A Comparison of Optimization Methods for Multi-Objective Constrained Bin Packing Problems

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Outline

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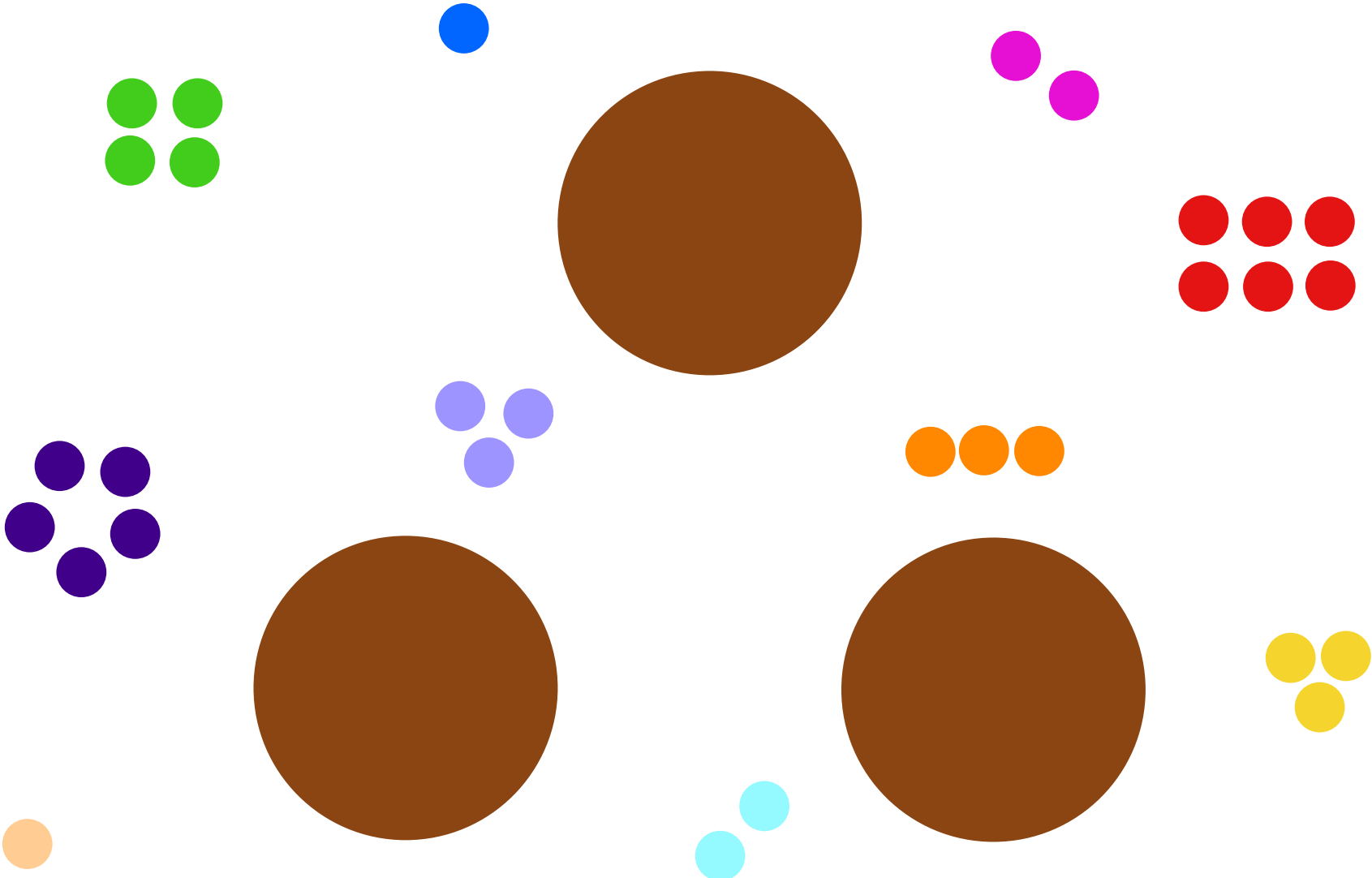
The Wedding Seating Problem



