



Folien-2 fpv in technische universitat munchen

Funktionale Programmierung (Technische Universität München)

# Example

assignment:	$x = x - y;$
post-condition:	$x > 0$
weakest pre-condition:	$x - y > 0$
stronger pre-condition:	$x - y > 2$
even stronger pre-condition:	$x - y = 3$

... in the GCD Program (1):

assignment:  $x = x - y;$

post-condition:  $A$

weakest pre-condition:

$$\begin{aligned} A[x - y/x] &\equiv \gcd(a, b) = \gcd(x - y, y) \\ &\equiv \gcd(a, b) = \gcd(x, y) \\ &\equiv A \end{aligned}$$

... in the GCD Program (2):

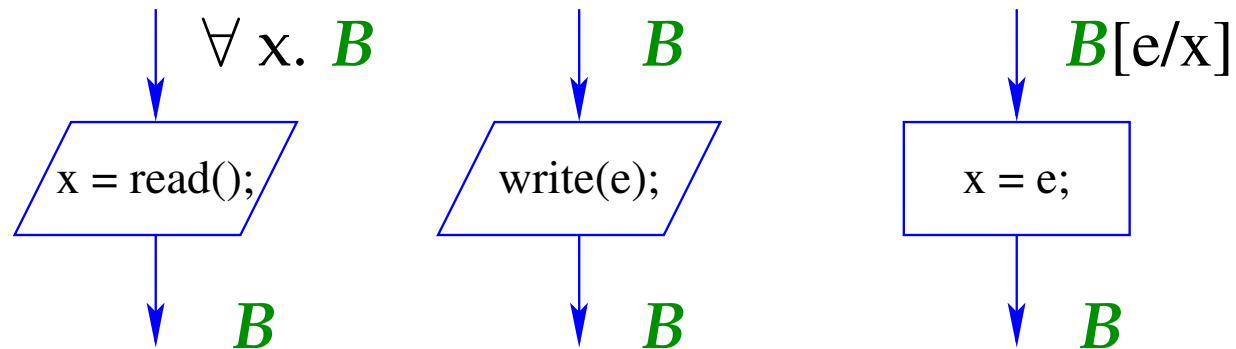
assignment:  $y = y - x;$

post-condition:  $A$

weakest pre-condition:

$$\begin{aligned} A[y - x/y] &\equiv \gcd(a, b) = \gcd(x, y - x) \\ &\equiv \gcd(a, b) = \gcd(x, y) \\ &\equiv A \end{aligned}$$

