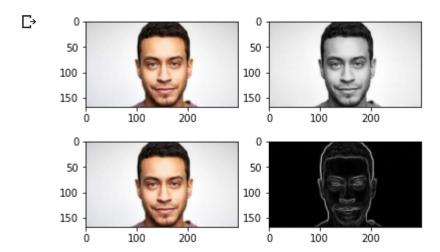
```
#oct 2022
from matplotlib.image import imread
import matplotlib.pyplot as plt
import numpy as np
#import image
image name = "face.jpg"
image input = imread(image name)
#convert color into gray scale
grayscale_image = np.dot(image_input,[1,1,1])//3
grayscale image = grayscale image/255
#display orig and gray image
fig1 = plt.figure(1)
ax1, ax2 = fig1.add subplot(121), fig1.add subplot(122) #2 grids of 1 by 1
ax1.imshow(image input) #show orig image
ax2.imshow(grayscale_image, cmap=plt.get_cmap('gray')) #show gray second
fig1.show()
#using sobel
#matrices associated with the Sobel filter
Gx = np.array([[1, 0, -1], [2, 0, -2], [1, 0, -1]])
Gy = np.array([[1, 2, 1], [0, 0, 0], [-1, -2, -1]])
                      and Gy = \begin{vmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{vmatrix}
     | 1
           0 -1 |
         0 -2 |
Gx = | 2
     | 1
           0 -1 |
[rows,cols] = np.shape(grayscale image) #gray image shape
sobel image = np.zeros(shape=(rows, cols)) # output image array (all elements are 0)
#traverses pixles - x and y direction #compute output
for i in range(rows - 2):
    for j in range(cols - 2):
        gx = np.sum(np.multiply(Gx, grayscale_image[i:i + 3, j:j + 3])) # x direction
        gy = np.sum(np.multiply(Gy, grayscale_image[i:i + 3, j:j + 3])) # y direction
        sobel_image[i + 1, j + 1] = np.sqrt(gx ** 2 + gy ** 2) # calculate the "hypotenuse"
```

```
fig2 = plt.figure(2)
ax1, ax2 = fig2.add_subplot(121), fig2.add_subplot(122)
ax1.imshow(image_input)
ax2.imshow(sobel_image, cmap=plt.get_cmap('gray'))
fig2.show()
```



sources

https://coderspacket.com/sobel-edge-detection-from-scratch-using-python
https://github.com/adamiao/sobel-filter-tutorial/blob/master/sobel_from_scratch.py

```
#a3
#oct 2022
#final project.#v4
#assumption: numbers and hands can stay in the picture. for example the digit 0 is part of th
#images were split and filled in by hand - assumes images were properly filled in
import cv2 as cv
import numpy as np
from google.colab.patches import cv2 imshow #since google collab cant use cv2.imshow
from PIL import Image
#min bounding box
def boundBox(image):
   threshold = 100
                        #determines cutoff for valid black pixel, decrease to tighten boundin
    img = cv.cvtColor(image, cv.COLOR_BGR2GRAY)
   height = img.shape[0]
   width = img.shape[1]
   top row = height - 1  #initialize as max height to insure the value gets change
   bottom_row = 0 #initialize as min height " " "
                            #initialize as max width " " " "
   left col = width - 1
                    #initialize as min width " " " "
   right_col = 0
```

```
for x in range(height):
        for y in range(width):
            if(img[x][y] < threshold): #if the pixel is black</pre>
                if(x < top_row):</pre>
                    top row = x
                                    #this will be the top of the image
                if(x > bottom row):
                    bottom_row = x #bottom of image
                if(y < left col):</pre>
                    left_col = y
                                    #left side of image
                if(y > right col):
                    right col = y #right side of image
    new height = bottom row - top row
    new_width = right_col - left_col
    new img = np.ones((new height, new width, 3), np.uint8)
    new_img = cv.cvtColor(new_img, cv.COLOR_BGR2GRAY)
    if(new height > 0 and new width > 0):
        for x in range(new_height):
            for y in range(new width): #go through the new image (bounding box image
                pixel = img[x+top_row][y+left_col] #get the corresponding pixel value in og i
                new_img[x][y] = pixel #set to new image
    return new_img
# Get the pixel from the given image #get colours
def get pixel(image, i, j):
    # Inside image bounds?
    width, height = image.size
    if i > width or j > height:
      return None
    # Get Pixel
    pixel = image.getpixel((i, j))
    return pixel
# count num of black pixles
def counter(img):
  count_black= 0
  for i in range (img.size[0]):
    for j in range (img.size[1]):
      if get_pixel(img, i,j) == 0:#(0,0,0): #if its black pixle
        count black +=1
  return count black
```

```
#main
x,y,z=[],[],[]
x_percent, y_percent, z_percent = [],[],[]
imageNames = ['zero.jpg','one.jpg','two.jpg', 'three.jpg','four.jpg','five.jpg','six.jpg','se
for imageName in imageNames:
 #read image
 img = cv.imread(imageName) #orig image as an array
 #display image
 print("orig pic",imageName)
 cv2 imshow(img)
 #find min bounding box
 bound = boundBox(img)
 img = bound
 img orig = Image.fromarray(img)
 #1-
        The aspect ratio. (This is the first feature x). The aspect ratio of an image is the
 height = img.shape[0]
 width = img.shape[1]
 print("calculate aspect ratio\n", width, ": ", height, "\n")
 s = width,":",height
 x.append(s)
 x percent.append( round(width/height,3))
 #x.append( width,":",height) #x[i] = width,":",height
        The ratio of the left half black pixels area to the rectangle that has the image. (Th
 #2-
 #3-
        The ratio of the right half black pixels area to the rectangle that has the image. (T
 # Cut the image into left and right half
 width cutoff = width // 2
 s1 = img[:, :width_cutoff]
 s2 = img[:, width_cutoff:]
 print("left pic")
 cv2 imshow(s1)
 print("right pic")
 cv2 imshow(s2)
  img from arr left = Image.fromarray(s1)
  img from arr right = Image.fromarray(s2)
 #count black pixels
  count_black_orig = counter(img_orig)#(img)
 #print("number of black pixles in orig pic", count_black_orig)
```

```
count black left = counter(img from arr left)#(s1)
 print("number of left black pixles: all black pixles\n", count_black_left,":", count_black_
 s = count_black_left,":", count_black_orig
 y.append( s)
 y percent.append( round(count black left/count black orig,3))
 count_black_right = counter(img_from_arr_right)
 print("number of right black pixles: all black pixles\n", count black right,":", count black
 s = count_black_right,":", count_black_orig
 z.append( s)
 z_percent.append( round(count_black_right/count_black_orig,3))
print("\n X Y Z \n")
print(x)
print(y)
print(z)
print("\n X Y Z as percents \n")
print(x_percent)
print(y percent)
print(z_percent)
```

```
orig pic zero.jpg
calculate aspect ratio
 35 : 67
left pic
right pic
number of left black pixles: all black pixles
 301 : 462
number of right black pixles: all black pixles
 161: 462
orig pic one.jpg
calculate aspect ratio
 34:68
left pic
right pic
number of left black pixles: all black pixles
 316 : 707
number of right black pixles: all black pixles
 391 : 707
orig pic two.jpg
calculate aspect ratio
 31:68
left pic
```



