1 FEM Solver Implementation

Full weak form:

$$-\delta W = \underbrace{\int_{\Omega_0} \mathbf{S} : \delta \mathbf{E} \, dV}_{-\delta W_{\text{int}}} - \underbrace{\int_{\Omega_0} \hat{\mathbf{b}}_0^T \delta \mathbf{u} \, dV}_{-\delta W_{\text{ext}}} - \underbrace{\int_{\Gamma_{0;\sigma}} \hat{\mathbf{t}}_0^T \delta \mathbf{u} \, dA}_{-\delta W_{\text{ext}}} \stackrel{!}{=} 0.$$
 (1.1)

We neglect $\delta W_{\rm ext}$ for now, and focus on internal work:

$$-\delta W_{\rm int} = \int_{\Omega_0} \mathbf{S} : \delta \mathbf{E} \, dV \equiv \int_{\Omega_0} \delta \mathbf{E} : \mathbf{S} \, dV \stackrel{!}{=} 0, \tag{1.2}$$

due to symmetry of both tensors.

We use the linear (engineering) strain

$$E = \text{symmetrize}(\nabla u) = \frac{1}{2}(\nabla u + (\nabla u)^{T}), \tag{1.3}$$

as well as the linear St. Venant-Kirchoff constitutive relation

$$S = C_{VK} : E, \tag{1.4}$$

$$(C_{VK})_{ijkl} = \lambda \delta_{ij} \delta k l + \mu (\delta_{ik} \delta_{il} + \delta_{il} \delta_{ik}), \tag{1.5}$$

with the Lamé constants λ and μ .

1.0.1 Discretization within an element

We use the discretized quantities (technically they should have an "h" subscript, but we leave it away here because we do not handle the analytical quantities anyways)

$$u_i = \sum_{k=1}^{\text{nnode}} N_k d_{\text{nodeldof2dof}(k,i)}, \qquad (1.6)$$

$$\delta u_i = \sum_{k=1}^{\text{nnode}} N_k \delta d_{\text{nodeldof2dof}(k,i)}, \tag{1.7}$$

$$x_i = \sum_{k=1}^{\text{nnode}} N_k X_{\text{nodeldof2dof}(k,i)}, \tag{1.8}$$

where

$$nodeldof2dof(k, i) = k \cdot nnode + i$$
 (1.9)

is the mapping from node k and node-local (node-scoped) dof i to the corresponding element-global (element-scoped) dof. The inverse of this mapping is

$$dof2nodeldof(g) = \{floor(g/ndofn), mod(g, ndofn)\}.$$
 (1.10)

We will henceforth use the shorthand notation

$$q_{(k,j)} := q_{\text{nodeldof2dof}(k,j)}, \tag{1.11}$$

for any non-tensor vector quantity q as above.

Now, given the need for the gradient of the unknown displacement in (1.3), we need to discretize it. In index notation,

$$\frac{\partial u_i}{\partial x_j} = \frac{\partial (\mathrm{Nd})_i}{\partial x_j} = \sum_{k=1}^{\mathrm{nnode}} \frac{\partial \mathrm{N}_k}{\partial x_j} \mathrm{d}_{\mathrm{nodeldof2dof}(k,i)}. \tag{1.12}$$

Now, we can find the gradient of the shape functions from the parametric coordinates and (inverse) Jacobian:

$$\frac{\partial N_k}{\partial x_j} = \sum_{l=1}^{\text{ndofn}} \frac{\partial N_k}{\partial \xi_l} \frac{\partial \xi_l}{\partial x_j}.$$
(1.13)

To find the inverse Jacobian, we need the Jacobian:

$$J_{lj} = \frac{\partial x_j}{\partial \xi_l} = \frac{\sum_{k=1}^{\text{nnode}} N_k X_{\text{nodeldof2dof}(k,j)}}{\partial \xi_l} = \sum_{k=1}^{\text{nnode}} \frac{N_k}{\partial \xi_l} X_{\text{nodeldof2dof}(k,j)}.$$
(1.14)

Ok, so, that was easy enough with the Jacobian. It is an isolated task. But, we now look at the rest of the stuff, i.e. (1.2). We start from (1.3) basically.

$$E_{ij} = frac 12(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i}) = frac 12(\frac{\partial N_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i})$$
(1.15)