Chapter 2. Matrix Algebra

1 Matrix Addition, Scalar Multiplication, Transposition

Multiplication

Matrix Inverse

Linear Transformations

Definition

• An $m \times n$ matrix A is an array of m row and n column:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

Definition

• An $m \times n$ matrix A is an array of m row and n column:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \cdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

• The (i, j)-entry of A is the number lying simultaneously in row i and column j.

Definition

• An $m \times n$ matrix A is an array of m row and n column:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \cdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

• The (i,j)-entry of A is the number lying simultaneously in row i and column j.

Example

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix}$$

Definition

• An $m \times n$ matrix A is an array of m row and n column:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

• The (i,j)-entry of A is the number lying simultaneously in row i and column j.

Example

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix}$$

This is a 3×4 matrix.

Definition

• An $m \times n$ matrix A is an array of m row and n column:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \cdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

• The (i,j)-entry of A is the number lying simultaneously in row i and column j.

Example

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix}$$

This is a 3×4 matrix.

The (2,3)-entry of A is 7.

Definition

• An $m \times n$ matrix A is an array of m row and n column:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

• The (i,j)-entry of A is the number lying simultaneously in row i and column j.

Example

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \end{bmatrix}$$

This is a 3×4 matrix.

The (2,3)-entry of A is 7.

- An $m \times m$ matrix is called a square matrix of size m.
- The zero matrix of size $m \times n$, denoted by $0_{m \times n}$ is the matrix that its all entries are 0

- An $m \times m$ matrix is called a square matrix of size m.
- The zero matrix of size $m \times n$, denoted by $0_{m \times n}$ is the matrix that its all entries are 0.
- If $A = [a_{ij}]$ is an $m \times n$ matrix then -A the negative matrix of A and defined by $-A = [-a_{ij}]$.

- An $m \times m$ matrix is called a square matrix of size m.
- The zero matrix of size $m \times n$, denoted by $0_{m \times n}$ is the matrix that its all entries are 0.
- If $A = [a_{ij}]$ is an $m \times n$ matrix then -A the negative matrix of A and defined by $-A = [-a_{ij}]$.

Definition

An identity matrix I_n is a square matrix with 1s on the main diagonal and zeros elsewhere.

- An $m \times m$ matrix is called a square matrix of size m.
- The zero matrix of size $m \times n$, denoted by $0_{m \times n}$ is the matrix that its all entries are 0.
- If $A = [a_{ij}]$ is an $m \times n$ matrix then -A the negative matrix of A and defined by $-A = [-a_{ij}]$.

Definition

An identity matrix I_n is a square matrix with 1s on the main diagonal and zeros elsewhere.

For example,

$$I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Chapter 2. Matrix Algebra

- An $m \times m$ matrix is called a square matrix of size m.
- The zero matrix of size $m \times n$, denoted by $0_{m \times n}$ is the matrix that its all entries are 0.
- If $A = [a_{ij}]$ is an $m \times n$ matrix then -A the negative matrix of A and defined by $-A = [-a_{ij}]$.

Definition

An identity matrix I_n is a square matrix with 1s on the main diagonal and zeros elsewhere.

For example,

$$I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Definition

• Addition $A + B = [a_{ij} + b_{ij}]_{m \times n}$.

Definition

- Addition $A + B = [a_{ij} + b_{ij}]_{m \times n}$.
- Scalar multiplication $kA = [ka_{ij}]_{m \times n}$.

Definition

- Addition $A + B = [a_{ij} + b_{ij}]_{m \times n}$.
- Scalar multiplication $kA = [ka_{ij}]_{m \times n}$.

Example

$$2\begin{bmatrix} -2 & 3 & 5 \\ 0 & 4 & 2 \\ 1 & -1 & 6 \end{bmatrix} - \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 1 \\ 4 & -1 & 3 \end{bmatrix} = \begin{bmatrix} -5 & 6 & 12 \\ 2 & 7 & 3 \\ -2 & -1 & 9 \end{bmatrix}$$



Definition

- Addition $A + B = [a_{ij} + b_{ij}]_{m \times n}$.
- Scalar multiplication $kA = [ka_{ij}]_{m \times n}$.

Example

$$2\begin{bmatrix} -2 & 3 & 5 \\ 0 & 4 & 2 \\ 1 & -1 & 6 \end{bmatrix} - \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 1 \\ 4 & -1 & 3 \end{bmatrix} = \begin{bmatrix} -5 & 6 & 12 \\ 2 & 7 & 3 \\ -2 & -1 & 9 \end{bmatrix}$$



•
$$A + B = B + A$$

•
$$A + B = B + A$$

•
$$A + (-A) = 0$$
 (zero matrix of size $m \times n$)

- A + B = B + A
- A + (-A) = 0 (zero matrix of size $m \times n$)
- (A + B) + C = A + (B + C)

- A + B = B + A
- A + (-A) = 0 (zero matrix of size $m \times n$)
- (A + B) + C = A + (B + C)
- k(hA) = (kh)A

- A + B = B + A
- A + (-A) = 0 (zero matrix of size $m \times n$)
- (A + B) + C = A + (B + C)
- k(hA) = (kh)A
- (k + h)A = kA + hA

- A + B = B + A
- A + (-A) = 0 (zero matrix of size $m \times n$)
- (A + B) + C = A + (B + C)
- k(hA) = (kh)A
- $\bullet (k+h)A = kA + hA$
- $\bullet \ k(A+B) = kA + kB$

- A + B = B + A
- A + (-A) = 0 (zero matrix of size $m \times n$)
- (A + B) + C = A + (B + C)
- k(hA) = (kh)A
- $\bullet (k+h)A = kA + hA$
- k(A+B) = kA + kB

- A + B = B + A
- A + (-A) = 0 (zero matrix of size $m \times n$)
- (A + B) + C = A + (B + C)
- k(hA) = (kh)A
- $\bullet (k+h)A = kA + hA$
- $\bullet \ k(A+B) = kA + kB$

Let A be $m \times n$ matrix. The transpose of A, written $A^T = [a_{ji}]$ is an $n \times m$ matrix.

Example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

Let A be $m \times n$ matrix. The transpose of A, written $A^T = [a_{ji}]$ is an $n \times m$ matrix.

Example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

Let A be $m \times n$ matrix. The transpose of A, written $A^T = [a_{ji}]$ is an $n \times m$ matrix.

Example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

Let A be $m \times n$ matrix. The transpose of A, written $A^T = [a_{ji}]$ is an $n \times m$ matrix.

Example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

$$(A + B)^T = A^T + B^T$$

Let A be $m \times n$ matrix. The transpose of A, written $A^T = [a_{ji}]$ is an $n \times m$ matrix.

Example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

•
$$(A + B)^T = A^T + B^T$$

•
$$(kA)^T = kA^T$$

Let A be $m \times n$ matrix. The transpose of A, written $A^T = [a_{ji}]$ is an $n \times m$ matrix.

Example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

Properties:

- $\bullet (A+B)^T = A^T + B^T$
- $(kA)^T = kA^T$



Chapter 2. Matrix Algebra

Let A be $m \times n$ matrix. The transpose of A, written $A^T = [a_{ji}]$ is an $n \times m$ matrix.

Example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

Properties:

- $\bullet (A+B)^T = A^T + B^T$
- $(kA)^T = kA^T$



Chapter 2. Matrix Algebra

Find the (2,1)-entry of the matrix A that satisfies

$$\left(2A^{T} - 3\begin{bmatrix} 1 & 0 \\ -2 & 2 \end{bmatrix}\right)^{T} = 4A - 7\begin{bmatrix} 1 & 2 \\ -2 & 0 \end{bmatrix}$$

Answer:

Find the (2,1)-entry of the matrix A that satisfies

$$\left(2A^{T} - 3\begin{bmatrix} 1 & 0 \\ -2 & 2 \end{bmatrix}\right)^{T} = 4A - 7\begin{bmatrix} 1 & 2 \\ -2 & 0 \end{bmatrix}$$

Answer: We have

$$2A - \begin{bmatrix} 3 & -6 \\ 0 & 6 \end{bmatrix} = 4A - \begin{bmatrix} 7 & 14 \\ -14 & 0 \end{bmatrix}$$

Find the (2,1)-entry of the matrix A that satisfies

$$\left(2A^{T} - 3\begin{bmatrix} 1 & 0 \\ -2 & 2 \end{bmatrix}\right)^{T} = 4A - 7\begin{bmatrix} 1 & 2 \\ -2 & 0 \end{bmatrix}$$

Answer: We have

$$2A - \begin{bmatrix} 3 & -6 \\ 0 & 6 \end{bmatrix} = 4A - \begin{bmatrix} 7 & 14 \\ -14 & 0 \end{bmatrix}$$

Hence

$$2A = \begin{bmatrix} 4 & 20 \\ -14 & -6 \end{bmatrix}$$

Find the (2,1)-entry of the matrix A that satisfies

$$\left(2A^{T} - 3\begin{bmatrix} 1 & 0 \\ -2 & 2 \end{bmatrix}\right)^{T} = 4A - 7\begin{bmatrix} 1 & 2 \\ -2 & 0 \end{bmatrix}$$

Answer: We have

$$2A - \begin{bmatrix} 3 & -6 \\ 0 & 6 \end{bmatrix} = 4A - \begin{bmatrix} 7 & 14 \\ -14 & 0 \end{bmatrix}$$

Hence

$$2A = \begin{vmatrix} 4 & 20 \\ -14 & -6 \end{vmatrix}$$

Thus, (2, 1)-entry of A is -14/2 = -7.

Chapter 2. Matrix Algebra

Find the (2,1)-entry of the matrix A that satisfies

$$\left(2A^{T} - 3\begin{bmatrix} 1 & 0 \\ -2 & 2 \end{bmatrix}\right)^{T} = 4A - 7\begin{bmatrix} 1 & 2 \\ -2 & 0 \end{bmatrix}$$

Answer: We have

$$2A - \begin{bmatrix} 3 & -6 \\ 0 & 6 \end{bmatrix} = 4A - \begin{bmatrix} 7 & 14 \\ -14 & 0 \end{bmatrix}$$

Hence

$$2A = \begin{bmatrix} 4 & 20 \\ -14 & -6 \end{bmatrix}$$

Thus, (2, 1)-entry of A is -14/2 = -7.

