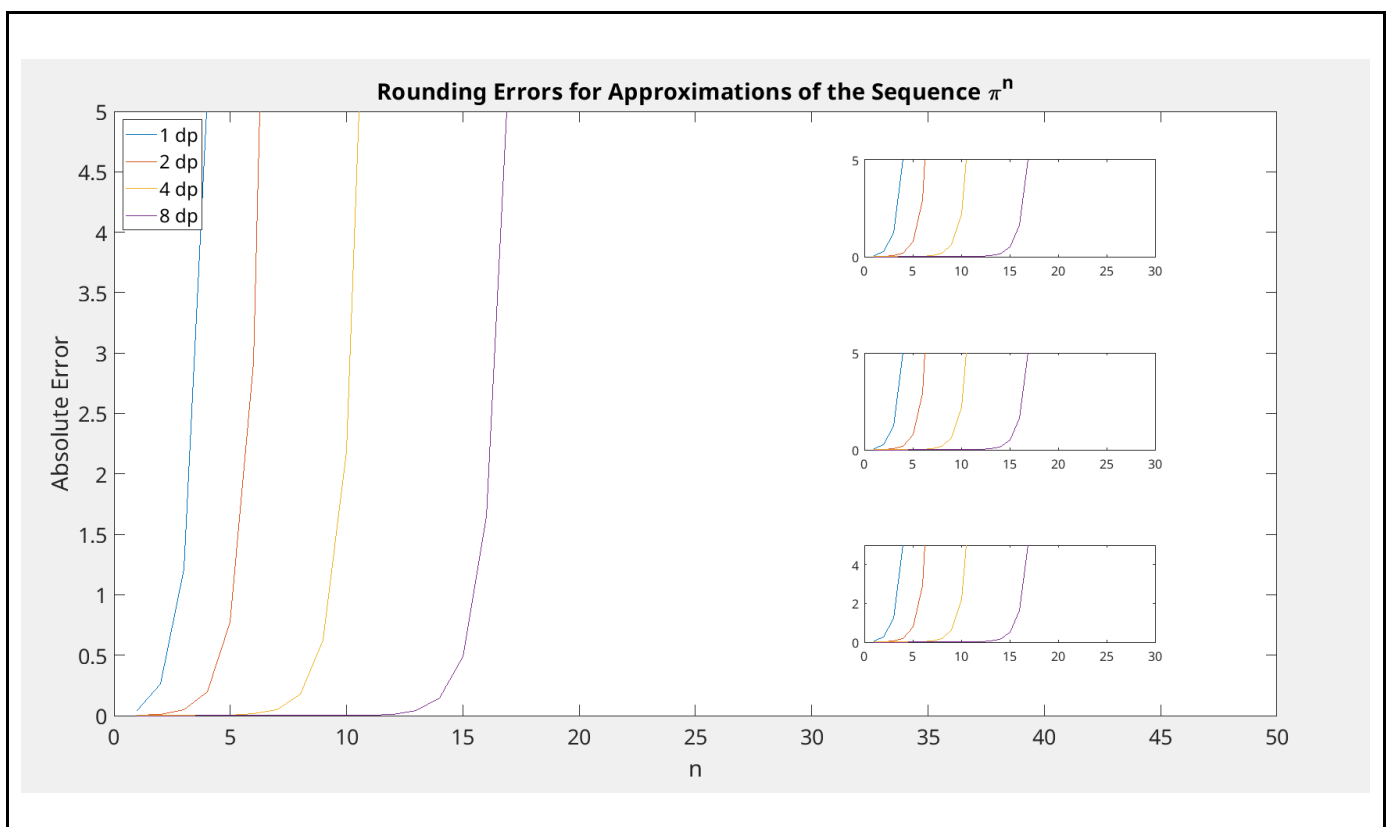


Practical Problems 4 – Errors & Bracketed Root Finding

1. **[Overflow Error]** Matlab returns **Inf** when an overflow error in double precision is encountered. Write a script that starts with $n = 1$, calculates $n!$ and increases n until overflow occurs (number is too big that Matlab can't handle it). Display the value of n that represents the largest factorial that Matlab can handle.

```
Command Window
>> Q1_sol
Highest factorial is: 170
```

