

# Urban Diversity Through an Information-Theoretic Lens

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# Introduction

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## Central Claim

These two questions are deeply related, and we should approach both using *information theory*.

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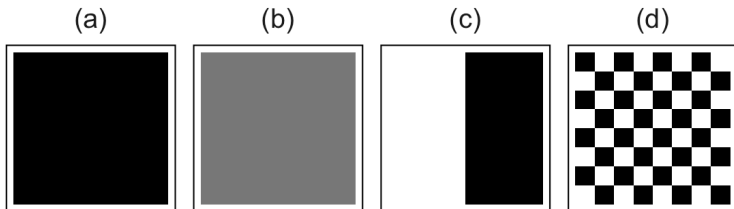
No global diversity  $\implies$  perfect evenness  $\implies$  maximal exposure.

# Neighborhoods, Exposure, and the Checkerboard

**Claim:** Spatial exposure is about the number, scale, and pattern of neighborhoods.

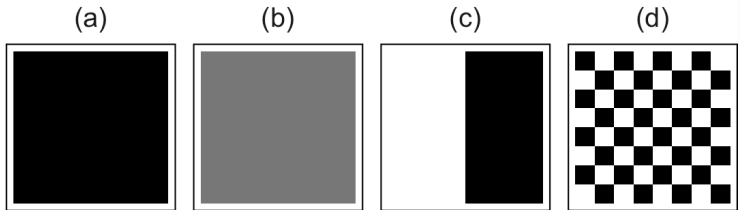
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City	Exposure	Neighborhoods
(c)	Low	Few, large
(d)	High	Many, small

# Diversity and Information Theory

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## Summary: Information Theory and Diversity

### Entropy Measures Diversity

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## Mutual Information Measures Evenness

$$I(X, Y) \triangleq \mathbb{E}_{X,Y} \left[ \log \frac{p(X,Y)}{p(X)p(Y)} \right]$$



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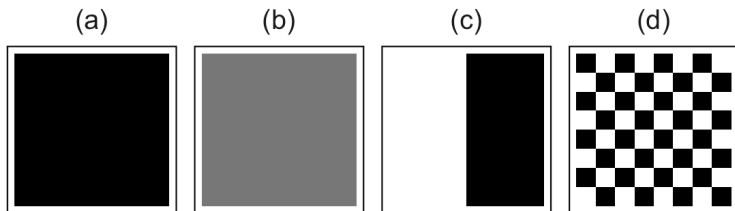
## Mutual Information Measures Evenness

$$I(X, Y) \triangleq \mathbb{E}_{X,Y} \left[ \log \frac{p(X,Y)}{p(X)p(Y)} \right]$$

## Mean Local Information Measures Exposure

$$J(X, Y) \triangleq \mathbb{E}_X[\text{trace } J_Y(X)]$$

## Back to the checkerboard



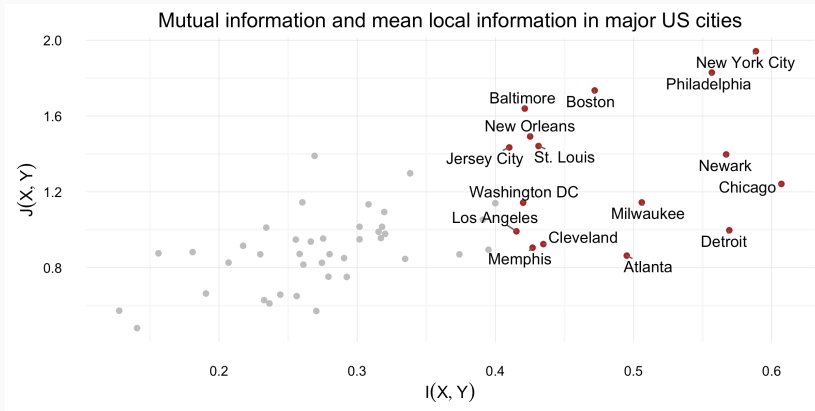
City	$H(Y)$	$I(X, Y)$	$J(X, Y)$
(a)	0.0	0.0	0.0
(b)	0.7	0.0	0.0
(c)	0.7	0.7	0.6
(d)	0.7	0.7	2.7

## A Three-Dimensional Characterization of Urban Diversity

City	$H(Y)$	$I(X, Y)$	$J(X, Y)$
Albuquerque	1.08	0.19	0.66
Detroit	1.12	0.57	1.00
Philadelphia	1.31	0.56	1.83

*Data accessed from the American Community Survey of the U.S. Census [1].*

# Visualizing Diversity Profiles in Major Cities



- Philadelphia has greater exposure / more neighborhood structure than Detroit.

# Identifying Natural Neighborhoods

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## Key Property of Mutual Information

Suppose we cluster the locations  $X$  into groups with labels  $C$ .

**“Additive Organizational Decomposability” (Chain Rule)**

$$I(X, Y) = I(C, Y) + I(X, Y|C) .$$

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We can use this to identify neighborhoods!