Definition

A matrix A is symmetric if $A^T = A$ (it means that (i, j)-entry of A = (j, i)-entry of A).

Example

```
\begin{bmatrix} 2 & 3 & 1 \\ 3 & -1 & 5 \\ 1 & 5 & 6 \end{bmatrix} is symmetric.
```

Definition

A matrix A is symmetric if $A^T = A$ (it means that (i, j)-entry of A =(j, i)-entry of A).

Example

$$\begin{bmatrix} 2 & 3 & 1 \\ 3 & -1 & 5 \\ 1 & 5 & 6 \end{bmatrix}$$
 is symmetric.

$$\begin{bmatrix} 1 & 2 \\ -2 & 4 \end{bmatrix}$$
 is not symmetric.

Definition

A matrix A is symmetric if $A^T = A$ (it means that (i, j)-entry of A = (j, i)-entry of A).

Example

$$\begin{bmatrix} 2 & 3 & 1 \\ 3 & -1 & 5 \\ 1 & 5 & 6 \end{bmatrix}$$
 is symmetric.

$$\begin{bmatrix} 1 & 2 \\ -2 & 4 \end{bmatrix}$$
 is not symmetric.

Properties

 $A_{m \times m}$ and $B_{m \times m}$ are symmetric $\Rightarrow kA + hB$ is symmetric, for all $k, h \in \mathbb{R}$.

Definition

A matrix A is symmetric if $A^T = A$ (it means that (i, j)-entry of A = (j, i)-entry of A).

Example

$$\begin{bmatrix} 2 & 3 & 1 \\ 3 & -1 & 5 \\ 1 & 5 & 6 \end{bmatrix}$$
 is symmetric.

$$\begin{bmatrix} 1 & 2 \\ -2 & 4 \end{bmatrix}$$
 is not symmetric.

Properties

 $A_{m \times m}$ and $B_{m \times m}$ are symmetric $\Rightarrow kA + hB$ is symmetric, for all $k, h \in \mathbb{R}$.

Determine a and b such that the following matrix is symmetric.

$$\begin{bmatrix} -3 & a+b & 8\\ 7 & 5 & -1\\ 8 & a-b & ab \end{bmatrix}$$

Answer:

Determine a and b such that the following matrix is symmetric.

$$\begin{bmatrix} -3 & a+b & 8\\ 7 & 5 & -1\\ 8 & a-b & ab \end{bmatrix}$$

Answer: Find a, b such that

$$\begin{cases} a+b=7\\ a-b=-1 \end{cases} \Rightarrow a=3, b=4$$

Determine a and b such that the following matrix is symmetric.

$$\begin{bmatrix} -3 & a+b & 8 \\ 7 & 5 & -1 \\ 8 & a-b & ab \end{bmatrix}$$

Answer: Find a, b such that

$$\begin{cases} a+b=7 \\ a-b=-1 \end{cases} \Rightarrow a=3, b=4$$

Definition (Dot product)

$$\begin{bmatrix} a_1 & a_2 & \cdots & a_m \end{bmatrix} imes \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} = a_1b_1 + a_2b_2 + \cdots + a_mb_m$$

Definition

Let $A_{m \times n}$, $B_{n \times p}$ be two matrices. The multiplication of A and B

$$AB = [c_{ij}]_{m \times p},$$

Definition (Dot product)

$$\begin{bmatrix} a_1 & a_2 & \cdots & a_m \end{bmatrix} \times \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} = a_1b_1 + a_2b_2 + \cdots + a_mb_m$$

Definition

Let $A_{m \times n}$, $B_{n \times p}$ be two matrices. The multiplication of A and B

$$AB = [c_{ij}]_{m \times p},$$

where c_{ij} is the dot product of i^{th} row of A and j^{th} column of B.

Definition (Dot product)

$$\begin{bmatrix} a_1 & a_2 & \cdots & a_m \end{bmatrix} \times \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} = a_1b_1 + a_2b_2 + \cdots + a_mb_m$$

Definition

Let $A_{m \times n}$, $B_{n \times p}$ be two matrices. The multiplication of A and B

$$AB = [c_{ij}]_{m \times p},$$

where c_{ij} is the dot product of i^{th} row of A and j^{th} column of B.

Definition (Dot product)

$$\begin{bmatrix} a_1 & a_2 & \cdots & a_m \end{bmatrix} \times \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} = a_1b_1 + a_2b_2 + \cdots + a_mb_m$$

Definition

Let $A_{m \times n}$, $B_{n \times p}$ be two matrices. The multiplication of A and B

$$AB = [c_{ij}]_{m \times p},$$

where c_{ij} is the dot product of i^{th} row of A and j^{th} column of B.

$$\begin{bmatrix} 1 & 2 & -3 \\ -2 & 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 & 5 \\ -1 & 1 & 4 & 6 \\ 2 & 4 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -7 & -10 & 7 & 20 \\ -7 & -1 & 14 & 9 \end{bmatrix}$$

Example

Let
$$A = \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 1 \\ 3 & 2 & -2 \end{bmatrix}$$
 and $B = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -3 & 2 \\ 0 & -1 & 3 \end{bmatrix}$.

Find (2,1)-entry of $AB - B^T A$.

$$\begin{bmatrix} 1 & 2 & -3 \\ -2 & 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 & 5 \\ -1 & 1 & 4 & 6 \\ 2 & 4 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -7 & -10 & 7 & 20 \\ -7 & -1 & 14 & 9 \end{bmatrix}$$

Example

Let
$$A = \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 1 \\ 3 & 2 & -2 \end{bmatrix}$$
 and $B = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -3 & 2 \\ 0 & -1 & 3 \end{bmatrix}$.

Find (2,1)-entry of $\overrightarrow{AB} - \overrightarrow{B}^T A$.

Answer:

$$\begin{bmatrix} 1 & 2 & -3 \\ -2 & 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 & 5 \\ -1 & 1 & 4 & 6 \\ 2 & 4 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -7 & -10 & 7 & 20 \\ -7 & -1 & 14 & 9 \end{bmatrix}$$

Example

Let
$$A = \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 1 \\ 3 & 2 & -2 \end{bmatrix}$$
 and $B = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -3 & 2 \\ 0 & -1 & 3 \end{bmatrix}$.

Find (2,1)-entry of $A\bar{B} - B^T A$.

Answer:

• The (2,1)-entry of AB is the dot product of the second row of A and the first column of B and equal to -2*2+1*4+1*0=0.



$$\begin{bmatrix} 1 & 2 & -3 \\ -2 & 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 & 5 \\ -1 & 1 & 4 & 6 \\ 2 & 4 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -7 & -10 & 7 & 20 \\ -7 & -1 & 14 & 9 \end{bmatrix}$$

Example

Let
$$A = \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 1 \\ 3 & 2 & -2 \end{bmatrix}$$
 and $B = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -3 & 2 \\ 0 & -1 & 3 \end{bmatrix}$.

Find (2,1)-entry of $\overrightarrow{AB} - \overrightarrow{B}^T A$.

Answer:

- The (2,1)-entry of AB is the dot product of the second row of A and the first column of B and equal to -2*2+1*4+1*0=0.
- The (2,1)-entry of B^TA is the dot product of the second column of B and the first column of A, is 1*1+(-3)*(-2)+(-1)*3=4.

$$\begin{bmatrix} 1 & 2 & -3 \\ -2 & 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 & 5 \\ -1 & 1 & 4 & 6 \\ 2 & 4 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -7 & -10 & 7 & 20 \\ -7 & -1 & 14 & 9 \end{bmatrix}$$

Example

Let
$$A = \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 1 \\ 3 & 2 & -2 \end{bmatrix}$$
 and $B = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -3 & 2 \\ 0 & -1 & 3 \end{bmatrix}$.

Find (2, 1)-entry of $A\bar{B} - B^T A$.

Answer:

- The (2,1)-entry of AB is the dot product of the second row of A and the first column of B and equal to -2*2+1*4+1*0=0.
- The (2,1)-entry of B^TA is the dot product of the second column of B and the first column of A, is 1*1+(-3)*(-2)+(-1)*3=4.

Hence (2, 1)-entry of $AB - B^T A$ is 0 - 4 = -4.

$$\begin{bmatrix} 1 & 2 & -3 \\ -2 & 3 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 & 5 \\ -1 & 1 & 4 & 6 \\ 2 & 4 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -7 & -10 & 7 & 20 \\ -7 & -1 & 14 & 9 \end{bmatrix}$$

Example

Let
$$A = \begin{bmatrix} 1 & 0 & -2 \\ -2 & 1 & 1 \\ 3 & 2 & -2 \end{bmatrix}$$
 and $B = \begin{bmatrix} 2 & 1 & 1 \\ 4 & -3 & 2 \\ 0 & -1 & 3 \end{bmatrix}$.

Find (2,1)-entry of $A\bar{B} - B^T A$.

Answer:

- The (2,1)-entry of AB is the dot product of the second row of A and the first column of B and equal to -2*2+1*4+1*0=0.
- The (2,1)-entry of B^TA is the dot product of the second column of B and the first column of A, is 1*1+(-3)*(-2)+(-1)*3=4.

Hence (2, 1)-entry of $AB - B^T A$ is 0 - 4 = -4.

Find the second entry of the first row of the matrix A that satisfies

$$A^{T} - \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^{T} \begin{bmatrix} 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix}$$

Answer:

Find the second entry of the first row of the matrix A that satisfies

$$A^{T} - \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^{T} \begin{bmatrix} 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix}$$

Answer: We have

$$A^{T} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ -1 & -2 \\ 2 & 4 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 1 & 2 \\ 5 & 10 \end{bmatrix}$$

Find the second entry of the first row of the matrix A that satisfies

$$A^{T} - \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^{T} \begin{bmatrix} 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix}$$

Answer: We have

$$A^{T} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ -1 & -2 \\ 2 & 4 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 1 & 2 \\ 5 & 10 \end{bmatrix}$$

Hence the second entry of the first row of the matrix A is 1.