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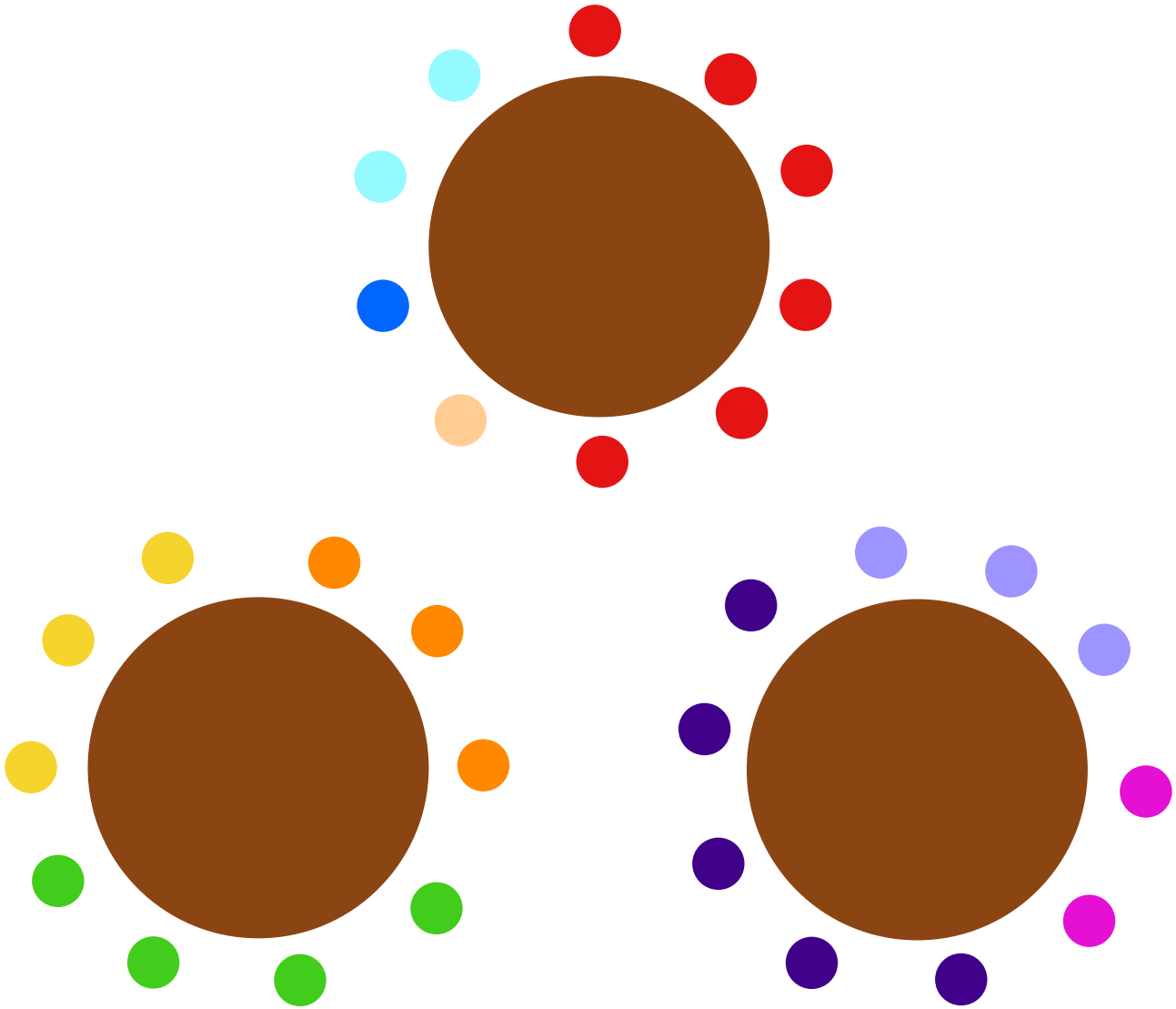

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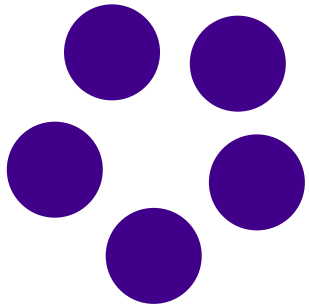

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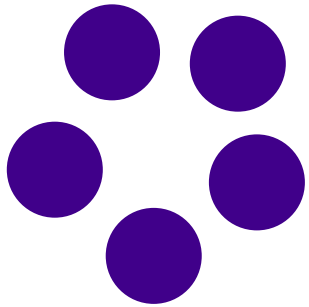

