Example Development and Evaluation of an MPC Controller

Workshop 1: Introduction to the BOPTEST framework for simulation-based benchmarking of advanced controllers

IBPSA Building Simulation 2021

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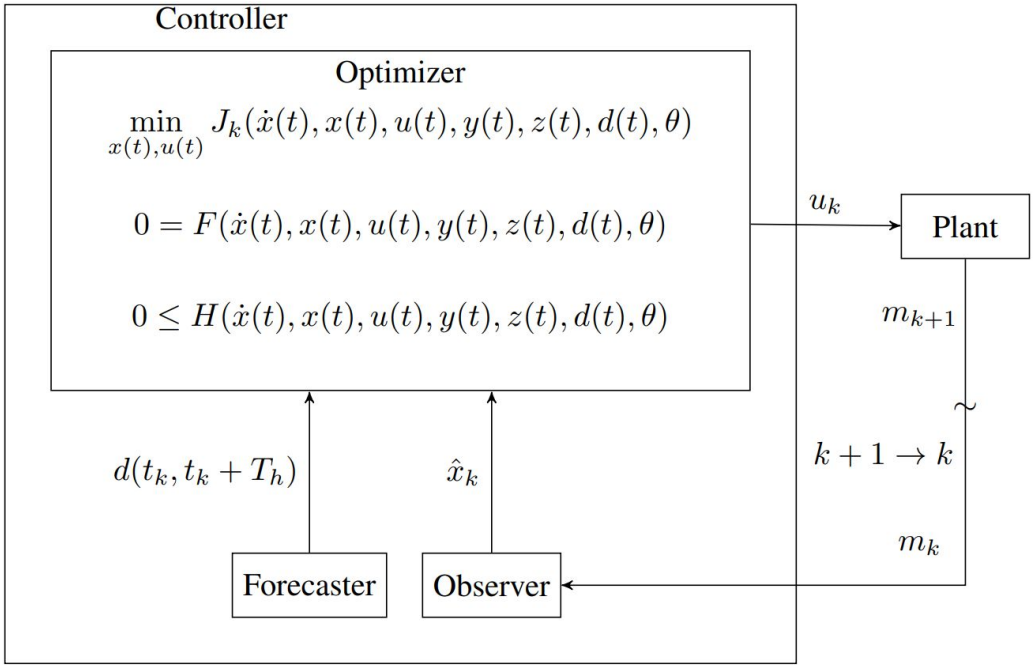
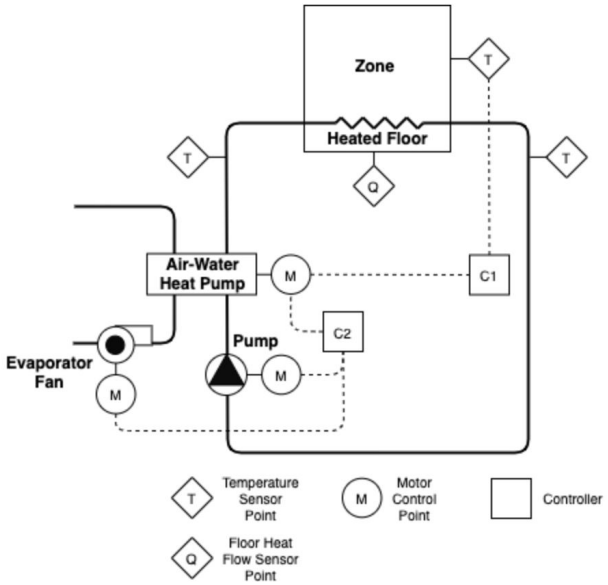
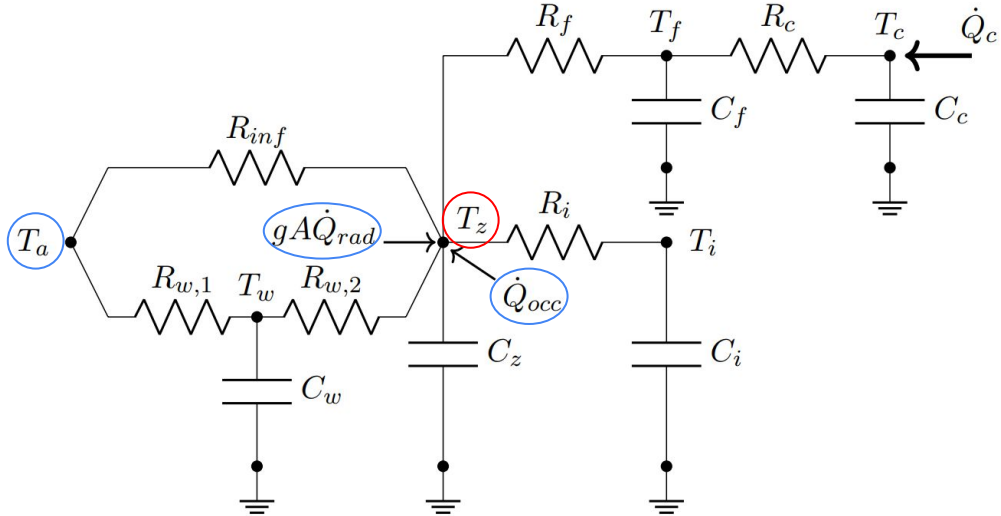
MPC working principle



