

Deep Learning

P.L.D. Tien
(520K0220)

Introduction

Overview

ResNet50

ResNet50
(Overfit)

ResNet50
(Vanishing)

CNN

CNN (Overfit)

CNN
(Vanishing)

Overall results

End

Deep Learning

Midterm Assignment

P.L.D. Tien (520K0220)

Ton Duc Thang University

March 10, 2023

Deep Learning

P.L.D. Tien
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What is this?

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An image captioning system, using ResNet50 and CNN, with independent handling of overfitting and vanishing problems. This submission uses the CIFAR-10¹ for it's dataset.

Note

The snippets of code are coming from the original notebook. It's advised to look at it for a better understanding.

¹<https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz> 🔍 🔍 🔍

What does it cover?

Deep Learning

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- ResNet50
- ResNet50 (w/ Overfit handling)
- ResNet50 (w/ Vanishing handling)
- CNN
- CNN (w/ Overfit handling)
- CNN (w/ Vanishing handling)

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Intentionally left blank.

Too much to
cover here, read
the notebook.

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ResNet50
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ResNet50
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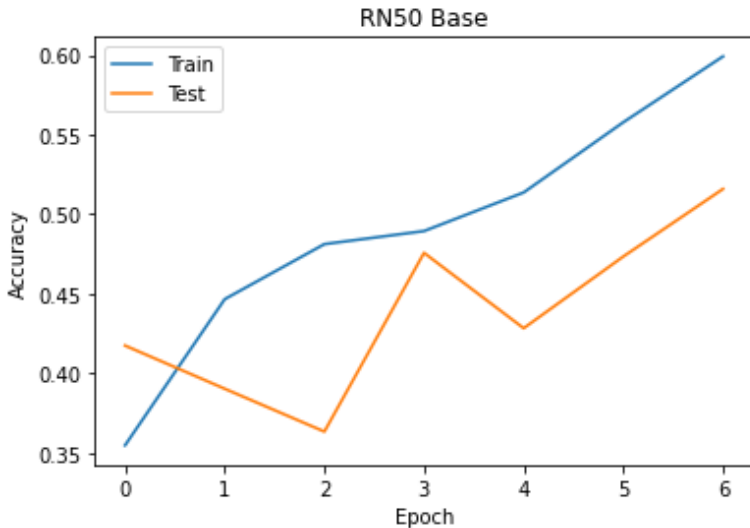
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```

39 X = AveragePooling2D(pool_size=(2, 2), padding='same')(X)
40 X = Flatten()(X)
41 #X = Dense(256, activation='relu', name='fc1', kernel_initializer='glorot_uniform')(X)
42 #X = Dense(128, activation='relu', name='fc2', kernel_initializer='glorot_uniform')(X)
43
44 X = Dense(256, activation='relu', name='fc1', kernel_initializer='glorot_uniform'\
45         , kernel_regularizer=regularizers.l2(0.01))(X)
46 X = Dense(128, activation='relu', name='fc2', kernel_initializer='glorot_uniform'\
47         , kernel_regularizer=regularizers.l2(0.01))(X)

```

Replace these lines with regularizers.

Dropout doesn't work here since they're not tensors.

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ResNet50
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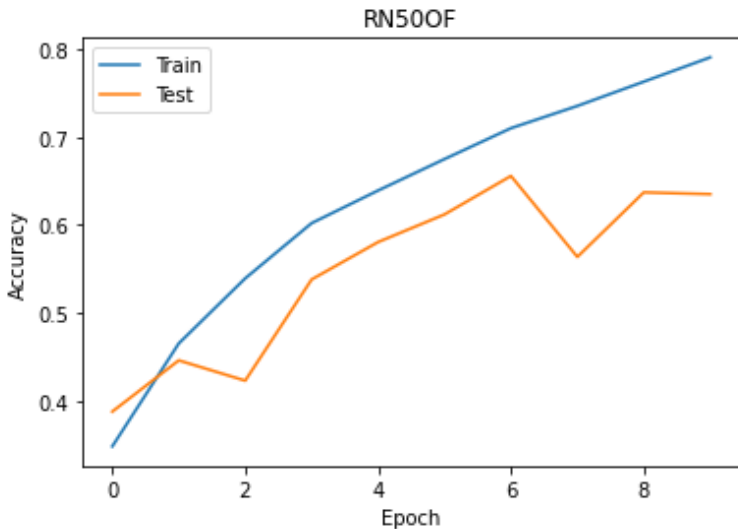
CNN

CNN (Overfit)

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```

16 # add batch normalization after ReLU activation
17 X = convolutional_block(X, f=3, filters=[64, 64, 256], stage=2, block='a', stride=1)
18 X = BatchNormalization(axis=3, name='bn_conv2')(X)
19 X = ReLU()(X)
20 X = identity_block(X, 3, [64, 64, 256], stage=2, block='b')
21 X = BatchNormalization(axis=3, name='bn_conv3')(X)
22 X = ReLU()(X)
23 X = identity_block(X, 3, [64, 64, 256], stage=2, block='c')
24 X = BatchNormalization(axis=3, name='bn_conv4')(X)
25 X = ReLU()(X)
26
27 X = convolutional_block(X, f=3, filters=[128, 128, 512], stage=3, block='a', stride=2)
28 X = BatchNormalization(axis=3, name='bn_conv5')(X)
29 X = ReLU()(X)
30 X = identity_block(X, 3, [128, 128, 512], stage=3, block='b')
31 X = BatchNormalization(axis=3, name='bn_conv6')(X)
32 X = ReLU()(X)
33 X = identity_block(X, 3, [128, 128, 512], stage=3, block='c')
34 X = BatchNormalization(axis=3, name='bn_conv7')(X)
35 X = ReLU()(X)
36 X = identity_block(X, 3, [128, 128, 512], stage=3, block='d')
--

