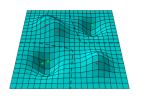
Introduction to Machine Learning

The Gaussian RBF Kernel



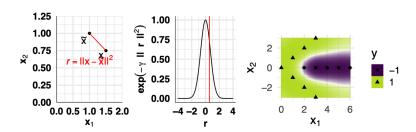
Learning goals

- Know the Gaussian (RBF) kernel
- Understand that all data sets are separable with this kernel
- Understand the effect of the kernel hyperparameter σ

RBF KERNEL

The "radial" Gaussian kernel is defined as

$$k(\mathbf{x}, \tilde{\mathbf{x}}) = \exp(-\frac{\|\mathbf{x} - \tilde{\mathbf{x}}\|^2}{2\sigma^2})$$
 or $k(\mathbf{x}, \tilde{\mathbf{x}}) = \exp(-\gamma \|\mathbf{x} - \tilde{\mathbf{x}}\|^2)$



A straightforward extension is

$$k(\mathbf{x}, \tilde{\mathbf{x}}) = \exp\left(-(\mathbf{x} - \tilde{\mathbf{x}})^T C(\mathbf{x} - \tilde{\mathbf{x}})\right)$$

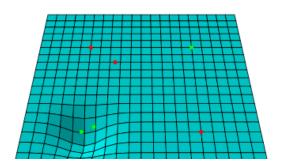
for a symmetric, positive definite matrix C.

RBF KERNEL

- With a Gaussian kernel, all RKHS basis functions $\phi(\mathbf{x}) = k(\mathbf{x}, \cdot)$ are linearly independent which we will not prove here.
- This means that all (finite) data sets are linearly separable!
- Do we then need soft-margin machines? The answer is "yes". The roles of the nonlinear feature map and the soft-margin constraints are very different:
 - The purpose of the kernel (and its feature map) is to make learning "easy".
 - Even in an infinite-dimensional feature space we may want some margin violators because we should not trust noisy data. A hard-margin SVM with Gaussian kernels may be able to separate any dataset but will usually overfit.

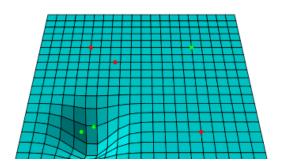
Via the RKHS / basis function intuition we can understand the effect of the RBF kernel much better as a local model.

$$f(\mathbf{x}) = \sum_{i=1}^{n} \alpha_i \mathbf{y}^{(i)} k(\mathbf{x}^{(i)}, \mathbf{x}) + \theta_0$$



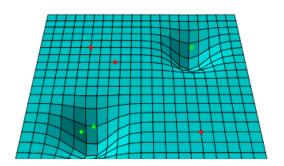
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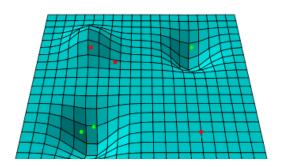
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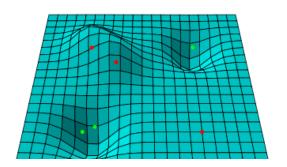
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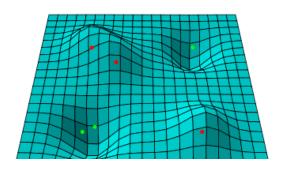
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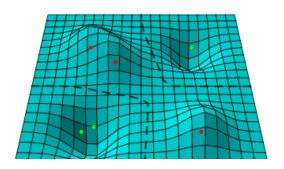
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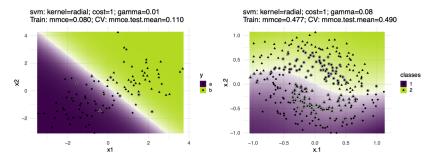
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RBF KERNEL WIDTH

A large σ (or a small γ) will make the decision boundary very smooth and in the limit almost linear.



RBF KERNEL WIDTH

A small σ parameter makes the function more "wiggly", in the limit we totally over fit the data by basically modelling each training data point - and maximal uncertainty at all other test points.

