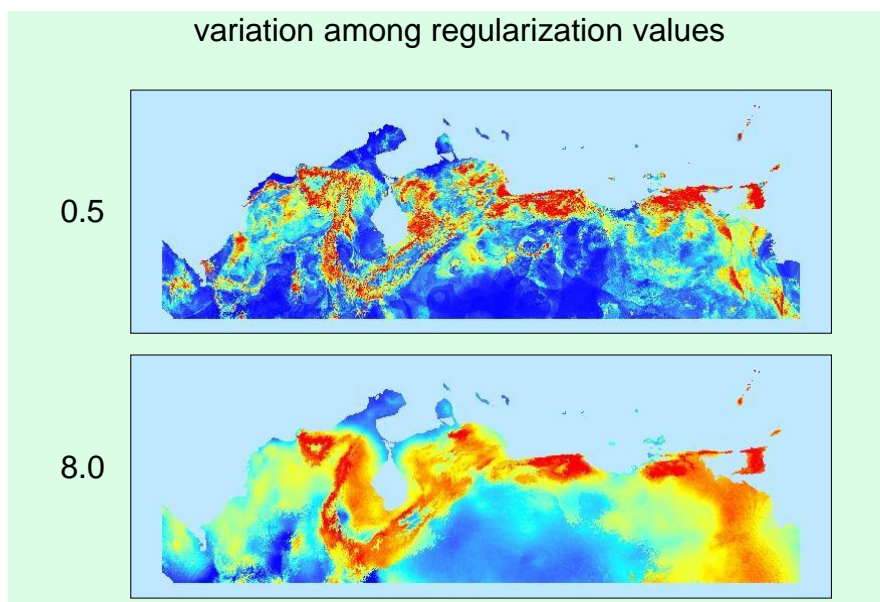
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Advanced considerations

- Model complexity:
 - Occurrence data suffer from (among other things):
 - Biased sampling across geography
 - Which may also be biased in environmental space
- Overly complex models may overfit to this bias (or to noise)
 - What is overly complex?
 - Number of variables, feature classes considered, level of regularization

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Overfitting



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Advanced considerations

- Background selection

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Advanced considerations

- ENMEval R package
 - Try different regularization values, design spatially independent training and test datasets, feature classes, number of variables (Muscarella et al. 2014)
 - SDMToolbox for ArcGIS also does some of this (Brown et al. 2014)
- spThin R package
 - thin occurrence records re: spatial autocorrelation bias (Aiello-Lammens et al. 2015)
- Bias layer for Maxent
 - for known sampling bias masking (Phillips et al. 2009)

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