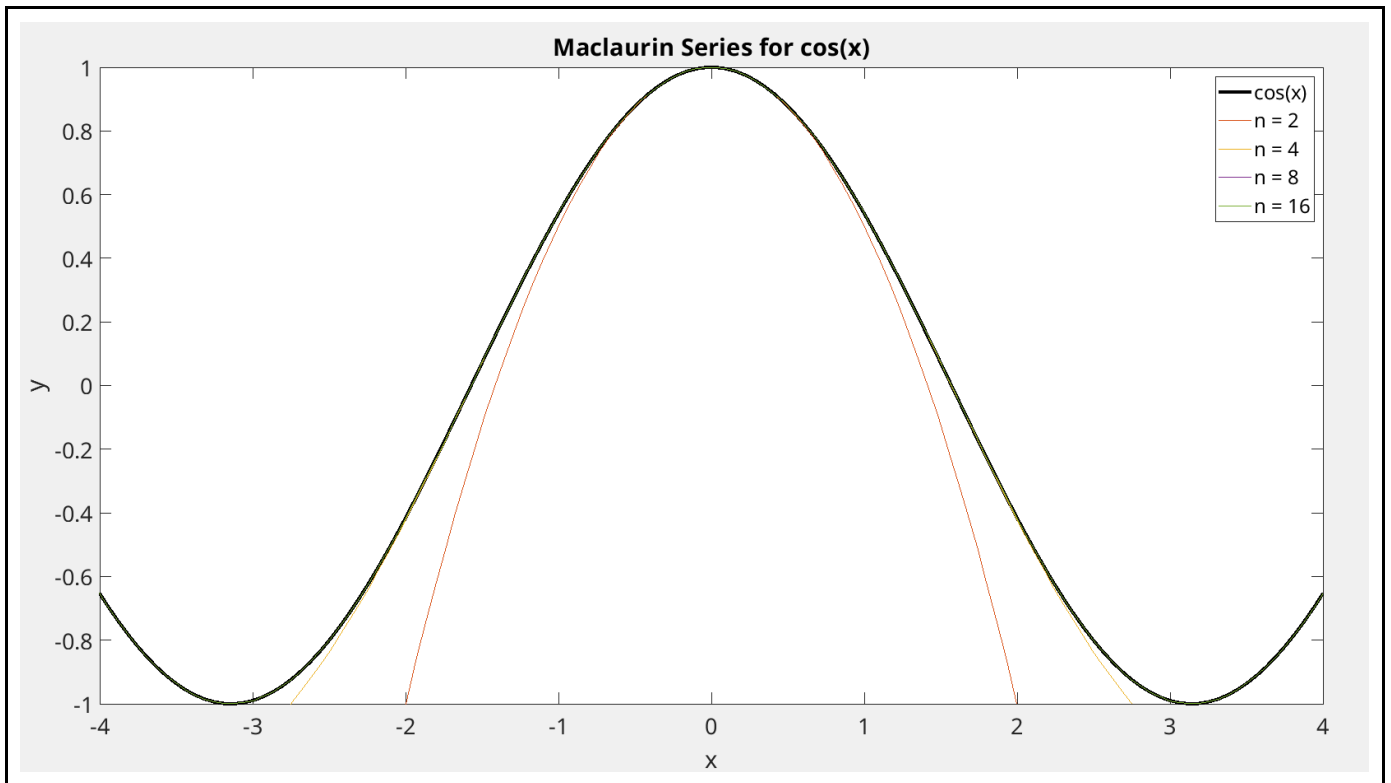
2. **[Rounding Error]** Approximate the sequence $\{\pi^n\}$ for $n = 1$ to 18 by rounding π to 1, 2, 4, and 8 decimal places. Calculate the absolute error for each sequence approximation from the sequence that uses π with double precision. Plot the errors for each approximate sequence on the same plot with y-axis between 0 and 5. See if you can figure out how to embed smaller plots within the main plot that zoom in on each of the sequences.