Find the second entry of the first row of the matrix A that satisfies

$$A^{T} - \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^{T} \begin{bmatrix} 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix}$$

Answer: We have

$$A^{T} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ -1 & -2 \\ 2 & 4 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 3 & 6 \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 1 & 2 \\ 5 & 10 \end{bmatrix}$$

Hence the second entry of the first row of the matrix A is 1.

- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$

- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$
- (A+B)C = AC + BC, for $A_{m \times n}, B_{m \times n}, C_{n \times p}$

- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$
- (A+B)C = AC + BC, for $A_{m \times n}, B_{m \times n}, C_{n \times p}$
- $AI_m = I_m A = A$, for $A_{m \times m}$

- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$
- (A+B)C = AC + BC, for $A_{m \times n}, B_{m \times n}, C_{n \times p}$
- $AI_m = I_m A = A$, for $A_{m \times m}$
- $\bullet (AB)^T = B^T A^T$

- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$
- (A+B)C = AC + BC, for $A_{m \times n}, B_{m \times n}, C_{n \times p}$
- $AI_m = I_m A = A$, for $A_{m \times m}$
- $\bullet (AB)^T = B^T A^T$
- In general, $AB \neq BA$

- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$
- (A+B)C = AC + BC, for $A_{m \times n}, B_{m \times n}, C_{n \times p}$
- $AI_m = I_m A = A$, for $A_{m \times m}$
- $(AB)^T = B^T A^T$
- In general, $AB \neq BA$

Example

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \neq \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} -1 & -2 \\ 3 & 5 \end{bmatrix}$$



- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$
- (A+B)C = AC + BC, for $A_{m \times n}, B_{m \times n}, C_{n \times p}$
- $AI_m = I_m A = A$, for $A_{m \times m}$
- $(AB)^T = B^T A^T$
- In general, $AB \neq BA$

Example

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \neq \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} -1 & -2 \\ 3 & 5 \end{bmatrix}$$

Definition

We say A and B are commute if AB = BA.

- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$
- (A+B)C = AC + BC, for $A_{m \times n}, B_{m \times n}, C_{n \times p}$
- $AI_m = I_m A = A$, for $A_{m \times m}$
- $(AB)^T = B^T A^T$
- In general, $AB \neq BA$

Example

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \neq \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} -1 & -2 \\ 3 & 5 \end{bmatrix}$$

Definition

We say A and B are commute if AB = BA.

- A(BC) = (AB)C, for $A_{m \times n}, B_{n \times p}, C_{p \times q}$
- A(B+C) = AB + AC, for $A_{m \times n}, B_{n \times p}, C_{n \times p}$
- (A+B)C = AC + BC, for $A_{m \times n}, B_{m \times n}, C_{n \times p}$
- $AI_m = I_m A = A$, for $A_{m \times m}$
- $(AB)^T = B^T A^T$
- In general, $AB \neq BA$

Example

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \neq \begin{bmatrix} -1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} -1 & -2 \\ 3 & 5 \end{bmatrix}$$

Definition

We say A and B are commute if AB = BA.

Decide the following statements are True or False.

(a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix).

Decide the following statements are True or False.

(a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix).

Decide the following statements are True or False.

(a) If AB=0 then either A=0 or B=0, (where 0 is zero matrix). \vdash

(b) $(A+B)(A-B) = A^2 - B^2$.

Decide the following statements are True or False.

- (a) If AB=0 then either A=0 or B=0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$.

Decide the following statements are True or False.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A+B)(A-B) = A^2 B^2$.
- (c) If A^2 can be formed then A must be square matrix.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A+B)(A-B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix.

Decide the following statements are True or False.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A+B)(A-B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. \top
- (d) If A is symmetric and square, then A^2 is symmetric.

Chapter 2. Matrix Algebra

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A+B)(A-B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric.

Decide the following statements are True or False.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. \top
- (e) If A is square then AA^T is symmetric.

Chapter 2. Matrix Algebra

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A+B)(A-B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. \top
- (f) If AB and BA can be formed then A and B must be square matrices.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices.
- (g) If A, B are symmetric matrices of the same size, then A+B is symmetric.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices. F
- (g) If A, B are symmetric matrices of the same size, then A+B is symmetric.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices. F
- (g) If A, B are symmetric matrices of the same size, then A+B is symmetric. \top
- (h) If A, B are symmetric matrices of the same size, then AB is symmetric.

Decide the following statements are True or False.

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices.
- (g) If A, B are symmetric matrices of the same size, then A+B is symmetric. T
- (h) If A, B are symmetric matrices of the same size, then AB is symmetric.

Chapter 2. Matrix Algebra

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices. F
- (g) If A, B are symmetric matrices of the same size, then A+B is symmetric. T
- (h) If A, B are symmetric matrices of the same size, then AB is symmetric. \vdash
- (i) Let A is 3×5 matrix and B is 6×7 matrix, and ACB can be performed. What is the size of C?

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices. F
- (g) If A, B are symmetric matrices of the same size, then A+B is symmetric. T
- (h) If A, B are symmetric matrices of the same size, then AB is symmetric. F
- (i) Let A is 3×5 matrix and B is 6×7 matrix, and ACB can be performed. What is the size of C?

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A + B)(A B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices.
- (g) If A, B are symmetric matrices of the same size, then A+B is symmetric. T
- (h) If A, B are symmetric matrices of the same size, then AB is symmetric. F
- (i) Let A is 3×5 matrix and B is 6×7 matrix, and ACB can be performed. What is the size of C? 5×6

- (a) If AB = 0 then either A = 0 or B = 0, (where 0 is zero matrix). F
- (b) $(A+B)(A-B) = A^2 B^2$. F
- (c) If A^2 can be formed then A must be square matrix. T
- (d) If A is symmetric and square, then A^2 is symmetric. T
- (e) If A is square then AA^T is symmetric. T
- (f) If AB and BA can be formed then A and B must be square matrices. F
- (g) If A, B are symmetric matrices of the same size, then A+B is symmetric. T
- (h) If A, B are symmetric matrices of the same size, then AB is symmetric. F
- (i) Let A is 3×5 matrix and B is 6×7 matrix, and ACB can be performed. What is the size of C? 5×6

A system of m linear equations and n variables:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \dots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

can be rewritten in the matrix form

$$AX = b,$$

A system of m linear equations and n variables:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \dots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

can be rewritten in the matrix form

$$AX = b$$

where
$$X = \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix}$$
 is the variables,

Chapter 2. Matrix Algebra

A system of *m* linear equations and *n* variables:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \dots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

can be rewritten in the matrix form

$$AX = b$$
,

$$AX = b,$$
 where $X = \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix}$ is the variables, $b = \begin{bmatrix} b_1 \\ b_2 \\ \dots \\ b_n \end{bmatrix}$ and

Chapter 2. Matrix Algebra

A system of *m* linear equations and *n* variables:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \dots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

can be rewritten in the matrix form

$$AX = b,$$

where
$$X=\begin{bmatrix}x_1\\x_2\\\dots\\x_n\end{bmatrix}$$
 is the variables, $b=\begin{bmatrix}b_1\\b_2\\\dots\\b_n\end{bmatrix}$ and A is the coefficient

A system of *m* linear equations and *n* variables:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \dots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

can be rewritten in the matrix form

$$AX = b$$
,

where
$$X=\begin{bmatrix}x_1\\x_2\\\ldots\\x_n\end{bmatrix}$$
 is the variables, $b=\begin{bmatrix}b_1\\b_2\\\ldots\\b_n\end{bmatrix}$ and A is the coefficient

matrix



The system of linear equations

$$2x + 3y - 5z = 9$$

 $-x - 2y + 4z = 11$

can be written in the matrix form

$$\begin{bmatrix} 2 & 3 & -5 \\ -1 & -2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 9 \\ 11 \end{bmatrix}$$

Chapter 2. Matrix Algebra

The system of linear equations

$$2x + 3y - 5z = 9$$

 $-x - 2y + 4z = 11$

can be written in the matrix form

$$\begin{bmatrix} 2 & 3 & -5 \\ -1 & -2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 9 \\ 11 \end{bmatrix}$$

Let A be a square $n \times n$ matrix.

Definition

A matrix B is called an inverse of A if and only if

Let A be a square $n \times n$ matrix.

Definition

A matrix B is called an inverse of A if and only if

$$AB = I$$
 and $BA = I$

Let A be a square $n \times n$ matrix.

Definition

A matrix B is called an inverse of A if and only if

$$AB = I$$
 and $BA = I$

A matrix A that has an inverse is called an invertible matrix

Let A be a square $n \times n$ matrix.

Definition

A matrix B is called an inverse of A if and only if

$$AB = I$$
 and $BA = I$

A matrix A that has an inverse is called an invertible matrix

Find the inverse matrix of $A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}$.

Answer:

Find the inverse matrix of
$$A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}$$
.

Answer: Say
$$B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$$
. We have

Find the inverse matrix of
$$A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}$$
.

Answer: Say $B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$. We have

$$AB = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} 2x + z & 2y + t \\ z & t \end{bmatrix} = I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Find the inverse matrix of $A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}$.

Answer: Say $B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$. We have

$$AB = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} 2x + z & 2y + t \\ z & t \end{bmatrix} = I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Find the inverse matrix of
$$A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}$$
.

Answer: Say $B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$. We have

$$AB = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} 2x + z & 2y + t \\ z & t \end{bmatrix} = I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Hence
$$A^{-1} = \begin{bmatrix} 1/2 & -1/2 \\ 0 & 1 \end{bmatrix}$$
.

Find the inverse matrix of
$$A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}$$
.

Answer: Say $B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$. We have

$$AB = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} 2x + z & 2y + t \\ z & t \end{bmatrix} = I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Hence
$$A^{-1} = \begin{bmatrix} 1/2 & -1/2 \\ 0 & 1 \end{bmatrix}$$
.

