



**វិទ្យាស្ថានបច្ចេកវិទ្យាកម្ពុជា**  
INSTITUTE OF TECHNOLOGY OF CAMBODIA

GRADUATE SCHOOL  
MASTER'S DEGREE OF ENGINEERING  
IN  
MECHATRONICS, INFORMATION AND COMMUNICATION  
ENGINEERING

**PATH PLANNING AND CONTROL OF WHEELED  
MOBILE ROBOT WITH OCCUPANCY GRID MAP**

A THESIS SUBMITTED BY

**YONRITH Phayuth**

UNDER CO-SUPERVISION OF

Dr. SRANG Sarot, Mr. SAKAL Morokot

JULY 2021

# PATH PLANNING AND CONTROL OF WHEELED MOBILE ROBOT WITH OCCUPANCY GRID MAP

A THESIS PRESENTED BY

**YONRITH Phayuth**

TO

THE INSTITUTE OF TECHNOLOGY OF CAMBODIA

IN PARTIAL FULFILMENT OF THE REQUIREMENTS

FOR THE AWARD OF

MASTER'S DEGREE OF ENGINEERING

SPECIALIZATION: *Mechatronics, Information and Communication Engineering*

SUPERVISOR: **Dr. SRANG Sarot**

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