## Wrap-up



$$\mathbf{WP}[\text{;}] (B) \equiv B$$

$$\mathbf{WP}[x = e;] (B) \equiv B[e/x]$$

$$\mathbf{WP}[x = \text{read();}] (B) \equiv \forall x. B$$

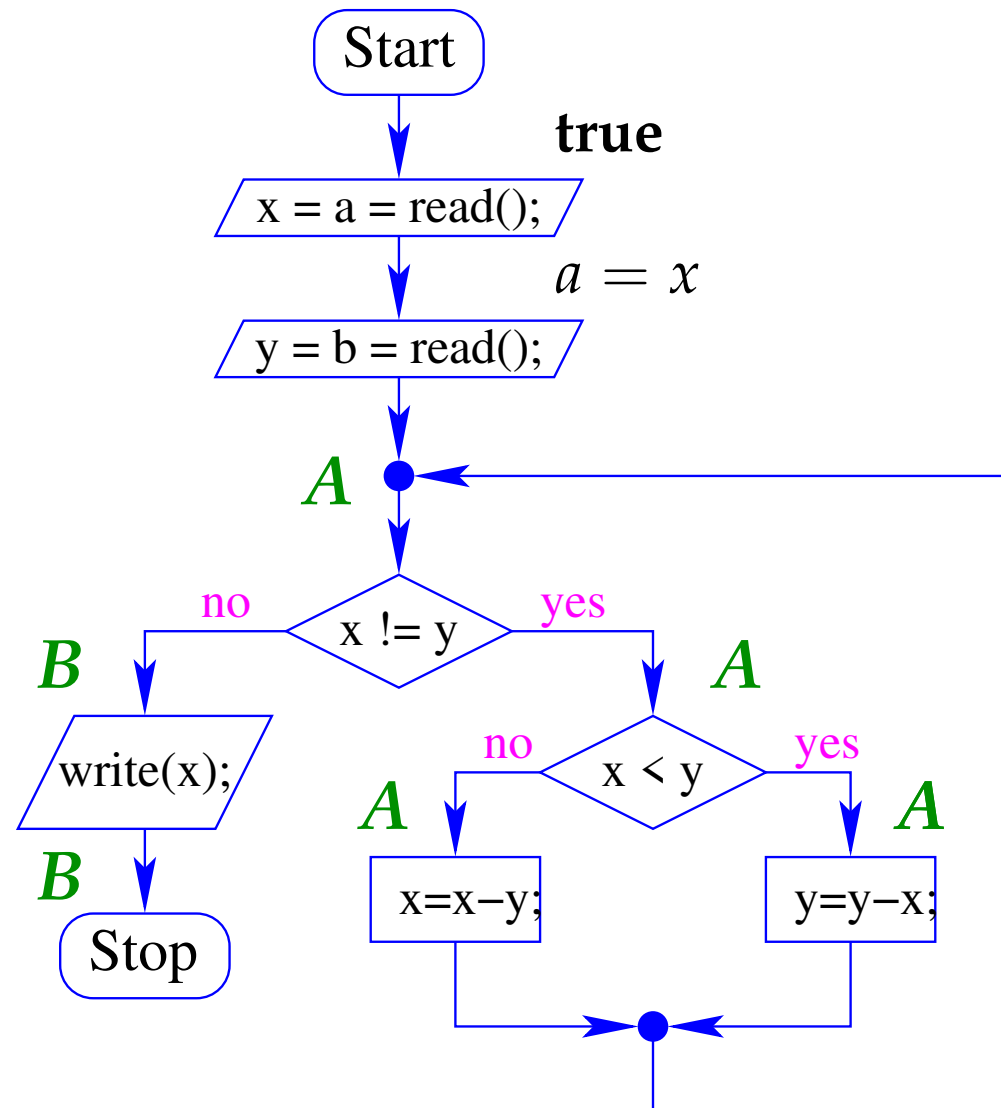
$$\mathbf{WP}[\text{write(e);}] (B) \equiv B$$

# Discussion

- For all actions, the wrap-up provides the corresponding **weakest** pre-conditions for a post-condition  $B$ .
- An output statement does not change any variable. Therefore, the weakest pre-condition is  $B$  itself.
- An input statement  $x = \text{read}();$  modifies the variable  $x$  unpredictably.

In order  $B$  to hold after the input,  $B$  must hold for every possible  $x$  **before** the input.

# Orientation



For the statements: `b = read(); y = b;` we calculate:

$$\begin{aligned}\mathbf{WP}[[y = b;]] (A) &\equiv A[b/y] \\ &\equiv gcd(a, b) = gcd(x, b)\end{aligned}$$