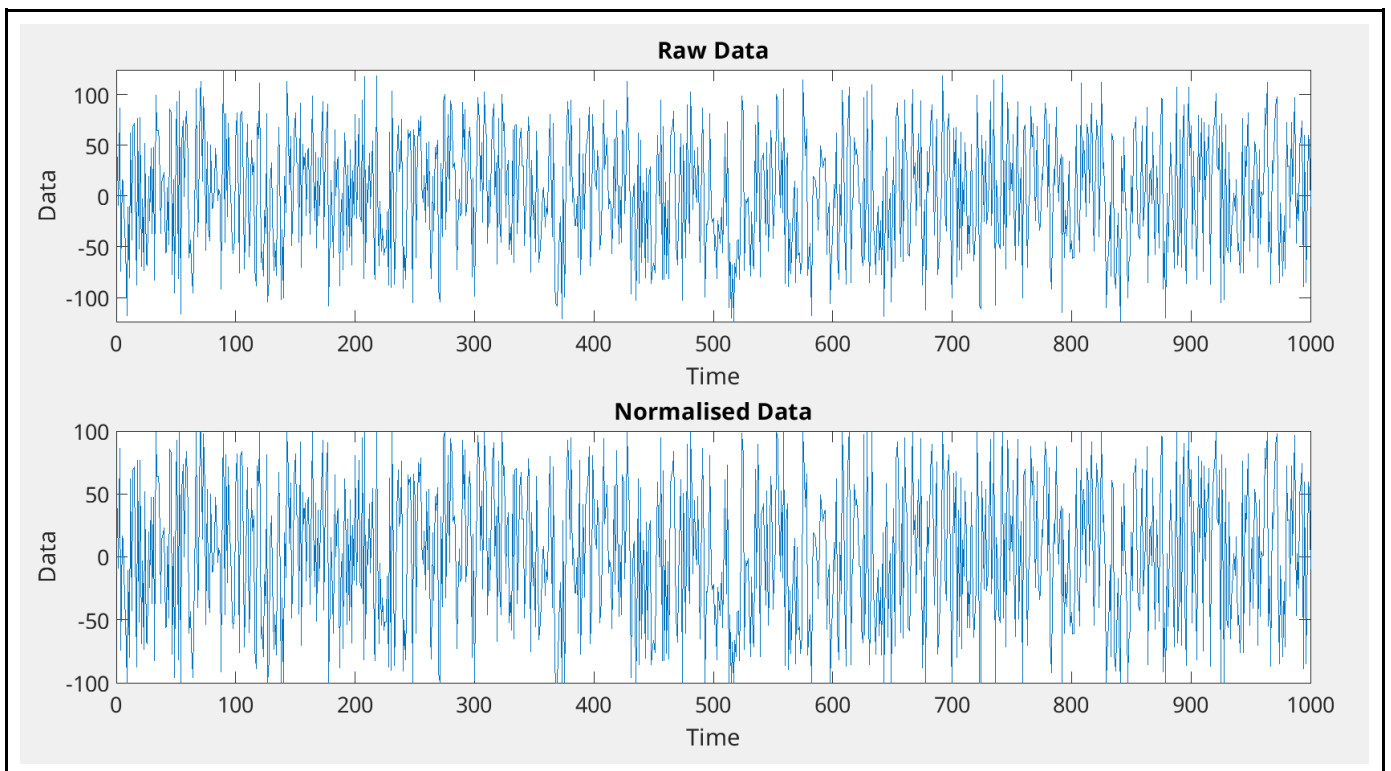
3. **[Truncation Error]** The Maclaurin series for $\cos(x)$ is

$$\cos(x) = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n}}{(2n)!}$$

Plot the cosine function in a thick black line between -2π and 2π . On the same graph plot the Maclaurin series approximation for n equal to 2, 4, 8 and 16.