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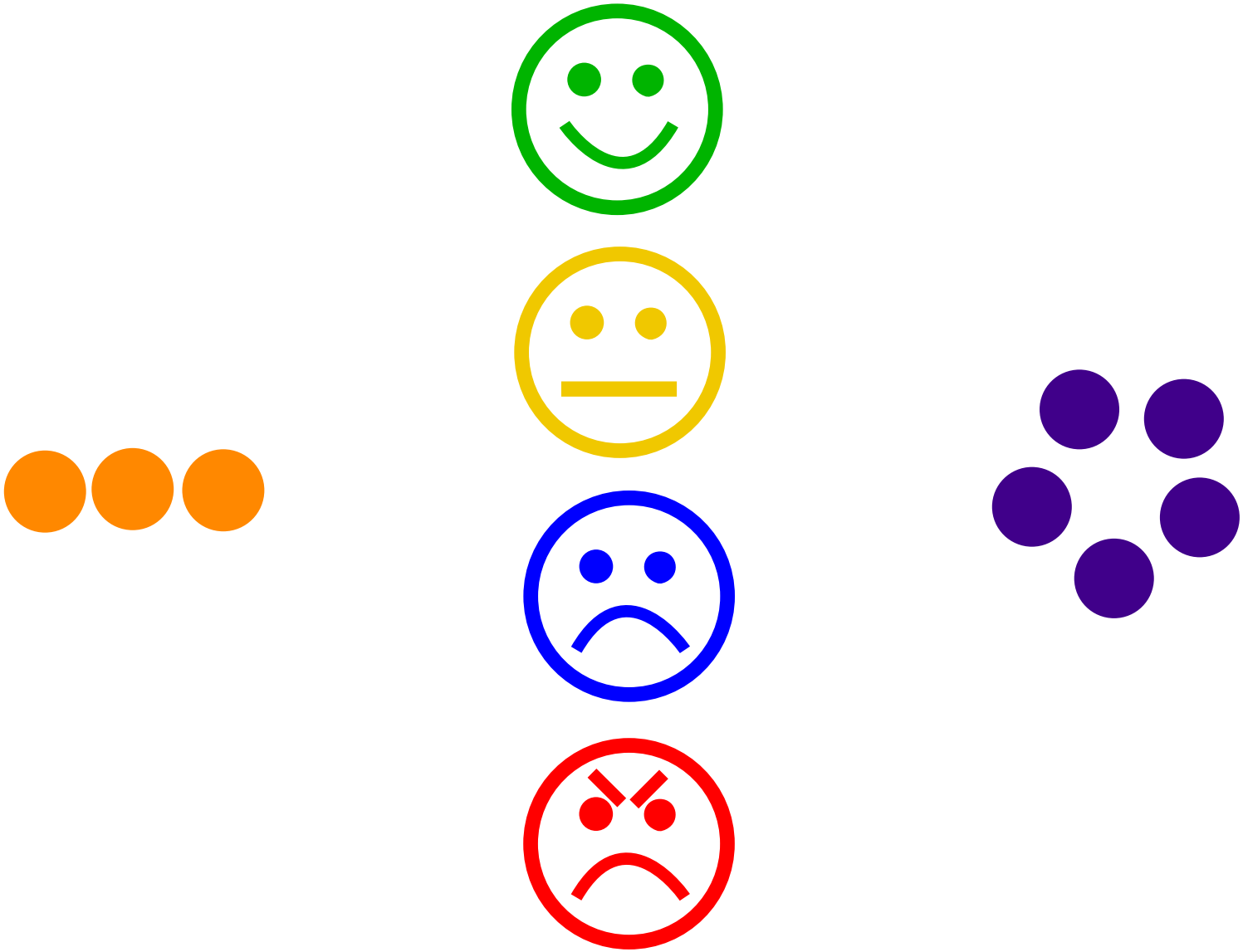