System identification



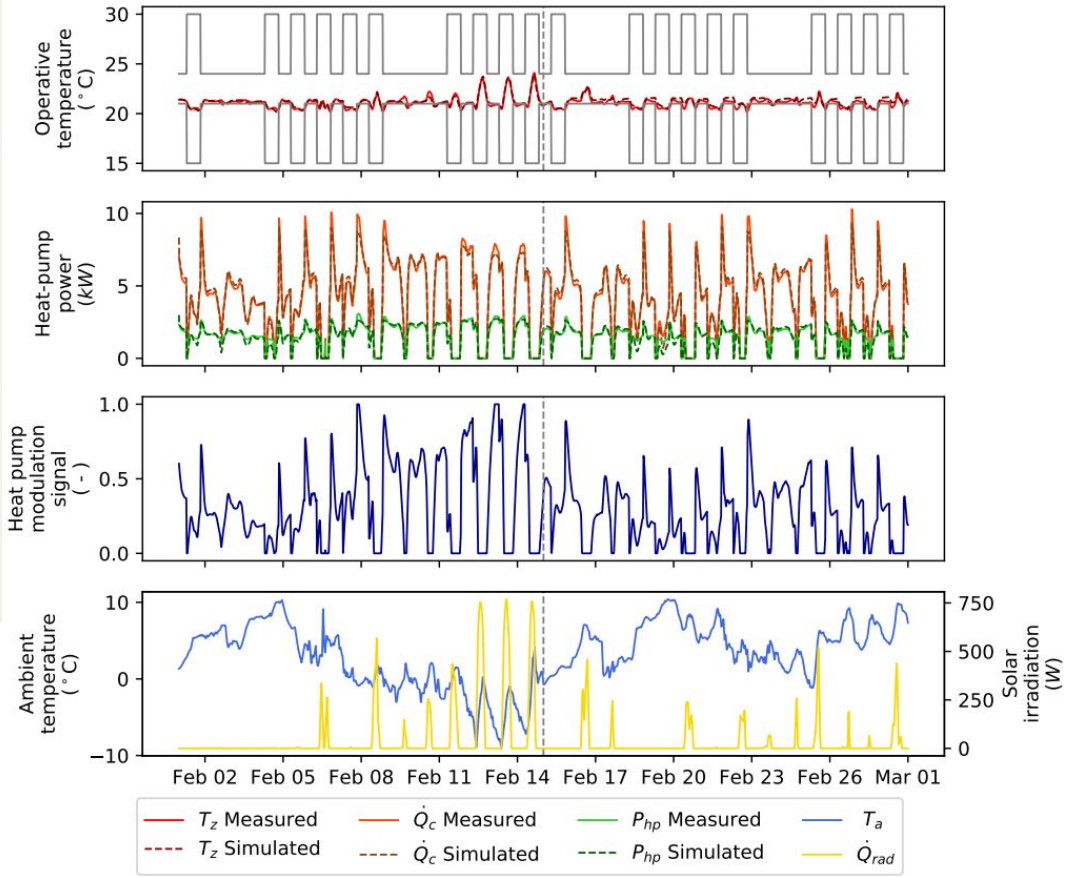
$$\dot{Q}_c = (a_c + b_c(T_c - T_{c,n}) + c_c(T_a - T_{a,n}))k_c\, u_{hp}$$
$$\dot{Q}_e = (a_e + b_e(T_c - T_{c,n}) + c_e(T_a - T_{a,n}))k_e\, u_{hp}$$
$$P_{hp} = \dot{Q}_c - \dot{Q}_e$$
$$COP = \frac{\dot{Q}_c}{P_{hp}},$$