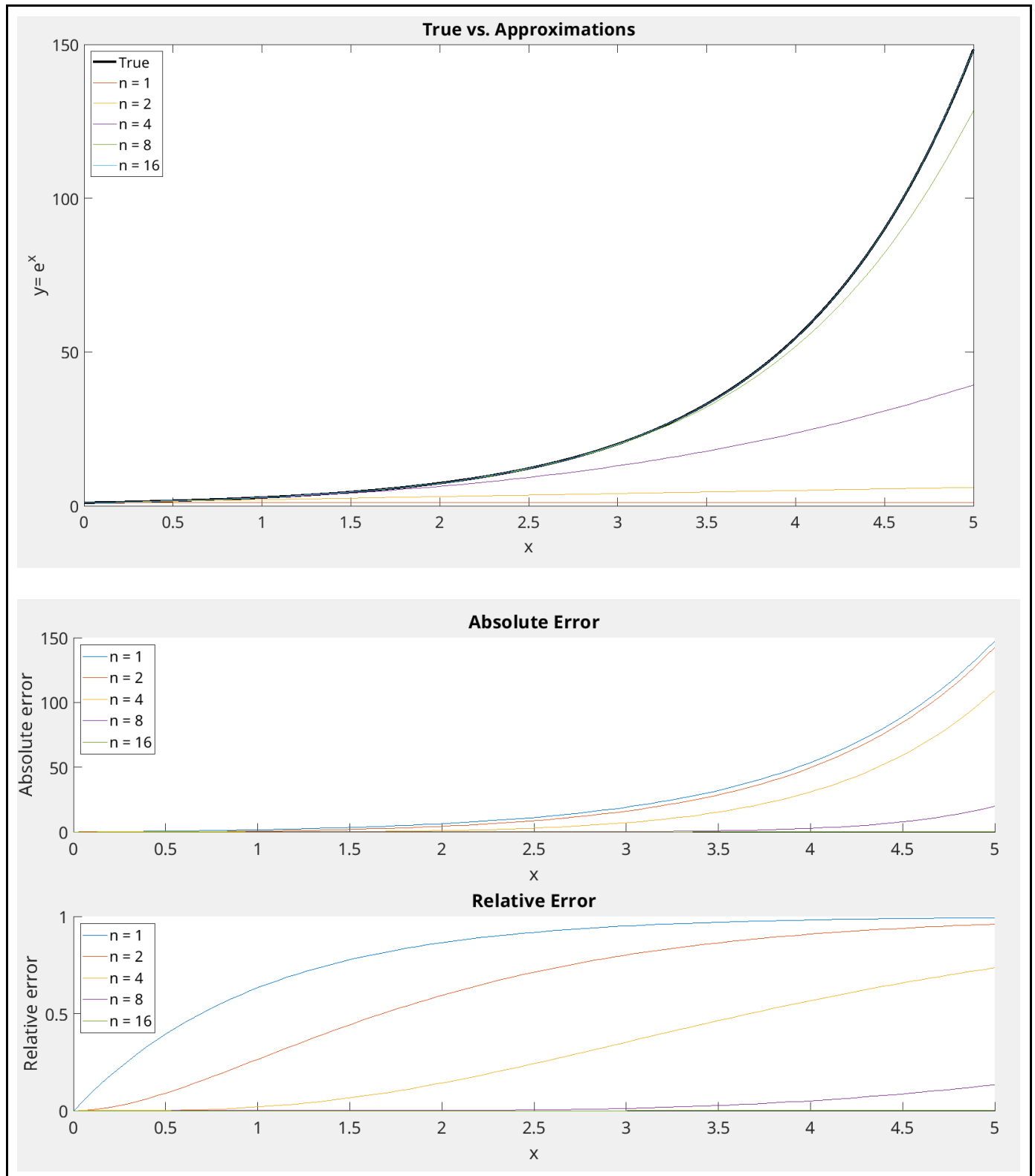
4. **[Correcting Measurement Data]** Import the data from the file **data_pp4_q4.xls** using the import wizard (or using the **xlsread** command) then plot the Data against Time. The data should be corrected so that all values above 100 are normalised to exactly 100, and all values below -100 are normalised to exactly -100 . Plot the corrected data on a subplot below the original.