Show that
$$A = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix}$$
 is not invertible.

Answer:

Show that
$$A = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix}$$
 is not invertible.

Answer: Say
$$B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$$
.

Show that
$$A = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix}$$
 is not invertible.

Answer: Say
$$B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$$
. We have

$$AB = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} x - 2z & y - 2t \\ -x + 2z & -y + 2t \end{bmatrix} = I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

Show that
$$A = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix}$$
 is not invertible.

Answer: Say $B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$. We have

$$AB = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} x - 2z & y - 2t \\ -x + 2z & -y + 2t \end{bmatrix} = I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

$$x-2z = 1$$

$$y-2t = 0$$

$$-x+2z = 0$$

$$-y+2t = 1$$

Example

Show that
$$A = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix}$$
 is not invertible.

Answer: Say $B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$. We have

$$AB = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} x - 2z & y - 2t \\ -x + 2z & -y + 2t \end{bmatrix} = I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

This is equivalent to

$$x-2z = 1$$

$$y-2t = 0$$

$$-x+2z = 0$$

$$-y+2t = 1$$

This system has no solution. Hence, A is not invertible.

Example

Show that
$$A = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix}$$
 is not invertible.

Answer: Say $B = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$. We have

$$AB = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} x - 2z & y - 2t \\ -x + 2z & -y + 2t \end{bmatrix} = I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

This is equivalent to

$$x-2z = 1$$

$$y-2t = 0$$

$$-x+2z = 0$$

$$-y+2t = 1$$

This system has no solution. Hence, A is not invertible.

Theorem

Let
$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
. Then A is invertible if $det(A) = ad - bc \neq 0$ and

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Example

$$\begin{bmatrix} 3 & 1 \\ 2 & 4 \end{bmatrix}^{-1} = \frac{1}{10} \begin{bmatrix} 4 & -1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} 0.4 & -0.1 \\ -0.2 & 0.3 \end{bmatrix}$$

Theorem

Let
$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
. Then A is invertible if $det(A) = ad - bc \neq 0$ and

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Example

$$\begin{bmatrix} 3 & 1 \\ 2 & 4 \end{bmatrix}^{-1} = \frac{1}{10} \begin{bmatrix} 4 & -1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} 0.4 & -0.1 \\ -0.2 & 0.3 \end{bmatrix}$$

$$(AB)^{-1} = B^{-1}A^{-1}$$
,

- $(AB)^{-1} = B^{-1}A^{-1}$,
- $(A^{-1})^{-1} = A$,

- $(AB)^{-1} = B^{-1}A^{-1}$,
- $(A^{-1})^{-1} = A$,
- $I^{-1} = I$.

- $(AB)^{-1} = B^{-1}A^{-1}$,
- $(A^{-1})^{-1} = A$,
- $I^{-1} = I$.
- $[A^k]^{-1} = (A^{-1})^k$,

- $(AB)^{-1} = B^{-1}A^{-1}$,
- $(A^{-1})^{-1} = A$,
- $I^{-1} = I$.
- $(aA)^{-1} = 1/aA^{-1}$, for any $a \neq 0$.

- $(AB)^{-1} = B^{-1}A^{-1}$,
- $(A^{-1})^{-1} = A$,
- $I^{-1} = I$.
- $(aA)^{-1} = 1/aA^{-1}$, for any $a \neq 0$.
- $\bullet (A^T)^{-1} = (A^{-1})^T.$

- $(AB)^{-1} = B^{-1}A^{-1}$,
- $(A^{-1})^{-1} = A$,
- $I^{-1} = I$.
- $(aA)^{-1} = 1/aA^{-1}$, for any $a \neq 0$.
- $(A^T)^{-1} = (A^{-1})^T$.

- $(AB)^{-1} = B^{-1}A^{-1}$,
- $(A^{-1})^{-1} = A$,
- $I^{-1} = I$.
- $(aA)^{-1} = 1/aA^{-1}$, for any $a \neq 0$.
- $(A^T)^{-1} = (A^{-1})^T$.

$$(2A^{-1}+I)^{-1}=\left[\begin{array}{cc}3&4\\5&7\end{array}\right].$$

Answer:

$$(2A^{-1}+I)^{-1}=\begin{bmatrix} 3 & 4 \\ 5 & 7 \end{bmatrix}.$$

Answer: We have

$$2A^{-1} + I = \begin{bmatrix} 3 & 4 \\ 5 & 7 \end{bmatrix}^{-1} = \frac{1}{3 * 7 - 4 * 5} \begin{bmatrix} 7 & -4 \\ -5 & 3 \end{bmatrix}.$$

Hence

$$(2A^{-1}+I)^{-1}=\begin{bmatrix} 3 & 4 \\ 5 & 7 \end{bmatrix}.$$

Answer: We have

$$2A^{-1} + I = \begin{bmatrix} 3 & 4 \\ 5 & 7 \end{bmatrix}^{-1} = \frac{1}{3*7 - 4*5} \begin{bmatrix} 7 & -4 \\ -5 & 3 \end{bmatrix}.$$

Hence

$$2A^{-1} = \begin{bmatrix} 7 & -4 \\ -5 & 3 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 6 & -4 \\ -5 & 2 \end{bmatrix}.$$

$$\Rightarrow A = \begin{bmatrix} 3 & -2 \\ -5/2 & 1 \end{bmatrix}^{-1} = \frac{1}{3*1 - (-2)*(-\frac{5}{2})} \begin{bmatrix} 1 & 2 \\ 5/2 & 3 \end{bmatrix} = \begin{bmatrix} -1/2 & -1 \\ -5/4 & -3/2 \end{bmatrix}$$

$$(2A^{-1}+I)^{-1}=\begin{bmatrix} 3 & 4 \\ 5 & 7 \end{bmatrix}.$$

Answer: We have

$$2A^{-1} + I = \begin{bmatrix} 3 & 4 \\ 5 & 7 \end{bmatrix}^{-1} = \frac{1}{3*7 - 4*5} \begin{bmatrix} 7 & -4 \\ -5 & 3 \end{bmatrix}.$$

Hence

$$2A^{-1} = \begin{bmatrix} 7 & -4 \\ -5 & 3 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 6 & -4 \\ -5 & 2 \end{bmatrix}.$$

$$\Rightarrow A = \begin{bmatrix} 3 & -2 \\ -5/2 & 1 \end{bmatrix}^{-1} = \frac{1}{3*1 - (-2)*(-\frac{5}{2})} \begin{bmatrix} 1 & 2 \\ 5/2 & 3 \end{bmatrix} = \begin{bmatrix} -1/2 & -1 \\ -5/4 & -3/2 \end{bmatrix}$$

Thus, the (2,1)-entry of A is -5/4.

$$(2A^{-1}+I)^{-1}=\begin{bmatrix} 3 & 4 \\ 5 & 7 \end{bmatrix}.$$

Answer: We have

$$2A^{-1} + I = \begin{bmatrix} 3 & 4 \\ 5 & 7 \end{bmatrix}^{-1} = \frac{1}{3*7 - 4*5} \begin{bmatrix} 7 & -4 \\ -5 & 3 \end{bmatrix}.$$

Hence

$$2A^{-1} = \begin{bmatrix} 7 & -4 \\ -5 & 3 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 6 & -4 \\ -5 & 2 \end{bmatrix}.$$

$$\Rightarrow A = \begin{bmatrix} 3 & -2 \\ -5/2 & 1 \end{bmatrix}^{-1} = \frac{1}{3*1 - (-2)*(-\frac{5}{2})} \begin{bmatrix} 1 & 2 \\ 5/2 & 3 \end{bmatrix} = \begin{bmatrix} -1/2 & -1 \\ -5/4 & -3/2 \end{bmatrix}$$

Thus, the (2,1)-entry of A is -5/4.

4□▶ 4□▶ 4 □ ▶ 4 □ ▶ 9 0 ○

$$\left(\left[\begin{array}{cc} 1 & 1 \\ 1 & 0 \end{array} \right] A \right)^{-1} = \left[\begin{array}{cc} 1 & 2 \\ 0 & -1 \end{array} \right].$$

Answer:

$$\left(\left[\begin{array}{cc} 1 & 1 \\ 1 & 0 \end{array}\right] A\right)^{-1} = \left[\begin{array}{cc} 1 & 2 \\ 0 & -1 \end{array}\right].$$

Answer: We have

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} A = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}^{-1} = \frac{1}{1 * (-1) - 0 * 2} \begin{bmatrix} -1 & -2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}.$$

$$\left(\left[\begin{array}{cc} 1 & 1 \\ 1 & 0 \end{array}\right] A\right)^{-1} = \left[\begin{array}{cc} 1 & 2 \\ 0 & -1 \end{array}\right].$$

Answer: We have

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} A = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}^{-1} = \frac{1}{1 * (-1) - 0 * 2} \begin{bmatrix} -1 & -2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}.$$

Hence.

$$\left(\left[\begin{array}{cc} 1 & 1 \\ 1 & 0 \end{array}\right] A\right)^{-1} = \left[\begin{array}{cc} 1 & 2 \\ 0 & -1 \end{array}\right].$$

Answer: We have

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} A = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}^{-1} = \frac{1}{1 * (-1) - 0 * 2} \begin{bmatrix} -1 & -2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}.$$

Hence,

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} = \frac{1}{-1} \begin{bmatrix} 0 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$$
$$= \begin{bmatrix} 0 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$$

$$\left(\left[\begin{array}{cc} 1 & 1 \\ 1 & 0 \end{array}\right] A\right)^{-1} = \left[\begin{array}{cc} 1 & 2 \\ 0 & -1 \end{array}\right].$$

Answer: We have

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} A = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}^{-1} = \frac{1}{1 * (-1) - 0 * 2} \begin{bmatrix} -1 & -2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}.$$

Hence,

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} = \frac{1}{-1} \begin{bmatrix} 0 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$$
$$= \begin{bmatrix} 0 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$$

The first entry of the second row of the matrix A is 1 * 1 + (-1) * 0 = 1.

$$\left(\left[\begin{array}{cc} 1 & 1 \\ 1 & 0 \end{array}\right] A\right)^{-1} = \left[\begin{array}{cc} 1 & 2 \\ 0 & -1 \end{array}\right].$$

Answer: We have

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} A = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}^{-1} = \frac{1}{1 * (-1) - 0 * 2} \begin{bmatrix} -1 & -2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}.$$

Hence,

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} = \frac{1}{-1} \begin{bmatrix} 0 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$$
$$= \begin{bmatrix} 0 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$$

The first entry of the second row of the matrix A is 1 * 1 + (-1) * 0 = 1.