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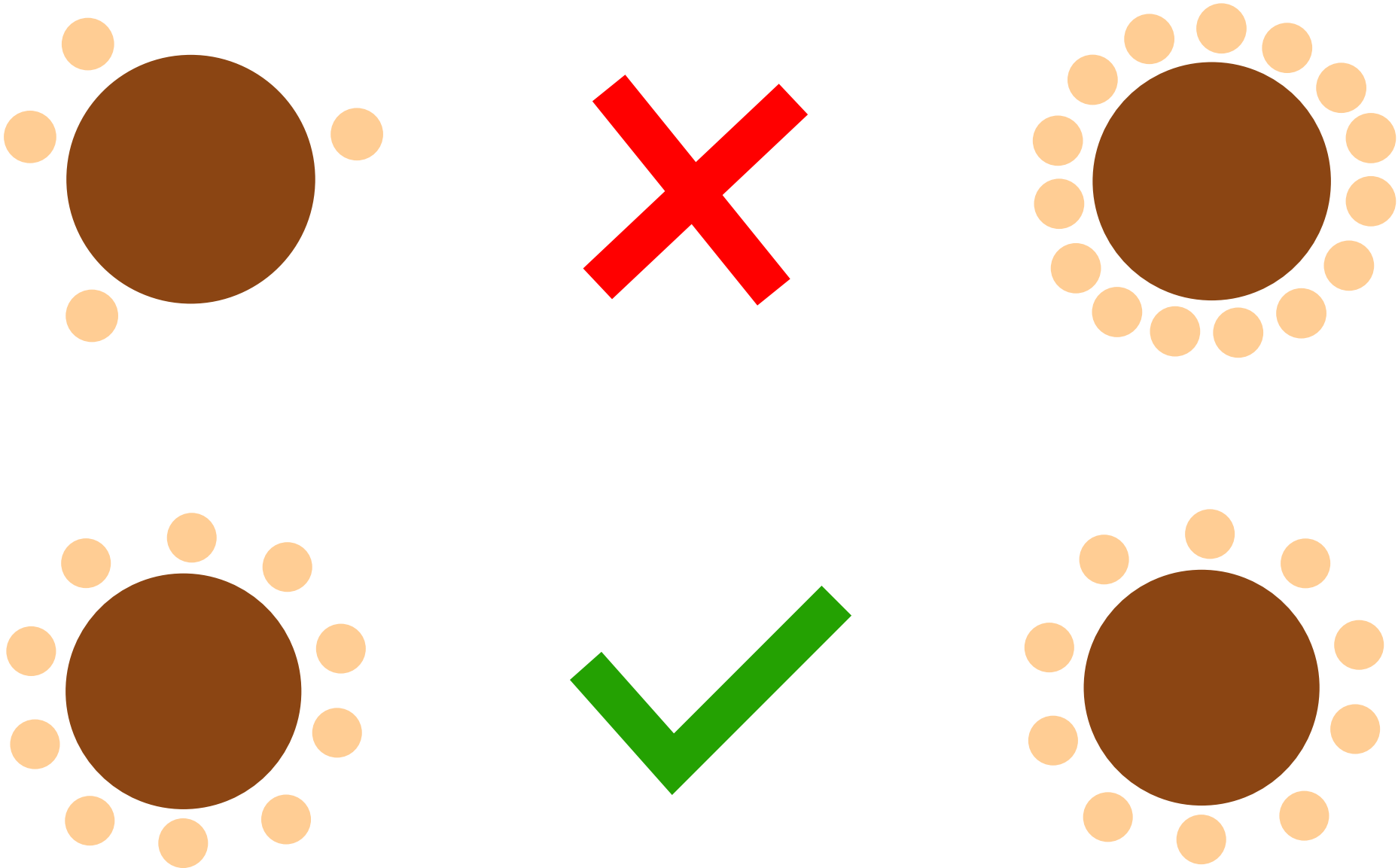

Outline

Existing Methods

Overview

- Original IP model [Bellows and Petersen, *Annals of Improbable Research*, 2012].
- Two-stage algorithm using tabu search [Lewis, *WorldComp International Conference Proceedings*, 2013].
- Improved IP model [Lewis and Carroll, *Journal of the Operational Research Society*, 2016].

Existing Methods

Two-stage algorithm using tabu search [Lewis, 2013]

Build a graph where nodes represent groups, edges represent relations, and colors represent tables.

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- Stage 1: Color nodes to find an initial feasible solution