5. **[True vs. Relative Error]** The Maclaurin series for e^x is

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$

Plot the true function from 0 to 5 then on the same graph plot the Maclaurin approximations for n equal to 1, 2, 4, 8, and 16. Calculate the true absolute and true relative errors then plot these together in a separate graph.



6. **[Convergence with Absolute Error Criterion]** The series

$$\sum_{n=0}^{\infty} \frac{4^{n+1}}{(3n+1)!}$$

is convergent. Write a script that finds the value the series converges to by using a loop and the **absolute approximate error** with a tolerance of 0.0001 (stopping criterion).

```
Command Window
>> Q6_Sol
Absolute error is: 0.66667
Absolute error is: 0.012698
Absolute error is: 7.0547e-05
The sum has converged to 4.6794
The number of terms required is 3
```

7. **[Convergence with Relative Error Criterion]** Write a script that finds the value that the series in question 6 converges to, by using a loop and the **relative approximate error** with a tolerance of 0.0001 (stopping criterion). Compare the results of this question with question 6.

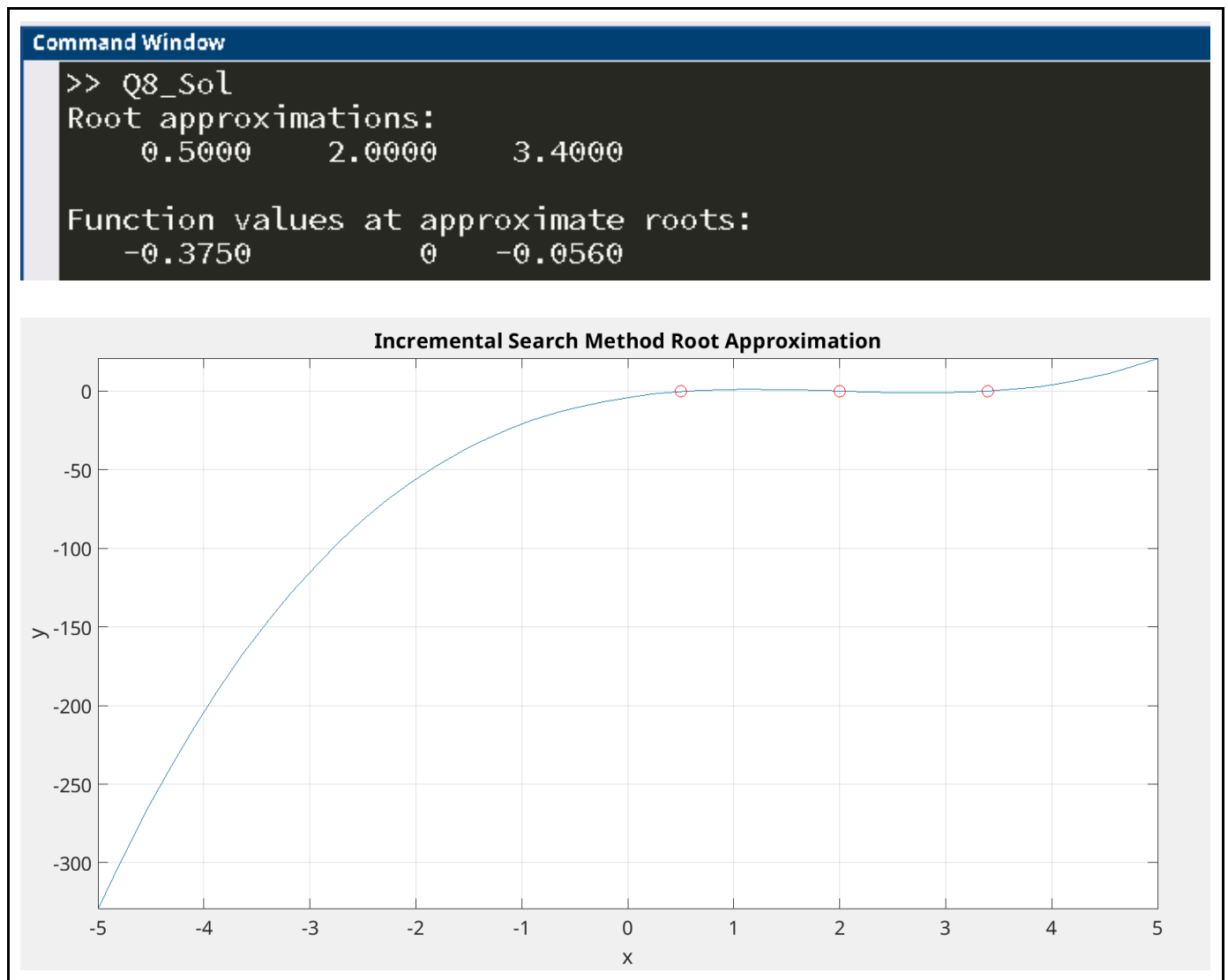
```
Command Window
>> Q7_Sol
Absolute error is: 0.14286
Absolute error is: 0.0027137
Absolute error is: 1.5076e-05
The sum has converged to 4.6794
The number of terms required is 3
```