Matrix inverse algorithm

If A is an invertible matrix, there exists a sequence of elementary row operations that

$$[A|I] \rightarrow [I|A^{-1}]$$

where the row operations on A and I are carried out simultaneously.

Matrix inverse algorithm

If A is an invertible matrix, there exists a sequence of elementary row operations that

$$[A|I] \to [I|A^{-1}]$$

where the row operations on A and I are carried out simultaneously.

Example

$$\begin{bmatrix} 1 & 2 & 0 & 1 & 0 & 0 \\ 0 & 2 & 3 & 0 & 1 & 0 \\ 1 & 3 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-R_1 + R_3} \begin{bmatrix} 1 & 2 & 0 & 1 & 0 & 0 \\ 0 & 2 & 3 & 0 & 1 & 0 \\ 0 & 1 & 1 & -1 & 0 & 1 \end{bmatrix}$$

$$\frac{1/2R_2}{-1/2R_2+R_3} \left[\begin{array}{ccc|ccc}
1 & 2 & 0 & 1 & 0 & 0 \\
0 & 1 & 3/2 & 0 & 1/2 & 0 \\
0 & 0 & -1/2 & -1 & -1/2 & 1
\end{array} \right]$$

$$\frac{-2R_3}{3R_3+R_2} \leftarrow \begin{bmatrix}
1 & 2 & 0 & 1 & 0 & 0 \\
0 & 1 & 0 & -3 & -1 & 3 \\
0 & 0 & 1 & 2 & 1 & -2
\end{bmatrix}$$



2.6 Linear transformation

Definition

Let A be $m \times n$ matrix. The transformation $T_A : \mathbb{R}^n \times \mathbb{R}^m$ defined by

$$T_A(x) = Ax$$

is called the matrix transformation induced by A.

Example

Let
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & -1 & 4 \end{bmatrix}$$
.

2.6 Linear transformation

Definition

Let A be $m \times n$ matrix. The transformation $T_A : \mathbb{R}^n \times \mathbb{R}^m$ defined by

$$T_A(x) = Ax$$

is called the matrix transformation induced by A.

Example

Let
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & -1 & 4 \end{bmatrix}$$
. Then the matrix transformation induced by A is

 $T_A \colon \mathbb{R}^3 \to \mathbb{R}^2$ defined by

$$T_A \begin{pmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \end{pmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & -1 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x + 2y + 3z \\ 2x - y + 4z \end{bmatrix}.$$

2.6 Linear transformation

Definition

Let A be $m \times n$ matrix. The transformation $T_A : \mathbb{R}^n \times \mathbb{R}^m$ defined by

$$T_A(x) = Ax$$

is called the matrix transformation induced by A.

Example

Let
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & -1 & 4 \end{bmatrix}$$
. Then the matrix transformation induced by A is

 $\mathcal{T}_A \colon \mathbb{R}^3 o \mathbb{R}^2$ defined by

$$T_A \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} 1 & 2 & 3 \\ 2 & -1 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x + 2y + 3z \\ 2x - y + 4z \end{bmatrix}.$$

Example

Consider a transformation

$$\mathcal{T}\colon \mathbb{R}^2 o \mathbb{R}^3$$
 given by

$$T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x - 3y \\ 5y \\ -x + 6y \end{bmatrix}.$$

Then
$$T$$
 is a matrix transformation induced by $A = \begin{bmatrix} 1 & -3 \\ 0 & 5 \\ -1 & 6 \end{bmatrix}$.

Example

Consider a transformation

$$T: \mathbb{R}^2 \to \mathbb{R}^3$$
 given by

$$T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x - 3y \\ 5y \\ -x + 6y \end{bmatrix}.$$

Then
$$T$$
 is a matrix transformation induced by $A = \begin{bmatrix} 1 & -3 \\ 0 & 5 \\ -1 & 6 \end{bmatrix}$.

A transformation $T: \mathbb{R}^n \to \mathbb{R}^m$ is called a linear transformation if it satisfies the following two conditions for all vectors x and y in \mathbb{R}^n and all scalars $a \in \mathbb{R}$:

(1)
$$T(x + y) = T(x) + T(y)$$

A transformation $T: \mathbb{R}^n \to \mathbb{R}^m$ is called a linear transformation if it satisfies the following two conditions for all vectors x and y in \mathbb{R}^n and all scalars $a \in \mathbb{R}$:

(1)
$$T(x + y) = T(x) + T(y)$$

(2)
$$T(ax) = aT(x)$$
.

A transformation $T: \mathbb{R}^n \to \mathbb{R}^m$ is called a linear transformation if it satisfies the following two conditions for all vectors x and y in \mathbb{R}^n and all scalars $a \in \mathbb{R}$:

- (1) T(x + y) = T(x) + T(y)
- (2) T(ax) = aT(x).

Note.

1. If T is a linear transformation, then T(0) = 0 (T preserves the zero vector).

A transformation $T: \mathbb{R}^n \to \mathbb{R}^m$ is called a linear transformation if it satisfies the following two conditions for all vectors x and y in \mathbb{R}^n and all scalars $a \in \mathbb{R}$:

- (1) T(x + y) = T(x) + T(y)
- (2) T(ax) = aT(x).

Note.

- 1. If T is a linear transformation, then T(0) = 0 (T preserves the zero vector).
- 2. The conditions (1) and (2) are equivalent to

$$T(ax + by) = aT(x) + bT(y)$$
, for all $x, y \in \mathbb{R}^n$; $a, b \in \mathbb{R}$.



A transformation $T: \mathbb{R}^n \to \mathbb{R}^m$ is called a linear transformation if it satisfies the following two conditions for all vectors x and y in \mathbb{R}^n and all scalars $a \in \mathbb{R}$:

- (1) T(x + y) = T(x) + T(y)
- (2) T(ax) = aT(x).

Note.

- 1. If T is a linear transformation, then T(0) = 0 (T preserves the zero vector).
- 2. The conditions (1) and (2) are equivalent to

$$T(ax + by) = aT(x) + bT(y)$$
, for all $x, y \in \mathbb{R}^n$; $a, b \in \mathbb{R}$.



 $T: \mathbb{R}^2 \to \mathbb{R}^2$ given by T(x,y) = (x,x+y) is a linear transformation. Indeed,

$$(1) \quad T\left(\begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} x' \\ y' \end{bmatrix}\right) = T\left(\begin{bmatrix} x + x' \\ y + y' \end{bmatrix}\right) = \begin{bmatrix} x + x' \\ x + x' + y + y' \end{bmatrix}$$

$$= \begin{bmatrix} x \\ x + y \end{bmatrix} + \begin{bmatrix} x' \\ x' + y' \end{bmatrix} = T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) + T\left(\begin{bmatrix} x' \\ y' \end{bmatrix}\right).$$

$$(2) \quad T\left(a\begin{bmatrix} x \\ y \end{bmatrix}\right) = T\left(\begin{bmatrix} ax \\ ay \end{bmatrix}\right) = \begin{bmatrix} ax \\ ax + ay \end{bmatrix} = a\begin{bmatrix} x \\ x + y \end{bmatrix} = aT\left(\begin{bmatrix} x \\ y \end{bmatrix}\right).$$

Example

 $T: \mathbb{R}^2 \to \mathbb{R}^3$ given by $T(x,y) = (x-y,0,y^2)$ is not a linear transformation since

 $T: \mathbb{R}^2 \to \mathbb{R}^2$ given by T(x,y) = (x,x+y) is a linear transformation. Indeed.

$$(1) \quad T\left(\begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} x' \\ y' \end{bmatrix}\right) = T\left(\begin{bmatrix} x + x' \\ y + y' \end{bmatrix}\right) = \begin{bmatrix} x + x' \\ x + x' + y + y' \end{bmatrix}$$

$$= \begin{bmatrix} x \\ x + y \end{bmatrix} + \begin{bmatrix} x' \\ x' + y' \end{bmatrix} = T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) + T\left(\begin{bmatrix} x' \\ y' \end{bmatrix}\right).$$

$$(2) \quad T\left(a\begin{bmatrix} x \\ y \end{bmatrix}\right) = T\left(\begin{bmatrix} ax \\ ay \end{bmatrix}\right) = \begin{bmatrix} ax \\ ax + ay \end{bmatrix} = a\begin{bmatrix} x \\ x + y \end{bmatrix} = aT\left(\begin{bmatrix} x \\ y \end{bmatrix}\right).$$

Example

 $T: \mathbb{R}^2 \to \mathbb{R}^3$ given by $T(x,y) = (x-y,0,y^2)$ is not a linear transformation since

$$T\left(2\begin{bmatrix}1\\1\end{bmatrix}\right) = T\left(\begin{bmatrix}2\\2\end{bmatrix}\right) = \begin{bmatrix}0\\0\\4\end{bmatrix} \neq 2T\left(\begin{bmatrix}1\\1\end{bmatrix}\right) = 2\begin{bmatrix}0\\0\\1\end{bmatrix} = \begin{bmatrix}0\\0\\2\end{bmatrix}$$

 $T: \mathbb{R}^2 \to \mathbb{R}^2$ given by T(x,y) = (x,x+y) is a linear transformation. Indeed.