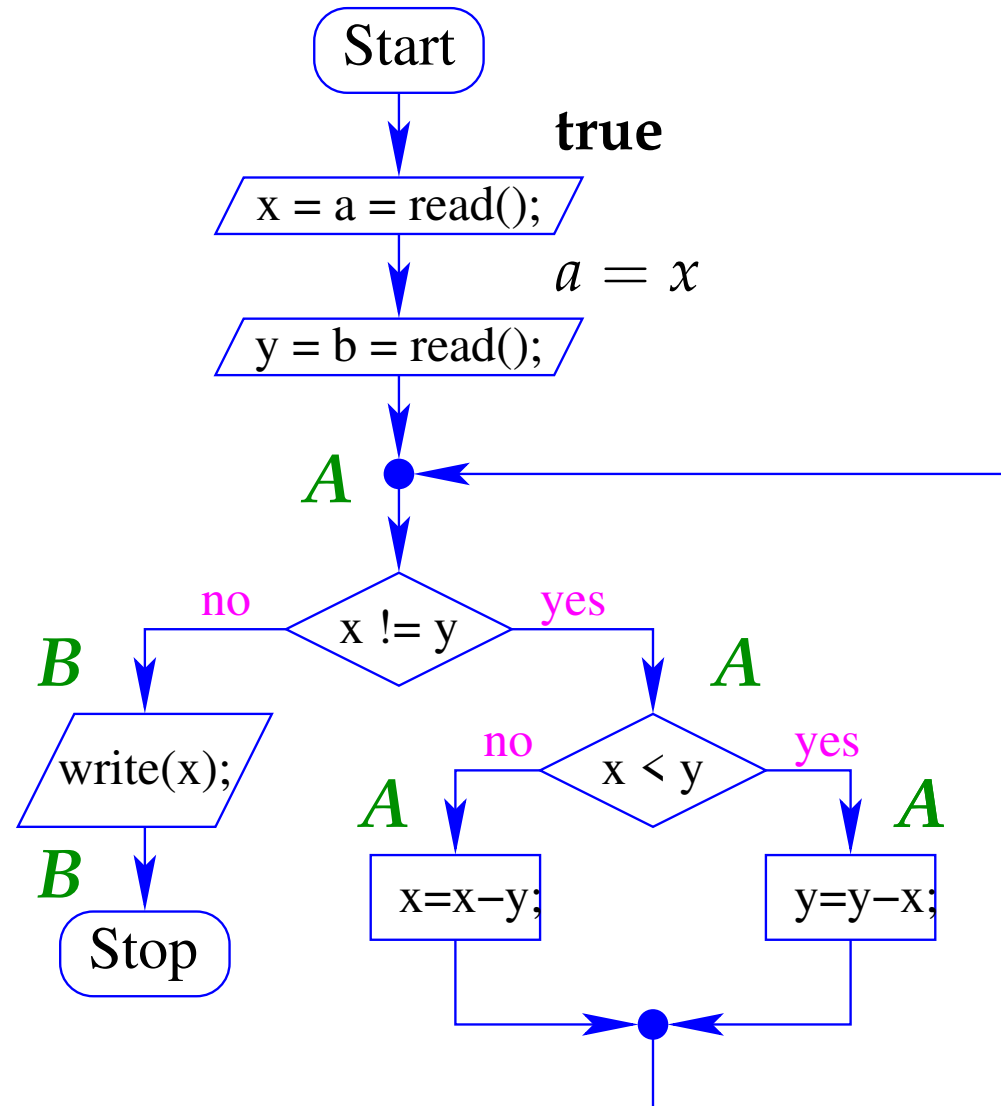


For the statements: `b = read(); y = b;` we calculate:

$$\begin{aligned}\mathbf{WP}[\![y = b;\!]\!] (A) &\equiv A[b/y] \\ &\equiv \gcd(a, b) = \gcd(x, b)\end{aligned}$$

$$\begin{aligned}\mathbf{WP}[\![b = \text{read}();\!]\!] (\gcd(a, b) = \gcd(x, b)) \\ &\equiv \forall b. \gcd(a, b) = \gcd(x, b) \\ &\Leftarrow a = x\end{aligned}$$

# Orientation

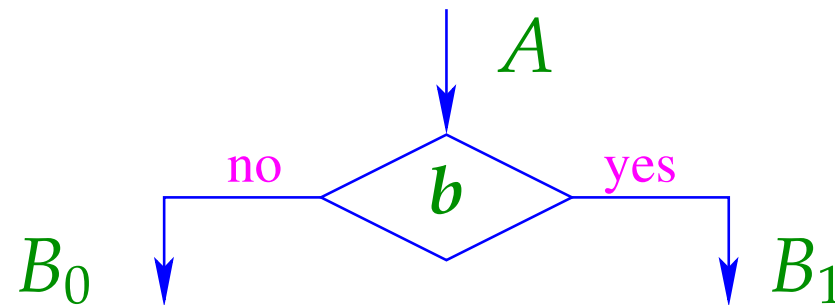


For the statements: `a = read(); x = a;` we calculate:

$$\begin{aligned}\mathbf{WP}[\![x = a;]\!] (a = x) &\equiv a = a \\ &\equiv \mathbf{true}\end{aligned}$$

$$\begin{aligned}\mathbf{WP}[\![a = \text{read()};]\!] (\mathbf{true}) &\equiv \forall a. \mathbf{true} \\ &\equiv \mathbf{true}\end{aligned}$$

## Sub-problem 2: Conditionals



It should hold:

- $A \wedge \neg b \Rightarrow B_0$  and
- $A \wedge b \Rightarrow B_1$  .

