

DS 1 Ne21a

2016-2017

$$\{T_{\text{wh}}\}_{G_1} = \begin{cases} 0 \\ -800 - 400 - 200 = -1400 \text{ N} \\ -800 \cdot (1.5 - x) - 400 \cdot (4 - x) - 200 \cdot (6 - x) = -1200 - 1600 - 1200 + (800 + 400 + 200) \cdot x \end{cases}$$

$$\boxed{\begin{cases} T_{\text{wh}}\}_{G_1} = \begin{cases} 0 \\ -1400 \text{ N} \\ -4000 + 1400 \cdot x \end{cases} \\ G_1(x, 0, 0) \\ 0 < x < 1.5 \end{cases}}$$

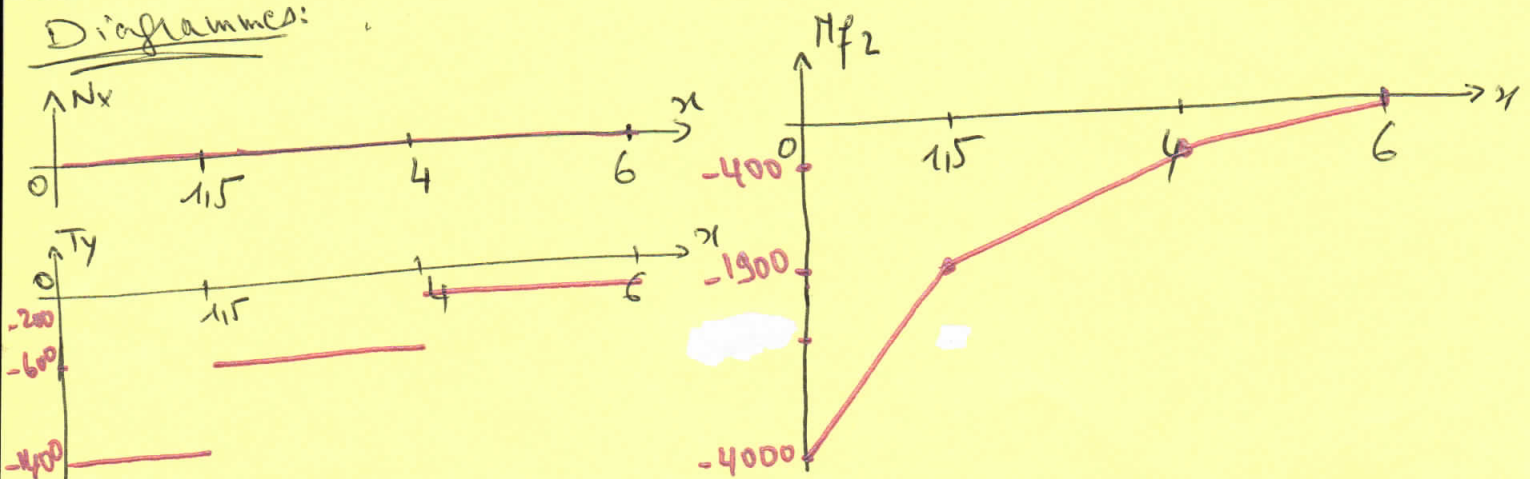
$$\{T_{\text{wh}}\}_{G_2} = \begin{cases} 0 \\ -600 \text{ N} \\ -400 \cdot (4 - x) - 200 \cdot (6 - x) = -1600 - 1200 + (400 + 200) \cdot x \end{cases}$$

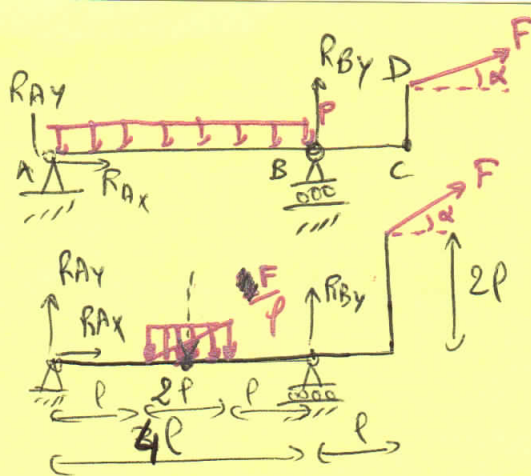
$$\boxed{\begin{cases} T_{\text{wh}}\}_{G_2} = \begin{cases} 0 \\ -600 \text{ N} \\ -2800 + 600 \cdot x \end{cases} \\ G_2(x, 0, 0) \\ 1.5 < x < 4 \end{cases}}$$

$$\{T_{\text{wh}}\}_{G_3} = \begin{cases} 0 \\ -200 \\ -200 \cdot (6 - x) = -1200 + 200 \cdot x \end{cases}$$

$$\boxed{\begin{cases} T_{\text{wh}}\}_{G_3} = \begin{cases} 0 \\ -200 \text{ N} \\ -1200 + 200 \cdot x \end{cases} \\ G_3(x, 0, 0) \\ 4 < x < 6 \end{cases}}$$

Diagrammes:





$$\cancel{R_{Ax} + F \cos \alpha = 0}$$

$$\cancel{R_{Ay} + R_{By} - pL = 0}$$

Ex 2

$$R_{Ax} + F \cos \alpha = 0 \quad (1)$$

$$R_{Ay} + R_{By} - \frac{F}{p} \cdot 2p + F \sin \alpha = 0 \quad (1)$$

$$R_{By} \cdot 4p - \frac{F}{p} \cdot 2p \cdot 2p - F \cos \alpha \cdot 2p + F \sin \alpha \cdot 5p = 0$$

$$R_{By} = \frac{F \cos \alpha \cdot 2p - F \sin \alpha \cdot 5p + 4F \cdot p}{4p}$$

$$R_{By} = \frac{(2 \cos \alpha - 5 \sin \alpha + 4) F}{4}$$

$$R_{Ay} = \frac{F \sin \alpha + 4F - F \cos \alpha \cdot 2}{4}$$

$$F = 50 \text{ N} ; l = 50 \text{ cm} ; \alpha = 40^\circ$$

$\alpha = 45^\circ$

$$R_{By} = 23,5 \text{ N}$$

$$R_{Ay} = 38,2 \text{ N}$$

$$R_{Ax} = -35,3 \text{ N}$$

$$AN: R_{By} = \frac{2 \cos 40^\circ - 5 \sin 40^\circ + 4}{4} \cdot 50$$

$$R_{By} \sim 29 \text{ N}$$

$$R_{Ay} = 2 \cdot 50 - 50 \sin 40^\circ - 29$$

$$R_{Ay} \sim 38,8 \text{ N}$$

$$R_{Ax} = -50 \cos 40^\circ$$

$$R_{Ax} \sim -38,3 \text{ N}$$

Optics and  
reflex