Existing Methods

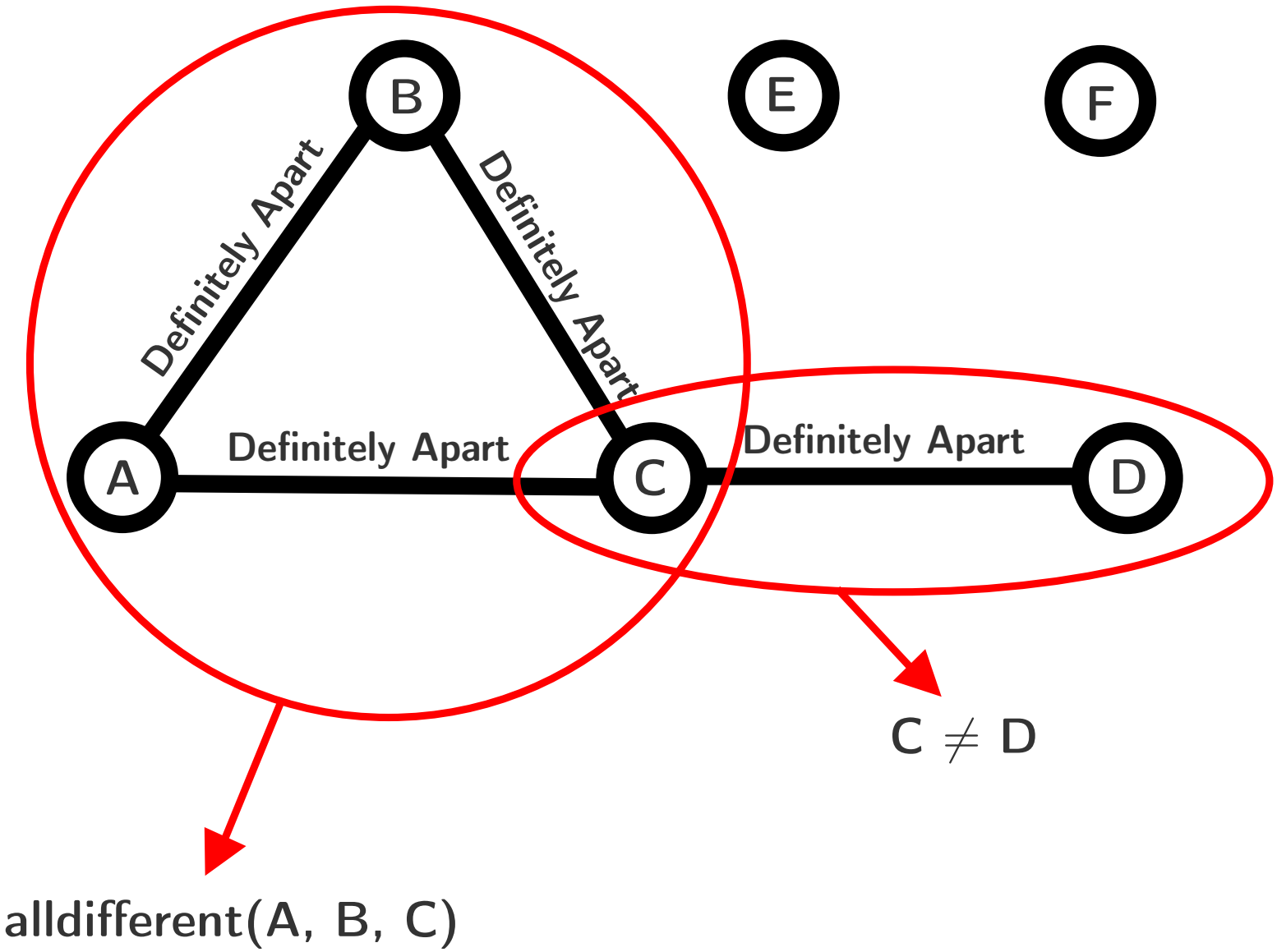
Two-stage algorithm using tabu search [Lewis, 2013]

Build a graph where nodes represent groups, edges represent relations, and colors represent tables.

- Stage 1: Color nodes to find an initial feasible solution
- Stage 2: Improve this feasible solution with a tabu search