$$(1) \quad T\left(\begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} x' \\ y' \end{bmatrix}\right) = T\left(\begin{bmatrix} x + x' \\ y + y' \end{bmatrix}\right) = \begin{bmatrix} x + x' \\ x + x' + y + y' \end{bmatrix}$$

$$= \begin{bmatrix} x \\ x + y \end{bmatrix} + \begin{bmatrix} x' \\ x' + y' \end{bmatrix} = T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) + T\left(\begin{bmatrix} x' \\ y' \end{bmatrix}\right).$$

$$(2) \quad T\left(a\begin{bmatrix} x \\ y \end{bmatrix}\right) = T\left(\begin{bmatrix} ax \\ ay \end{bmatrix}\right) = \begin{bmatrix} ax \\ ax + ay \end{bmatrix} = a\begin{bmatrix} x \\ x + y \end{bmatrix} = aT\left(\begin{bmatrix} x \\ y \end{bmatrix}\right).$$

Example

 $T: \mathbb{R}^2 \to \mathbb{R}^3$ given by $T(x,y) = (x-y,0,y^2)$ is not a linear transformation since

$$T\left(2\begin{bmatrix}1\\1\end{bmatrix}\right) = T\left(\begin{bmatrix}2\\2\end{bmatrix}\right) = \begin{bmatrix}0\\0\\4\end{bmatrix} \neq 2T\left(\begin{bmatrix}1\\1\end{bmatrix}\right) = 2\begin{bmatrix}0\\0\\1\end{bmatrix} = \begin{bmatrix}0\\0\\2\end{bmatrix}$$

If $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation, then for each $k = 1, 2, \ldots$:

$$T(a_1x_1 + a_2x_2 + \cdots + a_kx_k) = a_1T(x_1) + a_2T(x_2) + \cdots + a_kT(x_k),$$

for all scalars a_i and all vectors x_i in \mathbb{R}^n .

Example

Let $T:\mathbb{R}^2 \to \mathbb{R}^2$ be a linear transformation, and assume that

If $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation, then for each $k = 1, 2, \ldots$:

$$T(a_1x_1 + a_2x_2 + \cdots + a_kx_k) = a_1T(x_1) + a_2T(x_2) + \cdots + a_kT(x_k),$$

for all scalars a_i and all vectors x_i in \mathbb{R}^n .

Example

Let $\mathcal{T}:\mathbb{R}^2 o \mathbb{R}^2$ be a linear transformation, and assume that

$$T\begin{bmatrix} 2\\3 \end{bmatrix} = \begin{bmatrix} 2\\5 \end{bmatrix}$$
 and $T\begin{bmatrix} -1\\1 \end{bmatrix} = \begin{bmatrix} 4\\-3 \end{bmatrix}$. Find $T\begin{bmatrix} 0\\5 \end{bmatrix}$.

If $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation, then for each $k = 1, 2, \ldots$:

$$T(a_1x_1 + a_2x_2 + \cdots + a_kx_k) = a_1T(x_1) + a_2T(x_2) + \cdots + a_kT(x_k),$$

for all scalars a_i and all vectors x_i in \mathbb{R}^n .

Example

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be a linear transformation, and assume that

$$T\begin{bmatrix}2\\3\end{bmatrix}=\begin{bmatrix}2\\5\end{bmatrix}$$
 and $T\begin{bmatrix}-1\\1\end{bmatrix}=\begin{bmatrix}4\\-3\end{bmatrix}$. Find $T\begin{bmatrix}0\\5\end{bmatrix}$.

Answer:

If $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation, then for each $k = 1, 2, \ldots$:

$$T(a_1x_1 + a_2x_2 + \cdots + a_kx_k) = a_1T(x_1) + a_2T(x_2) + \cdots + a_kT(x_k),$$

for all scalars a_i and all vectors x_i in \mathbb{R}^n .

Example

Let $\mathcal{T}:\mathbb{R}^2 o \mathbb{R}^2$ be a linear transformation, and assume that

$$\mathcal{T} \left[\begin{array}{c} 2 \\ 3 \end{array} \right] = \left[\begin{array}{c} 2 \\ 5 \end{array} \right] \quad \text{and} \quad \mathcal{T} \left[\begin{array}{c} -1 \\ 1 \end{array} \right] = \left[\begin{array}{c} 4 \\ -3 \end{array} \right]. \ \text{Find} \quad \mathcal{T} \left[\begin{array}{c} 0 \\ 5 \end{array} \right].$$

Answer: Find
$$a, b: \begin{bmatrix} 0 \\ 5 \end{bmatrix} = a \begin{bmatrix} 2 \\ 3 \end{bmatrix} + b \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$
.

Chapter 2. Matrix Algebra

If $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation, then for each $k = 1, 2, \ldots$:

$$T(a_1x_1 + a_2x_2 + \cdots + a_kx_k) = a_1T(x_1) + a_2T(x_2) + \cdots + a_kT(x_k),$$

for all scalars a_i and all vectors x_i in \mathbb{R}^n .

Example

Let $\mathcal{T}:\mathbb{R}^2 o \mathbb{R}^2$ be a linear transformation, and assume that

$$T\begin{bmatrix}2\\3\end{bmatrix}=\begin{bmatrix}2\\5\end{bmatrix}$$
 and $T\begin{bmatrix}-1\\1\end{bmatrix}=\begin{bmatrix}4\\-3\end{bmatrix}$. Find $T\begin{bmatrix}0\\5\end{bmatrix}$.

Answer: Find
$$a, b: \begin{bmatrix} 0 \\ 5 \end{bmatrix} = a \begin{bmatrix} 2 \\ 3 \end{bmatrix} + b \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$
. Solve this system : $\begin{cases} a = 1 \\ b = 2 \end{cases}$

If $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation, then for each $k = 1, 2, \ldots$:

$$T(a_1x_1 + a_2x_2 + \cdots + a_kx_k) = a_1T(x_1) + a_2T(x_2) + \cdots + a_kT(x_k),$$

for all scalars a_i and all vectors x_i in \mathbb{R}^n .

Example

Let $\mathcal{T}:\mathbb{R}^2 o \mathbb{R}^2$ be a linear transformation, and assume that

$$T\begin{bmatrix}2\\3\end{bmatrix}=\begin{bmatrix}2\\5\end{bmatrix}$$
 and $T\begin{bmatrix}-1\\1\end{bmatrix}=\begin{bmatrix}4\\-3\end{bmatrix}$. Find $T\begin{bmatrix}0\\5\end{bmatrix}$.

Answer: Find
$$a, b$$
: $\begin{bmatrix} 0 \\ 5 \end{bmatrix} = a \begin{bmatrix} 2 \\ 3 \end{bmatrix} + b \begin{bmatrix} -1 \\ 1 \end{bmatrix}$. Solve this system : $\begin{cases} a = 1 \\ b = 2 \end{cases}$

Hence
$$T\begin{bmatrix}0\\5\end{bmatrix} = 1T\begin{bmatrix}2\\3\end{bmatrix} + 2T\begin{bmatrix}-1\\1\end{bmatrix} = \begin{bmatrix}2\\5\end{bmatrix} + 2\begin{bmatrix}4\\-3\end{bmatrix} = \begin{bmatrix}10\\-1\end{bmatrix}$$
.

4 D > 4 A > 4 B > 4 B > B = 90 C

If $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation, then for each $k = 1, 2, \ldots$:

$$T(a_1x_1 + a_2x_2 + \cdots + a_kx_k) = a_1T(x_1) + a_2T(x_2) + \cdots + a_kT(x_k),$$

for all scalars a_i and all vectors x_i in \mathbb{R}^n .

Example

Let $\mathcal{T}:\mathbb{R}^2 o \mathbb{R}^2$ be a linear transformation, and assume that

$$\mathcal{T} \left[\begin{array}{c} 2 \\ 3 \end{array} \right] = \left[\begin{array}{c} 2 \\ 5 \end{array} \right] \ \ \text{and} \ \ \mathcal{T} \left[\begin{array}{c} -1 \\ 1 \end{array} \right] = \left[\begin{array}{c} 4 \\ -3 \end{array} \right]. \ \ \text{Find} \ \ \mathcal{T} \left[\begin{array}{c} 0 \\ 5 \end{array} \right].$$

Answer: Find
$$a, b$$
: $\begin{bmatrix} 0 \\ 5 \end{bmatrix} = a \begin{bmatrix} 2 \\ 3 \end{bmatrix} + b \begin{bmatrix} -1 \\ 1 \end{bmatrix}$. Solve this system : $\begin{cases} a = 1 \\ b = 2 \end{cases}$

Hence
$$T\begin{bmatrix}0\\5\end{bmatrix} = 1T\begin{bmatrix}2\\3\end{bmatrix} + 2T\begin{bmatrix}-1\\1\end{bmatrix} = \begin{bmatrix}2\\5\end{bmatrix} + 2\begin{bmatrix}4\\-3\end{bmatrix} = \begin{bmatrix}10\\-1\end{bmatrix}$$
.

4 1 1 4 4 3 1 4 3 1 3 1 4

Let $T: \mathbb{R}^2 \to \mathbb{R}$ be a linear transformation and u, v be vectors such that T(u+v)=1 and T(u-v)=5. Find T(-u+2v).

Answer:

Let $T: \mathbb{R}^2 \to \mathbb{R}$ be a linear transformation and u, v be vectors such that T(u+v)=1 and T(u-v)=5. Find T(-u+2v).

Answer: We have

$$\begin{cases} T(u+v) = T(u) + T(v) = 1 \\ T(u-v) = T(u) - T(v) = 5 \end{cases} \Rightarrow \begin{cases} T(u) = 3 \\ T(v) = -2 \end{cases}$$

Hence

$$T(-u+2v) = -T(u) + 2T(v) = -3 + 2 \cdot (-2) = -7.$$

Let $T: \mathbb{R}^2 \to \mathbb{R}$ be a linear transformation and u, v be vectors such that T(u+v)=1 and T(u-v)=5. Find T(-u+2v).