8. **[Open Method Root Finding]** Write a script that implements the Incremental Search Method, with a step size of 0.1, to approximate the 3 roots to the following equation:

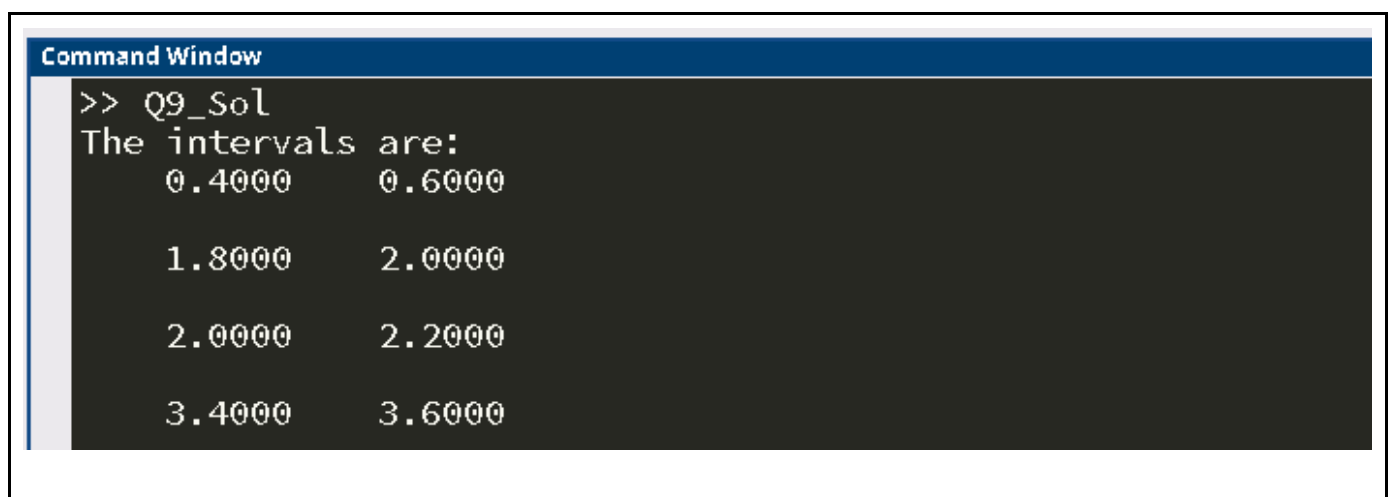
$$y = x^3 - 6x^2 + 10x - 4$$

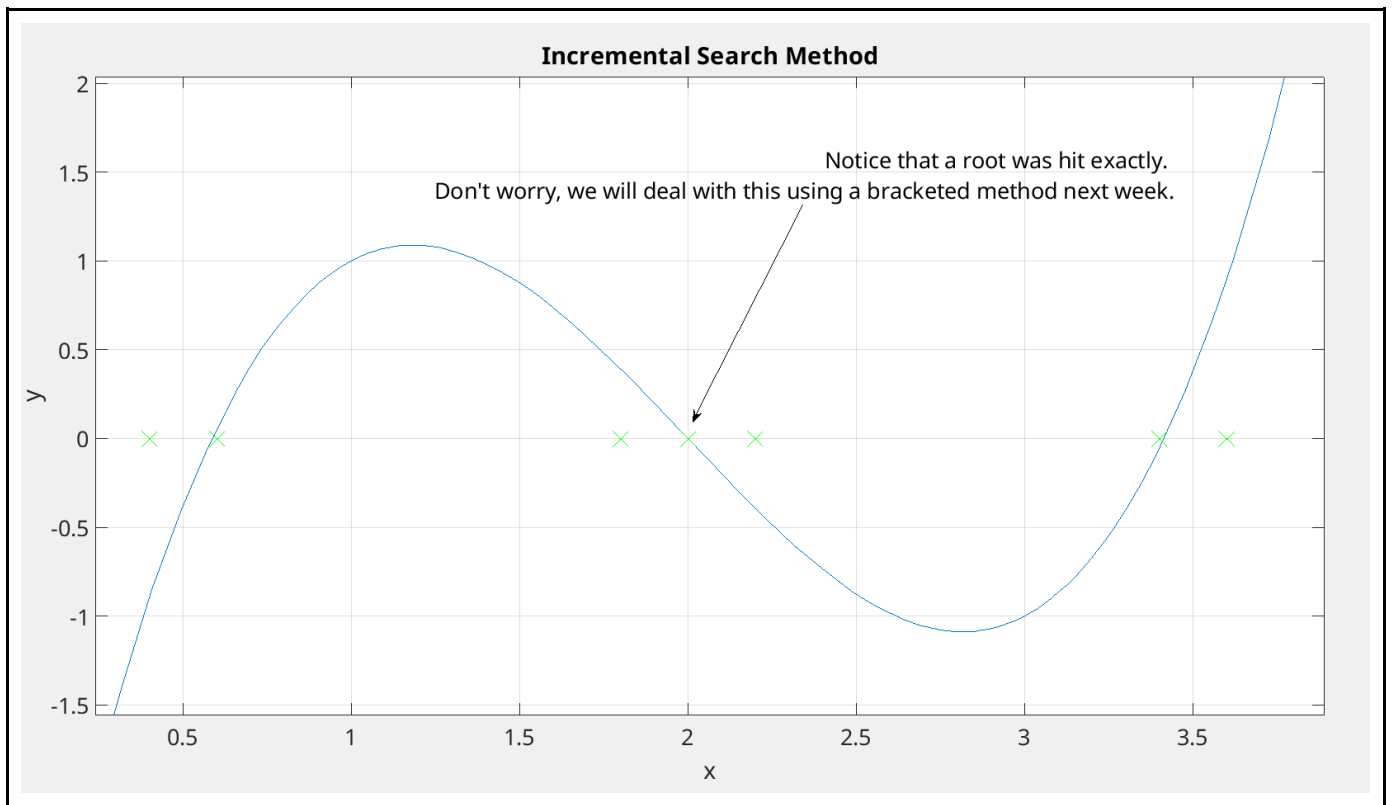
Choose a sensible initial guess for your algorithm (plotting the function might help you decide).

Find a way to test how closely you approximated the roots.
Can you see why this method is only good for initial bracketing?



9. **[Preparing Open Method for Use With Closed Method]** Rewrite your script from Q9 to output 3 intervals where the roots are located between.





10. **[Generalising Method to Any Function]** Write a Matlab function file that implements the Incremental Search Method. The user should be able to input a function $f(x)$, step size h , and range of values to search between $[x_0, x_{\text{end}}]$. The output should be a list of brackets (intervals) containing each root.

