view_frames Result

Recorded at time: 1744703762.472716

base_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

mb_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

front_left_wheel_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

front_right_wheel_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

inertial_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

rear_left_wheel_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

rear_right_wheel_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ur5e_base_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ur5e_base

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ur5e_base_link_inertia

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

ur5e_shoulder_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

ur5e_upper_arm_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

ur5e_forearm_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

ur5e_wrist_1_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

ur5e_wrist_2_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

ur5e_wrist_3_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ur5e_flange

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ur5e_ft_frame

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ur5e_tool0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

ur_to_robotiq_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

gripper_mount_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robotiq_85_base_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

robotiq_85_left_knuckle_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

robotiq_85_right_knuckle_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

robotiq_85_left_inner_knuckle_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

robotiq_85_right_inner_knuckle_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robotiq_85_left_finger_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robotiq_85_right_finger_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

robotiq_85_left_finger_tip_link

Broadcaster: default_authority
Average rate: 10.199
Buffer length: 5.0
Most recent transform: 1744703762.446429
Oldest transform: 1744703757.445969

robotiq_85_right_finger_tip_link