```

We add BatchNormalization after ReLU.

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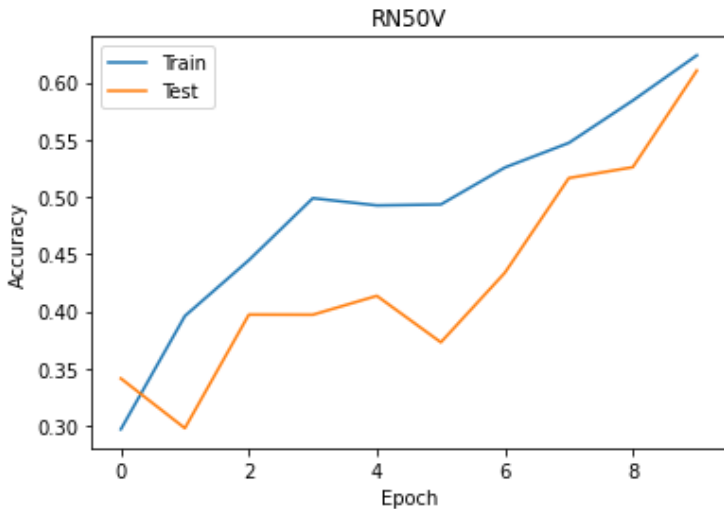
CNN

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```
model = models.Sequential([
    layers.Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same', input_shape=(32, 32, 3)),
    layers.Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),

    layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
    layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
    layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),

    layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
    layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
    layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),

    layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
    layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
    layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),

    layers.Flatten(),
    layers.Dense(64, activation='relu'),
    layers.BatchNormalization(),

    layers.Dense(10, activation='softmax')
])
```

Simple enough.

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ResNet50
(Vanishing)

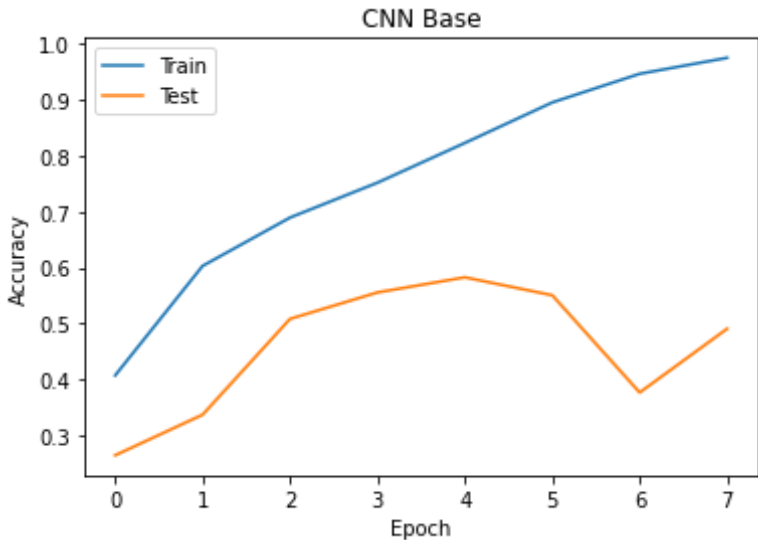
CNN

CNN (Overfit)

CNN
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```

layers.Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same', inp
layers.Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.1),

layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.1),

layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.1),

layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.1),

```

We simply add Dropout in between the blocks.