This is the case, if  $A$  implies the **weakest pre-condition** of the conditional branching:

$$\mathbf{WP}[[b]] (B_0, B_1) \equiv ((\neg b) \Rightarrow B_0) \wedge (b \Rightarrow B_1)$$

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The weakest pre-condition can be rewritten into:

$$\begin{aligned} \mathbf{WP}[[b]] (B_0, B_1) &\equiv (b \vee B_0) \wedge (\neg b \vee B_1) \\ &\equiv (\neg b \wedge B_0) \vee (b \wedge B_1) \vee (B_0 \wedge B_1) \\ &\equiv (\neg b \wedge B_0) \vee (b \wedge B_1) \end{aligned}$$

## Example

$$B_0 \equiv x > y \wedge y > 0$$

$$B_1 \equiv y > x \wedge x > 0$$

Assume that  $b$  is the condition  $y > x$ .

Then the weakest pre-condition is given by:

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Assume that  $b$  is the condition  $y > x$ .

Then the weakest pre-condition is given by:

$$\begin{aligned} & (x \geq y \wedge x > y \wedge y > 0) \vee (y > x \wedge y > x \wedge x > 0) \\ & \equiv (x > y \wedge y > 0) \vee (y > x \wedge x > 0) \\ & \equiv x > 0 \wedge y > 0 \wedge x \neq y \end{aligned}$$



... for the GCD Example

$$b \equiv y > x$$

$$\neg b \wedge A \equiv x \geq y \wedge \gcd(a, b) = \gcd(x, y)$$

$$b \wedge A \equiv y > x \wedge \gcd(a, b) = \gcd(x, y)$$

... for the GCD Example

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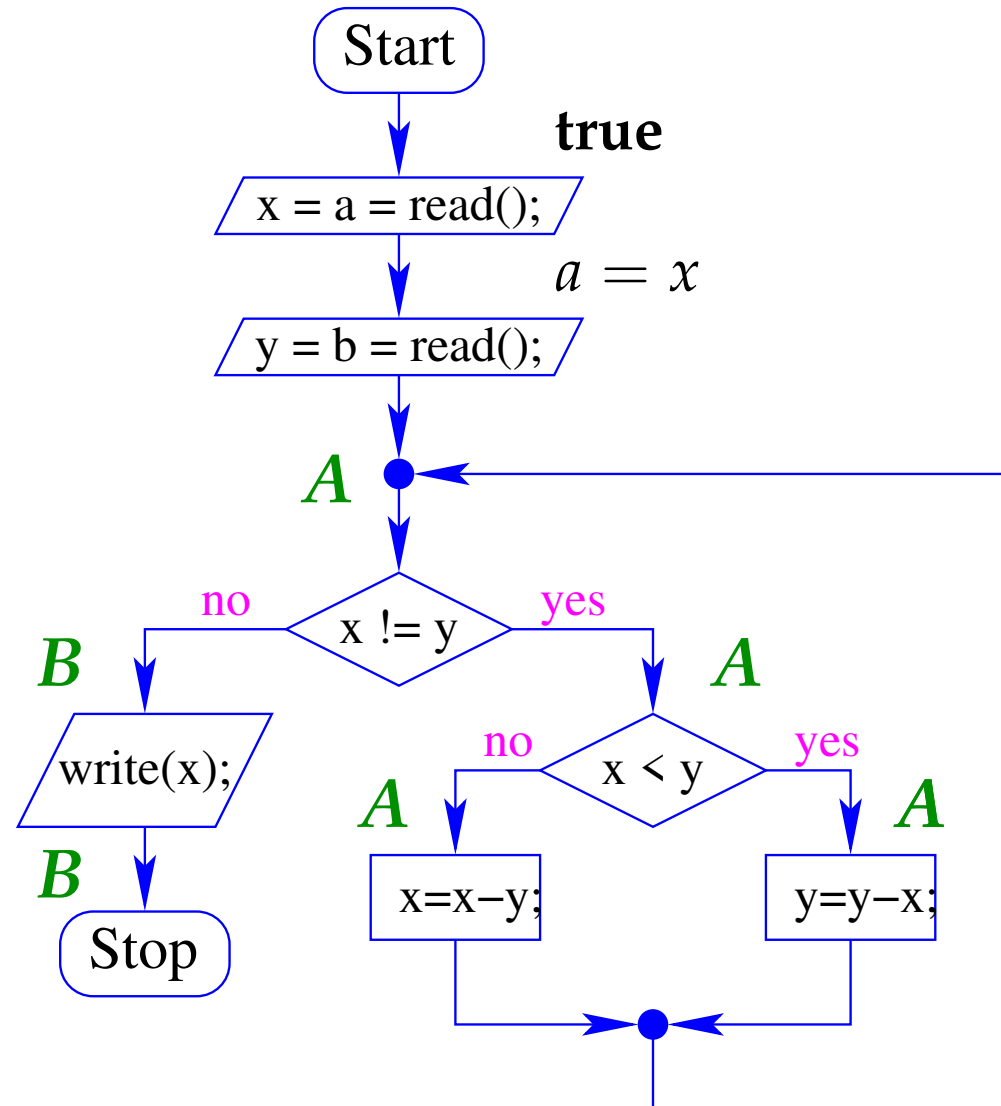


