

Automatic Exploration of Machine Learning Experiments on OpenML

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Abstract

Understanding the influence of hyperparameters on the performance of a machine learning algorithm is an important requirement for well performing and adequately tuned algorithms. As to date, data to help this required understanding of state-of-the-art algorithms like gradient boosting or random forest are rare, this paper presents a large, free and open dataset addressing this problem (see [Kühn et al., 2018] to access the dataset). The dataset contains the performance (AUC, accuracy and Brier score) of six different machine learning algorithms with randomly sampled hyperparameters, runtime and meta-data for 38 datasets. Each algorithm was cross-validated up to 500.000 times with different hyperparameters resulting in a dataset of around 2.5 million experiments overall. Such data can be invaluable for meta-learning, benchmarking and other tasks related to hyperparameters like finding good defaults or measuring the tunability of algorithms and hyperparameters.

1 Introduction

When applying machine learning algorithms on real world datasets, users have to choose from a large selection of different algorithms with many of them offering a set of hyperparameters. Even though sometimes default values exist, they can be suboptimal and need to be specified by the user which often has large influence on the performance of the algorithm. The *no free lunch theorem* [Wolpert, 2001] states that in algorithm selection one algorithm can not consistently outperform all others algorithms for every dataset, so a crucial question practitioners have to face on a daily basis therefore is the selection of the best algorithm with optimal hyperparameters for a given dataset. This problem is very hard to solve, since many algorithms exist, the evaluation of a single machine learning run is often computationally expensive and the hyperparameter-space is complex [Claesen and Moor, 2015]. The usual approach is to run a hyperparameter tuning algorithm like random search, grid search or Bayesian optimization [Snoek et al., 2012] to find the best hyperparameter setting. These methods have the drawback that a large number of runs might be necessary which can result in very high computational costs.

Meta-learning tries to decrease this cost [Feurer et al., 2015], by reusing information of previous runs of the algorithm on other datasets. A requirement for this, is to have a meta-learning dataset, that contains such information. With this paper we provide an freely accessible dataset that contains around 2.5 million runs of six different machine learning algorithms on 38 classification datasets. Large, freely available datasets like Imagenet [Deng et al., 2009] are important for the progress of machine learning, we hope to support the development in the area of meta-learning and benchmarking with this dataset. While similar meta-datasets were created in the past, we were not able to access them by the links provided in their respective papers: Smith et al. [2014] provides a repository with Weka-based machine learning experiments on 72 data sets, 9 machine learning algorithms, 10 hyperparameter settings for each algorithm, and several meta-features of each data set.

Reif [2012] created a meta-dataset based on machine learning experiments on 83 datasets, 6 classification algorithms, and 49 meta-features.

The results of the benchmark can be accessed in different ways:

- The easiest way to access them is to go to the figshare repository [Kühn et al., 2018] and download the .csv files or the .RData file.
- Alternatively the code for the extraction of the data from the nightly database snapshot of OpenML can be found here: https://github.com/ja-thomas/OMLbots/blob/master/snapshot_database/database_extraction.R

2 Creating the dataset

To create the dataset the following six supervised machine learning algorithms implemented in R are run with predefined ranges for their relevant hyperparameters on 38 classification tasks: elastic net (`glmnet` [Friedman et al., 2010]), decision tree (`rpart`, [Therneau and Atkinson, 2018]), k-nearest neighbors (`knn`, [Schliep and Hechenbichler, 2016]), support vector machines (`svm`, [Meyer et al., 2017]), random forest (`ranger`, [Wright and Ziegler, 2017]) and gradient boosting (`xgboost`, [Chen and Guestrin, 2016]). These algorithms cover a wide range of approaches to machine learning. For each algorithm the available hyperparameters are explored in a predefined range (see Table 1). Some of these hyperparameters are transformed by the function found in column *trafo* to sample from the range non-uniformly. This is often, if e.g. minor changes in a hyperparameter are not expected to have a significant impact on the performance of an algorithm.

These algorithms are run on a subset of the OpenML100 Benchmark suite [Bischl et al., 2017], which consists of 100 classification datasets carefully curated from the thousands of datasets available on OpenML. We only include datasets without missing data and with a binary outcome resulting in 38 datasets. The datasets with their specific characteristics can be found in Table 2.