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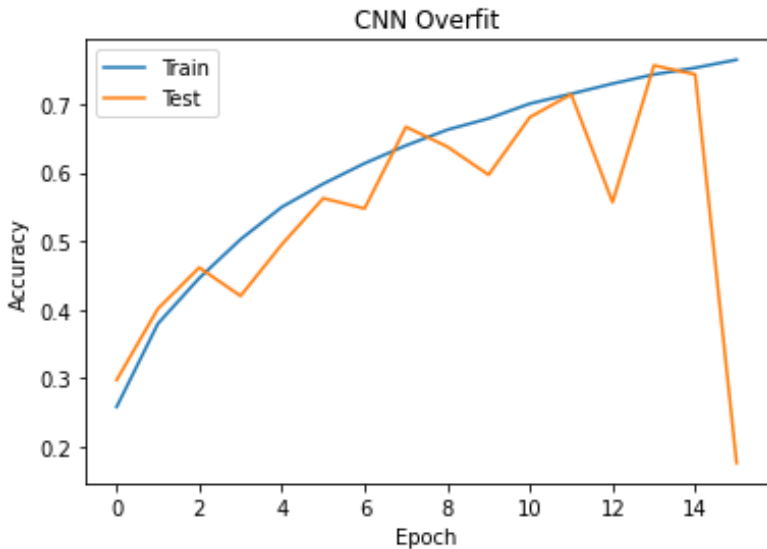
CNN

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```
layers.Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same', input_shape=(32, 32, 3)),
layers.BatchNormalization(),
layers.Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.2),

layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.3),

layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.4),

layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.Conv2D(256, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.5),
```

Add BatchNormalization in between Conv2D.

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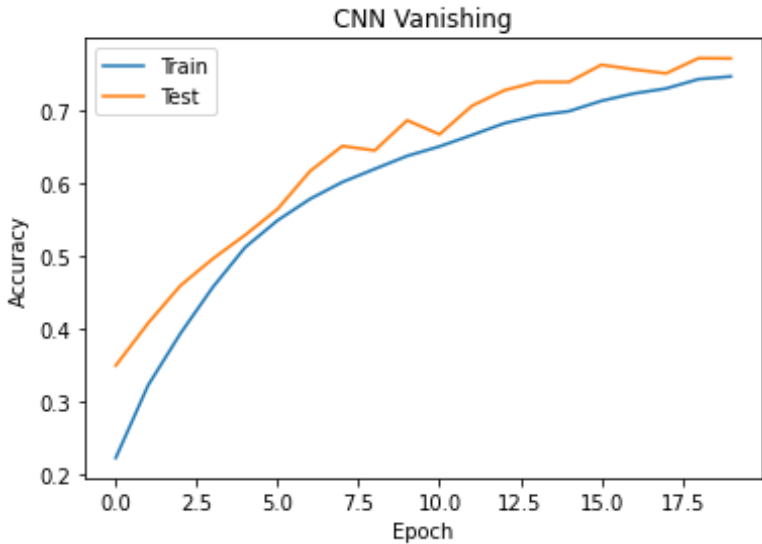
CNN

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All six of them together

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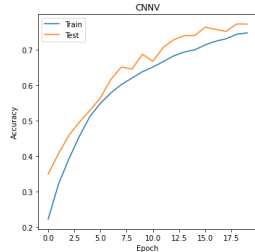
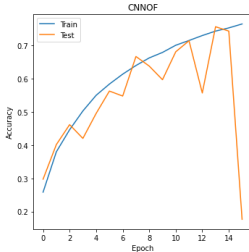
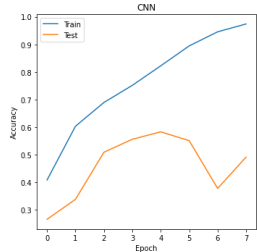
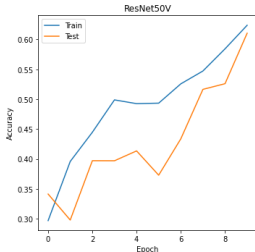
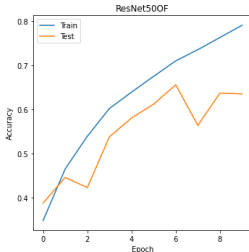
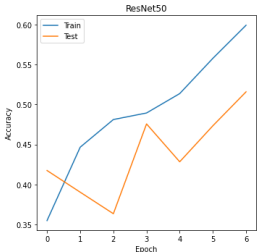
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Anything to talk about?