System identification

```python
import requests

# url for the BOPTEST service
url = "http://boptest-workshop.net"

# Select test case and get identifier
testcase = "bestest_hydronic_heat_pump"
testid = \
requests.post("{0}/testcases/{1}/select".format(url,testcase)).json()["testid"]

# Find all measurements and inputs of this emulator
inputs       = requests.get("{0}/inputs/{1}".format(url, testid)).json()
measurements = requests.get("{0}/measurements/{1}".format(url, testid)).json()
all_points   = measurements.keys() + inputs.keys()

# Set the emulator in the desired simulation period and initialize
requests.put("{0}/initialize/{1}".format(url, testid),
             data={"start_time":31*24*3600,
                   "warmup_period":7*24*3600}).json()

# Simulate with baseline control for one month
for _ in range(28*24)
    requests.post("{0}/advance/{1}".format(url, testid),
                  data={}).json()

# Gather data
data = {}
for point in all_points:
    res = requests.put("{0}/results/{1}".format(url, testid),
                       data={"point_name":point,
                             "start_time":0,
                             "final_time":3.1536e7}).json()
    data[point] = res
```

The **Grey-Box Toolbox**[1] is used to prototype the model and train its parameters



1 - R. D. Coninck, F. Magnusson, J. Akesson, and L. Helsen, "*Toolbox for development and validation of grey-box building models for forecasting and control*" Journal of Building Performance Simulation, vol. 9, no. 3, pp. 288–303, 2016. [Online]. Available:https://doi.org/10.1080/19401493.2015.1046933

MPC description

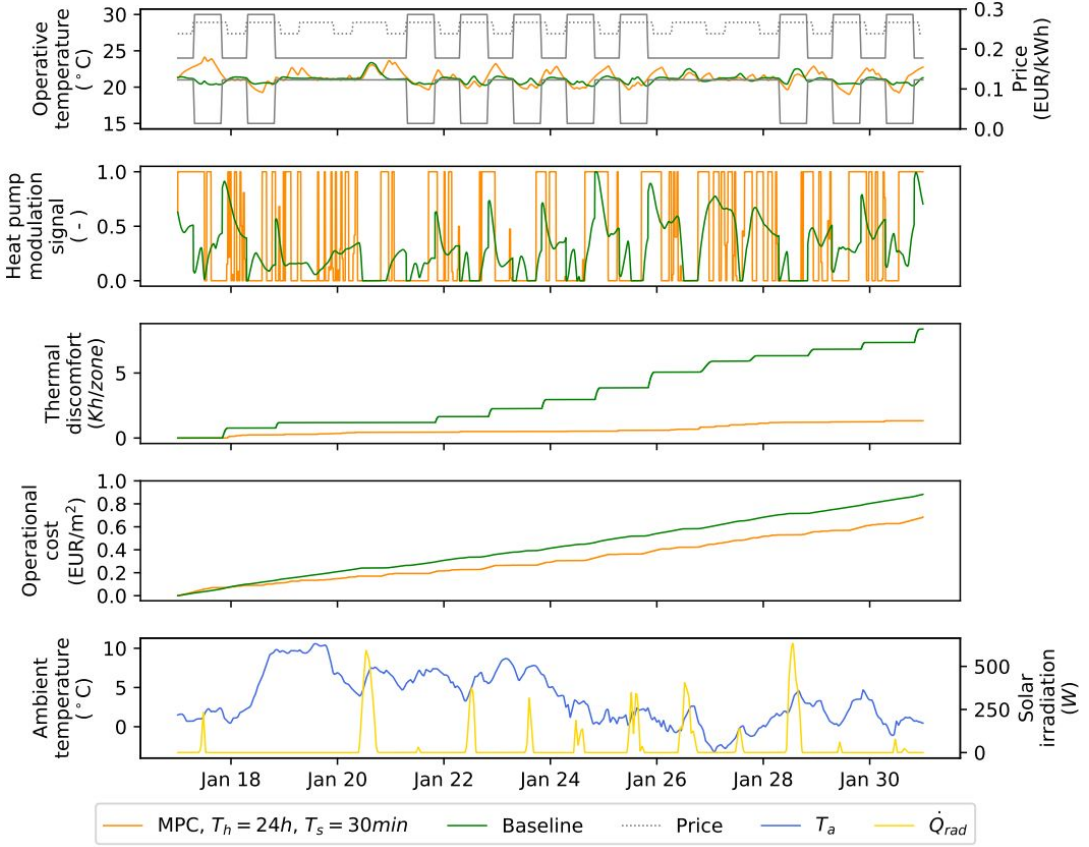
- Controlled variable: zone operative temperature
- Control variable: modulation signal for HP compressor frequency
- BOPTEST deterministic forecast
- Prediction horizon: 12, **24**, 48 hours
- Control step: 15, **30**, 60 minutes
- Direct collocation with JModelica
- Unscented Kalman filter