3 Random Experimentation Bot

To conduct a large number of experiments a bot was implemented to automatically plan and execute runs. Following the search paradigm of random search the bot iteratively executes several steps:

1. Randomly draw one of the six algorithms.
2. Randomly draw a hyperparameter setting of the chosen algorithm based on the ranges of Table 1.
3. Randomly draw one of the 38 binary classification benchmark datasets from Table 2.
4. Load the dataset from cache or download it from OpenML and cache it.
5. Evaluate the algorithm with the sampled hyperparameters on the selected dataset with 10-fold cross-validation. Consistent cross-validation splits are provided by OpenML.
6. Upload the benchmark results with hyperparameters, performance measures and time measurements to OpenML. The tag `mlrRandomBot` is used for identification.

An advantage of using random search instead of other tuning methods like grid search is that additional experiments can be easily added to existing ones. One could for example easily increase the hyperparameter range for a specific algorithm or add a new algorithm simply by adding new experiments to existing ones. Moreover, random search is more

algorithm	hyperparameter	type	lower	upper	trafo
glmnet	alpha	numeric	0	1	-
	lambda	numeric	-10	10	2^x
rpart	cp	numeric	0	1	-
	maxdepth	integer	1	30	-
	minbucket	integer	1	60	-
	minsplit	integer	1	60	-
kknn	k	integer	1	30	-
svm	kernel	discrete	-	-	-
	cost	numeric	-10	10	2^x
	gamma	numeric	-10	10	2^x
	degree	integer	2	5	-
ranger	num.trees	integer	1	2000	-
	replace	logical	-	-	-
	sample.fraction	numeric	0	1	-
	mtry	numeric	0	1	$x \cdot p$
	respect.unordered.factors	logical	-	-	-
	min.node.size	numeric	0	1	n^x
xgboost	nrounds	integer	1	5000	-
	eta	numeric	-10	0	2^x
	subsample	numeric	0	1	-
	booster	discrete	-	-	-
	max_depth	integer	1	15	-
	min_child_weight	numeric	0	7	2^x
	colsample_bytree	numeric	0	1	-
	colsample_bylevel	numeric	0	1	-
	lambda	numeric	-10	10	2^x
	alpha	numeric	-10	10	2^x

Table 1: Hyperparameters of the algorithms. p refers to the number of variables and n to the number of observations.

efficient in covering multidimensional hyperparameter spaces and finding optimal hyperparameter settings [Bergstra and Bengio, 2012].

The bot is developed open source and can be found on GitHub (<https://github.com/j-a-thomas/OMLbots>). To add a new algorithm it has to be included in the `R/botSetLearnerParamPairs.R` file of the GitHub repository with its hyperparameter ranges. The main function `runBot` executes the bot with a predefined number of experiments. The bot is based on the R packages `mlr` [Bischl et al., 2016] and `OpenML` [Casalicchio et al., 2017] and written in modular form such that it can be extended with new sampling strategies for hyperparameters, algorithms and datasets in the future.

After more than 6 million benchmark experiments the results of the bot are downloaded from OpenML. Since on dataset 4135 all algorithms except of `rpart` and `ranger` crashed is is excluded and 38 datasets remain.

For each of the algorithms 500.000 experiments are used to obtain a final dataset. The experiments are chosen by the following procedure: for each algorithm, a threshold B is set (see below) and, if the number of results for a dataset exceeds B , we draw randomly B of the results obtained for this algorithm and this dataset. For each algorithm, the threshold value B is chosen for each algorithm separately to exactly obtain 500000 results for each algorithm.

For `kknn` we only execute 30 experiments per dataset because this number of experiments is high enough to cover the hyperparameter space (that only consists of the parameter k for

Data_id	Name	nObs	nFeat	majPerc	numFeat	catFeat
3	kr-vs-kp	3196	37	0.52	0	37
31	credit-g	1000	21	0.70	7	14
37	diabetes	768	9	0.65	8	1
44	spambase	4601	58	0.61	57	1
50	tic-tac-toe	958	10	0.65	0	10
151	electricity	45312	9	0.58	7	2
312	scene	2407	300	0.82	294	6
333	monks-problems-1	556	7	0.50	0	7
334	monks-problems-2	601	7	0.66	0	7
335	monks-problems-3	554	7	0.52	0	7
1036	sylva_agnostic	14395	217	0.94	216	1
1038	gina_agnostic	3468	971	0.51	970	1
1046	mozilla4	15545	6	0.67	5	1
1049	pc4	1458	38	0.88	37	1
1050	pc3	1563	38	0.90	37	1
1063	kc2	522	22	0.80	21	1
1067	kc1	2109	22	0.85	21	1
1068	pc1	1109	22	0.93	21	1
1120	MagicTelescope	19020	12	0.65	11	1
1176	Internet-Advertisements	3279	1559	0.86	1558	1
1220	Click_prediction_small	39948	12	0.83	11	1
1461	bank-marketing	45211	17	0.88	7	10
1462	banknote-authentication	1372	5	0.56	4	1
1464	blood-transfusion-service-center	748	5	0.76	4	1
1467	climate-model-simulation-crashes	540	21	0.91	20	1
1471	eeg-eye-state	14980	15	0.55	14	1
1479	hill-valley	1212	101	0.50	100	1
1480	ilpd	583	11	0.71	9	2
1485	madelon	2600	501	0.50	500	1
1486	nomao	34465	119	0.71	89	30
1487	ozone-level-8hr	2534	73	0.94	72	1
1489	phoneme	5404	6	0.71	5	1
1504	steel-plates-fault	1941	34	0.65	33	1
1510	wdbc	569	31	0.63	30	1
1570	wilt	4839	6	0.95	5	1
4134	Bioresponse	3751	1777	0.54	1776	1
4135	Amazon_employee_access	32769	10	0.94	0	10
4534	PhishingWebsites	11055	31	0.56	0	31