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## Recipe for Neighborhood Identification

$$I(X, Y) = \underbrace{I(C, Y)}_{\text{maximize this}} + \overbrace{I(X, Y|C)}^{\text{minimize this}} .$$



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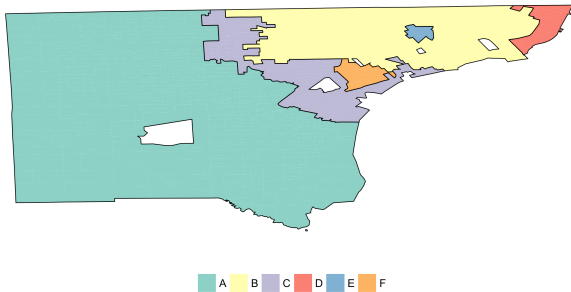
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## Recipe for Neighborhood Identification

$$I(X, Y) = \underbrace{I(C, Y)}_{\text{maximize this}} + \overbrace{I(X, Y|C)}^{\text{minimize this}} .$$

This optimization is hard to do exactly, but we can use a greedy approach based on hierarchical clustering.

# Practical Example: Racial Neighborhoods in Detroit



White	36	2	7	2	1	1
Black	5	29	4			
Hispanic	2		1			2
Asian	2				1	
Other	2	1	1			
	A	B	C	D	E	F

*Percentage of  
population by race  
and  
neighborhood.*

## Wrapping Up

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# Generality and future work

- **Other demographics:** education level, income, occupation type, etc.
- **Other dimensions:** time
  - Evolution of urban demographics (timescale: decades)
  - Dynamics of diversity in daily mobility (timescale: minutes)



Daily commuting flows in  
Riyad, Saudi Arabia.

*Image credit: Shan Jiang  
and MIT HuMNetLab*

## Download our tools!

R Package for Information-Theoretic Analysis

<https://github.com/PhilChodrow/compx>

This project: analysis and presentations

[https://github.com/PhilChodrow/spatial\\_complexity](https://github.com/PhilChodrow/spatial_complexity)

THANK YOU! Questions? Feedback?

## Supplementary Materials

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## Relation of local and Fisher informations

Suppose that  $p(y|x) > 0$  and that  $p(y|x)$  is differentiable as a function of  $x$  for all  $x, y \in \mathbb{R}^n \times \mathcal{Y}$ . Define

$B_r \triangleq B_r(x_0) \triangleq \{x \in \mathbb{R}^n \mid |x - x_0| \leq r\}$ . Additionally, define the *local mutual information* in  $B_r$  as the mutual information between  $X$  and  $Y$  where  $X$  is restricted to  $B_r$ :

$$I_r(x_0) \triangleq \mathbb{E}_X[D[p(\cdot|X) \| p(\cdot|X \in B_r)] | X \in B_r] \quad (1)$$

$$= \int_{B_r} p(x|X \in B_r) D[p(\cdot|x) \| p(\cdot|X \in B_r)] d^n x. \quad (2)$$

where  $D[p \| q] \triangleq \sum_y p(y) \log \frac{p(y)}{q(y)}$  is the Kullback-Leibler divergence of  $q$  from  $p$ .

# Relation of local and Fisher informations

## Theorem

Under the stated conditions,

$$\lim_{r \rightarrow 0} \frac{I_r(x_0)}{r^2} = \frac{n}{2(n+2)} \text{trace } J_Y(x_0) . \quad (3)$$

The Fisher information matrix  $J_Y$  is given by

$$J_Y(x) \triangleq \mathbb{E}_Y [\nabla_x S_Y(x) \nabla_x S_Y(x)^T] \quad (4)$$

$$S_Y(x) \triangleq \log p(y|x) . \quad (5)$$

# Information Measures Check the Boxes

Criterion	$H(Y)$	$I(X, Y)$	$J(X, Y)$
Organizational Equivalence	✓	✓	✓
Size/Density Invariance	✓	✓	✓
Additive Group Decomposability	✓	✓	✓
Additive Spatial Decomposability	NA	✓	*
Scale Interpretability	NA	✓	✓
Boundary Independence	NA	✓	✓
Exchanges	NA	✓	✓

\* We contend that [12]'s version is not a workable criterion for explicitly spatial measures.

✓ In the theoretical definition; in practice we are reliant on the data as it is provided.

# Some Comparative Clusters of Equal Information

## Example clusters

Atlanta:  $I(C,Y) = 0.27$

White	32	3
Other	3	1
Hispanic	7	2
Black	9	38
Asian	5	

Boston:  $I(C,Y) = 0.27$

	30	6	3	1	3
	2		1	2	1
	4	2	3	5	9
	4		3	12	1
	6				1

Chicago:  $I(C,Y) = 0.27$

White	37	2	1	2
Other	2	1		
Hispanic	10	2	8	5
Black	5	14	4	
Asian	6			

Detroit:  $I(C,Y) = 0.27$

	44	3	2
	3	1	
	5		
	9	29	
	2	1	

A

B

C

D

E

A

B

C

D

E