The weakest pre-condition is given by

$$\gcd(a, b) = \gcd(x, y)$$

... i.e., exactly  $A$

# Orientation



The argument for the assertion before the loop is analogous:

$$b \equiv y \neq x$$

$$\neg b \wedge B \equiv B$$

$$b \wedge A \equiv A \wedge x \neq y$$

$\implies A \equiv (A \wedge x = y) \vee (A \wedge x \neq y)$  is the weakest precondition for the conditional branching.

## Summary of the Approach

- Annotate each program point with an assertion.
- Program start should receive annotation **true**.
- Verify for each statement  $s$  between two assertions  $A$  and  $B$ , that  $A$  implies the weakest pre-condition of  $s$  for  $B$  i.e.,

$$A \Rightarrow \mathbf{WP}[[s]](B)$$

- Verify for each conditional branching with condition  $b$ , whether the assertion  $A$  before the condition implies the weakest pre-condition for the post-conditions  $B_0$  and  $B_1$  of the branching, i.e.,

$$A \Rightarrow \mathbf{WP}[[b]](B_0, B_1)$$

An annotation with the last two properties is called **locally consistent**.

## 1.2 Correctness

### Questions

- Which program properties can be verified by means of locally consistent annotations ?
- How can we be sure that our method does not prove wrong claims ??

## Recap (1)

- In **MiniJava**, the program state  $\sigma$  consists of a **variable assignment**, i.e., a mapping of program variables to integers (their values), e.g.,

$$\sigma = \{x \mapsto 5, y \mapsto -42\}$$

## Recap (1)

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$$\sigma = \{x \mapsto 5, y \mapsto -42\}$$

- A state  $\sigma$  **satisfies** an assertion  $A$ , if

$$A[\sigma(x)/x]_{x \in A}$$

// every variable in  $A$  is substituted by its value in  $\sigma$   
is a **tautology**, i.e., equivalent to **true**.

**We write:**  $\sigma \models A$ .



# Example

$$\sigma = \{x \mapsto 5, y \mapsto 2\}$$

$$A \equiv (x > y)$$

$$A[5/x, 2/y] \equiv (5 > 2)$$

$$\equiv \mathbf{true}$$

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$$\sigma = \{x \mapsto 5, y \mapsto 12\}$$

$$A \equiv (x > y)$$

$$A[5/x, 12/y] \equiv (5 > 12)$$

$$\equiv \mathbf{false}$$

# Trivial Properties

$\sigma \models \mathbf{true}$  for every  $\sigma$

$\sigma \models \mathbf{false}$  for no  $\sigma$

$\sigma \models A_1$  and  $\sigma \models A_2$  is equivalent to  
 $\sigma \models A_1 \wedge A_2$

$\sigma \models A_1$  or  $\sigma \models A_2$  is equivalent to  
 $\sigma \models A_1 \vee A_2$

## Recap (2)

- An execution trace  $\pi$  traverses a path in the control-flow graph.
- It starts in a program point  $u_0$  with an initial state  $\sigma_0$  and leads to a program point  $u_m$  with a final state  $\sigma_m$ .
- Every step of the execution trace performs an action and (possibly) changes program point and state.