Test your function with the function

$$f(x) = \sin(10x) + \cos(3x)$$

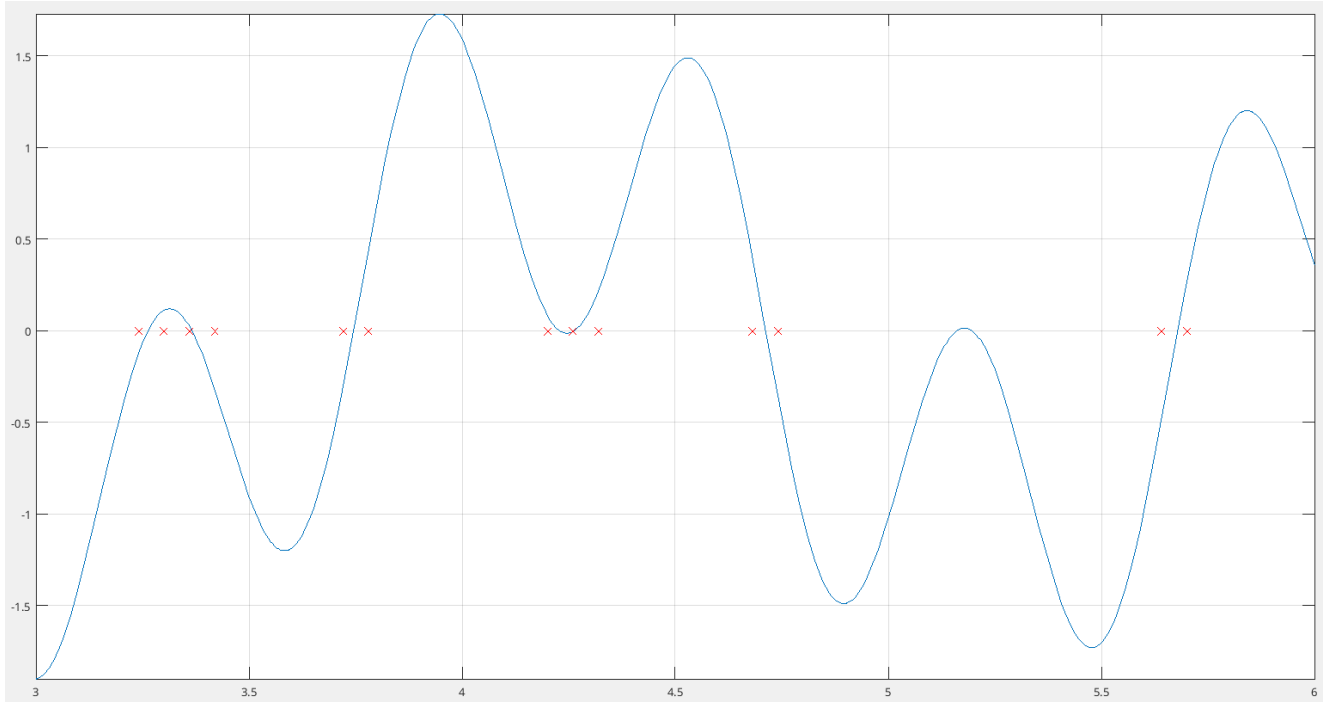
on the interval $[3, 6]$ with step sizes of 0.06 and 0.03.

```

Command Window
>> f = @(x) sin(10*x) + cos(3*x);
>> Q10_sol(f, 0.06, [3 6])

ans =

    3.2400    3.3000
    3.3600    3.4200
    3.7200    3.7800
    4.2000    4.2600
    4.2600    4.3200
    4.6800    4.7400
    5.6400    5.7000
  
```



Command Window

```
>> f = @(x) sin(10*x) + cos(3*x);
>> Q10_Sol(f, 0.03, [3 6])
```

```
ans =
```

```
3.2400    3.2700
3.3600    3.3900
3.7200    3.7500
4.2000    4.2300
4.2600    4.2900
4.7100    4.7400
5.1600    5.1900
5.1900    5.2200
5.6700    5.7000
```