Answer: We have

$$\begin{cases} T(u+v) = T(u) + T(v) = 1 \\ T(u-v) = T(u) - T(v) = 5 \end{cases} \Rightarrow \begin{cases} T(u) = 3 \\ T(v) = -2 \end{cases}.$$

Hence

$$T(-u+2v) = -T(u) + 2T(v) = -3 + 2 \cdot (-2) = -7.$$

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a transformation. Then T is linear if and only if it is a matrix transformation induced by an $m \times n$ matrix A, given in terms of its columns by

$$A = \begin{bmatrix} T(e_1) & T(e_2) \cdots T(e_n) \end{bmatrix}$$

where $\{e_1, e_2, \cdots, e_n\}$ is the standard basis of \mathbb{R}^n .

Example

Consider a linear transformation
$$T: \mathbb{R}^2 \to \mathbb{R}^2$$
: $T \begin{vmatrix} x \\ y \end{vmatrix} = \begin{vmatrix} 2x - 3y \\ x + 4y \end{vmatrix}$.

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a transformation. Then T is linear if and only if it is a matrix transformation induced by an $m \times n$ matrix A, given in terms of its columns by

$$A = \begin{bmatrix} T(e_1) & T(e_2) \cdots T(e_n) \end{bmatrix}$$

where $\{e_1, e_2, \cdots, e_n\}$ is the standard basis of \mathbb{R}^n .

Example

Consider a linear transformation
$$T: \mathbb{R}^2 \to \mathbb{R}^2$$
: $T \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x - 3y \\ x + 4y \end{bmatrix}$.

Then T is also a matrix transformation induced by

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a transformation. Then T is linear if and only if it is a matrix transformation induced by an $m \times n$ matrix A, given in terms of its columns by

$$A = \begin{bmatrix} T(e_1) & T(e_2) \cdots T(e_n) \end{bmatrix}$$

where $\{e_1, e_2, \cdots, e_n\}$ is the standard basis of \mathbb{R}^n .

Example

Consider a linear transformation $T: \mathbb{R}^2 \to \mathbb{R}^2$: $T \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x - 3y \\ x + 4y \end{bmatrix}$.

Then T is also a matrix transformation induced by

$$A = \begin{bmatrix} T(e_1) & T(e_2) \end{bmatrix} = \begin{bmatrix} T \begin{bmatrix} 1 \\ 0 \end{bmatrix} & T \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ 1 & 4 \end{bmatrix}.$$

We can see that

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a transformation. Then T is linear if and only if it is a matrix transformation induced by an $m \times n$ matrix A, given in terms of its columns by

$$A = \begin{bmatrix} T(e_1) & T(e_2) \cdots T(e_n) \end{bmatrix}$$

where $\{e_1, e_2, \dots, e_n\}$ is the standard basis of \mathbb{R}^n .

Example

Consider a linear transformation $T: \mathbb{R}^2 \to \mathbb{R}^2$: $T \begin{vmatrix} x \\ y \end{vmatrix} = \begin{vmatrix} 2x - 3y \\ x + 4y \end{vmatrix}$.

Then T is also a matrix transformation induced by

$$A = \begin{bmatrix} T(e_1) & T(e_2) \end{bmatrix} = \begin{bmatrix} T \begin{bmatrix} 1 \\ 0 \end{bmatrix} & T \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ 1 & 4 \end{bmatrix}.$$

We can see that
$$T\begin{bmatrix} x \\ y \end{bmatrix} = A\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x - 3y \\ x + 4y \end{bmatrix}$$
.

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a transformation. Then T is linear if and only if it is a matrix transformation induced by an $m \times n$ matrix A, given in terms of its columns by

$$A = \begin{bmatrix} T(e_1) & T(e_2) \cdots T(e_n) \end{bmatrix}$$

where $\{e_1, e_2, \cdots, e_n\}$ is the standard basis of \mathbb{R}^n .

Example

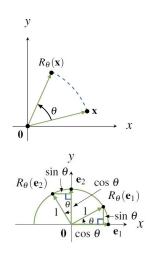
Consider a linear transformation $T: \mathbb{R}^2 \to \mathbb{R}^2$: $T \begin{vmatrix} x \\ y \end{vmatrix} = \begin{vmatrix} 2x - 3y \\ x + 4y \end{vmatrix}$.

Then T is also a matrix transformation induced by

$$A = \begin{bmatrix} T(e_1) & T(e_2) \end{bmatrix} = \begin{bmatrix} T \begin{bmatrix} 1 \\ 0 \end{bmatrix} & T \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ 1 & 4 \end{bmatrix}.$$

We can see that
$$T\begin{bmatrix} x \\ y \end{bmatrix} = A\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x - 3y \\ x + 4y \end{bmatrix}$$
.

Rotation

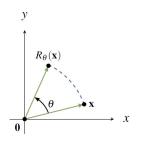


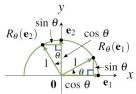
Given an angle θ , let

$$R_{\theta} \colon \mathbb{R}^2 \to \mathbb{R}^2$$

denote counterclockwise rotation of \mathbb{R}^2 about the origin through the angle θ .

Rotation





Given an angle θ , let

$$R_{\theta} \colon \mathbb{R}^2 \to \mathbb{R}^2$$

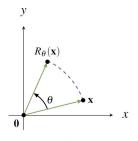
denote counterclockwise rotation of \mathbb{R}^2 about the origin through the angle θ .

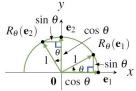
Then R_{θ} is a linear transformation induced by matrix

$$\begin{bmatrix}
R_{\theta}(\mathbf{e}_1) & R_{\theta}(\mathbf{e}_2) \\
\cos \theta & \mathbf{e}_1
\end{bmatrix} = \begin{bmatrix}
\cos \theta & -\sin \theta \\
\sin \theta & \cos \theta
\end{bmatrix}.$$



Rotation





Given an angle θ , let

$$R_{\theta} \colon \mathbb{R}^2 \to \mathbb{R}^2$$

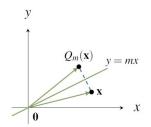
denote counterclockwise rotation of \mathbb{R}^2 about the origin through the angle θ .

Then R_{θ} is a linear transformation induced by matrix

$$\frac{\sin \theta}{\mathbf{e}_1} \theta_{\chi} \quad \left[R_{\theta}(\mathbf{e}_1) \quad R_{\theta}(\mathbf{e}_2) \right] = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}.$$



Reflection

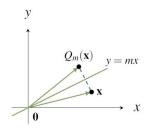


The line through the origin with slope m has equation y=mx, and we let $Q_m \colon \mathbb{R}^2 \to \mathbb{R}^2$ denote reflection in the line y=mx.

Then Q_m is a linear transformation induced by matrix

$$\frac{1}{1+m^2} \begin{bmatrix} 1-m^2 & 2m \\ 2m & m^2-1 \end{bmatrix}.$$

Reflection

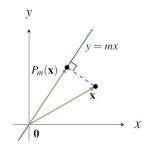


The line through the origin with slope m has equation y=mx, and we let $Q_m\colon \mathbb{R}^2\to \mathbb{R}^2$ denote reflection in the line y=mx.

Then Q_m is a linear transformation induced by matrix

$$\frac{1}{1+m^2}\begin{bmatrix}1-m^2 & 2m\\2m & m^2-1\end{bmatrix}.$$

Projection

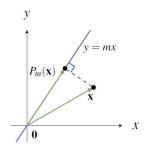


Let $P_m : \mathbb{R}^2 \to \mathbb{R}^2$ denote projection on the line y = mx.

Then P_m is a linear transformation with matrix

$$\frac{1}{1+m^2} \begin{bmatrix} 1 & m \\ m & m^2 \end{bmatrix}.$$

Projection



Let $P_m \colon \mathbb{R}^2 \to \mathbb{R}^2$ denote projection on the line y = mx.

Then P_m is a linear transformation with matrix

$$\frac{1}{1+m^2} \begin{bmatrix} 1 & m \\ m & m^2 \end{bmatrix}.$$

Given two "linked" transformations

$$\begin{array}{ccccc} \mathbb{R}^k & \xrightarrow{T} & \mathbb{R}^n & \xrightarrow{S} & \mathbb{R}^m \\ x & \mapsto & T(x) & \mapsto & S[T(x)] \end{array}$$

The composite of S and T:

$$S \circ T : \mathbb{R}^k \to \mathbb{R}^m$$

defined by

Given two "linked" transformations

$$\begin{array}{ccccc} \mathbb{R}^k & \xrightarrow{T} & \mathbb{R}^n & \xrightarrow{S} & \mathbb{R}^m \\ x & \mapsto & T(x) & \mapsto & S[T(x)] \end{array}$$

The composite of S and T:

$$S \circ T \colon \mathbb{R}^k \to \mathbb{R}^m$$

defined by

$$(S \circ T)(x) = S[T(x)]$$
 for all $x \in \mathbb{R}^k$.

Given two "linked" transformations

The composite of S and T:

$$S \circ T \colon \mathbb{R}^k \to \mathbb{R}^m$$

defined by

$$(S \circ T)(x) = S[T(x)]$$
 for all $x \in \mathbb{R}^k$.

Theorem

Let $\mathbb{R}^k \xrightarrow{T} \mathbb{R}^n \xrightarrow{S} \mathbb{R}^m$ be linear transformations, and let A and B be

the matrices of T and S respectively. Then $S \circ T$ is linear with matrix BA.

Given two "linked" transformations

$$\begin{array}{cccccc}
\mathbb{R}^k & \xrightarrow{T} & \mathbb{R}^n & \xrightarrow{S} & \mathbb{R}^m \\
x & \mapsto & T(x) & \mapsto & S[T(x)]
\end{array}$$

The composite of S and T:

$$S \circ T \colon \mathbb{R}^k \to \mathbb{R}^m$$

defined by

$$(S \circ T)(x) = S[T(x)]$$
 for all $x \in \mathbb{R}^k$.

Theorem

Let $\mathbb{R}^k \xrightarrow{T}_{A_{n \times k}} \mathbb{R}^n \xrightarrow{S}_{B_{m \times n}} \mathbb{R}^m$ be linear transformations, and let A and B be the matrices of T and S respectively. Then $S \circ T$ is linear with matrix BA.