$$
\begin{aligned}
&\min_{u_{HP}} \int_{t=t_i}^{t_h} (p^{e,\tau}(P_{hp} + P_{fan} + P_{pum}) + w\delta^{T_z})dt \\
&\dot{T}_z, P_{hp}, P_{fan}, P_{pum} = F(u_{hp}, \dot{Q}_{rad}, \dot{Q}_{occ}, T_a, T_z, T_c, T_f, T_i, T_w) \\
&\underline{T}_z - \delta^{T_z} \leq T_z \leq \overline{T}_z + \delta^{T_z} \\
&\delta^{T_z} \geq 0 \\
&0 \leq u_{hp} \leq 1.
\end{aligned}
$$

MPC results

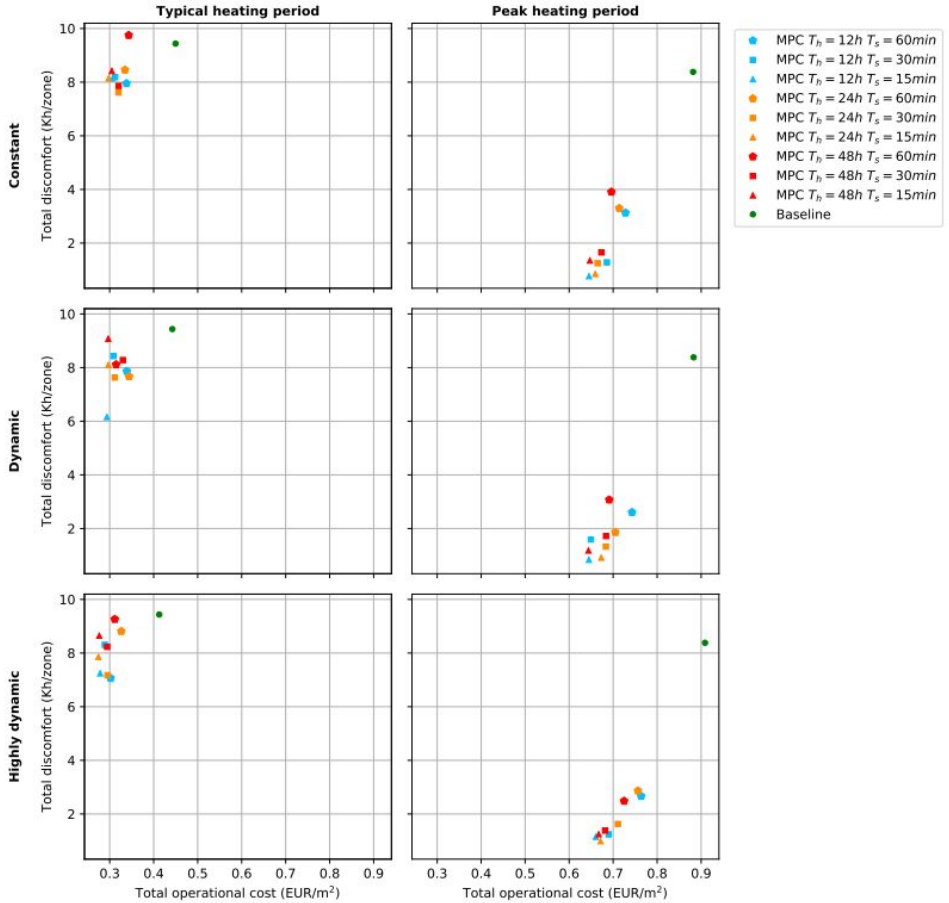
```
34
35 # -- Implement your MPC magic --
36
```

```
37 # Set step
38 requests.put("{0}/step/{1}".format(url, testid),
39               data={"step":30*60})
40
41 # Move to the peak heat testing period with dynamic pricing
42 y = requests.put("{0}/scenario/{1}".format(url, testid),
43                  data={"time_period":"peak_heat_day",
44                        "electricity_price":"dynamic"}).json()
45
46 # Test your MPC magic
47 while y:
48     # Get forecast
49     f = requests.get("{0}/forecast/{1}".format(url, testid)).json()
50
51     # Compute control signal
52     u = mpc.compute_control(y, f)
53
54     # Advance simulation with control signal
55     y = requests.post("{0}/advance/{1}".format(url, testid),
56                       data=u).json()
57
58     # Get KPIs
59     kpi = requests.get("{0}/kpi/{1}".format(url, testid)).json()
60
```



MPC results

```
61 # Get KPIs
62 kpi = requests.get("{0}/kpi/{1}".format(url, testid)).json()
```



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Thank you!

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