right pic



number of left black pixles: all black pixles

289 : 649

number of right black pixles: all black pixles

360: 649

orig pic three.jpg



calculate aspect ratio

46:68

left pic



right pic



number of left black pixles: all black pixles

619 : 909

number of right black pixles: all black pixles

290: 909

orig pic four.jpg



calculate aspect ratio

50:68

left pic



right pic



number of left black pixles: all black pixles

272 : 808

number of right black pixles: all black pixles

F36 000

536 : 808 orig pic five.jpg



calculate aspect ratio
62 : 69

left pic



right pic



number of left black pixles: all black pixles

504 : 928

number of right black pixles: all black pixles

424 : 928

orig pic six.jpg



calculate aspect ratio

33:69

left pic



right pic



number of left black pixles: all black pixles

238 : 769

number of right black pixles: all black pixles

531 : 769

orig pic seven.jpg



calculate aspect ratio

37 : 69

left pic



number of left black pixles: all black pixles
152: 749
number of right black pixles: all black pixles
597: 749
orig pic eight.jpg
8



calculate aspect ratio
46 : 77



number of left black pixles: all black pixles
300 : 872

 $\hbox{number of right black pixles: all black pixles}\\$

572 : 872

orig pic nine.jpg



a3 sources

https://gist.github.com/Integralist/4ca9ff94ea82b0e407f540540f1d8c6c

http://2017.compciv.org/guide/topics/python-nonstandard-libraries/pillow.html

https://stackoverflow.com/questions/72623020/calculate-the-pixel-ratio-of-two-halves-of-an-image

https://stackoverflow.com/questions/45384968/how-to-cut-an-image-vertically-into-two-equal-sized-images

https://www.codementor.io/@isaib.cicourel/image-manipulation-in-python-du1089j1u

 $\frac{https://thispointer.com/convert-a-numpy-array-to-an-image-in-python/\#:\sim:text=The\%20Approach\%20to\%20convert\%20NumPy,using\%20the\%20save()\%20method$

```
[(35, ':', 67), (34, ':', 68), (31, ':', 68), (46, ':', 68), (50, ':', 68), (62, ':', 69)
import cv2 as cv
import numpy as np
def boundBox(image):
   threshold = 100
                       #determines cutoff for valid black pixel, decrease to tighten boundin
    img = cv.cvtColor(image, cv.COLOR BGR2GRAY)
   height = img.shape[0]
   width = img.shape[1]
   top_row = height - 1 #initialize as max height to insure the value gets change
   bottom_row = 0 #initialize as min height " " " "
   left_col = width - 1 #initialize as max width " " " "
   right col = 0 #initialize as min width " " " "
   for x in range(height):
        for y in range(width):
            if(img[x][y] < threshold): #if the pixel is black</pre>
                if(x < top row):
                    top\_row = x
                                    #this will be the top of the image
                if(x > bottom row):
                    bottom_row = x #bottom of image
                if(y < left col):</pre>
                    left col = y  #left side of image
                if(y > right_col):
                    right col = y #right side of image
   new height = bottom row - top row
    new_width = right_col - left_col
   new_img = np.ones((new_height, new_width, 3), np.uint8)
    new img = cv.cvtColor(new img, cv.COLOR BGR2GRAY)
   if(new height > 0 and new width > 0):
        for x in range(new_height):
            for y in range(new_width): #go through the new image (bounding box image
                pixel = img[x+top row][y+left col] #get the corresponding pixel value in og i
                new_img[x][y] = pixel #set to new image
   return new_img
from google.colab.patches import cv2 imshow #since google collab cant use cv2.imshow
```

#from bounding_box import *

```
import numpy as np
import cv2 as cv

zero = cv.imread("zero.jpg")
#print(type(zero))
#zero = cv2_imread("zero.jpg")
zero_bound = boundBox(zero)
#cv.imshow("Zero", zero_bound)
cv2_imshow( zero_bound)
cv.waitKey(0)
```



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