

Introduction to *PointedSDMs*

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Introduction

- ▶ Point 1
- ▶ Point 2
- ▶ Point 3

Introduction to integrated modelling

Process model

The underlying process model is a log-Gaussian cox process (LGCP) with a spatially varying intensity function, $\lambda(s) = \exp\{\eta(s)\}$, where:

$$\eta(s) = \alpha_0 + \sum_{k=1}^p \beta_k X_k(s) + \zeta(s),$$

where:

- ▶ α_0 is an intercept term,
- ▶ β_k is the k^{th} coefficient for the k^{th} environmental covariate, which varies in space (denoted by the index, s),
- ▶ $\zeta(s)$ is a zero-mean Gaussian random field determined by a Matèrn covariance function.

Observation models

- Observation models are chosen based on the underlying sampling protocols of a given dataset.

Data type	Distribution
Present absent	Binomial (with a <i>cloglog link</i>)
Present only	Thinned Poisson
Count data	Poisson
Marks/traits	Variety

PointedSDMs R package

- ▶ Package is designed to simplify the construction of ISDMs using a joint-likelihood framework.
- ▶ Wrapper around *R-INLA* and *inlabru* packages.

Installation of the package

- ▶ Install from either *CRAN* or *Github*.

```
install.packages("PointedSDMs")
```

or

```
devtools::install_github("PhilipMostert/PointedSDMs")
```

Package structure

Initializing model

startISDM

```
args(startISDM)
```

```
## function (... , spatialCovariates = NULL, Projection  
  , Mesh, IPS = NULL,  
##      Boundary = NULL, pointCovariates = NULL, Offset  
  = NULL, pointsIntercept = TRUE,  
##      pointsSpatial = "copy", responseCounts = "  
  counts", responsePA = "present",  
##      trialsPA = NULL, temporalName = NULL, Formulas  
  = list(covariateFormula = NULL,  
##      biasFormula = NULL))  
## NULL
```

startSpecies

```
args(startSpecies)
```

```
## function (... , spatialCovariates = NULL, Projection
, Mesh, speciesSpatial = "replicate",
##   speciesIntercept = TRUE, speciesEnvironment =
TRUE, speciesName,
##   IPS = NULL, Boundary = NULL, pointCovariates =
NULL, Offset = NULL,
##   pointsIntercept = TRUE, pointsSpatial = "copy",
responseCounts = "counts",
##   responsePA = "present", trialsPA = NULL,
temporalName = NULL,
##   Formulas = list(covariateFormula = NULL,
biasFormula = NULL))
## NULL
```

startMarks

```
args(startMarks)
```

```
## function (... , spatialCovariates = NULL, Projection
, Mesh, IPS = NULL,
##      Boundary = NULL, markNames = NULL, markFamily =
      NULL, marksSpatial = TRUE,
##      pointCovariates = NULL, pointsIntercept = TRUE,
      marksIntercept = TRUE,
##      Offset = NULL, pointsSpatial = "copy",
      responseCounts = "counts",
##      responsePA = "present", trialsPA = NULL,
      trialsMarks = NULL,
##      temporalName = NULL, Formulas = list(
      covariateFormula = NULL,
##      biasFormula = NULL))
## NULL
```

Specifying model

Available slot functions

Name	Use
<code>\$plot()</code>	Plot data
<code>\$addBias()</code>	Add second spatial effect
<code>\$updateFormula()</code>	Update a likelihood's formula
<code>\$changeComponents()</code>	Update model components
<code>\$priorsFixed()</code>	Specify priors for the fixed effects
<code>\$specifySpatial()</code>	Specify the spatial effects
<code>\$changeLink()</code>	Change the link function of a process
<code>\$spatialBlock()</code>	Initiate spatial-block cross-validation
<code>\$addSamplers()</code>	Change the integration domain for a likelihood
<code>\$specifyRandom()</code>	Specify the priors for other random effects

Information about slot functions

- ▶ Obtain documentation through the `.$help()` function.

```
obj <- startISDM(...)  
obj.$help()
```

Estimate the model

fitISDM

```
args(fitISDM)
```

```
## function (data, options = list())  
## NULL
```

Post-estimation

Predict and plot

```
Predictions <- predict(model,  
  ...)  
plot(Predictions)
```

Model evaluation

Spatial block

```
args(blockedCV)
```

```
## function (data, options = list())  
## NULL
```

Leave-one-out

```
args(datasetOut)
```

```
## function (model, dataset, predictions = TRUE)  
## NULL
```

Quick example

Next steps

- ▶ Questions and discussions.
- ▶ Pull *Github* repository:
PhilipMostert/PointedSDMs_Workshop.
- ▶ We will through *Vignette 1: Basic model* together.