## Recap (2)

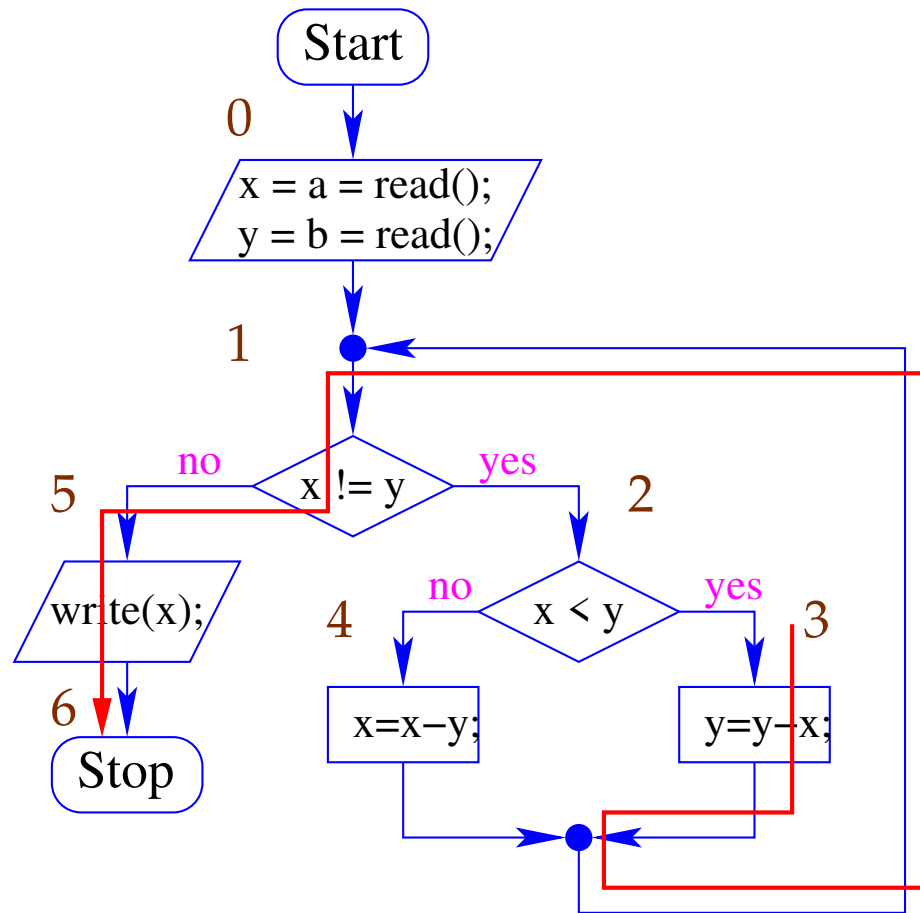
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$\implies$  The trace  $\pi$  can be represented as a sequence

$$(u_0, \sigma_0) s_1 (u_1, \sigma_1) \dots s_m (u_m, \sigma_m)$$

where  $s_i$  are elements of the control-flow graph, i.e., basic statements or (possibly negated) conditional expressions (guards) ...

# Example



Assume that we start in point **3** with  $\{x \mapsto 6, y \mapsto 12\}$ .

Then we obtain the following **execution trace**:

$$\begin{aligned}\pi = & (\mathbf{3}, \{x \mapsto 6, y \mapsto 12\}) \quad y = y - x; \\ & (\mathbf{1}, \{x \mapsto 6, y \mapsto 6\}) \quad \neg(x \neq y) \\ & (\mathbf{5}, \{x \mapsto 6, y \mapsto 6\}) \quad \text{write}(x); \\ & (\mathbf{6}, \{x \mapsto 6, y \mapsto 6\})\end{aligned}$$

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**Important operation:**      Update of of state

$$\sigma \oplus \{x \mapsto d\} = \{z \mapsto \sigma z \mid z \neq x\} \cup \{x \mapsto d\}$$



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$$\begin{aligned}\sigma \oplus \{x \mapsto d\} &= \{z \mapsto \sigma z \mid z \neq x\} \cup \{x \mapsto d\} \\ \{x \mapsto 6, y \mapsto 12\} \oplus \{y \mapsto 6\} &= \{x \mapsto 6, y \mapsto 6\}\end{aligned}$$

# Theorem

Let  $p$  be a MiniJava program, let  $\pi$  be an execution trace starting in program point  $u$  and leading to program point  $v$ .