Let T and S be linear transformations given by:

$$T: \mathbb{R}^2 \to \mathbb{R}^2, \quad T\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x + 3y \\ -x + 2y \end{bmatrix}$$

 $S: \mathbb{R}^2 \to \mathbb{R}, \quad S\begin{bmatrix} x \\ y \end{bmatrix} = x + 5y$

Then $S \circ T : \mathbb{R}^2 \to \mathbb{R}$ defined by:

Let T and S be linear transformations given by:

$$T: \mathbb{R}^2 \to \mathbb{R}^2, \quad T\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x + 3y \\ -x + 2y \end{bmatrix}$$

 $S: \mathbb{R}^2 \to \mathbb{R}, \quad S\begin{bmatrix} x \\ y \end{bmatrix} = x + 5y$

Then $S \circ T : \mathbb{R}^2 \to \mathbb{R}$ defined by:

$$S \circ T \begin{bmatrix} x \\ y \end{bmatrix} = S \left(T \begin{bmatrix} x \\ y \end{bmatrix} \right) = S \begin{bmatrix} 2x + 3y \\ -x + 2y \end{bmatrix}$$
$$= (2x + 3y) + 5(-x + 2y) = -3x + 13y.$$

Let T and S be linear transformations given by:

$$T: \mathbb{R}^2 \to \mathbb{R}^2, \quad T\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x + 3y \\ -x + 2y \end{bmatrix}$$

 $S: \mathbb{R}^2 \to \mathbb{R}, \quad S\begin{bmatrix} x \\ y \end{bmatrix} = x + 5y$

Then $S \circ T : \mathbb{R}^2 \to \mathbb{R}$ defined by:

$$S \circ T \begin{bmatrix} x \\ y \end{bmatrix} = S \left(T \begin{bmatrix} x \\ y \end{bmatrix} \right) = S \begin{bmatrix} 2x + 3y \\ -x + 2y \end{bmatrix}$$
$$= (2x + 3y) + 5(-x + 2y) = -3x + 13y.$$

We can see that the matrices of T, S and $S \circ T$ respectively are

$$A = \begin{bmatrix} 2 & 3 \\ -1 & 2 \end{bmatrix}, B = \begin{bmatrix} 1 & 5 \end{bmatrix}, \text{ and } BA = \begin{bmatrix} -3 & 13 \end{bmatrix}.$$

Let T and S be linear transformations given by:

$$T: \mathbb{R}^2 \to \mathbb{R}^2, \quad T\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x + 3y \\ -x + 2y \end{bmatrix}$$

 $S: \mathbb{R}^2 \to \mathbb{R}, \quad S\begin{bmatrix} x \\ y \end{bmatrix} = x + 5y$

Then $S \circ T : \mathbb{R}^2 \to \mathbb{R}$ defined by:

$$S \circ T \begin{bmatrix} x \\ y \end{bmatrix} = S \left(T \begin{bmatrix} x \\ y \end{bmatrix} \right) = S \begin{bmatrix} 2x + 3y \\ -x + 2y \end{bmatrix}$$
$$= (2x + 3y) + 5(-x + 2y) = -3x + 13y.$$

We can see that the matrices of T, S and $S \circ T$ respectively are

$$A = \begin{bmatrix} 2 & 3 \\ -1 & 2 \end{bmatrix}, B = \begin{bmatrix} 1 & 5 \end{bmatrix}, \text{ and } BA = \begin{bmatrix} -3 & 13 \end{bmatrix}.$$

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be rotation through $\frac{\pi}{2}$ followed by reflection in the line y=-x. Find the matrix of T.

 1^{st} way. The matrix of the rotation through $\frac{\pi}{2}$ is

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be rotation through $\frac{\pi}{2}$ followed by reflection in the line y = -x. Find the matrix of T.

 1^{st} way. The matrix of the rotation through $\frac{\pi}{2}$ is

$$\begin{bmatrix} \cos\frac{\pi}{2} & -\sin\frac{\pi}{2} \\ \sin\frac{\pi}{2} & \cos\frac{\pi}{2} \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

The matrix of the reflection in the line y = -x is

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be rotation through $\frac{\pi}{2}$ followed by reflection in the line y = -x. Find the matrix of T.

 1^{st} way. The matrix of the rotation through $\frac{\pi}{2}$ is

$$\begin{bmatrix} \cos\frac{\pi}{2} & -\sin\frac{\pi}{2} \\ \sin\frac{\pi}{2} & \cos\frac{\pi}{2} \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

The matrix of the reflection in the line y = -x is

$$\frac{1}{1+(-1)^2} \begin{bmatrix} 1-(-1)^2 & 2.(-1) \\ 2.(-1) & (-1)^2 - 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

Hence, the matrix of T is

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be rotation through $\frac{\pi}{2}$ followed by reflection in the line y = -x. Find the matrix of T.

 1^{st} way. The matrix of the rotation through $\frac{\pi}{2}$ is

$$\begin{bmatrix} \cos\frac{\pi}{2} & -\sin\frac{\pi}{2} \\ \sin\frac{\pi}{2} & \cos\frac{\pi}{2} \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

The matrix of the reflection in the line y = -x is

$$\frac{1}{1+(-1)^2} \begin{bmatrix} 1-(-1)^2 & 2.(-1) \\ 2.(-1) & (-1)^2 - 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

Hence, the matrix of T is $\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$.

Chapter 2. Matrix Algebra

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be rotation through $\frac{\pi}{2}$ followed by reflection in the line y = -x. Find the matrix of T.

 1^{st} way. The matrix of the rotation through $\frac{\pi}{2}$ is

$$\begin{bmatrix} \cos\frac{\pi}{2} & -\sin\frac{\pi}{2} \\ \sin\frac{\pi}{2} & \cos\frac{\pi}{2} \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

The matrix of the reflection in the line y = -x is

$$\frac{1}{1+(-1)^2} \begin{bmatrix} 1-(-1)^2 & 2.(-1) \\ 2.(-1) & (-1)^2 - 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

Hence, the matrix of T is $\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$.

Chapter 2. Matrix Algebra

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be rotation through $\frac{\pi}{2}$ followed by reflection in the line y = -x. Find the matrix of T.

 2^{nd} way. We can see

$$\begin{array}{l} e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \xrightarrow{\text{rotation through } \pi/2} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \xrightarrow{\text{reflection in } y = -x} \begin{bmatrix} -1 \\ 0 \end{bmatrix} \\ e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \xrightarrow{\text{rotation through } \pi/2} \begin{bmatrix} -1 \\ 0 \end{bmatrix} \xrightarrow{\text{reflection in } y = -x} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{array}$$

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be rotation through $\frac{\pi}{2}$ followed by reflection in the line y = -x. Find the matrix of T.

 2^{nd} way. We can see

$$e_1 = egin{bmatrix} 1 \ 0 \end{bmatrix} \xrightarrow{\operatorname{rotation through} \pi/2} egin{bmatrix} 0 \ 1 \end{bmatrix} \xrightarrow{\operatorname{reflection in } y = -x} egin{bmatrix} -1 \ 0 \end{bmatrix}$$
 $e_2 = egin{bmatrix} 0 \ 1 \end{bmatrix} \xrightarrow{\operatorname{rotation through} \pi/2} egin{bmatrix} -1 \ 0 \end{bmatrix} \xrightarrow{\operatorname{reflection in } y = -x} egin{bmatrix} 0 \ 1 \end{bmatrix}$

Hence, the matrix of T is

$$\begin{bmatrix} T(e_1) & T(e_2) \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}.$$

Chapter 2. Matrix Algebra

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be rotation through $\frac{\pi}{2}$ followed by reflection in the line y = -x. Find the matrix of T.

 2^{nd} way. We can see

$$e_1 = egin{bmatrix} 1 \ 0 \end{bmatrix} \xrightarrow{\text{rotation through } \pi/2} egin{bmatrix} 0 \ 1 \end{bmatrix} \xrightarrow{\text{reflection in } y = -x} egin{bmatrix} -1 \ 0 \end{bmatrix}$$
 $e_2 = egin{bmatrix} 0 \ 1 \end{bmatrix} \xrightarrow{\text{rotation through } \pi/2} egin{bmatrix} -1 \ 0 \end{bmatrix} \xrightarrow{\text{reflection in } y = -x} egin{bmatrix} 0 \ 1 \end{bmatrix}$

Hence, the matrix of T is

$$egin{bmatrix} T(e_1) & T(e_2) \end{bmatrix} = egin{bmatrix} -1 & 0 \ 0 & 1 \end{bmatrix}.$$



Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the matrix transformation induced by

$$A = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}. \text{ Find } (T \circ T) \begin{bmatrix} -1 \\ 2 \end{bmatrix}.$$

Answer:

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the matrix transformation induced by

$$A = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$
. Find $(T \circ T) \begin{bmatrix} -1 \\ 2 \end{bmatrix}$.

Answer: We have

$$(T \circ T) \begin{bmatrix} -1\\2 \end{bmatrix} = A^2 \begin{bmatrix} -1\\2 \end{bmatrix} = \begin{bmatrix} 1 & -1\\0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1\\0 & 1 \end{bmatrix} \begin{bmatrix} -1\\2 \end{bmatrix}$$
$$= \begin{bmatrix} 1 & -2\\0 & 1 \end{bmatrix} \begin{bmatrix} -1\\2 \end{bmatrix} = \begin{bmatrix} -5\\2 \end{bmatrix}.$$

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the matrix transformation induced by

$$A = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$
. Find $(T \circ T) \begin{bmatrix} -1 \\ 2 \end{bmatrix}$.

Answer: We have

$$(T \circ T) \begin{bmatrix} -1 \\ 2 \end{bmatrix} = A^2 \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -5 \\ 2 \end{bmatrix}.$$

Exercises

```
Section 2.1: 1ad, 2aef, 3acd, 4, 14, 15, 19 (page 45, 46)
```

Section 2.3 : 1adef, 2, 3, 4, 6, 7, 12, 22 (page 76 - 79)

Section 2.4: 1bd, 2aeg, 3acd, 4, 5, 6, 9, 12 (page 91 - 93)

Section 2.6: 1, 3, 7, 8, 9, 12 (page 115, 116)