Outline

Constraint Programming Model



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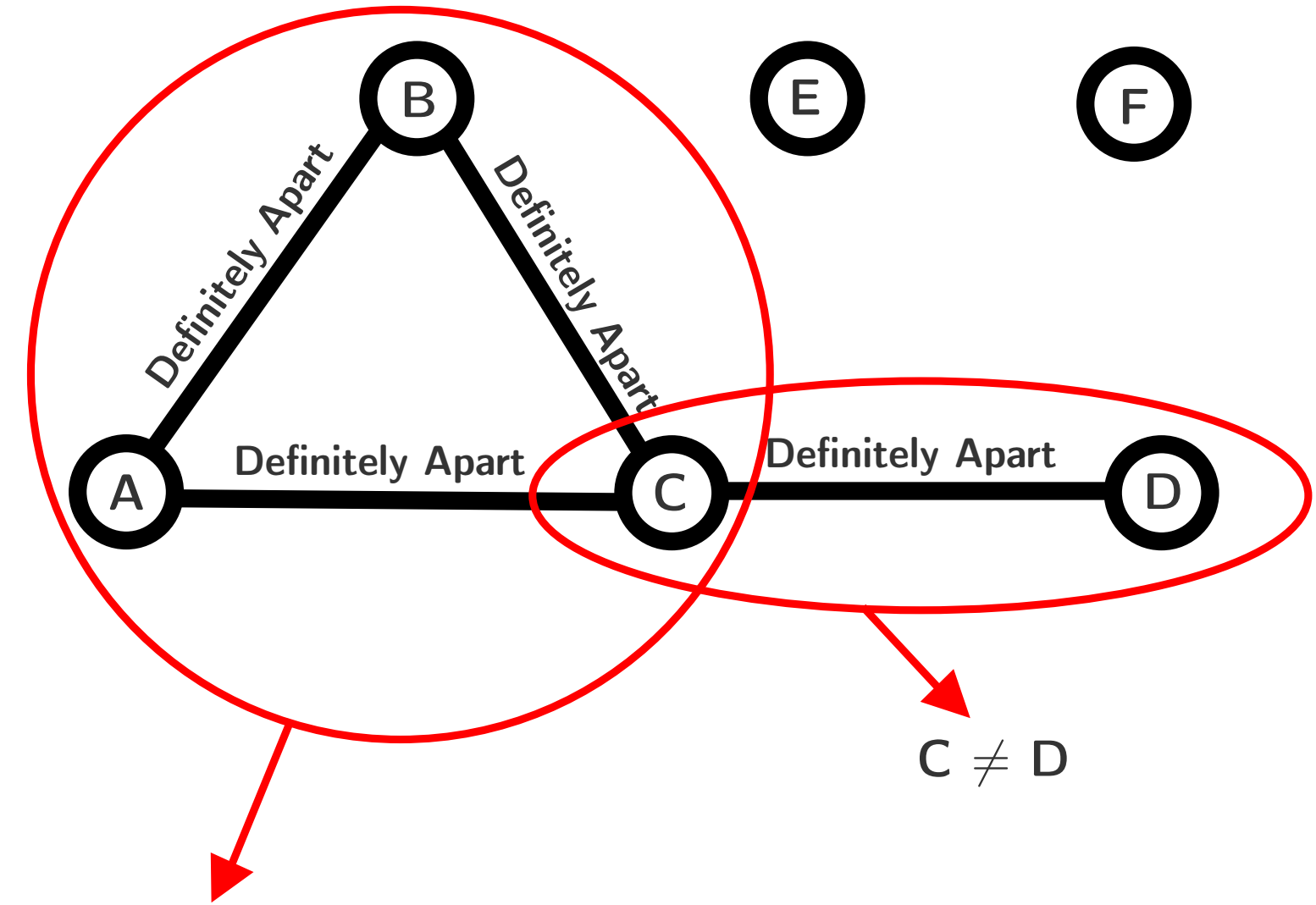

Constraint Programming Model

Constraint Programming Model

binpacking(

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Constraint Programming Model

binpacking(

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alldifferent(

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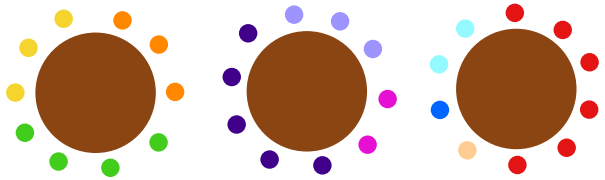
Constraint Programming Model

binpacking( **)**

alldifferent( **)**

balance( **)**

Constraint Programming Model

binpacking( **)**

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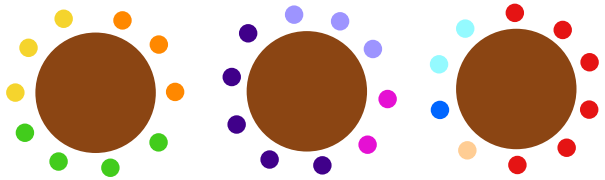
balance( **)**

maximize 

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Branching Heuristic

Similar to *best fit decreasing*:

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1. Pick the largest group yet unassigned
2. Sit that group at the best possible table

Constraint Programming Model

Branching Heuristic

Similar to *best fit decreasing*:

1. Pick the largest group yet unassigned
2. Sit that group at the best possible table
3. If no table has enough room, start a new table