## Assumptions:

- The program points in  $p$  are annotated by assertions which are locally consistent.
- The program point  $u$  is annotated with  $A$ .
- The program point  $v$  is annotated with  $B$ .

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- The program point  $u$  is annotated with  $A$ .
- The program point  $v$  is annotated with  $B$ .

## Conclusion:

If the initial state of  $\pi$  satisfies the assertion  $A$ , then the final state satisfies the assertion  $B$ .

## Remarks

- If the start point of the program is annotated with **true**, then every execution trace reaching program point  $v$  satisfies the assertion at  $v$ .
- In order to prove that an assertion  $A$  holds at a program point  $v$ , we require a locally consistent annotation satisfying:
  - (1) The start point is annotated with **true**.
  - (2) The assertion at  $v$  implies  $A$ .

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  - (1) The start point is annotated with **true**.
  - (2) The assertion at  $v$  implies  $A$ .
- So far, our method does not provide any guarantee that  $v$  is ever reached !!!
- If a program point  $v$  can be annotated with the assertion **false**, then  $v$  cannot be reached.

# Proof

Let  $\pi = (u_0, \sigma_0) s_1 (u_1, \sigma_1) \dots s_m (u_m, \sigma_m)$

Assumption:  $\sigma_0 \models A$ .

Proof obligation:  $\sigma_m \models B$ .

## Idea

Induction on the length  $m$  of the execution trace.

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## Idea

Induction on the length  $m$  of the execution trace.

**Base**  $m = 0$ :

The endpoint of the execution equals the startpoint.

$\implies \sigma_0 = \sigma_m$  and  $A \equiv B$

$\implies$  the claim holds.

# Important Notion: Evaluation of Expressions

## Program State

$$\sigma = \{x \mapsto 5, y \mapsto -1, z \mapsto 21\}$$

## Arithmetic Expression

$$t \equiv 2 * z + y$$

## Evaluation

$$\begin{aligned} \llbracket t \rrbracket \sigma &= \llbracket 2 * z + y \rrbracket \{x \mapsto 5, y \mapsto -1, z \mapsto 21\} \\ &= 2 \cdot 21 + (-1) \\ &= 41 \end{aligned}$$



# Proposition

For (arithmetic) expressions  $t, e$ ,

$$\llbracket t \rrbracket (\sigma \oplus \{x \mapsto \llbracket e \rrbracket \sigma\}) = \llbracket t[e/x] \rrbracket \sigma$$

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E.g., consider  $t \equiv x + y$ ,  $e \equiv 2 * z$

for  $\sigma = \{x \mapsto 5, y \mapsto -1, z \mapsto 21\}$ .

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E.g., consider  $t \equiv \mathbf{x} + \mathbf{y}$ ,  $e \equiv 2 * \mathbf{z}$

for  $\sigma = \{x \mapsto 5, y \mapsto -1, z \mapsto 21\}$ .

$$\begin{aligned}\llbracket t \rrbracket (\sigma \oplus \{x \mapsto \llbracket e \rrbracket \sigma\}) &= \llbracket t \rrbracket (\sigma \oplus \{x \mapsto 42\}) \\ &= \llbracket t \rrbracket (\{x \mapsto 42, y \mapsto -1, z \mapsto 21\}) \\ &= 42 + (-1) = 41\end{aligned}$$

$$\begin{aligned}\llbracket t[e/\mathbf{x}] \rrbracket \sigma &= \llbracket (2 * \mathbf{z}) + \mathbf{y} \rrbracket \sigma \\ &= (2 \cdot 21) - 1 = 41\end{aligned}$$

# Proposition

$$\sigma \oplus \{x \mapsto \llbracket e \rrbracket \sigma\} \models t_1 < t_2 \quad \text{iff} \quad \sigma \models t_1[e/x] < t_2[e/x]$$

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$$\begin{aligned} \sigma \oplus \{x \mapsto \llbracket e \rrbracket \sigma\} &\models t_1 < t_2 \\ \text{iff} \quad \llbracket t_1 \rrbracket (\sigma \oplus \{x \mapsto \llbracket e \rrbracket \sigma\}) &< \llbracket t_2 \rrbracket (\sigma \oplus \{x \mapsto \llbracket e \rrbracket \sigma\}) \\ \text{iff} \quad \llbracket t_1[e/x] \rrbracket \sigma &< \llbracket t_2[e/x] \rrbracket \sigma \\ \text{iff} \quad \sigma \models t_1[e/x] &< t_2[e/x] \quad \square \end{aligned}$$