Table 2: Included datasets with meta-data. *nObs* are the number of observations, *nFeat* the number of Features, *majPerc* the percentage of observations with the most common class, *numFeat* the number of numeric features and *catFeat* the number of categorical features.

$k \in \{1, \dots, 30\}$) appropriately, resulting in 1140 experiments. In total this results in around 2.5 million experiments.

The distribution of the runs on the datasets and algorithms can be seen in table 3.

4 Discussion and potential usage of the results

The presented data can be used to discover effects of hyperparameters on performances of different algorithms over different datasets.

Possible applications are:

- Find good defaults for the algorithms that work well on many datasets.
- Measure and investigate differences between algorithms.
- Improve hyperparameter tuning algorithms:
 - Measure the tunability of algorithms and find out which parameters should be tuned [see Probst et al., 2018]
 - Get priors for tuning algorithms to search important regions of the hyperparameter space with higher probability.
- Train models based on dataset characteristics and propose hyperparameter settings that perform good on a new dataset.

Data_id	glmnet	rpart	kknn	svm	ranger	xgboost	Total
3	15547	14633	30	19644	15139	16867	81860
31	15547	14633	30	19644	15139	16867	81860
37	15546	14633	30	15985	15139	16866	78199
44	15547	14633	30	19644	15139	16867	81860
50	15547	14633	30	19644	15139	16866	81859
151	15547	14632	30	2384	12517	16866	61976
312	6613	13455	30	18740	12985	15886	67709
333	15546	14632	30	19644	15139	16867	81858
334	15547	14633	30	19644	14492	16867	81213
335	15547	14633	30	15123	15139	10002	70474
1036	14937	14633	30	2338	7397	2581	41916
1038	15547	5151	30	5716	4827	1370	32641
1046	6466	14633	30	10121	3788	16867	51905
1049	15547	14633	30	5422	8842	11812	56286
1050	7423	14632	30	12064	15139	4453	53741
1063	15547	14633	30	19644	11357	13758	74969
1067	15547	14633	30	19644	7914	16866	74634
1068	15546	14632	30	10229	7386	16866	64689
1120	15546	14633	30	13893	8173	16866	69141
1176	15531	7477	30	3908	9760	8143	44849
1220	13005	14632	30	14451	15140	13047	70305
1461	6970	14073	30	2678	14323	2215	40289
1462	8955	14633	30	6320	15139	16867	61944
1464	15547	14632	30	19644	15139	16867	81859
1467	15547	14633	30	4441	15139	16866	66656
1471	15547	14633	30	9725	13523	16866	70324
1479	15546	14633	30	19644	15140	16867	81860
1480	15024	14633	30	19644	15139	16254	80724
1485	8247	10923	30	10334	15139	9237	53910
1486	3866	11389	30	1490	15139	5813	37727
1487	15547	6005	30	19644	15139	11194	67559
1489	15547	14633	30	17298	15139	16867	79514
1504	15547	14632	30	19644	15139	16867	81859
1510	15547	14633	30	19644	15140	16867	81861
1570	15547	14633	30	19644	15139	16867	81860
4134	15546	14632	30	19644	15139	16867	81858
4135	1493	3947	30	560	14516	2222	22768
4534	2801	3231	30	2476	15139	947	24624
Total	500000	500000	1140	500000	500000	500000	2501140

Table 3: Number of experiments for each combination of dataset and algorithm.

A potential weakness of this dataset is that the dimension of hyperparameter spaces for example for **xgboost** can be very high and the number of experiments is not sufficient to explore it appropriately, especially regions in which very high performance can be achieved. This could potentially be improved by using smarter sampling strategies similar to tuning algorithms to explore these regions more thoroughly.

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