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for every formula  $A$ ,

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# Proof

Induction on the structure of formula  $A$   $\square$

## Induction Proof of Correctness (cont.)

**Step**  $m > 0$ :

**Inductive Hypothesis:** The statement holds already for  $m - 1$ .

Let  $B'$  denote the assertion at point  $u_{m-1}$ .

$$\implies \sigma_{m-1} \models B'$$



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**Step**  $m > 0$ :

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Let  $B'$  denote the assertion at point  $u_{m-1}$ .

$$\implies \sigma_{m-1} \models B'$$

First, consider tests  $s_m \equiv b$ .

Then in particular,  $\sigma_{m-1} = \sigma_m$

**Case 1.**  $\sigma_m \models b$

$$\begin{aligned} \implies B' &\Rightarrow \mathbf{WP}[[b]](C, B) && \text{where} \\ &\mathbf{WP}[[b]](C, B) \equiv (\neg b \Rightarrow C) \wedge (b \Rightarrow B) \end{aligned}$$

$$\implies \sigma_m \models b \wedge (b \Rightarrow B)$$

$$\implies \sigma_m \models B \quad \square$$

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**Case 2.**  $\sigma_m \models \neg b$

$$\begin{aligned} \implies B' &\Rightarrow \mathbf{WP}[[b]](B, C) && \text{where} \\ &\mathbf{WP}[[b]](B, C) \equiv (\neg b \Rightarrow B) \wedge (b \Rightarrow C) \end{aligned}$$

$$\implies \sigma_m \models \neg b \wedge (\neg b \Rightarrow B)$$

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## Induction Proof of Correctness (cont.)

**Step**  $m > 0$ :

**Induction Hypothesis:** The statement holds already for  $m - 1$ .

Let  $B'$  denote the assertion at point  $u_{m-1}$ .

$$\implies \sigma_{m-1} \models B'$$

Now we deal with statements.

**Case 1.**  $s_m \equiv$  ;

Then

- $\sigma_{m-1} = \sigma_m$
- $\mathbf{WP}[\text{;}] (B) \equiv B$

$$\implies B' \Rightarrow B$$

$$\implies \sigma_{m-1} = \sigma_m \models B \quad \square$$

**Case 2.**  $s_m \equiv \text{write}(e);$

Then

- $\sigma_{m-1} = \sigma_m$
- $\mathbf{WP}[\text{;write}(e)](B) \equiv B$

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$\implies \sigma_{m-1} = \sigma_m \models B \quad \square$

**Case 3.**  $s_m \equiv x = \text{read}();$

Then

- $\sigma_m = \sigma_{m-1} \oplus \{x \mapsto c\}$  for some  $c \in \mathbb{Z}$
- $\mathbf{WP}[x = \text{read}();](B) \equiv \forall x. B$

$\implies B' \Rightarrow \forall x. B \Rightarrow B[c/x]$

$\implies \sigma_m \models B \quad \square$

**Case 4.**  $s_m \equiv x = e;$

Then we have:

- $\sigma_m = \sigma_{m-1} \oplus \{x \mapsto \llbracket e \rrbracket \sigma_{m-1}\}$
- $B' \implies \mathbf{WP}[\llbracket x = e \rrbracket] (B) \equiv B[e/x]$

$$\implies \sigma_{m-1} \models B[e/x]$$

$$\implies \sigma_{m-1} \models B[e/x] \text{ iff } \sigma_m \models B$$

$$\implies \sigma_m \models B \quad \square$$

**Case 4.**  $s_m \equiv x = e;$

Then we have:

- $\sigma_m = \sigma_{m-1} \oplus \{x \mapsto \llbracket e \rrbracket \sigma_{m-1}\}$
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$$\implies \sigma_m \models B \quad \square$$

This completes the proof of the theorem.



# Conclusion

- The method of Floyd allows us to prove that an assertion  $B$  holds whenever (or under certain assumptions) a program point is reached ...
- For the implementation, we require:
  - the assertion **true** at the start point
  - assertions for each further program point
  - a proof that the assertions are locally consistent

⇒ Logic, automated theorem proving